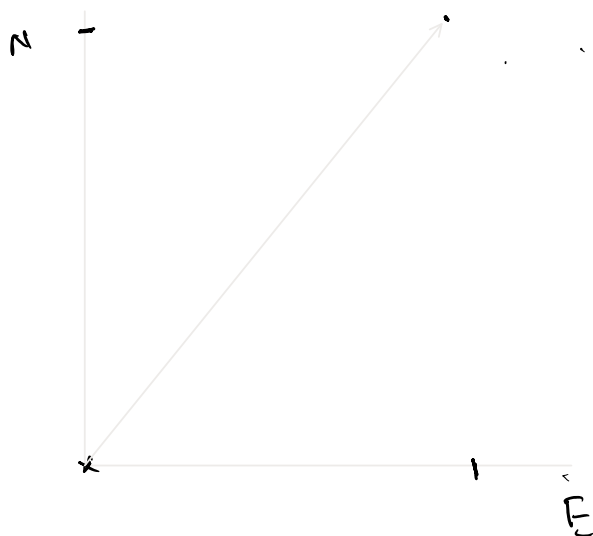


↳ Combination of rows and column.

function $\rightarrow y = x^2 \leftarrow x$

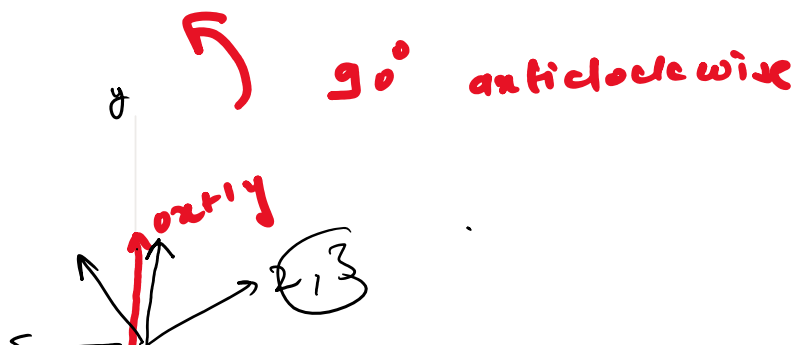
vector $\rightarrow \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix}$

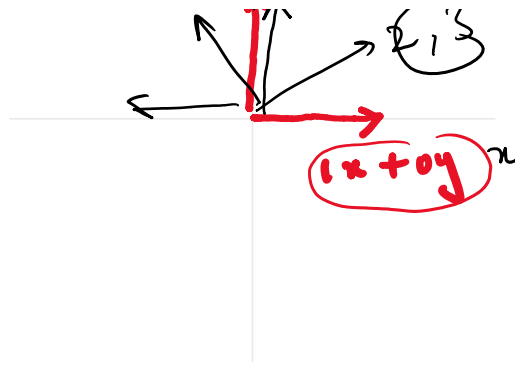
SE, 10 N



$$y = x^2 \leftarrow$$

(4.67, 5.98)





$$x \rightarrow y$$

$$y \rightarrow -x$$

x_i

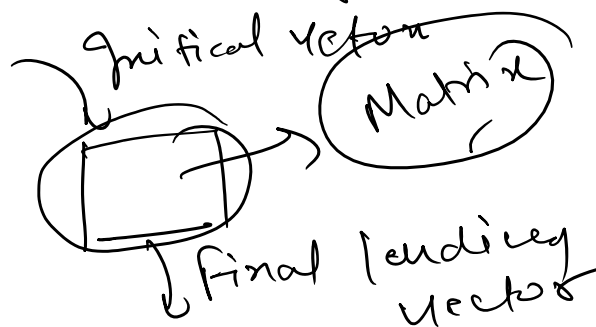
$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \xrightarrow{\text{Transformation}} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

y_i

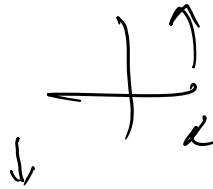
$$\begin{bmatrix} 0 \\ 1 \end{bmatrix} \xrightarrow{\text{Transformation}} \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

After transformation it is difficult to find the landing vector of any vector on coordinate system.



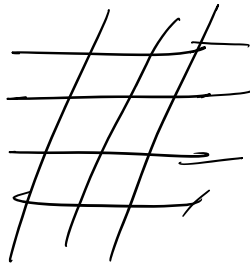
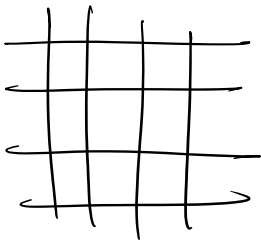
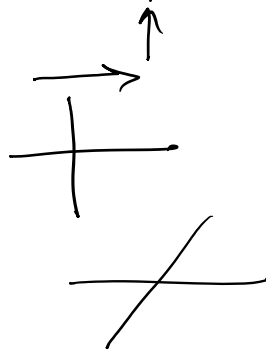
Rotation



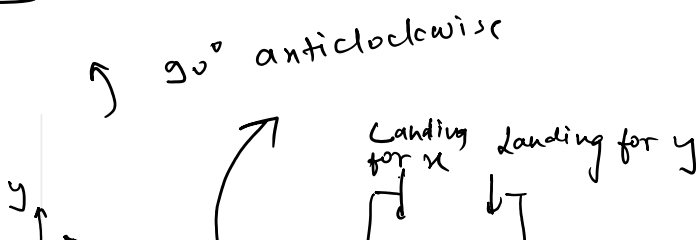
Compress

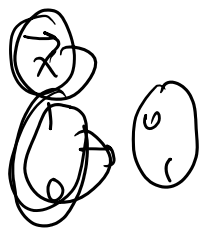


Skew



Maths:





$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

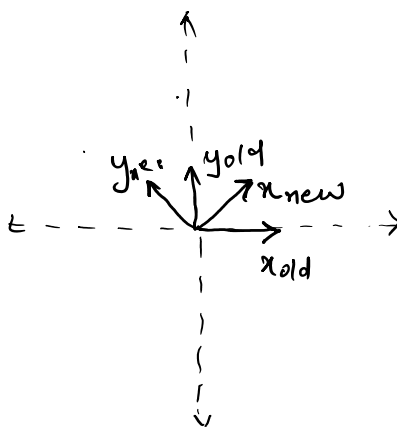
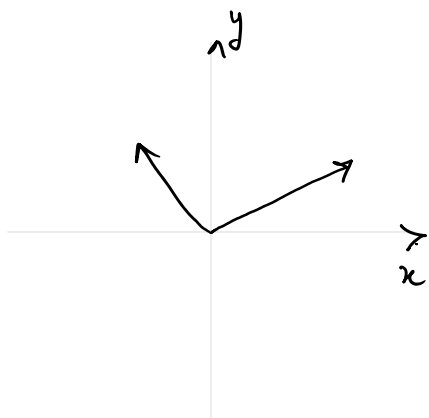
$A\vec{x} = \text{final vector}$

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

2.7

3.5

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 2.7 \\ 3.5 \end{bmatrix} = \begin{bmatrix} -3.5 \\ 2.7 \end{bmatrix}$$

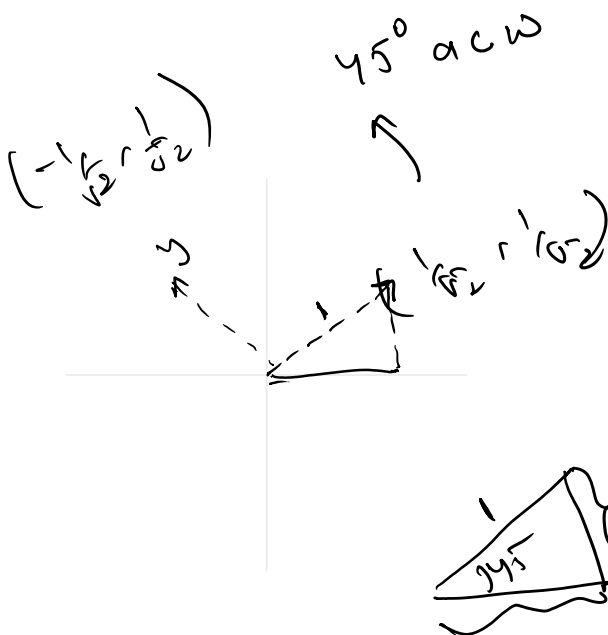
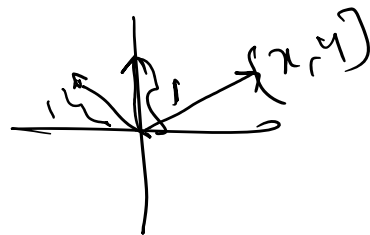
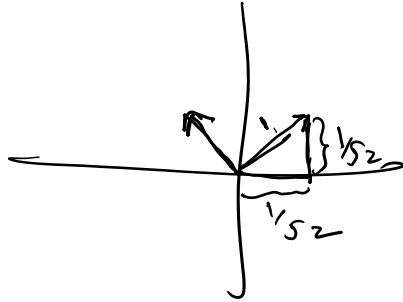


$$x_{old} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$x_{new} \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

$$y_{old} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

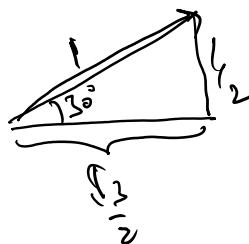
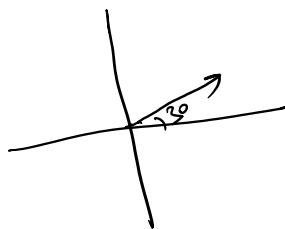
$$y_{new} \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$



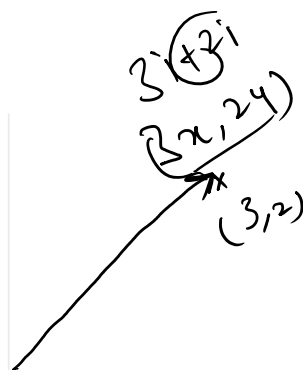
$$x \rightarrow \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

$$y \rightarrow \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

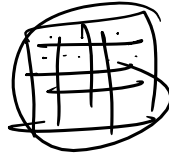
$$\begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \\ \end{bmatrix}$$



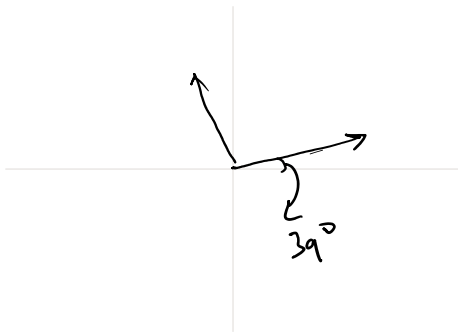
$$\begin{bmatrix} \sqrt{3}/2 \\ 1/2 \end{bmatrix}$$



Matrix Algebra



$$\begin{bmatrix} a & d & b \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix}_{3 \times 3}$$



Matrix Algebra:

Addition of Matrices

$$\begin{bmatrix} 10 & 6 \\ 3 & 6 \end{bmatrix} + \begin{bmatrix} 2 & 10 \\ 9 & 4 \end{bmatrix}$$

$$\begin{pmatrix} 3 & 4 \\ 5 & 6 \end{pmatrix} + \begin{pmatrix} 4 & 10 \\ 9 & 4 \end{pmatrix} \\ = \begin{bmatrix} 3 & 14 \\ 12 & 10 \end{bmatrix}$$

Subtraction of Matrices:

$$\begin{bmatrix} 4 & 6 \\ 10 & 12 \end{bmatrix} - \begin{bmatrix} 2 & 1 \\ 3 & 9 \end{bmatrix} \\ = \begin{bmatrix} 2 & 5 \\ 7 & 3 \end{bmatrix}$$

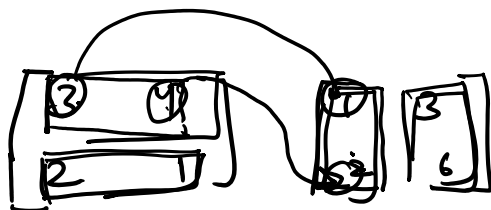
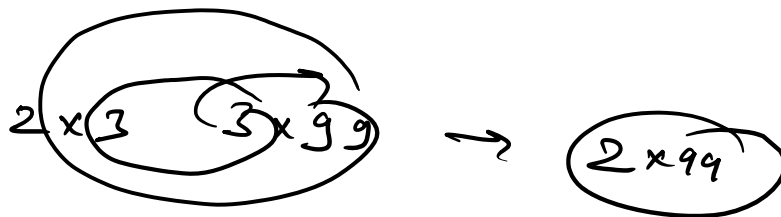
Multiplication

Multiplication of Matrices:

$$\begin{bmatrix} 2 & 3 \\ 4 & 6 \end{bmatrix}_{2 \times 2} \quad \begin{bmatrix} 1 & 4 \\ 1 & 2 \end{bmatrix}_{2 \times 2}$$

$$3 \times 4 \quad 5 \times 6 \quad \times$$

$$3 \times (4) \quad (4) \times 10 \quad \hookrightarrow$$



$$3 \times 1 + 4 \times 2 = 11$$

$$3 \times 3 + 4 \times 6 = 33$$

$$2 \times 1 + 1 \times 2 = 4$$

$$2 \times 3 + 1 \times 6 = 12$$



$$A = \begin{bmatrix} 10 & 20 \\ \sim & \end{bmatrix}$$

$$A = \begin{bmatrix} 10 & 20 \\ 5 & 15 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 4 \\ 6 & 2 \end{bmatrix}$$

$$A \times B = \begin{bmatrix} 10 & 20 \\ 5 & 15 \end{bmatrix} \begin{bmatrix} 1 \\ 6 \end{bmatrix} \begin{bmatrix} 4 \\ 2 \end{bmatrix}$$

$$\approx \begin{bmatrix} 130 & 80 \\ 95 & 50 \end{bmatrix}$$

$10 \times 1 + 20 \times 6$
 $10 \times 4 + 20 \times 2$
 $5 \times 1 + 15 \times 6$
 $= 95$
 $5 \times 4 + 15 \times 2$
 $= 50$

$$\begin{bmatrix} 1 & 4 \\ 6 & 2 \end{bmatrix}$$

2×2

$$\begin{bmatrix} 4 & 6 \\ 9 & 1 \\ 10 & 11 \end{bmatrix}$$

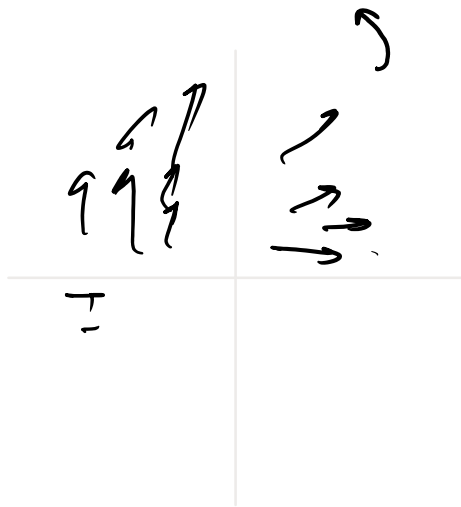
3×2

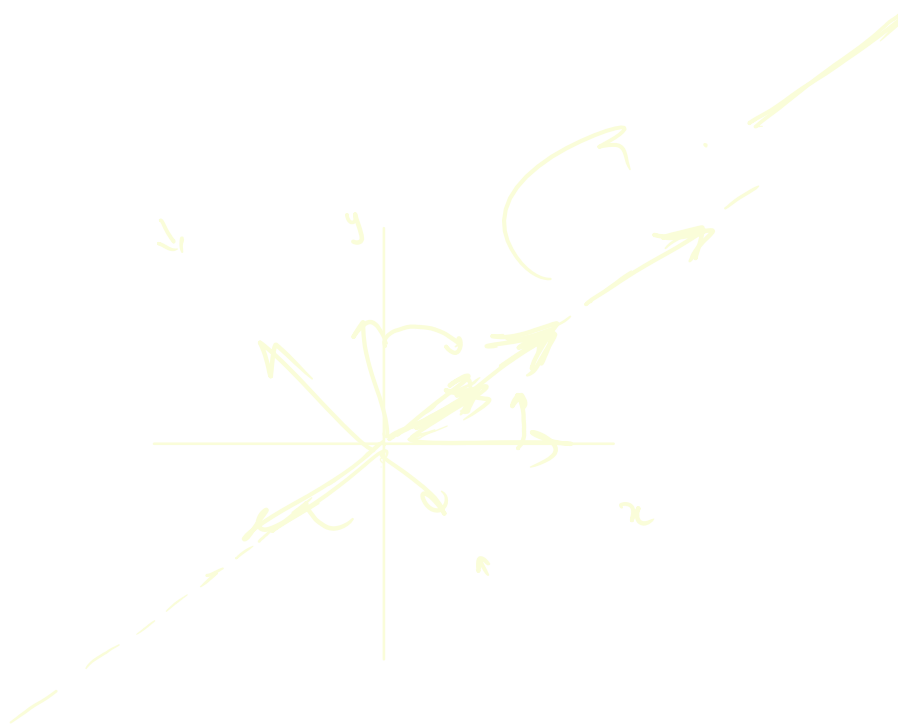
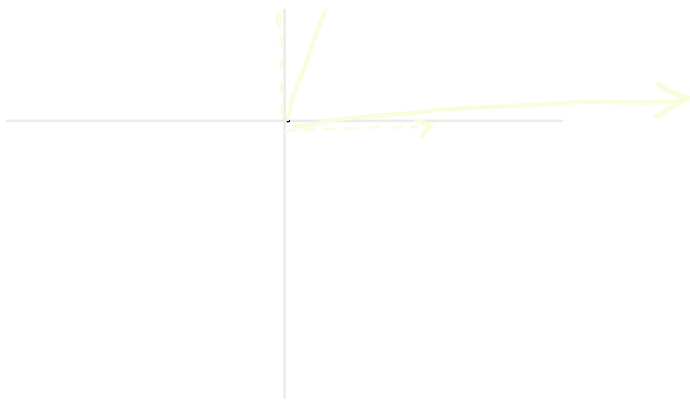
$$\begin{bmatrix} 1 & 4 \\ 9 & 6 \end{bmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{bmatrix} 1 & 4 \\ 9 & 6 \end{bmatrix}$$

Identity matrix

Eigen value and Eigen vector:

\rightarrow PCA (Principle component Analysis)
 \rightarrow SVD (Singular value decomposition)





Eigen vector: It is simply
a vector which does not
change its direction
on a transformation

— —

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