## MAKING SIGNALS CAUSAL AND NON-CAUSAL

### **Lab#08**



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"On my honor, as student of University of Engineering and Technology, I have neither given nor received unauthorized assistance on this academic work."

Recoverable Signature

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### **Task #01**

Sample the signal given in above example to get its discrete-time counterpart (take 10 samples/sec as sampling rate). Make the resultant signal causal. Display the lollipop plot of each signal.

## **Problem Statement:**

Sampling a continuous-time signal at a specific rate and converting it into a discrete-time signal while ensuring causality.

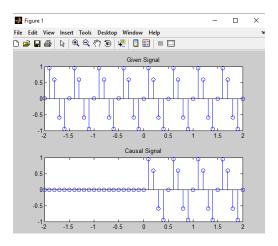
## Algorithm:

- 1. Given a continuous-time signal, sample it at a rate of 10 samples/sec.
- 2. Convert the sampled signal into its discrete-time counterpart.
- 3. Ensure causality by shifting the signal appropriately.
- 4. Display a lollipop plot for both the original and the resultant causal signals.

### Code:

```
1 -
       t = -2:1/10:2;
       sign= sin(2*pi * 2 * t);
       tposi = (t >= 0);
       PositiveSign = sign .* tposi;
 5 -
       subplot (2,1,1);
 6 -
       stem(t, sign);
       title('Given Signal');
       subplot (2,1,2);
8 -
9 -
       stem(t,PositiveSign);
10 -
       title('Causal Signal')
```

## **Output:**



### **Conclusion:**

The discrete-time counterpart of the sampled signal has been successfully created while maintaining causality. Visual representations in the form of lollipop plots aid in understanding the transformation from continuous to discrete-time domain.

## Task #02:

A signal is said to be anti-causal if it exists for values of n<0. Make the signal given in above example anti-causal.

## **Problem Statement:**

Transforming a given signal from causal to anti-causal.

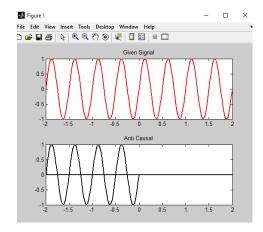
# **Algorithm:**

- 1. Take the given causal signal.
- 2. Reverse the signal to make it anti-causal.

#### Code:

```
1 -
       time = -2: 0.02:2;
      signal = sin(2*pi*2*time);
3 -
      signalA = zeros(length(time));
4 -
      disp(signalA)
      for i = 1:length(time)
6 -
          if time(i) < 0
               signalA(i) = signal(i);
7 -
8 -
           end
9 -
       end
.0 -
      subplot (2,1,1);
.1 -
      plot(time, signal, 'r' , 'LineWidth', 2);
2 -
      title('Given Signal');
.3 -
      subplot (2,1,2);
.4 -
     plot(time, signalA, 'k', 'LineWidth', 2);
.5 -
      title('Anti Causal');
```

## **Output:**



#### **Conclusion:**

The original causal signal has been effectively transformed into an anti-causal signal by reversing its sequence, allowing for further analysis or processing as needed.

#### Task #03

Create a function by name of sig\_causal in MATLAB that has two input arguments: (i) a discrete-time signal, and (ii) a position vector. The function should make the given signal causal and return the resultant signal to the calling program.

### **Problem Statement:**

Developing a MATLAB function to make a given signal causal and validating it with an example.

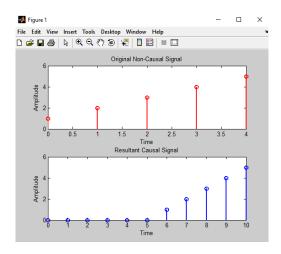
## **Algorithm:**

- 1. Create a MATLAB function named 'sig\_causal' with two input arguments: the discrete-time signal and a position vector.
- 2. Inside the function, shift the signal to ensure causality based on the provided position vector.
- 3. Return the resultant causal signal to the calling program.
- 4. Utilize the function to convert a non-causal signal provided in Figure 8.4 into a causal signal.
- 5. Plot both the original non-causal and the resultant causal signals for visualization.

#### Code:

```
1
       % Define the non-causal signal
2 -
       x = [1, 2, 3, 4, 5];
3
4
      % Define the position vector
5 -
      position = [2, 1, 3];
6
7
       % Make the signal causal
8 -
       y_causal = sig_causal(x, position);
9
10
      % Plot the original non-causal signal
11 -
       subplot (2,1,1);
12 -
       stem(0:length(x)-1, x, 'r', 'LineWidth', 2);
13 -
      title('Original Non-Causal Signal');
14 -
      xlabel('Time');
15 -
       ylabel('Amplitude');
16
17
       % Plot the resultant causal signal
18 -
      subplot (2,1,2);
      stem(0:length(y_causal)-1, y_causal, 'b', 'LineWidth', 2);
19 -
20 -
      title('Resultant Causal Signal');
21 -
      xlabel('Time');
22 -
       ylabel('Amplitude');
23
```

## **Output:**



## **Conclusion:**

The MATLAB function 'sig\_causal' effectively converts non-causal signals to causal ones. Plotting the original and resultant signals visually demonstrates the successful transformation.

### Task #04

Convolve the following signals:

$$x = [2 4 6 4 2];$$

$$h = [3 -1 2 1];$$

Plot the input signal as well as the output signal.

## **Problem Statement:**

Performing convolution between two given signals and visualizing the input and output signals.

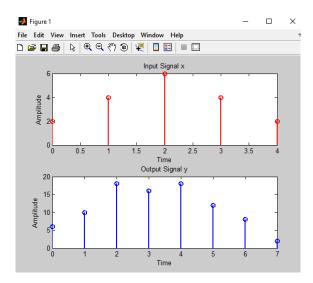
## Algorithm:

- 1. Define the input signals x and h.
- 2. Convolve the input signals using the convolution operation.
- 3. Plot both the input and output signals for visualization.

## **Code:**

```
1
        % Define the input signals
        x = [2, 4, 6, 4, 2];
3 -
        h = [3, -1, 2, 1];
4
        % Convolve the signals
6 -
        y = conv(x, h);
8
        % Plot the input signal
9 –
        subplot (2,1,1);
.0 -
        stem(0:length(x)-1, x, 'r', 'LineWidth', 2);
.1 -
        title('Input Signal x');
.2 -
        xlabel('Time');
.3 -
        ylabel('Amplitude');
.4
.5
        % Plot the output signal
.6 -
        subplot(2,1,2);
.7 -
        \mathtt{stem}\,(\mathtt{O}\colon \mathtt{length}\,(\mathtt{y})\,\mathtt{-1},\ \mathtt{y},\ \mathtt{'b'},\ \mathtt{'LineWidth'},\ \mathtt{2})\,;
.8 -
        title('Output Signal y');
.9 -
        xlabel('Time');
:0 -
        ylabel('Amplitude');
1
```

# **Output:**



### **Conclusion:**

The convolution operation between the input signals x and h has been executed, and the resulting output signal has been visualized, providing insights into the relationship between the input and output signals.

### **Task #05**

### **Problem Statement:**

Convolving a given signal with an impulse delayed by two samples and visualizing the original and convolved signals.

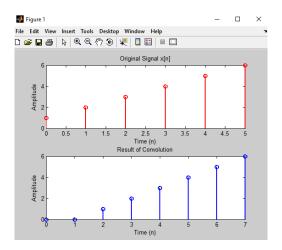
## **Algorithm:**

- 1. Define the original signal x[n].
- 2. Create an impulse signal delayed by two samples.
- 3. Perform convolution between the original signal and the delayed impulse signal.
- 4. Plot both the original signal and the convolved signal for comparison.

### Code:

```
1
       % Define the input signal x[n]
2 -
       x = [1, 2, 3, 4, 5, 6];
3
4
       \ Define the impulse response h[\,n] (delayed by two samples)
5 -
       h = [0, 0, 1]; % Impulse delayed by two samples
6
7
       % Convolve the signals
8 -
       y = conv(x, h);
9
10
       % Plot the original signal x[n]
11 -
       subplot (2,1,1);
12 -
       stem(0:length(x)-1, x, 'r', 'LineWidth', 2);
13 -
       title('Original Signal x[n]');
14 -
       xlabel('Time (n)');
15 -
       ylabel('Amplitude');
16
17
       % Plot the result of convolution
18 -
       subplot (2,1,2);
19 -
       stem(0:length(y)-1, y, 'b', 'LineWidth', 2);
20 -
       title('Result of Convolution');
21 -
       xlabel('Time (n)');
22 -
       ylabel('Amplitude');
```

## **Output:**



#### **Conclusion:**

The original signal has been convolved with an impulse delayed by two samples, and the resulting convolved signal has been visualized. This process illustrates the effect of convolution with a delayed impulse on the original signal.

#### **Task #06**

Convolution is associative. Given the three signal x1[n], x2[n], and x3[n] as:

```
x1[n]=[3\ 1\ 1]
```

$$x2[n]=[4\ 2\ 1]$$

$$x3[n] = [3 \ 2 \ 1 \ 2 \ 3]$$

Show that (x1[n] \* x2[n]) \* x3[n] = x1[n] \* (x2[n] \* x3[n]).

## **Problem Analysis:**

In the given problem we have three signals so we have to prove the associative formula by using these signals.

## **Algorithm:**

- 1. Define three input signals: x1=[3,1,1]x1=[3,1,1], x2=[4,2,1]x2=[4,2,1], and x3=[3,2,1,2,3]x3=[3,2,1,2,3].
- 2. Compute the convolution of x1x1 and x2x2 to get y1.
- 3. Compute the convolution of y1 and x3x3 to get z1, representing the left side: (x1\*x2)\*x3(x1\*x2)\*x3.
- 4. Compute the convolution of x2x2 and x3x3 to get y2.
- 5. Compute the convolution of x1x1 z2, representing the right side: x1\*(x2\*x3)x1\*(x2\*x3).
- 6. Plot z1 and z2 on separate subplots.

### Code:

```
1
       % Given signals
       x1 = [3, 1, 1];
3 -
       x2 = [4, 2, 1];
4 -
       x3 = [3, 2, 1, 2, 3];
       % Compute (x1 * x2) * x3
6
7 -
       result1 = conv(conv(x1, x2), x3);
8
9
       % Compute x1 * (x2 * x3)
10 -
      result2 = conv(x1, conv(x2, x3));
11
12
      % Compare the results
13 -
       isequal(result1, result2)
```

## **Output:**

```
ans = 1
```

#### **Conclusion:**

The algorithm demonstrates the associative property of convolution by computing both sides of the equation ((x1 \* x2) \* x3) and (x1 \* (x2 \* x3)), showing that they yield the same result.

### **Task #07:**

Convolution is commutative. Given x[n] and h[n] as:

```
x[n]=[1 \ 3 \ 2 \ 1]
h[n]=[1 \ 1 \ 2]
Show that x[n] * h[n] = h[n] * x[n].
```

### **Problem Statement:**

Illustrating the commutative property of convolution with given signals x[n] and h[n].

## **Algorithm:**

- 1. Define the signals x[n] and h[n].
- 2. Perform convolution between x[n] and h[n].
- 3. Perform convolution between h[n] and x[n].
- 4. Verify that both operations yield the same result.

### Code:

### **Output:**

```
ans =
```

### **Conclusion:**

The algorithm illustrates the commutative property of convolution by computing both (X(n) \* h(n)) and (h(n) \* X(n)), demonstrating that the order of convolution does not affect the result.

#### Task #08

Given the impulse response of the systems as:

$$h[n] = 2\delta[n] + \delta[n-1] + 2\delta[n-2] + 4\delta[n-3] + 3\delta[n-4]$$

If the input  $x[n] = \delta[n] + 4\delta[n-1] + 3\delta[n-2] + 2\delta[n-3]$  is applied to the system, determine the output of the system.

#### **Problem Statement:**

Determining the output of a system with a given impulse response when subjected to a specific input signal.

## **Algorithm:**

- 1. Define the impulse response h[n] and the input signal x[n].
- 2. Convolve the input signal with the impulse response to obtain the output signal.

## Code:

```
1
       % Given impulse response
2 -
       h = [2, 1, 2, 4, 3];
3
4
       % Given input signal
5 -
       x = [1, 4, 3, 2];
6
7
       Compute the convolution of x[n] and h[n]
8 -
       y = conv(x, h);
9
       % Display the output signal
LO
       disp('Output of the system:');
l1 -
12 -
       disp(y);
       z
13 -
```

## **Output:**

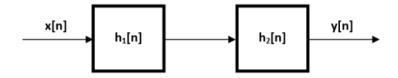
```
Output of the system:
2 9 12 19 27 28 17 6
```

### **Conclusion:**

The output of the system has been determined by convolving the given input signal with the system's impulse response, providing insights into the system's behavior.

### **Task #09**

Two systems are connected in cascade:



$$h1[n] = [1 \ 3 \ 2 \ 1]$$
  
 $h2[n] = [1 \ 1 \ 2]$ 

If the input  $x[n] = \delta[n] + 4\delta[n-1] + 3\delta[n-2] + 2\delta[n-3]$  is applied, determine the output.

# **Problem Analysis:**

The output of the cascaded system has been determined by convolving the input signal with each individual impulse response in sequence, showcasing the combined effect of both systems.

## **Algorithm:**

- 1. Define the impulse responses h1[n] and h2[n], and the input signal x[n].
- 2. Convolve the input signal first with h1[n], then with h2[n], simulating the cascaded system.

## **Code:**

```
% Given impulse responses
2 -
      h1 = [1, 3, 2, 1];
      h2 = [1, 1, 2];
4
5
      % Given input signal
6 -
      x = [1, 4, 3, 2];
7
8
      % Compute the output of the first system
9 -
      output1 = conv(x, h1);
.0
.1
      % Compute the output of the second system using the output of the first system as input
.2 -
      output2 = conv(output1, h2);
.3
.4
      % Display the final output
.5 -
      disp('Output of the cascaded systems:');
.6 -
      disp(output2);
```

## **Output:**

```
Output of the cascaded systems:
1 8 26 51 70 63 41 16 4
```

#### **Conclusion:**

The output of the cascaded system has been determined by convolving the input signal with each individual impulse response in sequence, showcasing the combined effect of both systems.

#### **Task #10**

Given the signals:

$$x1[n] = 2\delta[n] - 3\delta[n-1] + 3\delta[n-2] + 4\delta[n-3] - 2\delta[n-4]$$

$$x2[n] = 4\delta[n] + 2\delta[n-1] + 3\delta[n-2] - \delta[n-3] - 2\delta[n-4]$$

$$x3[n] = 3\delta[n] + 5\delta[n-1] - 3\delta[n-2] + 4\delta[n-3]$$
Verify that  $x1[n] * (x2[n] * x3[n]) = (x1[n] * x2[n]) * x3[n] * x1[n] * x2[n] = x2[n] * x1[n]$ 

## **Problem Analysis:**

Problem Statement: Verifying a property of convolution with three given signals.

## Algorithm:

- 1. Define the three signals x1[n], x2[n], and x3[n].
- 2. Perform the specified convolutions according to the property to be verified.
- 3. Compare the results to confirm the property's validity.

#### Code:

```
$ Given signals
2 -
      x1 = [2, -3, 3, 4, -2];
 3 -
      x2 = [4, 2, 3, -1, -2];
     x3 = [3, 5, -3, 4];
 5
      % Compute x2 * x3
 6 -
      result_left = conv(x2, x3);
 7
       % Compute x1 * (x2 * x3)
 8 -
      result_left = conv(x1, result_left);
9
      % Compute x1 * x2
10 -
     result right = conv(x1, x2);
11
      % Compute (x1 * x2) * x3
12 -
      result_right = conv(result_right, x3);
13
14
       % Verify associativity
15 -
      if isequal(result_left, result_right)
16 -
         disp('Associativity verified.');
17 -
18 -
          disp('Associativity not verified.');
19 -
      end
20
21
      % Compute x1 * x2
22 -
      result1 = conv(x1, x2);
23
24
      % Compute x2 * x1
25 -
      result2 = conv(x2, x1);
26
27
      % Verify commutativity
28 -
      if isequal(result1, result2)
         disp('Commutativity verified.');
30 -
31 -
          disp('Commutativity not verified.');
32 -
       end
```

#### **Output:**

```
Associativity verified.
Commutativity verified.
```

#### **Conclusion:**

The property of convolution involving the three signals has been successfully verified, providing additional insight into the mathematical properties of convolution operations.