Autoencoders

Main idea:

Take data in some original (high-dimensional) space;

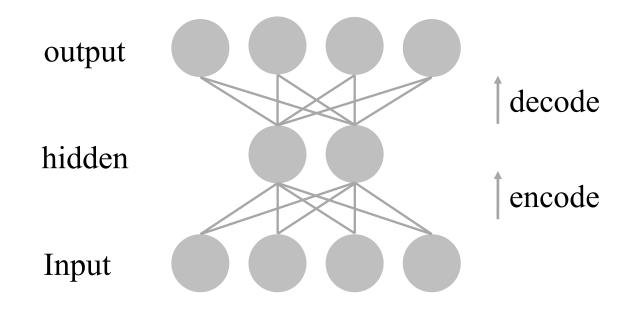
Project data into a new space from which it can then be accurately restored

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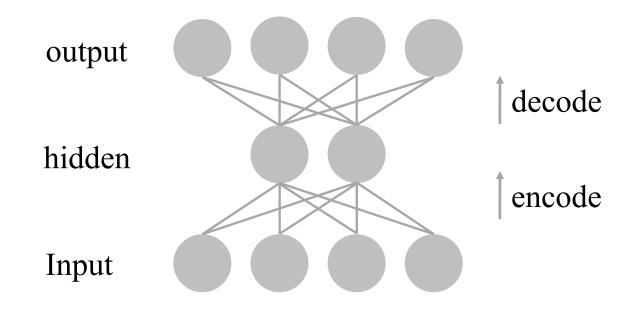
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Autoencoders

- Encoder = data to hidden
- Decoder = hidden to data
- Decoder(Encoder(x)) \sim x



Why do we ever need that?

- Compress data
 - |code| << |data|
- Dimensionality reduction
 - Before feeding data to your XGBoost :)
- <to be continued>

Linear case

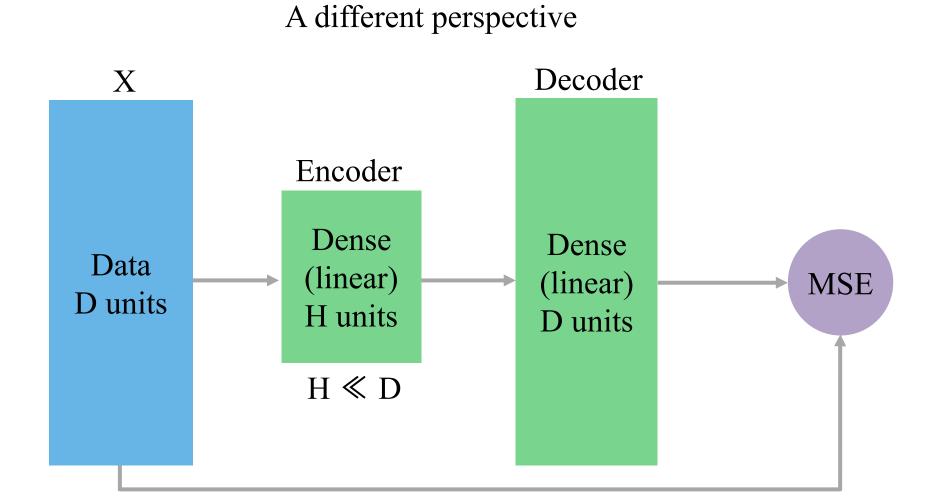
Example: matrix factorization

$$X = U \times V^{T}$$

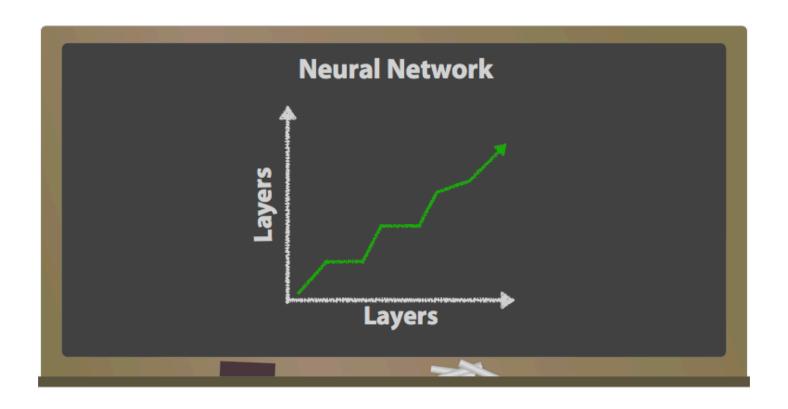
Minimizing reconstruction error

$$||X - U \cdot V^T|| \rightarrow \min_{U,V}$$

Matrix decompositions



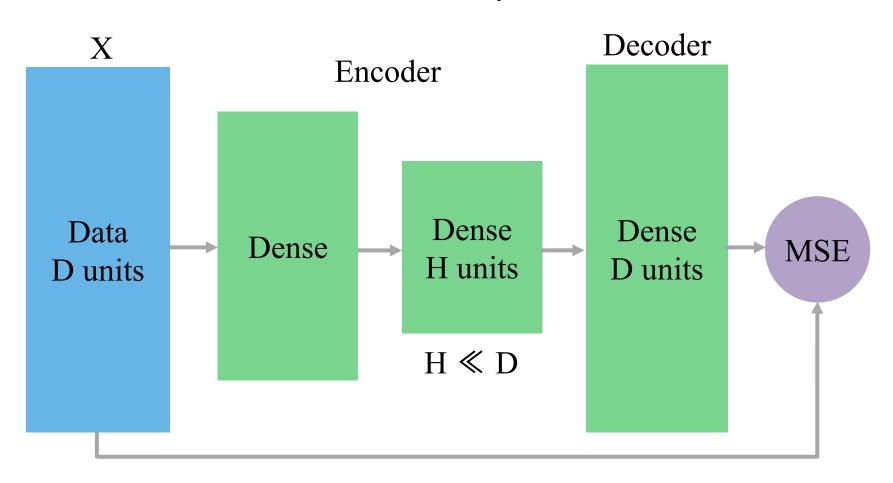
Matrix decompositions



«STACK MORE LAYERS»

Deep autoencoder

Stack more layers!



Deep autoencoder

Stack more layers! Decoder X Encoder Dense Dense Data Dense **MSE** D units H units D units $H \ll D$

Quiz: What if data is an image?

Image2image: convolutional

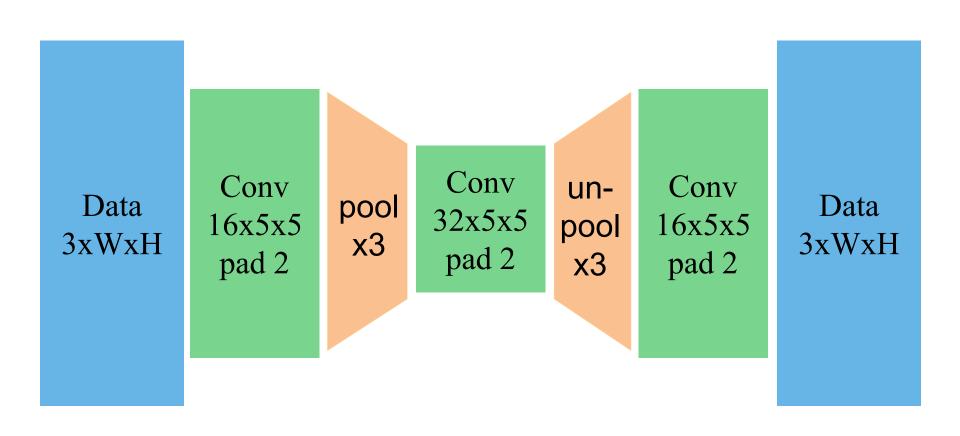


Image2image: fully-convolutional

