

Sequence processing and language modelling

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Roadmap

Introduction

Neural Language Model: overview

Recurrent architecture

Gated recurrent cells

Outline

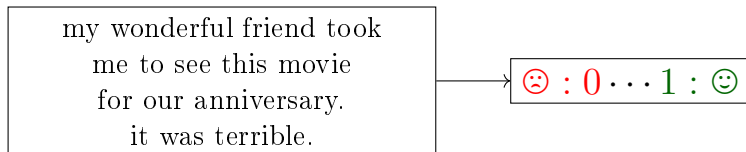
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Sequence classification



Many examples:

- Properties Detection, content classification for an input text (stance, toxicity, bias, fake news, ...)
- Paraphrase detection and textual entailment

Output:

A class or a score (regression)

Sequence tagging

Semantic Role Labelling

Assign semantic role to words, *e.g.*:

$$y_i \in [\text{Agent, Patient, Source, Destination, Instrument}, \dots, \text{Other}]$$

$\mathbf{x} =$	John	drove	Mary	from	Austin	to	Dallas	in	Peugeot
$\mathbf{y} =$	A	O	P	O	S	O	D	O	I

From words to phrases (with BIO scheme for segmentation)

Output:

A sequence of labels, one for each input token.

Conditionnal generation

QA, Prompt, Summarization, ...

- Input/Output belong to the same *domain*.
- The prompt is a kind of "prefix"/context of the generation.


Output:

A text of "arbitrary" length (words, sentences, paragraphs, ...)

tell me more about measure ? A measure is a mapping from ...
context: w_1^6 generation: w_7^L

Use the model to generate: \$\$

Speech recognition / Machine Translation

<i>Input</i>	<i>Output</i>
	[Martine, boude]
[il, est, temps]	[es , ist , zeit]
\mathbf{x}	$\mathbf{w} = (w_1, w_2, \dots, w_I)$

$$P(\mathbf{w}|\mathbf{x}) = \prod_i^I P(w_i|\mathbf{w}_{<\mathbf{i}}, \mathbf{x})$$

- Evaluate \mathbf{w} in the context \mathbf{x}
- Generate \mathbf{w} from \mathbf{x}
- Find the best \mathbf{w} given \mathbf{x}

Deep-Learning blocks

Encoder:

- Compute a representation of the input
 - can be one vector: extraction, compression, ...
 - can be a new sequence of "annotations" or vectors.
- Extract meaningful information for the downstream task

Decoder (QA, bot, ...)

A generative model for sequence: $P(w_1^L) = \underbrace{P(w_1^K)}_{\text{prompt}} \underbrace{P(w_{K+1}^L | w_1^K)}_{\text{answer}}$

Encoder-Decoder (ASR, MT, ...)

$$P(\mathbf{w}|\mathbf{x}) = \prod_i^I P(w_i | \mathbf{w}_{<\mathbf{i}}, \mathbf{x})$$

$\mathbf{x} \rightarrow \text{Encoder} \rightarrow \mathbf{z}$ the internal state $\rightarrow \text{Decode} \rightarrow \mathbf{w}$

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Language modelling task

A word prediction game

$$\begin{array}{cccc} \text{time} & \text{goes} & \text{by} & \text{so} \\ w_1 & w_2 & \cdots & w_{i-1} \end{array} \longrightarrow w_i = ? \left\{ \begin{array}{l} \text{a} \\ \vdots \\ \text{fastly} \\ \vdots \\ \text{slowly} \\ \vdots \end{array} \right.$$

A probability distribution over words

$$P(w_i | w_1^{i-1}), \quad w_i \in \mathcal{V}$$

A probabilistic and generative model

$$P(w_1^L) = \prod_{i=1}^L P(w_i | w_1^{i-1}), \quad \forall i, w_i \in \mathcal{V}$$

Challenges

- Large vocabulary (from 10k to millions)
- Very sparse observation
- Large amount of available data but noisy, heterogenous, ...

Count based model (from 80's to 2000)

Count (or n -gram) based model

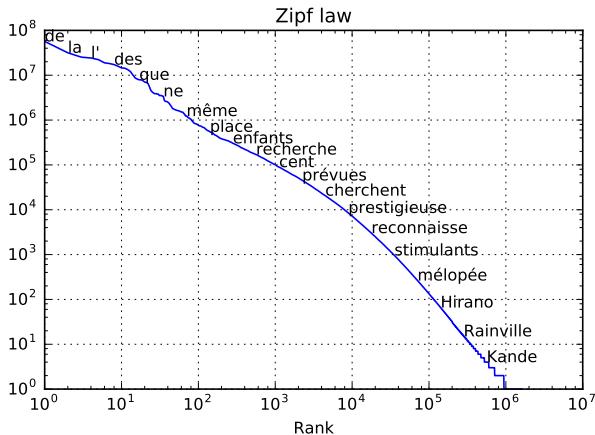
Under a markovian assumption:

$$P(w_i | w_1^{i-1}) \approx P(w_i | \underbrace{w_{i-n+1}^{i-1}}_{\substack{n-1 \\ \text{last words}}}) = \frac{c(w_i | w_1^{i-n+1})}{c(w_1^{i-n+1})}$$

Lack of generalization

- smoothing methods as a workaround
- but no similarity between words

The Zipf law



A second life as an unsupervised learning task

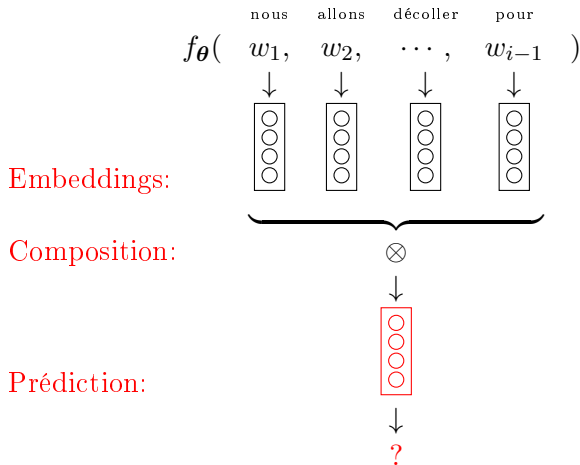
"Language Models are Unsupervised Multitask Learners"

- Leveraging the huge amount of unlabeled texts
- To pre-train word representations
- Along with their contextualization at the sentence level
- That can be fine-tuned for downstream tasks

A profusion of architectures

- Starting with convolution networks [3]
- More recently ELMo and ULMFit with LSTM [7, 6]
- BERT and GPT with Transformers [4, 8]

Neural Language Model



First step: word embeddings [1]

Learning

Leverage all the data you can access !

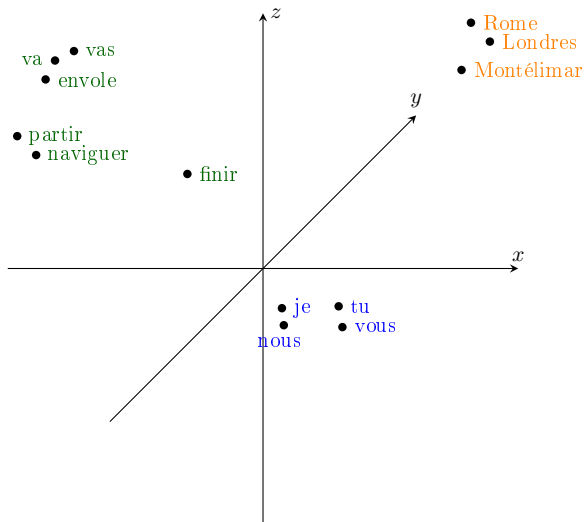
...
tu	vas	partir	pour	Montélimar
je	m'	envole	pour	Londres
ils	vont	finir	à	Montluçon
vous	préférez	naviguer	vers	Brest
...

Prédiction

nous décollons pour → ?

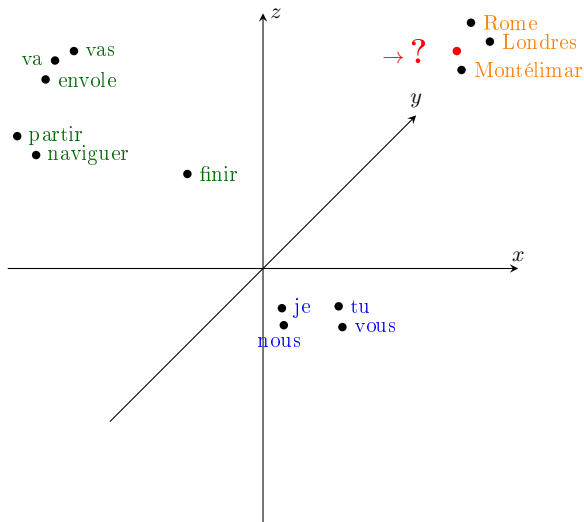
Intuition

nous décollons pour \rightarrow ?

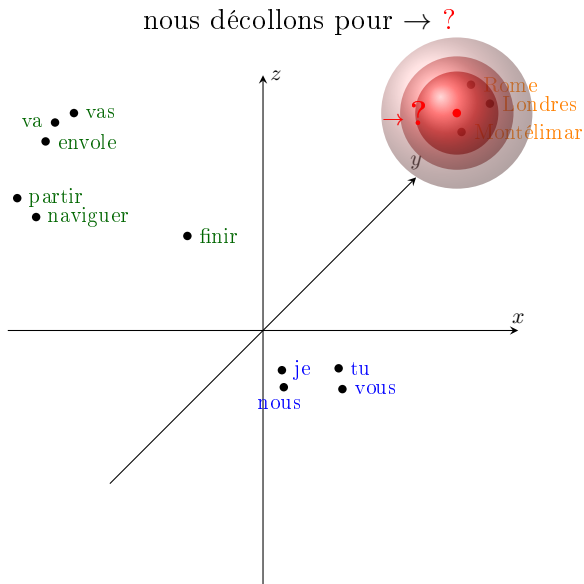


Intuition

nous décollons pour $\rightarrow ?$



Intuition



Architecture for Neural Language Model

The goal

$$P(\mathbf{w}) = \prod_i^I P(w_i | \mathbf{w}_{<i})$$

Oldies but goodies

- n-gram (with NNet):

$$P(w_i | w_{i-n+1}^{i-1}) = f_{\boldsymbol{\theta}}(w_{i-n+1}^{i-1})$$

- recurrent network:

$$P(w_i | w_1^{i-1}) = f_{\boldsymbol{\theta}}(w_1^{i-1})$$

Transformers

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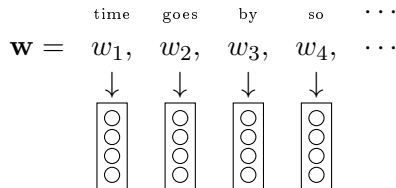
Recurrent architecture

Gated recurrent cells

A dynamical model for sequence - 1

The object under study

A word sequence or its embedded version



Embeddings: $\mathbf{X} = \mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4, \dots$

Assumption

This sequence is generated by a discrete dynamical system

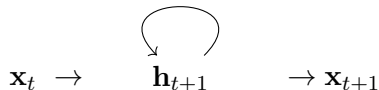
- at each time step: a new word is observed
- update the memory or hidden state
- generate the next word given the hidden state

A dynamical model for sequence - 2

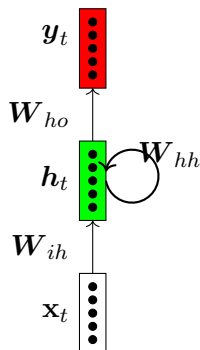
Definition

$$\left\{ \begin{array}{ll} \mathbf{h}_{t+1} = f_{\boldsymbol{\theta}}(\underbrace{\mathbf{x}_t}_{\text{observation}}, \underbrace{\mathbf{h}_t}_{\text{recurrence}}), & \text{memory} \\ \mathbf{x}_{t+1} = g_{\Phi}(\mathbf{h}_{t+1}), & \text{generation} \end{array} \right.$$

At each time step:



The Elman Cell for LM [5]



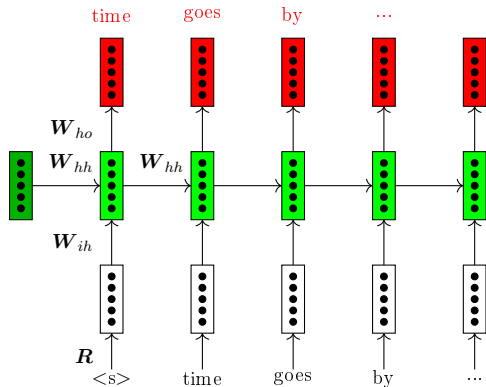
A dynamic system, at time t :

- maintains a hidden vector (the memory): h_t
- Updated with the observation of \mathbf{x}_t and h_{t-1}
- The (optional) prediction y_t depends on the internal state (h_t)
- For a language model, \mathbf{x}_t comes from word embeddings

The parameters are shared !

(Vanilla) Recurrent network language model

Unfolding the structure: a deep-network



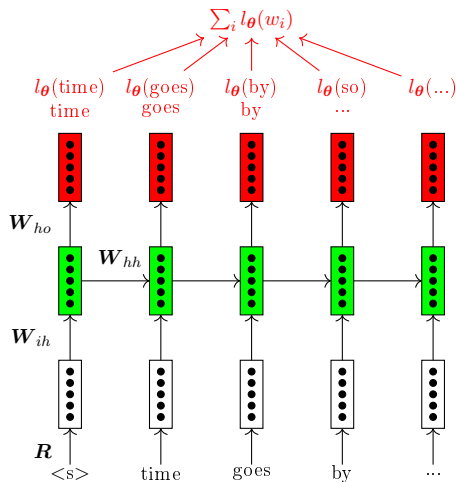
At each step t :

$$h_t = f(W_{ih}x_t + W_{hh}h_{t-1})$$

$$y_t = g(W_{ho}h_t)$$

g is the softmax function
over the vocabulary

Training recurrent language model



Back-Propagation through time or BPTT [9]

Issues with Elman Cell

Gradient vanishing / exploding

- The unfolded network is (very) deep
- The architecture is difficult to train

Long range dependencies

- Difficult to infer long range dependencies
- Unstable dynamical system difficult to control
- No memory management

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Motivations

- Address the gradient propagation issue
- Allow the model to skip/keep information through time

Starting point

$$\mathbf{h}_{t+1} = f_{\theta}\left(\overbrace{\mathbf{x}_t}^{\text{observation}}, \underbrace{\mathbf{h}_t}_{\text{recurrence}} \right)$$

- This function is too simple
- Same for output prediction

From recurrent network to LSTM/GRU: the gate

$$\mathbf{h}_t = f(\mathbf{W}_{ih}\mathbf{x}_t + \mathbf{W}_{hh}\mathbf{h}_{t-1})$$

- What if we want to mitigate the impact of \mathbf{h}_{t-1} ?
- To reset (softly) the memory for some components

A Gate is a filter

$$\underbrace{\begin{pmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \\ \cdot \\ \dots \end{pmatrix}}_{\mathbf{h}_{t-1}} \rightarrow \underbrace{\begin{matrix} \times 1 \\ \times 0 \\ \times 0.5 \\ \times 0.14397 \\ \times 0.88972 \\ \times \dots \end{matrix}}_{\text{filter values: } \mathbf{r}} \Leftrightarrow \mathbf{h}_{t-1} * \mathbf{r}$$

The values of \mathbf{r} can be inferred as a function of \mathbf{h}_{t-1} and \mathbf{x}_t .

Implementation of a gate as a NNet

$$\mathbf{r}_t = \sigma(\mathbf{W}_{ir}\mathbf{x}_t + \mathbf{W}_{hr}\mathbf{h}_{t-1})$$

- A simple Linear layer
- Followed by a sigmoid
- Each output component is between 0 and 1
- A soft learnable gate

Gated Recurrent unit (GRU)[2]

The updated hidden state :

$$\mathbf{h}_t = (1 - \mathbf{z}_t) * \mathbf{h}_{t-1} + \mathbf{z}_t * \hat{\mathbf{h}}_t$$

The candidate $\hat{\mathbf{h}}_t$:

$$\hat{\mathbf{h}}_t = \phi_h(\mathbf{W}_{ih}\mathbf{x}_t + \mathbf{W}_{hh}(\mathbf{r}_t * \mathbf{h}_{t-1}))$$

The gates:

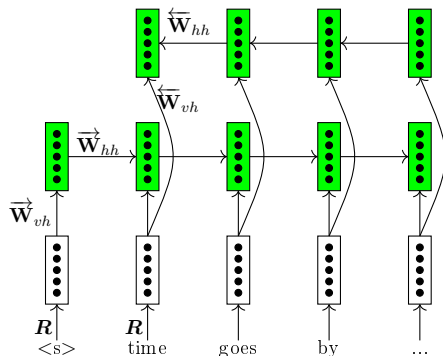
$$\begin{aligned}\mathbf{z}_t &= \sigma_g(\mathbf{W}_{iz}\mathbf{x}_t + \mathbf{W}_{hz}\mathbf{h}_{t-1}) \\ \mathbf{r}_t &= \sigma_g(\mathbf{W}_{ir}\mathbf{x}_t + \mathbf{W}_{hr}\mathbf{h}_{t-1})\end{aligned}$$

LSTM : Control flow - in one slide

$$\text{Input: } \underbrace{[\mathbf{h}_{t-1}; \mathbf{x}_t]}_{z_t} \longrightarrow \left\{ \begin{array}{ll} \tilde{C}_t = \tanh(\mathbf{W}_C z_t + \mathbf{b}_C), & \text{basic update} \\ i_t = \sigma(\mathbf{W}_i z_t + \mathbf{b}_i), & \text{input gate} \\ f_t = \sigma(\mathbf{W}_f z_t + \mathbf{b}_f), & \text{forget gate} \\ o_t = \sigma(\mathbf{W}_o z_t + \mathbf{b}_o), & \text{output gate} \end{array} \right.$$

$$\text{Output: } \mathbf{C}_t = \underbrace{f_t * \mathbf{C}_{t-1}}_{\text{previous state}} + \underbrace{i_t * \tilde{\mathbf{C}}_t}_{\text{recurrence}}$$
$$\mathbf{h}_t = o_t * \tanh(\mathbf{C}_t)$$

Sentence encoder : the bi-recurrent solution



At each step t , from left to right

- $w_t \rightarrow \mathbf{x}_t$
- $\vec{\mathbf{h}}_t = f(\vec{\mathbf{W}}_{vh} \mathbf{x}_t + \vec{\mathbf{W}}_{hh} \vec{\mathbf{h}}_{t-1})$

And from right to left

- $w_t \rightarrow \mathbf{x}_t$
- $\overleftarrow{\mathbf{h}}_t = f(\overleftarrow{\mathbf{W}}_{vh} \mathbf{x}_t + \overleftarrow{\mathbf{W}}_{hh} \overleftarrow{\mathbf{h}}_{t-1})$

$[\vec{\mathbf{h}}_t; \overleftarrow{\mathbf{h}}_t]$: contextualized representation of w_t

Conclusion on recurrent architecture

A powerful architecture for sequence

- Useful for classification
- Sequence tagging and language model
- Encoder / Decoder architecture
- And works with attention (of course)

Some limitations

- Auto-regressive inference (encoder or decoder)
- Issues with long-term memories