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Lifeline3: RouteSelectActivity

Lifeline4: MapViewModel

Lifeline5: Repository

Lifeline6: QNode

Lifeline2: Robot

1 [origin.floor == destination.floor] : bidaia hasi

2 : publishOrigin()

3 : publishOrigin()

6 : publishGoal()

7 : multilevel\_goal

5 : OK

4 : AppNavPhase = RACHING\_ORIGIN

8 : goal reached  
«LiveData»

9 : showAlert()

10 : next goal?

alt Ibilbidea jarraitu

[jarraitu=false]

11 : NO

[jarraitu=true]

12 : OK

13 : publishDestination()

14 : publishOrigin()

16 : publishGoal()

18 : multilevel\_goal

15 : AppNavPhase = REACHING\_DESTINATION

17 : OK

19 : showAlert()

21 : destination reached

20 : goal reached  
«LiveData»