

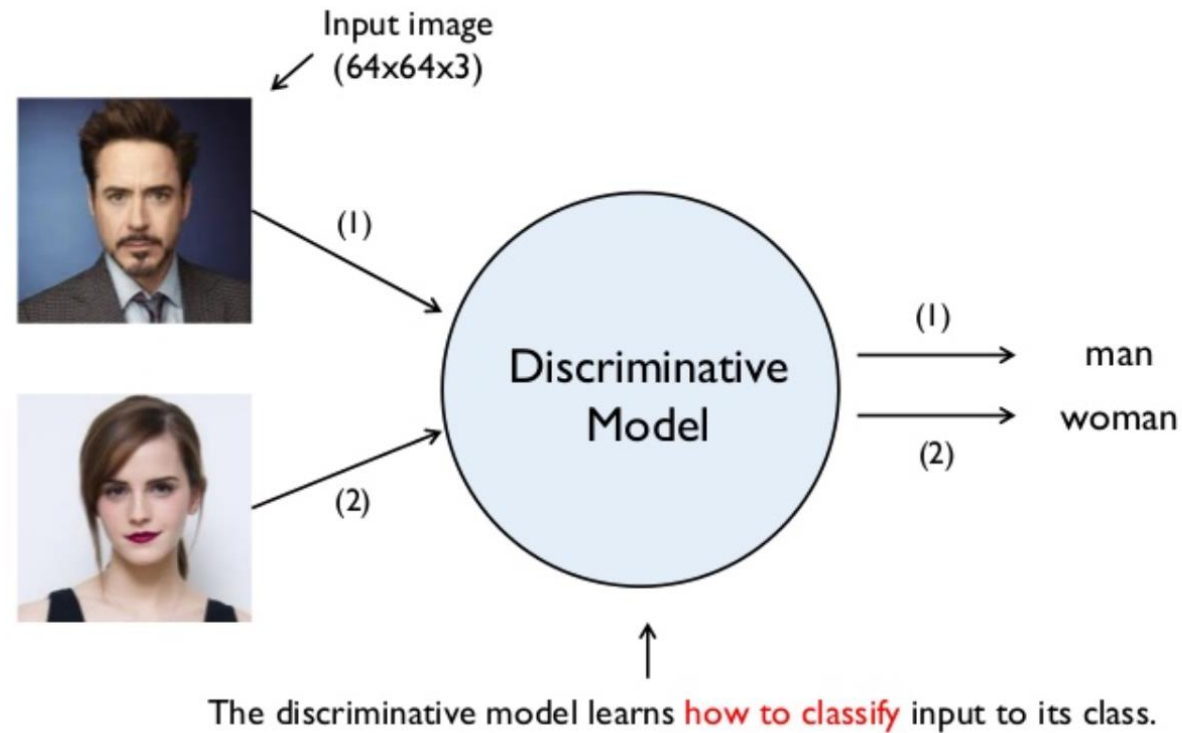


# 진동신호 생성을 위한 적대적 생성 신경망 (GAN)

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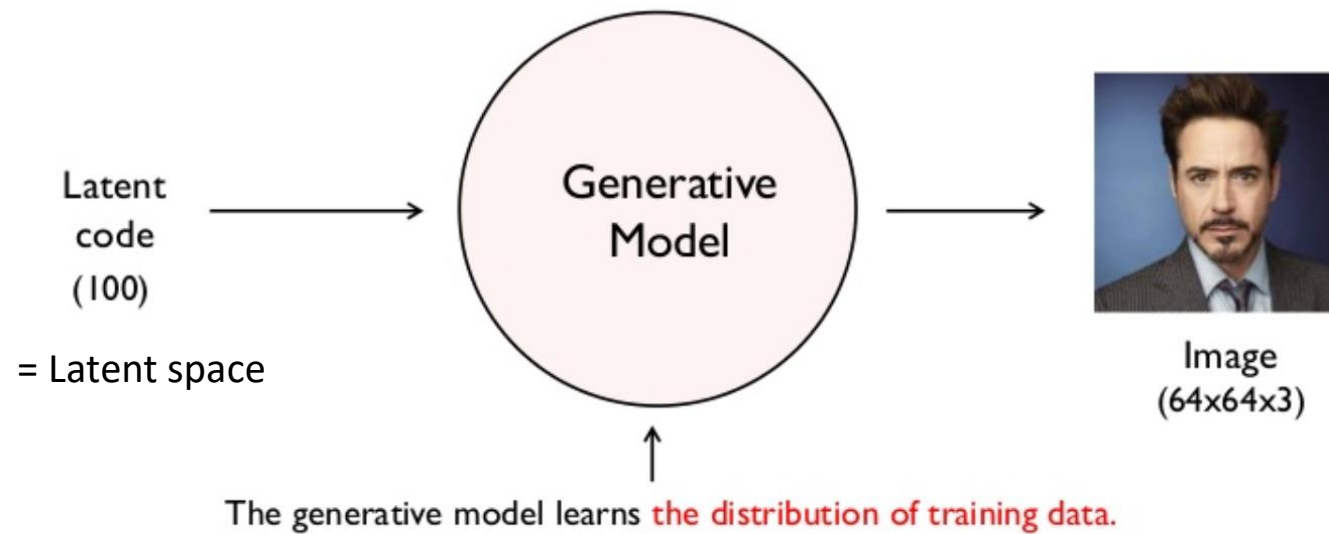
# Supervised Learning

- Discriminative model



# Unsupervised Learning

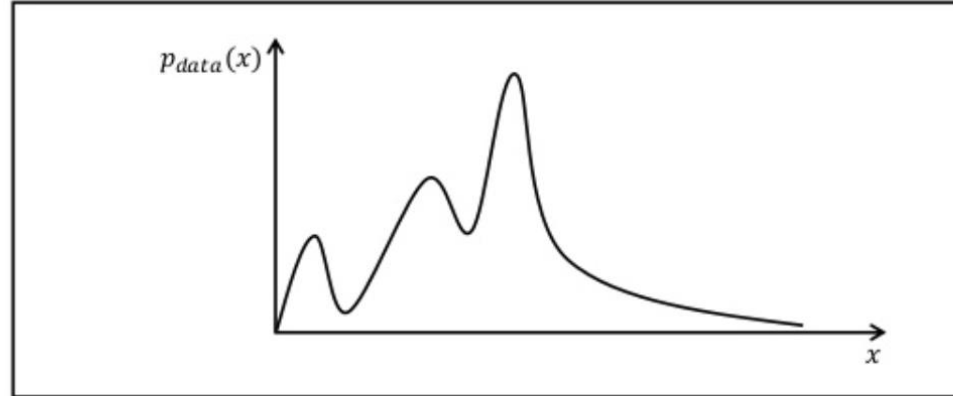
- Generative model



# Probability Distribution

Probability density function

There is a  $p_{data}(x)$  that represents the distribution of actual images.

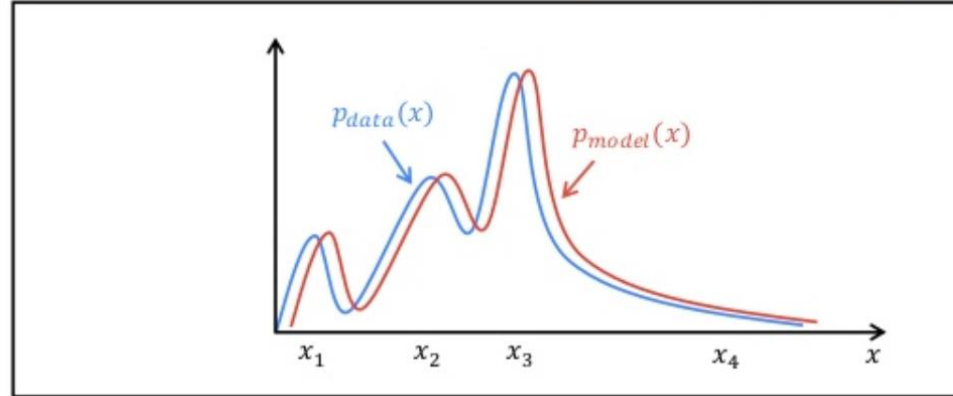


# Probability Density Estimation Problem

- If  $P_{model}(x)$  can be estimated as close to  $P_{data}(x)$ , then data can be generated by sampling from  $P_{model}(x)$

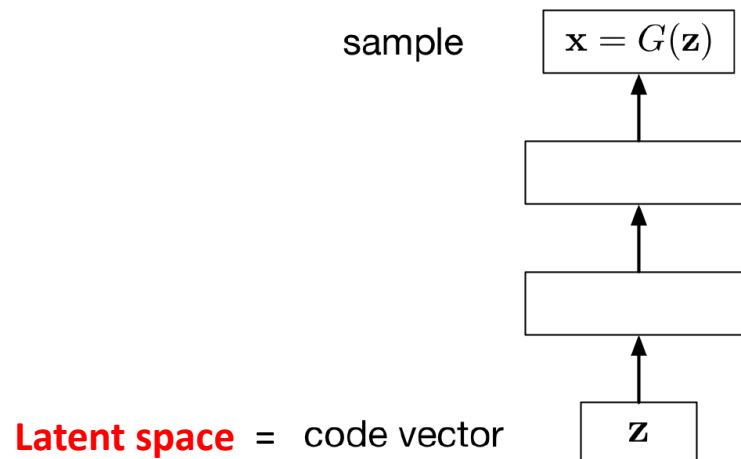
The goal of the generative model is to find a  $p_{model}(x)$  that approximates  $p_{data}(x)$  well.

↗ Distribution of images generated by the model  
↘ Distribution of actual images



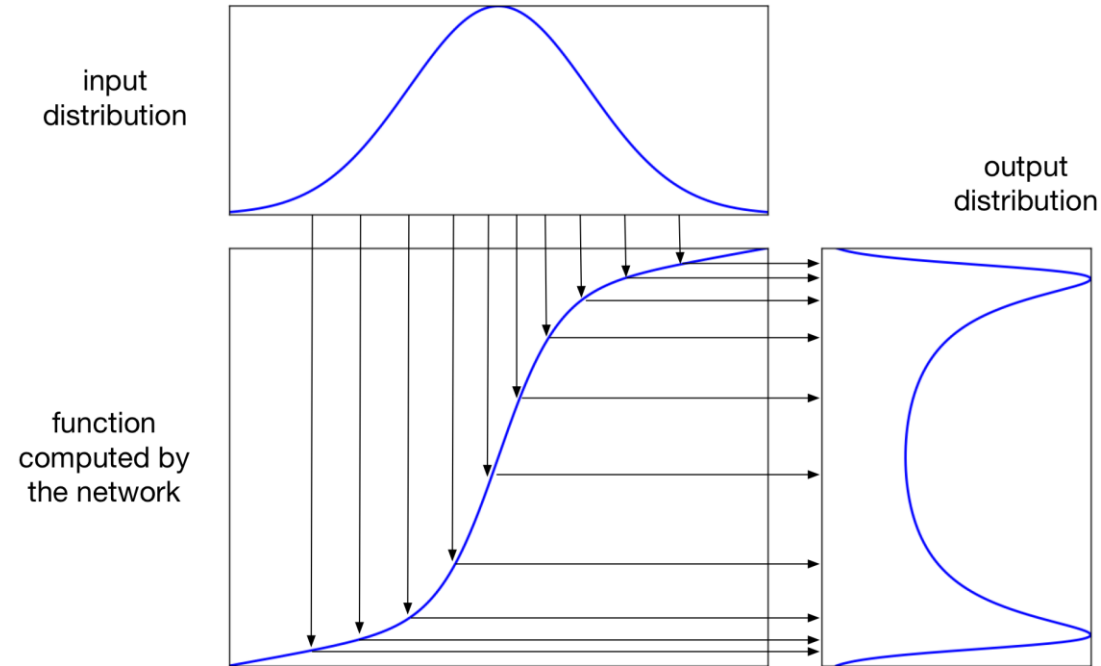
# Generative Models from Lower Dimension

- Learn transformation via a neural network
- Start by sampling the code vector  $z$  from a fixed, simple distribution (e.g. uniform distribution or Gaussian distribution)
- Then this code vector is passed as input to a deterministic generator network  $G$ , which produces an output sample  $x = G(z)$



# Deterministic Transformation (by Network)

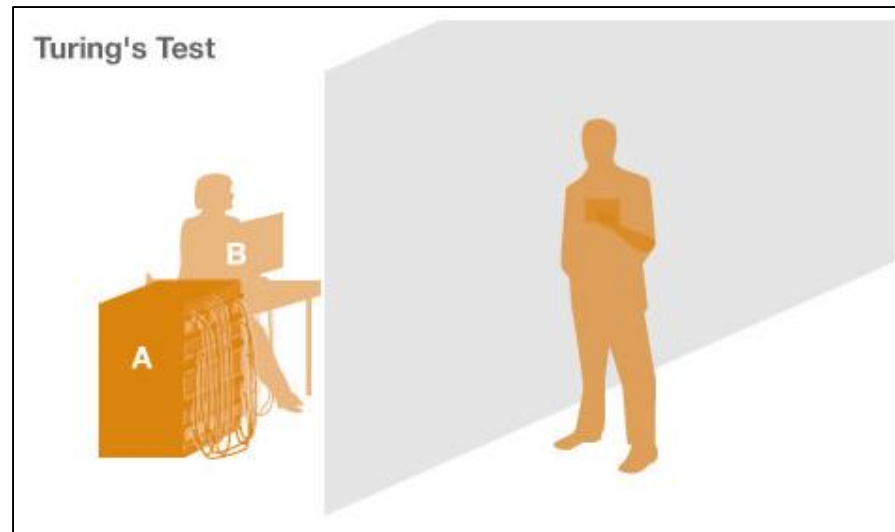
- 1-dimensional example:



- Remember
  - Network does not generate distribution, but
  - It maps known distribution to target distribution

# Generative Adversarial Networks (GANs)

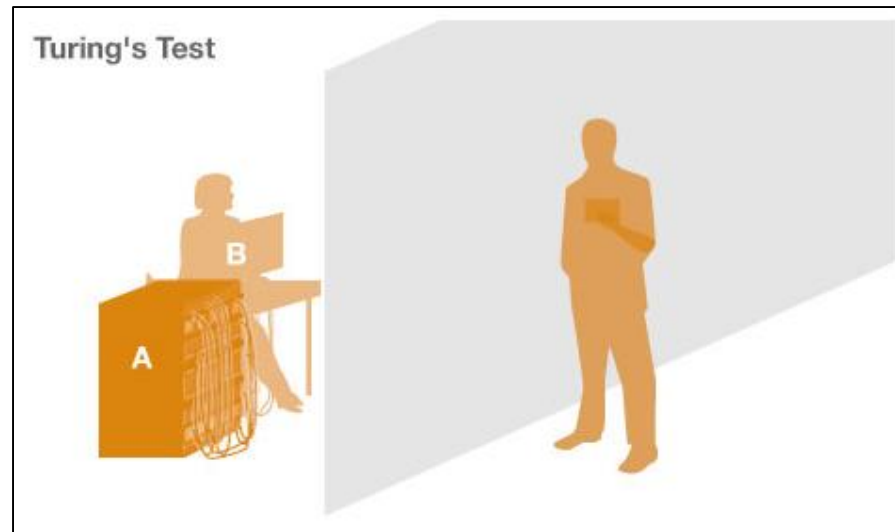
- In generative modeling, we'd like to train a network that models a distribution, such as a distribution over images.
- GANs do not work with any **explicit** density function !
  - Instead, take game-theoretic approach





# Turing Test

- One way to judge the quality of the model is to sample from it.
- GANs are based on a very different idea:
  - Model to produce samples which are indistinguishable from the real data, as judged by a discriminator network whose job is to tell real from fake

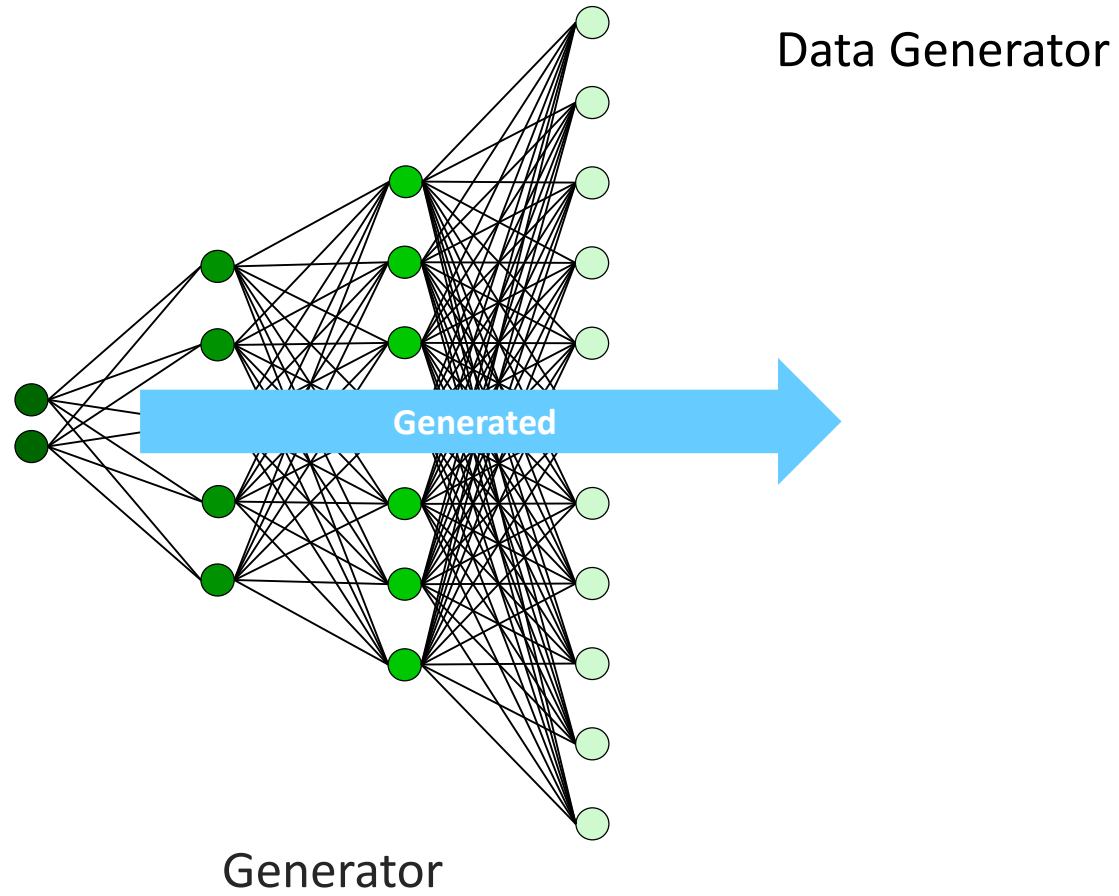


# Generative Adversarial Networks (GAN)

- The idea behind Generative Adversarial Networks (GANs): train two different networks
  - Generator network: try to produce realistic-looking samples
  - Discriminator network: try to distinguish between real and fake data
- The generator network tries to fool the discriminator network

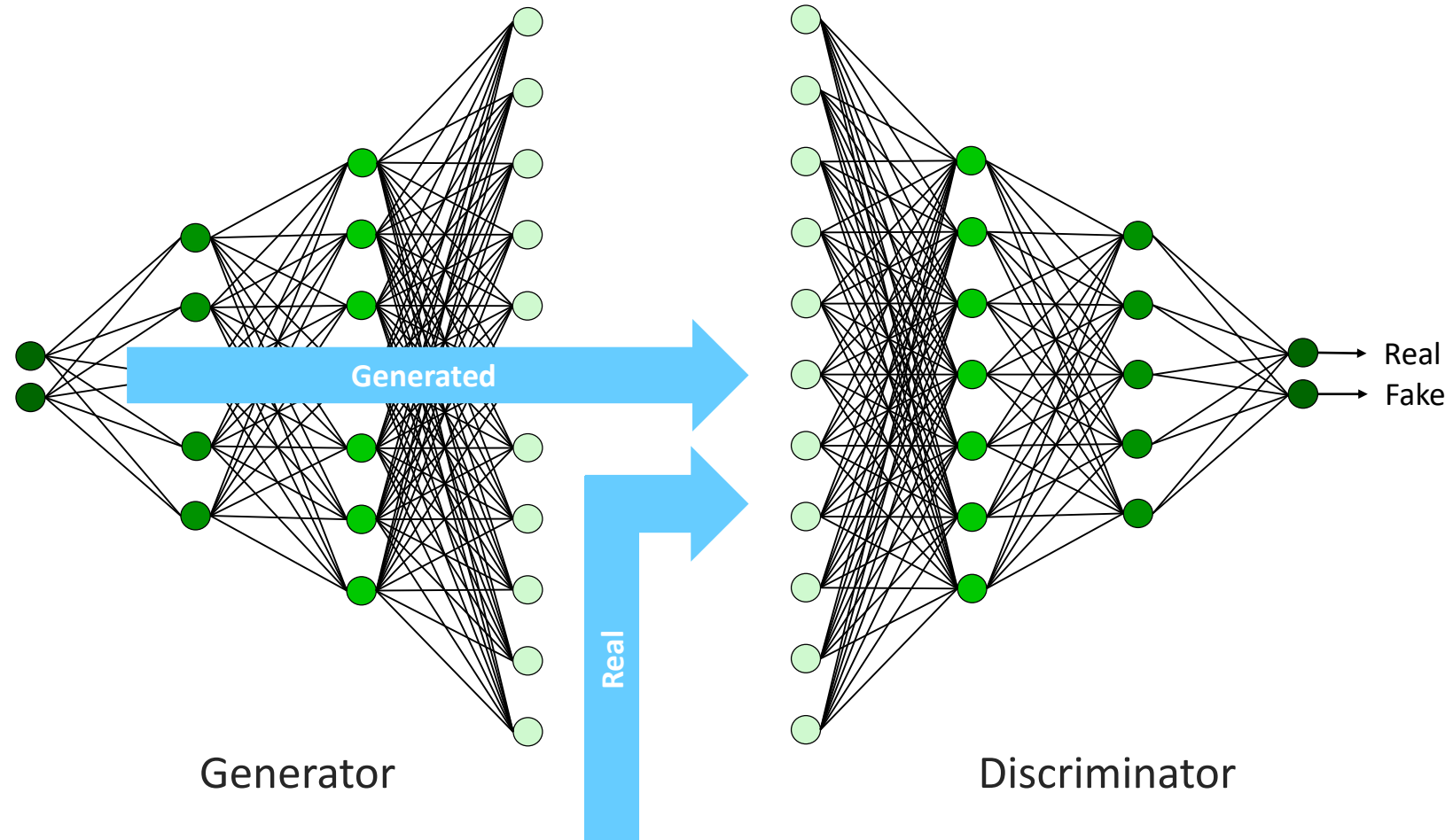
# Generative Adversarial Networks (GAN)

- Analogous to Turing Test

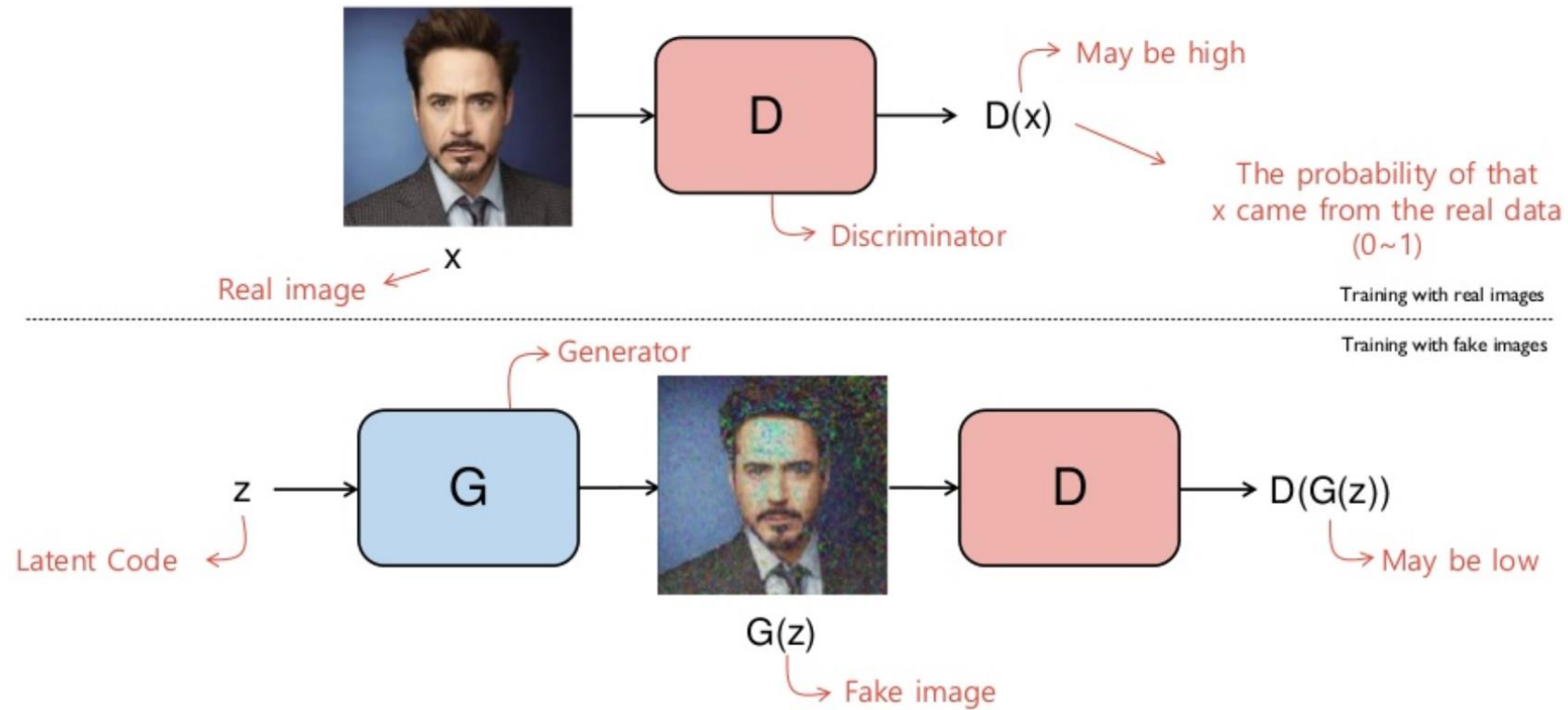


# Generative Adversarial Networks (GAN)

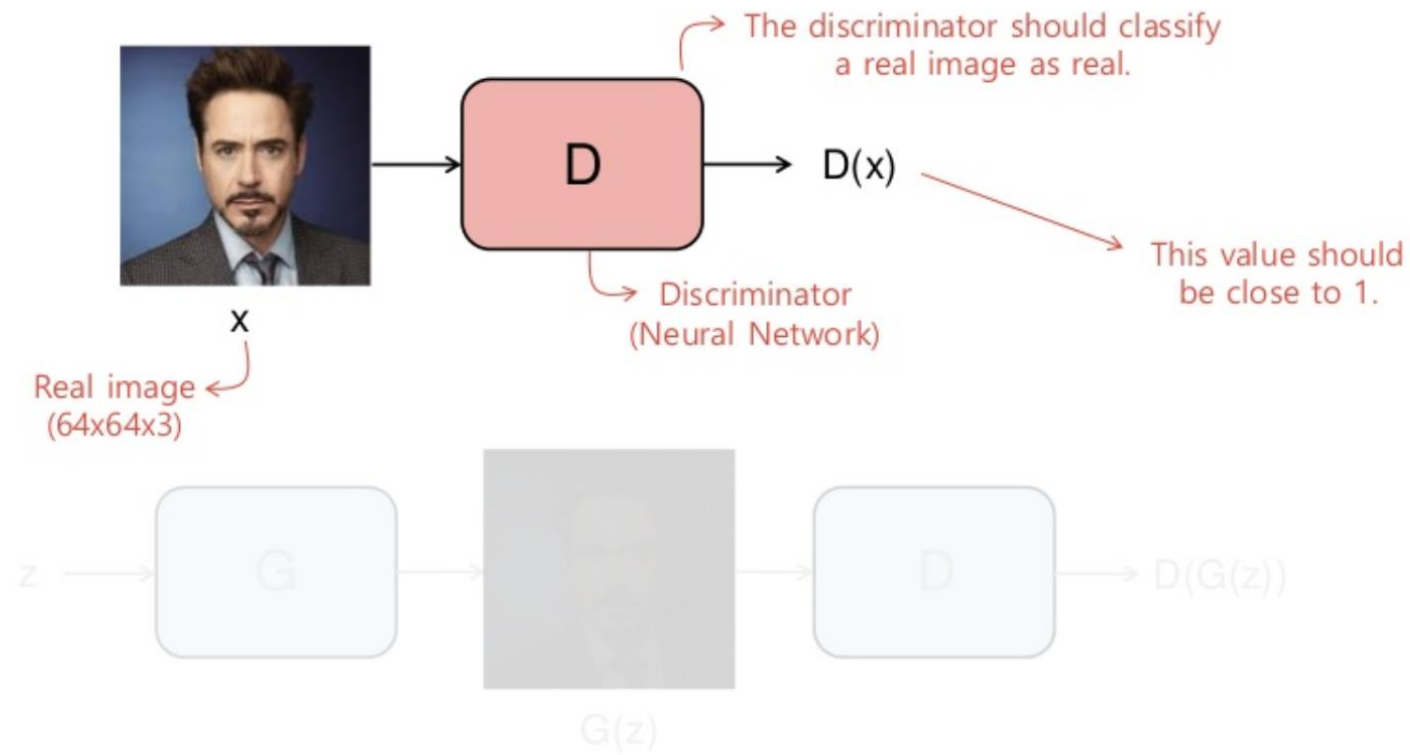
- Analogous to Turing Test



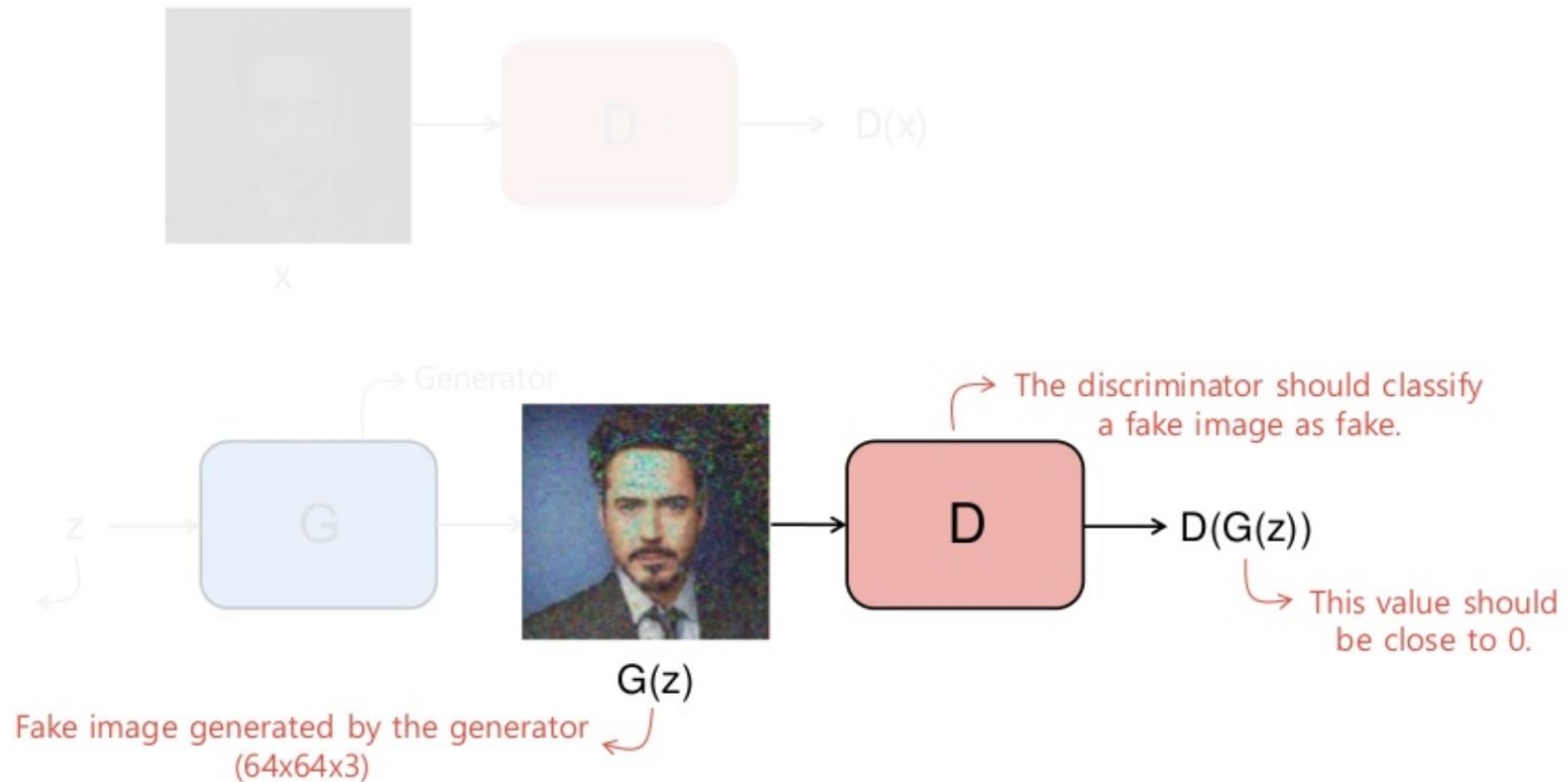
# Intuition for GAN



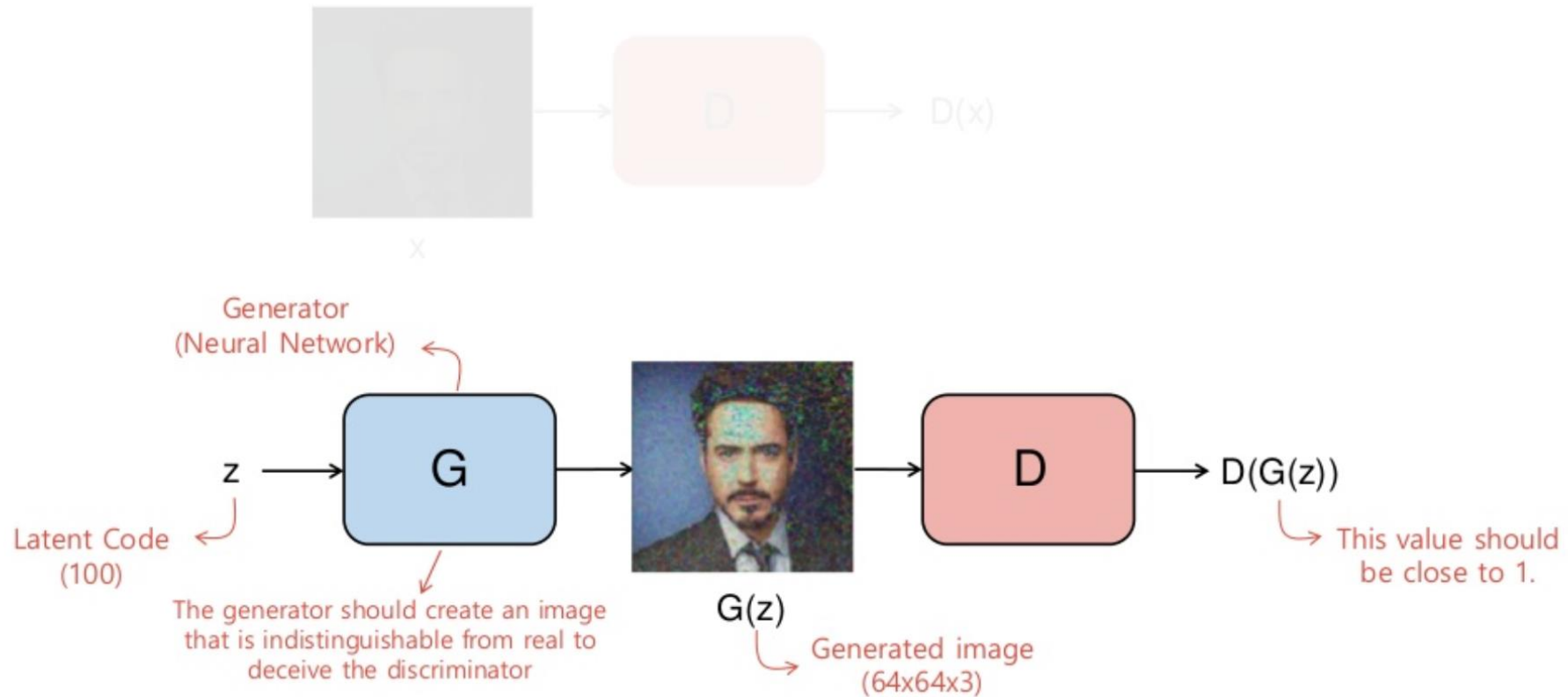
# Discriminator Perspective (1/2)



## Discriminator Perspective (2/2)



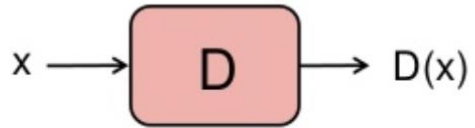
# Generator Perspective





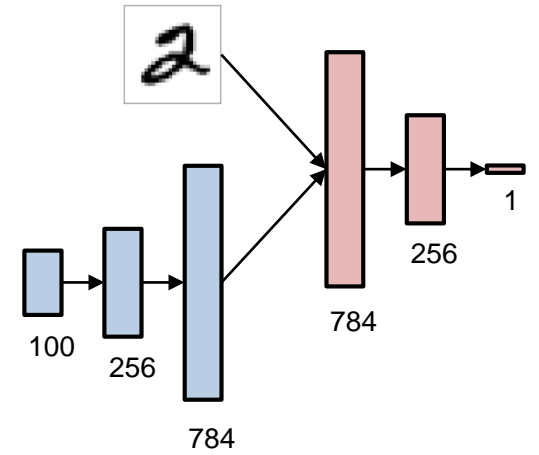
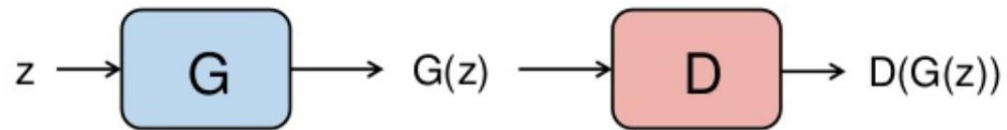
# GAN Implementation in TensorFlow

# TensorFlow Implementation



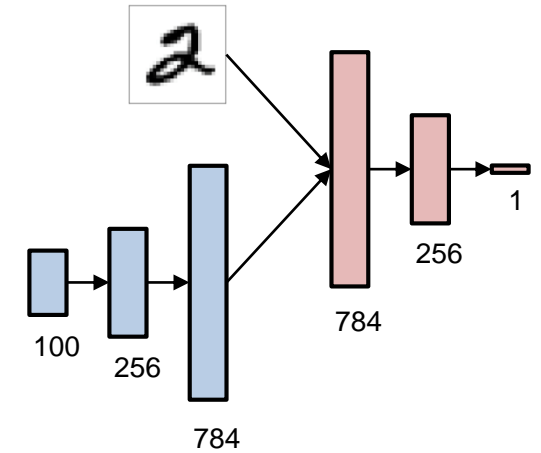
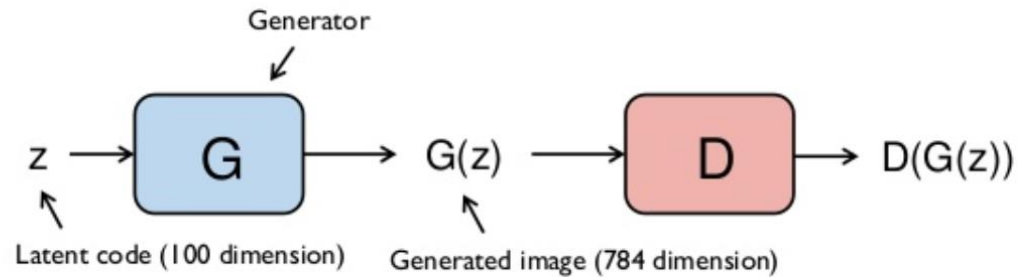
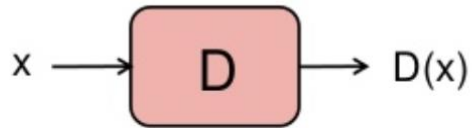
Training with real images

Training with fake images



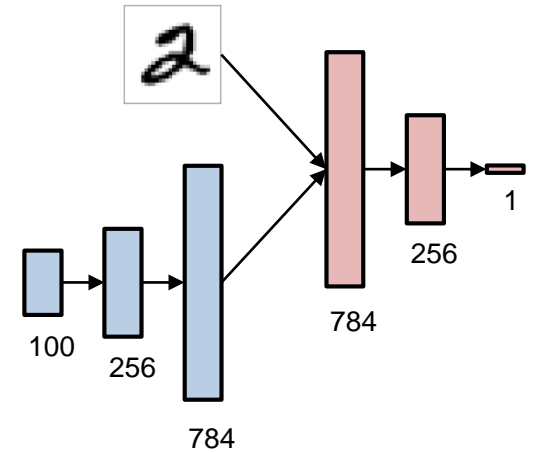
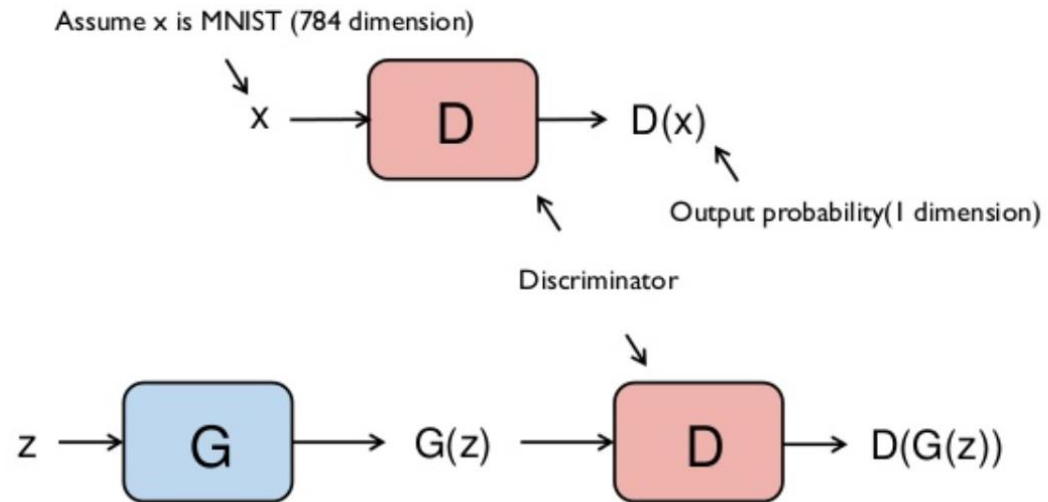
# Generator

```
generator = tf.keras.models.Sequential([  
    tf.keras.layers.Dense(units = 256, input_dim = 100, activation = 'relu'),  
    tf.keras.layers.Dense(units = 784, activation = 'sigmoid')  
])
```



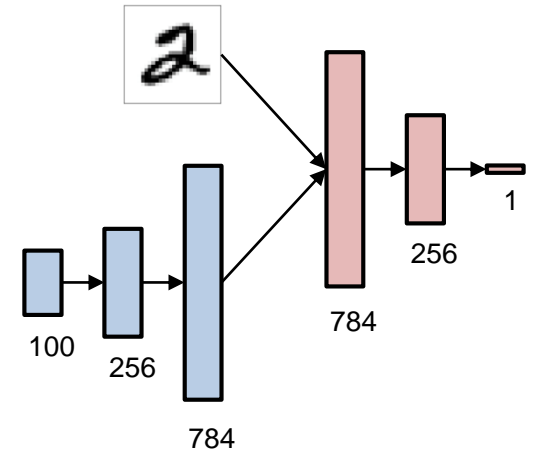
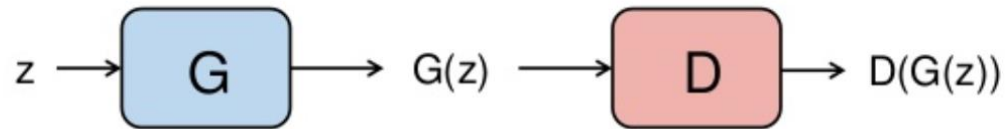
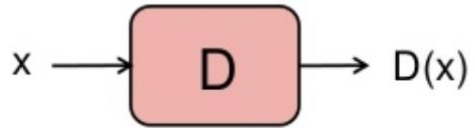
# Discriminator

```
discriminator = tf.keras.models.Sequential([
    tf.keras.layers.Dense(units = 256, input_dim = 784, activation = 'relu'),
    tf.keras.layers.Dense(units = 1, activation = 'sigmoid'),
])
```

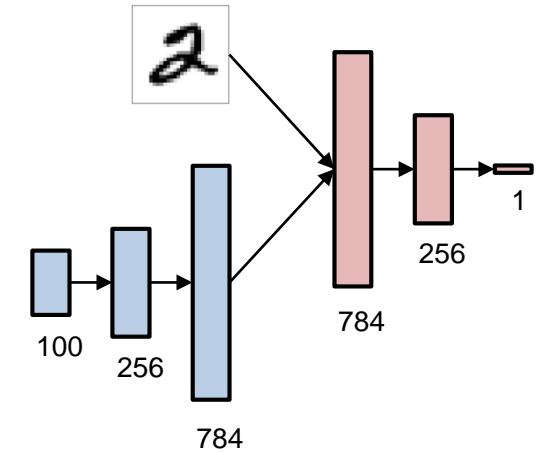
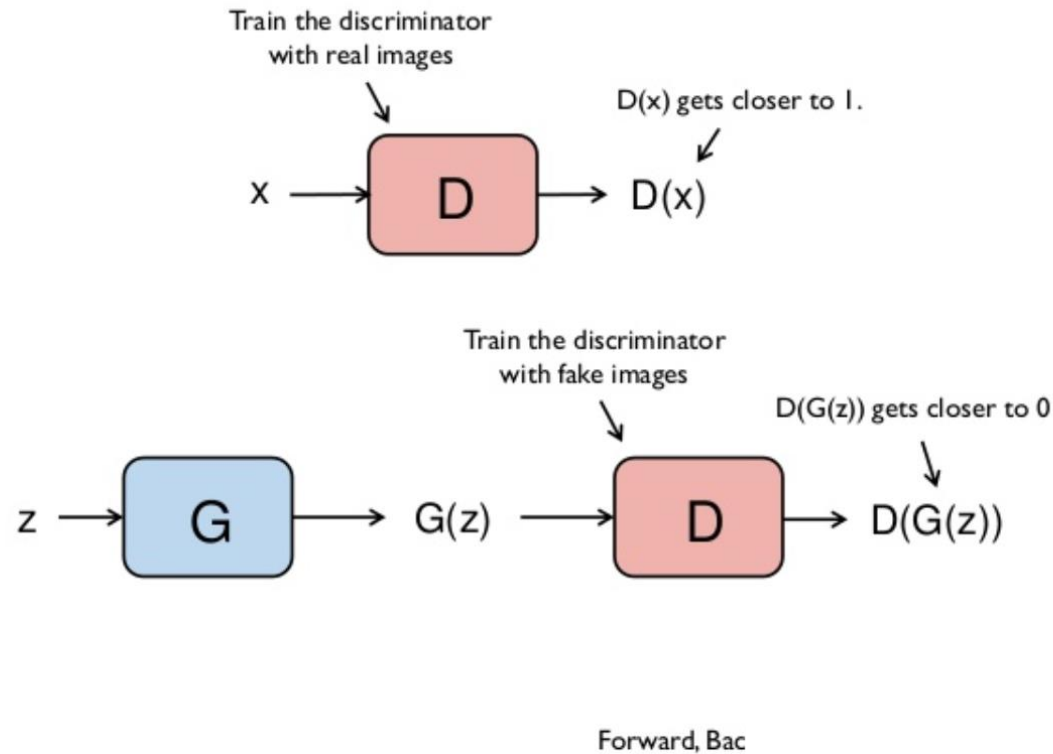


# Combined

```
combined_input = tf.keras.layers.Input(shape = (100,))  
generated = generator(combined_input)  
discriminator.trainable = False  
combined_output = discriminator(generated)  
  
combined = tf.keras.models.Model(inputs = combined_input, outputs = combined_output)
```



# Training: Discriminator



```
n_iter = 5000
batch_size = 50

fake = np.zeros(batch_size)
real = np.ones(batch_size)

for i in range(n_iter):

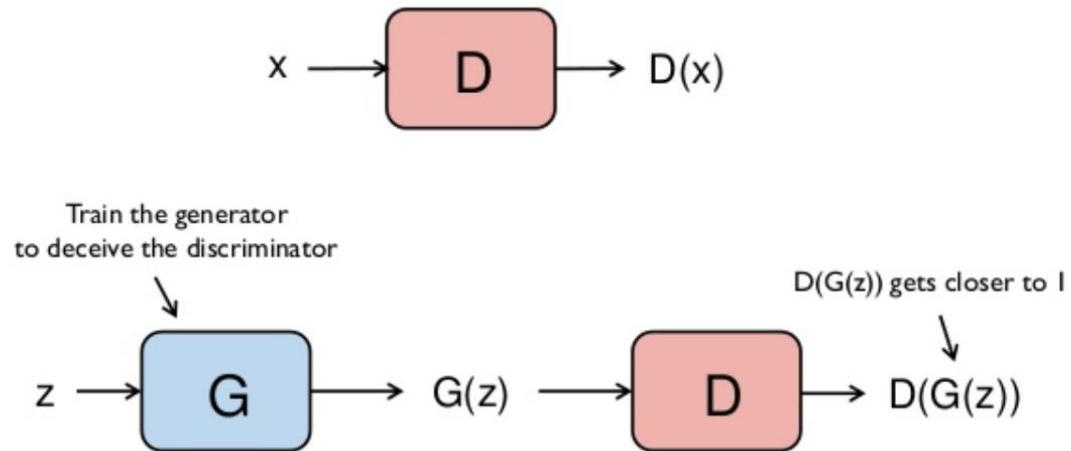
    # Train Discriminator
    noise = make_noise(batch_size)
    generated_images = generator.predict(noise)

    idx = np.random.randint(0, train_x.shape[0], batch_size)
    real_images = train_x[idx]

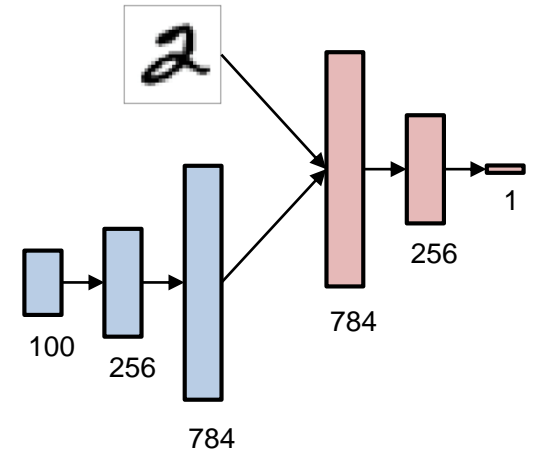
    D_loss_real = discriminator.train_on_batch(real_images, real)
    D_loss_fake = discriminator.train_on_batch(generated_images, fake)
    D_loss = D_loss_real + D_loss_fake

    # Train Generator
    noise = make_noise(batch_size)
    G_loss = combined.train_on_batch(noise, real)
```

# Training: Generator



Forward, Backward



```
n_iter = 5000
batch_size = 50

fake = np.zeros(batch_size)
real = np.ones(batch_size)

for i in range(n_iter):

    # Train Discriminator
    noise = make_noise(batch_size)
    generated_images = generator.predict(noise)

    idx = np.random.randint(0, train_x.shape[0], batch_size)
    real_images = train_x[idx]

    D_loss_real = discriminator.train_on_batch(real_images, real)
    D_loss_fake = discriminator.train_on_batch(generated_images, fake)
    D_loss = D_loss_real + D_loss_fake

    # Train Generator
    noise = make_noise(batch_size)
    G_loss = combined.train_on_batch(noise, real)
```

# Generated Images

Discriminator Loss: 0.371719628572464  
Generator Loss: 2.474647283554077



Discriminator Loss: 0.38926680386066437  
Generator Loss: 2.30230712890625





# GAN with Vibration Signals

$$x = 4 \sin(2\pi 2t) + 2 \sin(2\pi 5t) + \varepsilon$$

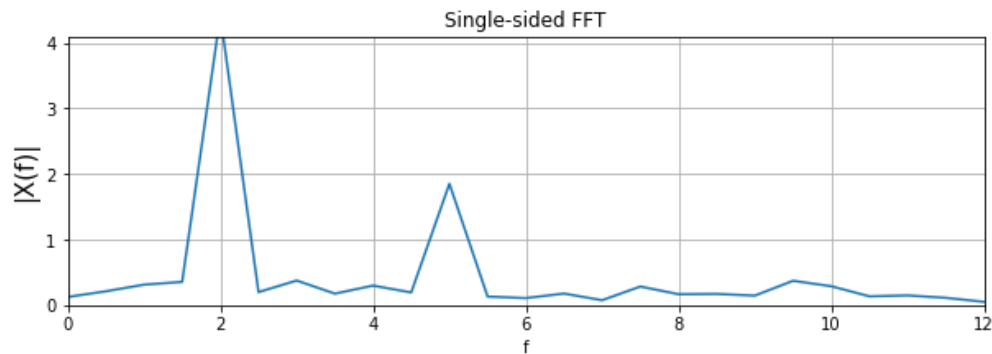
```
# Gen. & plot signal
Fs = 24
T = 1/Fs

N = 48

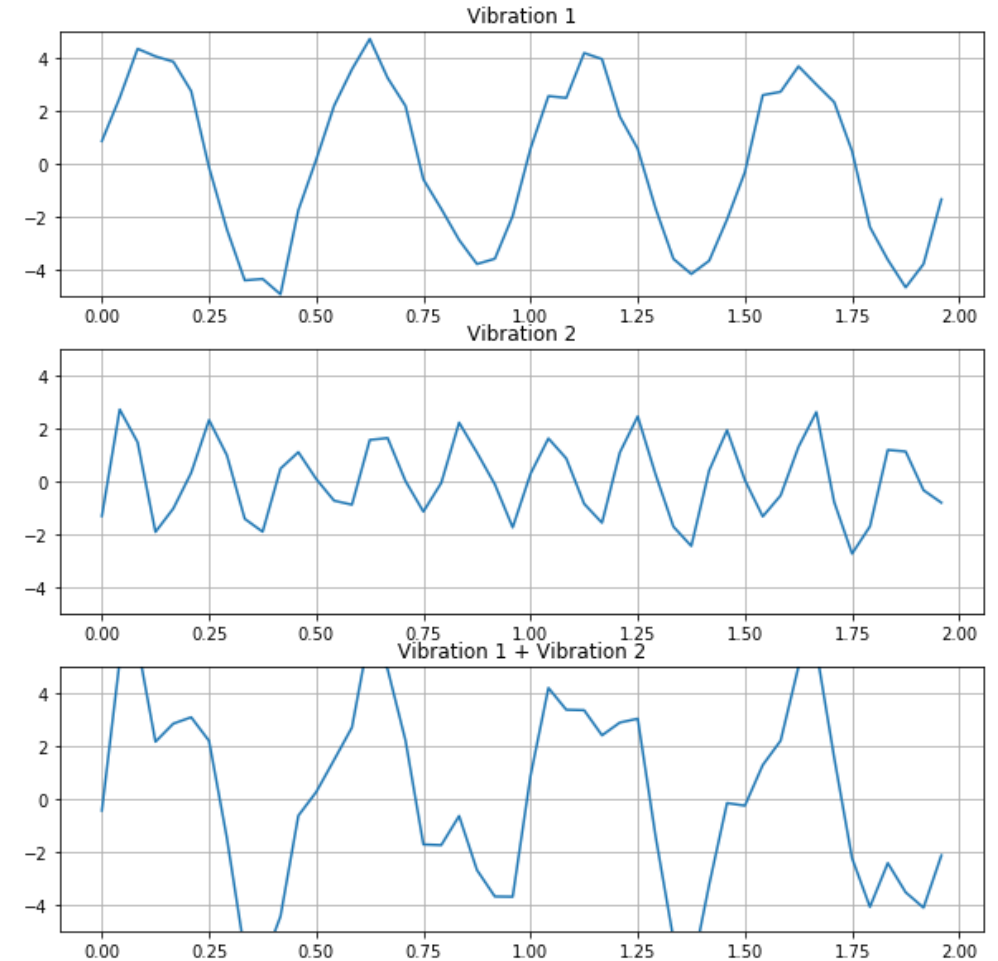
t = np.arange(0, N)*T

k = np.arange(0, N)
f = (Fs/N)*k

x1 = 4*np.sin(2*np.pi*2*t) + 0.5*np.random.randn(N)
x2 = 2*np.sin(2*np.pi*5*t) + 0.5*np.random.randn(N)
x = x1 + x2
```



FFT  
←



# GAN with Vibration Signals

```
generator = tf.keras.models.Sequential([
    tf.keras.layers.Dense(units = 32, input_dim = 10, activation = 'relu'),
    tf.keras.layers.Dense(units = 32, activation = 'relu'),
    tf.keras.layers.Dense(units = 48, activation = 'relu'),
    tf.keras.layers.Dense(units = 48, activation = 'tanh'),
])
```

```
discriminator = tf.keras.models.Sequential([
    tf.keras.layers.Dense(units = 50, input_dim = 48, activation = 'relu'),
    tf.keras.layers.Dense(units = 32, activation = 'relu'),
    tf.keras.layers.Dense(units = 32, activation = 'relu'),
    tf.keras.layers.Dense(units = 1, activation = 'sigmoid'),
])
```

