

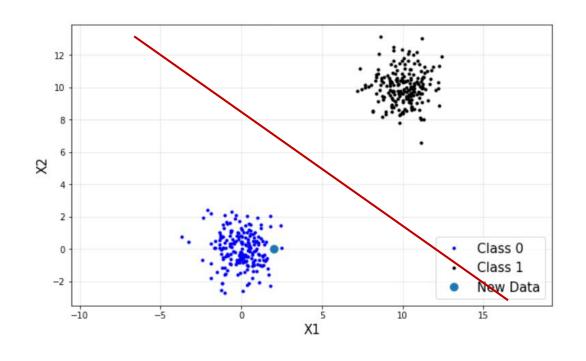
# Classification: Perceptron

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#### Classification

- Where y is a discrete value
  - Develop the classification algorithm to determine which class a new input should fall into
- We will learn
  - Perceptron
  - Logistic regression
- To find a classification boundary

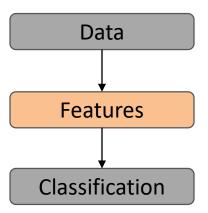




#### **Perceptron**

• For input 
$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$$
 'attributes of a customer'

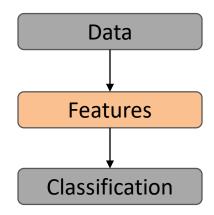
• Weights 
$$\omega = \begin{bmatrix} \omega_1 \\ \vdots \\ \omega_d \end{bmatrix}$$



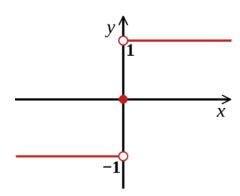
## **Perceptron**

• For input 
$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$$
 'attributes of a customer'

• Weights 
$$\omega = \begin{bmatrix} \omega_1 \\ \vdots \\ \omega_d \end{bmatrix}$$



$$ext{Approve credit if } \sum_{i=1}^d \omega_i x_i > ext{threshold},$$
  $ext{Deny credit if } \sum_{i=1}^d \omega_i x_i < ext{threshold}.$ 



$$h(x) = ext{sign}\left(\left(\sum_{i=1}^d \omega_i x_i
ight) - ext{threshold}
ight) = ext{sign}\left(\left(\sum_{i=1}^d \omega_i x_i
ight) + \omega_0
ight)$$

#### **Perceptron**

$$h(x) = ext{sign}\left(\left(\sum_{i=1}^d \omega_i x_i
ight) - ext{threshold}
ight) = ext{sign}\left(\left(\sum_{i=1}^d \omega_i x_i
ight) + \omega_0
ight)$$

• Introduce an artificial coordinate  $x_0 = 1$ :

$$h(x) = \mathrm{sign}\left(\sum_{i=0}^d \omega_i x_i
ight)$$

• In a vector form, the perceptron implements

$$h(x) = \mathrm{sign}\left(\omega^T x\right)$$

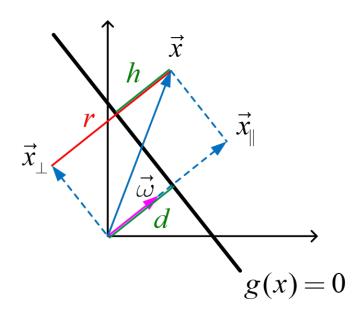
• Let's see geometrical meaning of perceptron

ω

• If  $\vec{p}$  and  $\vec{q}$  are on the decision line

$$egin{aligned} g\left(ec{p}
ight) &= g\left(ec{q}
ight) = 0 & \Rightarrow & \omega_0 + \omega^Tec{p} = \omega_0 + \omega^Tec{q} = 0 \ & \Rightarrow & \omega^T\left(ec{p} - ec{q}
ight) = 0 \end{aligned}$$

 $\therefore \omega : \text{normal to the line (orthogonal)}$  $\implies \text{tells the direction of the line}$ 



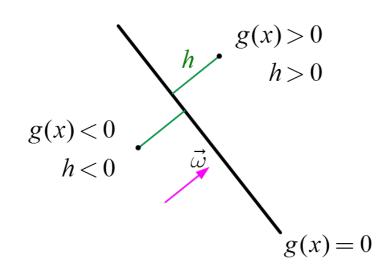
## Signed Distance from a Line: h

$$\therefore h = \frac{g(x)}{\|\omega\|} \implies ext{ orthogonal signed distance from the line}$$

Sign with respect to a line

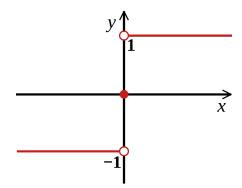
$$\omega = \begin{bmatrix} \omega_1 \\ \omega_2 \end{bmatrix}, \quad x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \implies g(x) = \omega_1 x_1 + \omega_2 x_2 + \omega_0 = \omega^T x + \omega_0$$

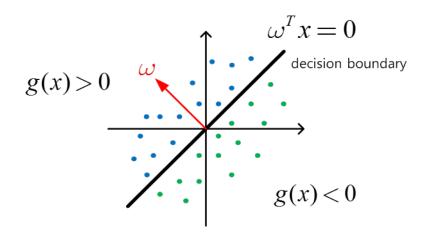
$$\omega = \begin{bmatrix} \omega_0 \\ \omega_1 \\ \omega_2 \end{bmatrix}, \quad x = \begin{bmatrix} 1 \\ x_1 \\ x_2 \end{bmatrix} \implies g(x) = \omega_0 + \omega_1 x_1 + \omega_2 x_2 = \omega^T x$$



#### How to Find $\omega$

- All data in class 1 (y = 1)
  - -g(x) > 0
- All data in class 0 (y = -1)
  - -g(x)<0





### **Perceptron Algorithm**

• The perceptron implements

$$h(x) = ext{sign}\left(\omega^T x
ight)$$

Given the training set

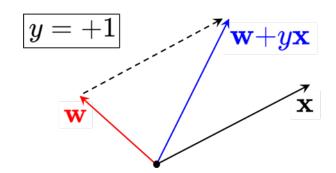
$$(x_1,y_1),(x_2,y_2),\cdots,(x_N,y_N) \quad ext{where } y_i \in \{-1,1\}$$

1) pick a misclassified point

$$\mathrm{sign}\left(\omega^T x_n\right) \neq y_n$$

2) and update the weight vector

$$\omega \leftarrow \omega + y_n x_n$$



### **Iterations of Perceptron**

- 1. Randomly assign  $\omega$
- 2. One iteration of the PLA (perceptron learning algorithm)

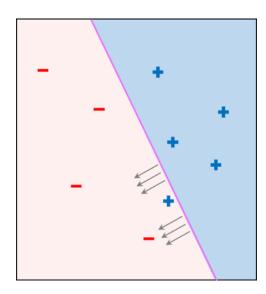
$$\omega \leftarrow \omega + yx$$

where (x, y) is a misclassified training point

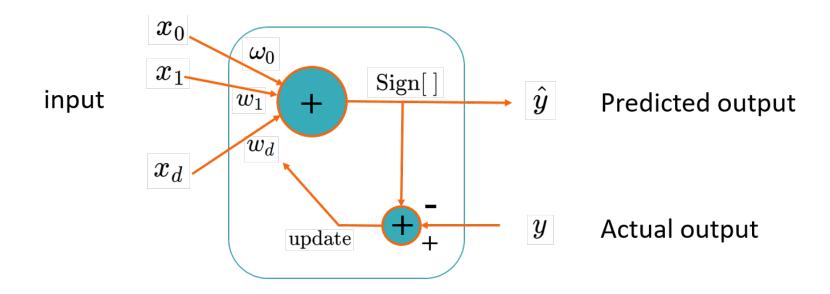
3. At iteration  $t=1,2,3,\cdots$ , pick a misclassified point from

$$(x_1,y_1),(x_2,y_2),\cdots,(x_N,y_N)$$

- 4. And run a PLA iteration on it
- 5. That's it!



### **Diagram of Perceptron**



• Perceptron will be shown to be a basic unit for neural networks and deep learning later



#### **Scikit-Learn for Perceptron**

```
X1 = np.hstack([x1[C1], x2[C1]])
X2 = np.hstack([x1[C2], x2[C2]])
X = np.vstack([X1, X2])

y = np.vstack([np.ones([C1.shape[0],1]), -np.ones([C2.shape[0],1])])
```

```
from sklearn import linear_model

clf = linear_model.Perceptron(tol=1e-3)
clf.fit(X, np.ravel(y))
```

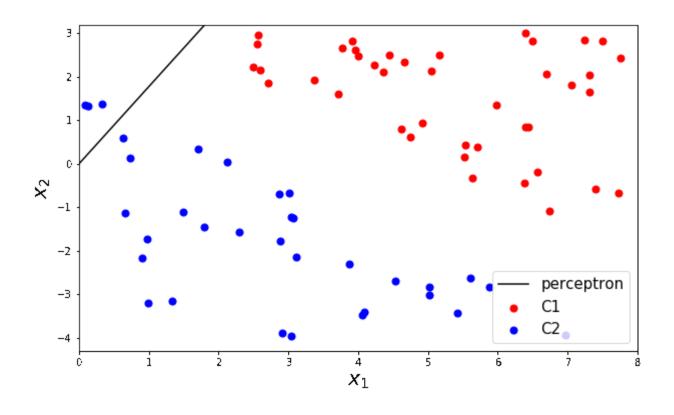
```
clf.predict([[3, -2]])
```

$$x = egin{bmatrix} \left(x^{(1)}
ight)^T \ \left(x^{(2)}
ight)^T \ \left(x^{(3)}
ight)^T \ dots \ \left(x^{(3)}
ight)^T \end{bmatrix} = egin{bmatrix} x_1^{(1)} & x_2^{(1)} \ x_1^{(2)} & x_2^{(2)} \ x_1^{(3)} & x_2^{(3)} \ dots \ \left(x_1^{(m)} & x_2^{(m)} \ 
ight) \end{bmatrix}$$

$$y=egin{bmatrix} y^{(1)}\ y^{(2)}\ y^{(3)}\ dots\ y^{(m)} \end{bmatrix}$$

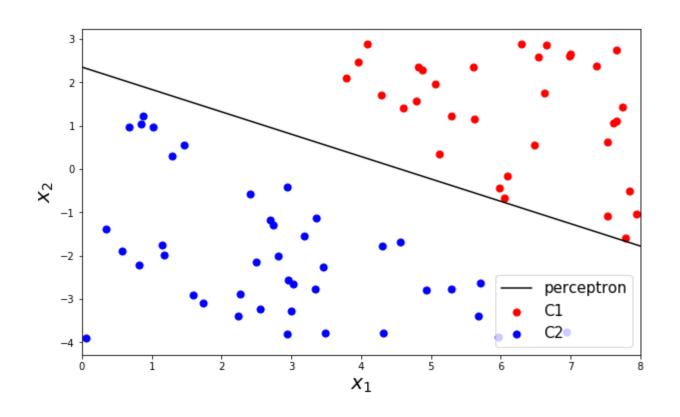


### **Perceptron Algorithm in Python**





### **Perceptron Algorithm in Python**





#### The Best Hyperplane Separator?

- Perceptron finds one of the many possible hyperplanes separating the data if one exists
- Of the many possible choices, which one is the best?
- Utilize distance information from all data samples
  - We will see this formally when we discuss the logistic regression

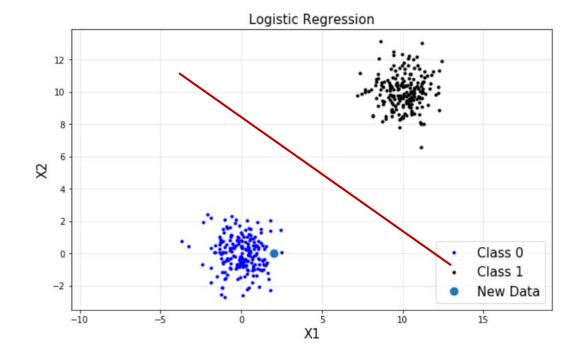


## Classification: Logistic Regression



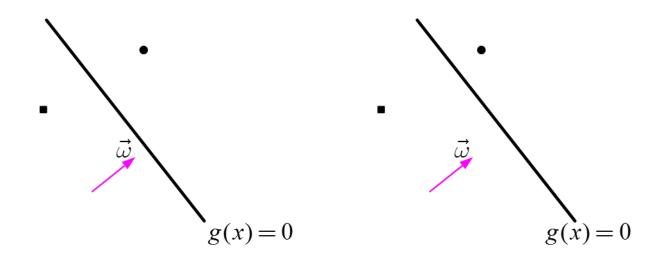
### **Classification: Logistic Regression**

- Perceptron: make use of sign of data
- Logistic regression: make use of distance of data
- Logistic regression is a classification algorithm
  - don't be confused from its name
- To find a classification boundary

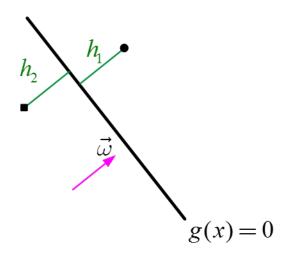


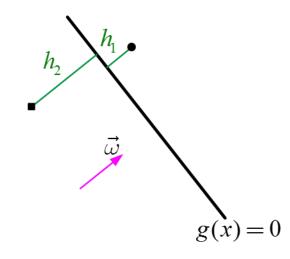


## **Using Distances**



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$$|h_1|+|h_2|$$

$$|h_1|\cdot |h_2|$$

$$|h_1|+|h_2|$$

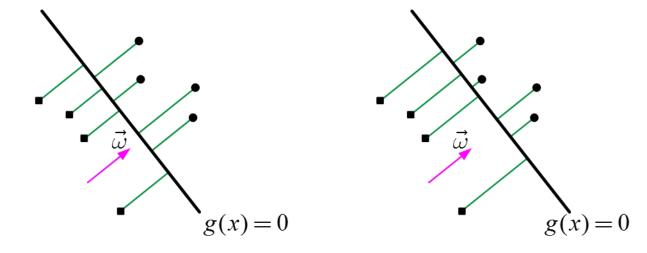
$$|h_1|\cdot |h_2|$$

$$rac{|h_1|+|h_2|}{2} \geq \sqrt{|h_1|\cdot |h_2|} \qquad ext{equal iff} \quad |h_1|=|h_2|$$

$$|h_1| = |h_2|$$

### **Using all Distances**

• basic idea: to find the decision boundary (hyperplane) of  $g(x) = \omega^T x = 0$  such that maximizes  $\prod_i |h_i| \to \text{optimization}$ 

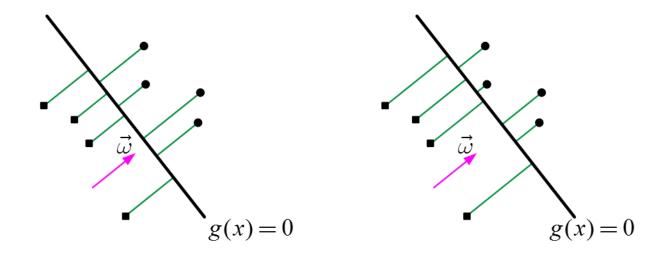


Inequality of arithmetic and geometric means

$$rac{x_1+x_2+\cdots+x_m}{m} \geq \sqrt[m]{x_1\cdot x_2\dots x_m}$$

and that equality holds if and only if  $x_1 = x_2 = \cdots = x_m$ 

### **Using all Distances**

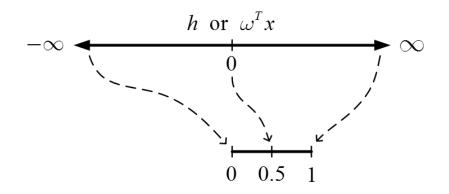


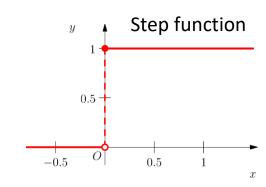
• Roughly speaking, this optimization of  $\max \prod_i |h_i|$  tends to position a hyperplane in the middle of two classes

$$h = rac{g(x)}{\|\omega\|} = rac{\omega^T x}{\|\omega\|} \sim \omega^T x$$

### **Sigmoid Function**

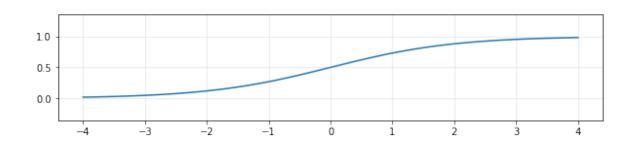
• We link or squeeze  $(-\infty, +\infty)$  to (0, 1) for several reasons:





- $\sigma(z)$  is the sigmoid function, or the logistic function
  - Logistic function always generates a value between 0 and 1
  - Crosses 0.5 at the origin, then flattens out

$$\sigma(z) = rac{1}{1 + e^{-z}} \implies \sigma(\omega^T x) = rac{1}{1 + e^{-\omega^T x}}$$



## **Sigmoid Function**

- Benefit of mapping via the logistic function
  - Monotonic: same or similar optimization solution
  - Continuous and differentiable: good for gradient descent optimization
  - Probability or confidence: can be considered as probability

$$P\left(y=+1\mid x,\omega
ight)=rac{1}{1+e^{-\omega^{T}x}}~\in~\left[0,1
ight]$$

- Probability that the label is +1

$$P(y = +1 \mid x; \omega)$$

Probability that the label is 0

$$P\left(y=0\mid x\,;\omega
ight)=1-P\left(y=+1\mid x\,;\omega
ight)$$

### Goal: We Need to Fit $\omega$ to our Data

• For a single data point (x, y) with parameters  $\omega$ 

$$egin{aligned} P\left(y=+1\mid x\,;\omega
ight) &= h_{\omega}(x) = \sigma\left(\omega^T x
ight) \ P\left(y=0\mid x\,;\omega
ight) &= 1-h_{\omega}(x) = 1-\sigma\left(\omega^T x
ight) \end{aligned}$$

• It can be compactly written as

$$P(y \mid x; \omega) = (h_{\omega}(x))^{y} (1 - h_{\omega}(x))^{1-y}$$

#### **Scikit-Learn for Logistic Regression**

```
from sklearn import linear_model

clf = linear_model.LogisticRegression(solver='lbfgs')
clf.fit(X,np.ravel(y))
```

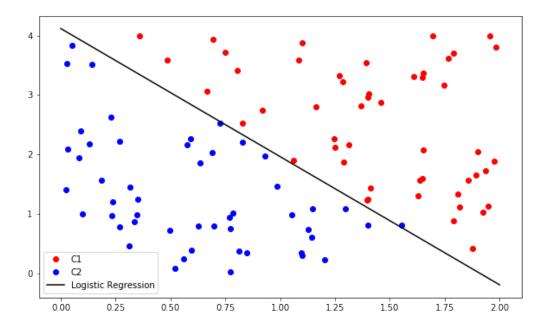
```
w1 = clf.coef_[0,0]
w2 = clf.coef_[0,1]
w0 = clf.intercept_[0]

xp = np.linspace(0,2,100).reshape(-1,1)
yp = - w1/w2*xp - w0/w2

plt.figure(figsize = (10,6))
plt.plot(X[C1,0], X[C1,1], 'ro', label='C1')
plt.plot(X[C2,0], X[C2,1], 'bo', label='C2')
plt.plot(xp, yp, 'k', label='Logistic Regression')
plt.legend()
plt.show()
```

$$\omega = \left[egin{array}{c} \omega_1 \ \omega_2 \end{array}
ight], \qquad \omega_0, \qquad x = \left[egin{array}{c} x_1 \ x_2 \end{array}
ight]$$

$$X = egin{bmatrix} egin{pmatrix} egin{pmatrix}$$



#### **Multiclass Classification**

- Generalization to more than 2 classes is straightforward
  - one vs. all (one vs. rest)
  - one vs. one

