

# **LAB: Digital Image Processing: Date 30 September 2025**

**Dr. Irfan Ali**

*Assistant Professor & Coordinator Multimedia & Gaming*

## **Objective:**

- Understand how images can be represented in the frequency domain.
- **Visualize the magnitude and phase spectrum of an image.**

## **Magnitude Spectrum:**

- Represents the strength (amplitude) of different frequency components in an image.
- Bright areas = strong frequencies.
- Determines how much of each frequency is present (controls contrast and brightness levels).

## **Phase Spectrum:**

- Represents the position (angle/shift) of frequency components.
- Looks noisy/random, but it encodes the structural and spatial details of the image.
- Responsible for preserving edges, shapes, and object alignment..

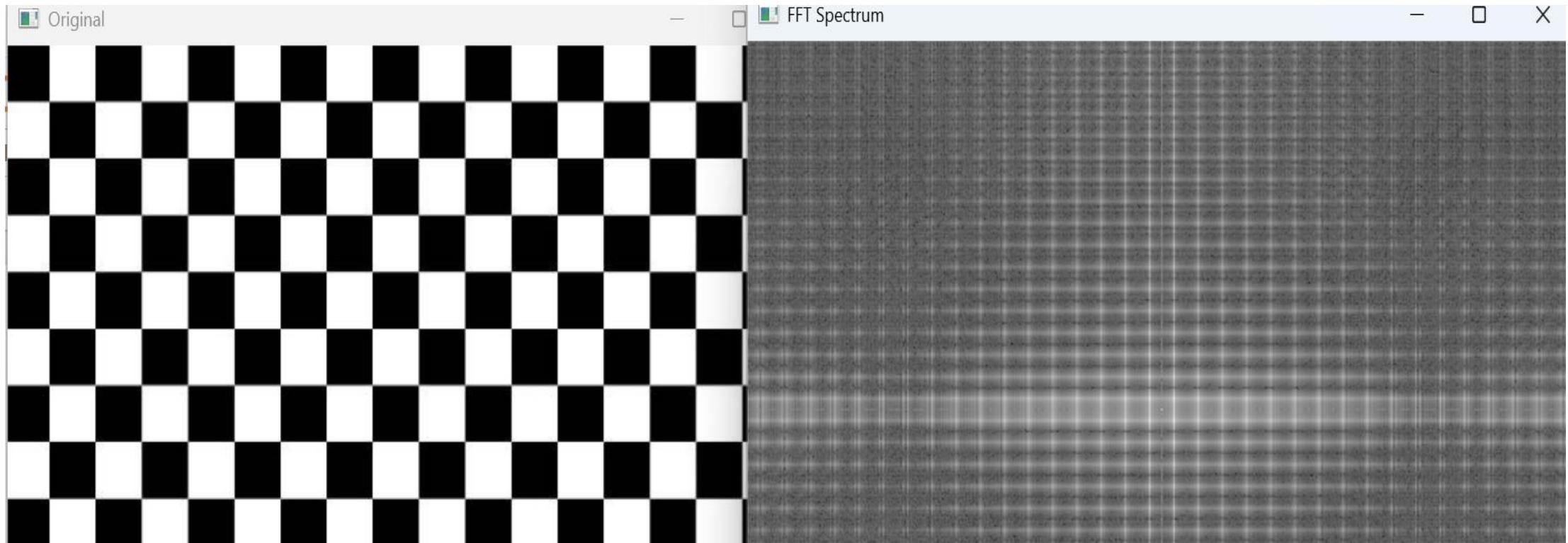
## Hands-On Lab: Image Spectrum Visualization and Reconstruction

```
[*]: import cv2, numpy as np

img = cv2.imread("img3.jpg", 0)
f = np.fft.fftshift(np.fft.fft2(img))
spectrum = np.log(np.abs(f)+1)

cv2.imshow("Original", img)
cv2.imshow("FFT Spectrum", np.uint8(spectrum/spectrum.max()*255))
cv2.waitKey(0)
cv2.destroyAllWindows()
```

# Hands-On Lab: Image Spectrum Visualization and Reconstruction



## Hands-On Lab: Image Spectrum Visualization and Reconstruction

```
[ ]: f = np.fft.fft2(img)
      f = np.fft.fftshift(f)
```

- ❖ **np.fft.fft2(img)** → Performs a 2D Fast Fourier Transform (FFT) on the image.
- ❖ This converts the image from the spatial domain (pixel intensities) into the frequency domain (sinusoidal components).
- ❖ **np.fft.fftshift(f)** → Moves the low frequencies (DC component) from the corners of the spectrum to the center of the image, which makes it easier to visualize

## Hands-On Lab: Image Spectrum Visualization and Reconstruction

```
[ ]: spectrum = np.log(np.abs(f) + 1)
cv2.imshow("Original", img)
cv2.imshow("FFT Spectrum", np.uint8(spectrum/spectrum.max()*255))
```

- ❖ **np.abs(f)** → Gets the magnitude (removes the imaginary part).
- ❖ **np.log(...+1)** → Log scaling is applied because the frequency values can vary a lot, and without log the image would be too bright in the center and too dark elsewhere.
- ❖ The +1 avoids log(0) errors.

## Hands-On Lab: Image Spectrum Visualization and Reconstruction

**spectrum/spectrum.max()\*255** → normalizes values between 0–255  
(so it can be displayed as an image).

**np.uint8(...)** → converts to 8-bit image format.

## **Hands-On Lab: Image Spectrum Visualization and Reconstruction**

### **TASK: Experiment with Different Images by using fft function**

- Run the same code on **three different types of images**:
  - A smooth image (sky or gradient)
  - A textured image (brick wall, grass)
  - A text/edge-heavy image (document, chessboard)
- Compare how the **magnitude spectrum** changes.

# Hands-On Lab: Image Spectrum Visualization and Reconstruction

```
[*]: import cv2, numpy as np

# Read image in grayscale
img = cv2.imread("img3.jpg", 0)

# Apply 2D Fourier Transform and shift
f = np.fft.fftshift(np.fft.fft2(img))

# Magnitude Spectrum
magnitude = np.log(np.abs(f) + 1)

# Phase Spectrum
phase = np.angle(f)

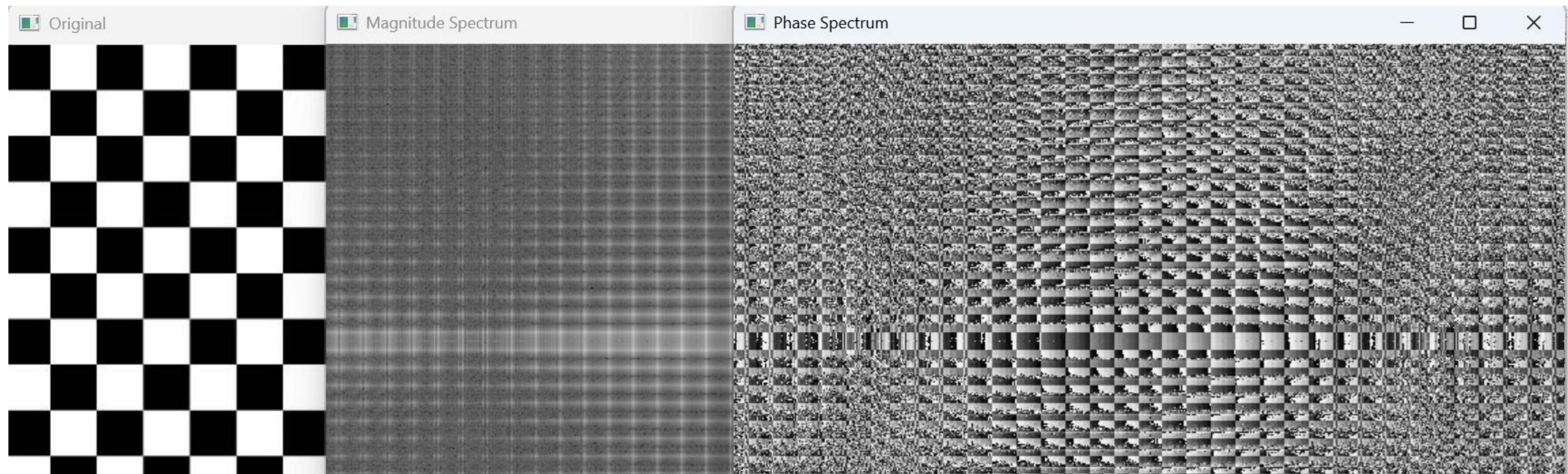
# Normalize for display (0-255)
magnitude_display = np.uint8(magnitude / magnitude.max() * 255)
phase_display = np.uint8((phase + np.pi) / (2*np.pi) * 255) # Map [-π,π] → [0,255]
```

## Hands-On Lab: Image Spectrum Visualization and Reconstruction

```
# Show images
cv2.imshow("Original", img)
cv2.imshow("Magnitude Spectrum", magnitude_display)
cv2.imshow("Phase Spectrum", phase_display)

cv2.waitKey(0)
cv2.destroyAllWindows()
```

# Hands-On Lab: Image Spectrum Visualization and Reconstruction



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# Hands-On Lab: Image Spectrum Visualization and Reconstruction

## Inverse Fourier transform to reconstruct image

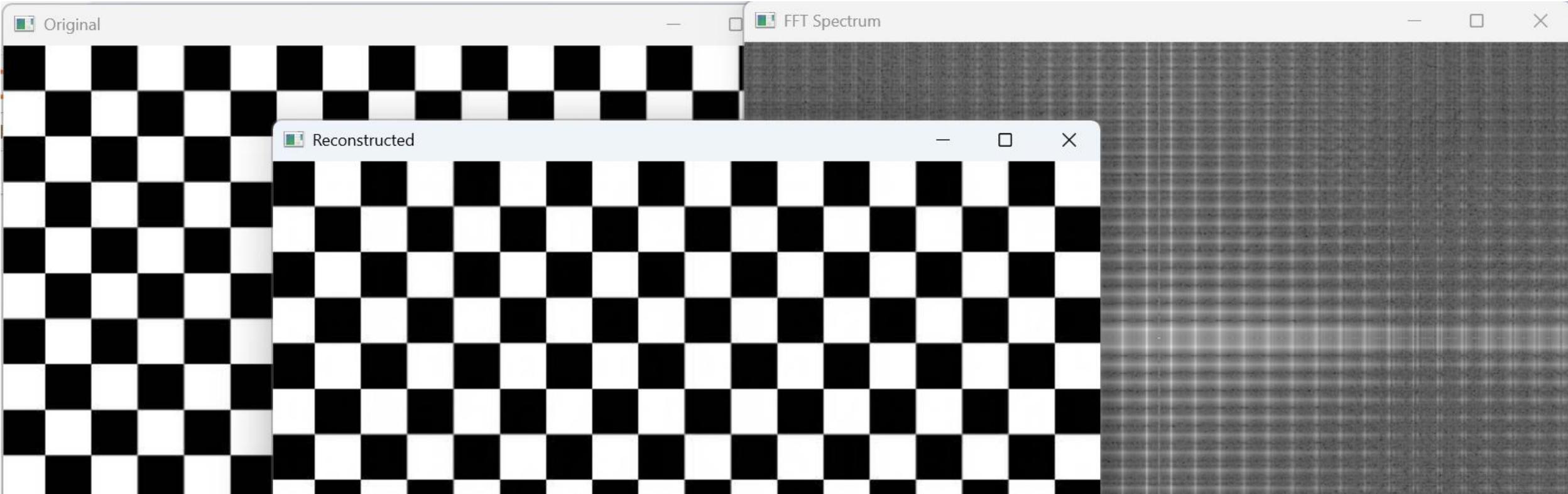
```
[8]: import cv2, numpy as np

img = cv2.imread("img3.jpg", 0)
f = np.fft.fftshift(np.fft.fft2(img))
spectrum = np.log(np.abs(f)+1)

# Inverse FFT
reconstructed = np.fft.ifft2(np.fft.ifftshift(f))
reconstructed = np.abs(reconstructed)

cv2.imshow("Original", img)
cv2.imshow("FFT Spectrum", np.uint8(spectrum/spectrum.max()*255))
cv2.imshow("Reconstructed", np.uint8(reconstructed))

cv2.waitKey(0)
cv2.destroyAllWindows()
```



## **TASK: Experiment with Different Images to reconstruct image**

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# Hands-On Lab: Image Spectrum Visualization and Reconstruction

## Apply high-low frequencies to observe the effects

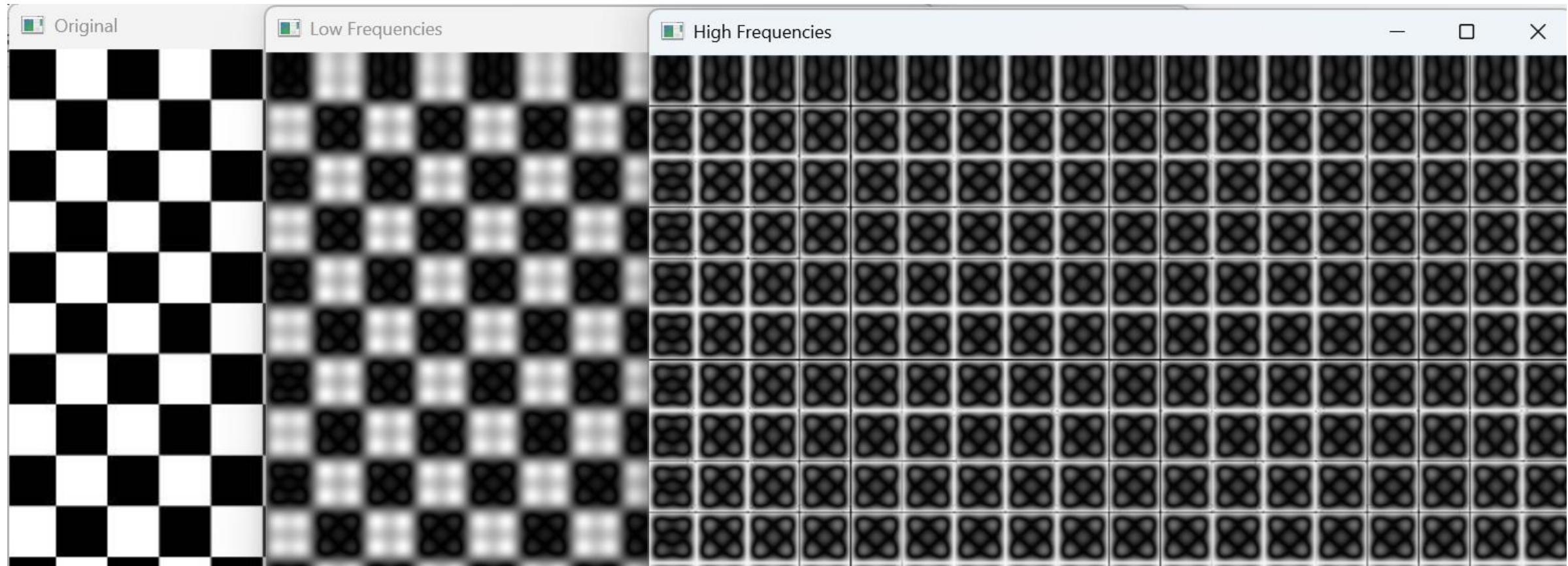
```
[*]: import cv2, numpy as np

img = cv2.imread("img3.jpg", 0)
r,c = img.shape
cr,cc = r//2, c//2
f = np.fft.fftshift(np.fft.fft2(img))

mask = np.zeros((r,c), np.uint8)
mask[cr-30:cr+30, cc-30:cc+30] = 1

low = np.fft.ifft2(np.fft.ifftshift(f*mask))
high = np.fft.ifft2(np.fft.ifftshift(f*(1-mask)))

cv2.imshow("Original", img)
cv2.imshow("Low Frequencies", np.uint8(np.abs(low)/np.abs(low).max()*255))
cv2.imshow("High Frequencies", np.uint8(np.abs(high)/np.abs(high).max()*255))
```



## **Task:**

- Run the code and observe the Original Image, Low Frequencies Image, and High Frequencies Image.
- Change the mask size in the line:
  - Try different sizes like 10, 50, 80, 120.
  - Observe how the Low Frequency Image becomes more/less blurred.
  - Observe how the High Frequency Image changes (edges more/less visible)

## Task:

- **Modify the shape of the mask:**
- Instead of a square, try a rectangular region or circular region.
- Discuss how the **shape of the mask changes** the filtering result.
- **Compare results:**
  - Which filter preserves smooth regions better?
  - Which filter enhances edges and fine details?
  - How does **increasing/decreasing the mask size** affect the balance between smoothness and sharpness?.