# DATA ANALYSIS I

Data: Algebraic and Geometric View

2019-20

#### Sources

• Zaki, M. J., Meira Jr, W. (2014). Data Mining and Analysis: Fundamental Concepts and Algorithms. Cambridge University Press. [1-13]

#### Data Matrix

Data can be represented or abstracted as an n×d data matrix, with n rows and d columns.

Rows correspond to objects in the dataset.

Columns represent attributes or properties of interest.

#### Data matrix

$$D = \begin{pmatrix} X_1 & X_2 & \cdots & X_d \\ x_1 & x_{11} & x_{12} & \cdots & x_{1d} \\ x_2 & x_{21} & x_{22} & \cdots & x_{2d} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ x_n & x_{n1} & x_{n2} & \cdots & x_{nd} \end{pmatrix}$$

$$\mathbf{x}_i = (x_{i1}, x_{i2}, \dots, x_{id})$$

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  $X_j = (x_{1j}, x_{2j}, \dots, x_{nj})$ 

#### Data Point

• If the *d* attributes or dimensions in the data matrix *D* are all numeric, then each row can be considered as a *d*-dimensional point

$$\mathbf{x}_i = (x_{i1}, x_{i2}, \dots, x_{id}) \in \mathbb{R}^d$$

$$\mathbf{x}_{i} = \begin{pmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ x_{id} \end{pmatrix} = \begin{pmatrix} x_{i1} & x_{i2} & \cdots & x_{id} \end{pmatrix}^{\mathrm{T}} \in \mathbb{R}^{d}$$

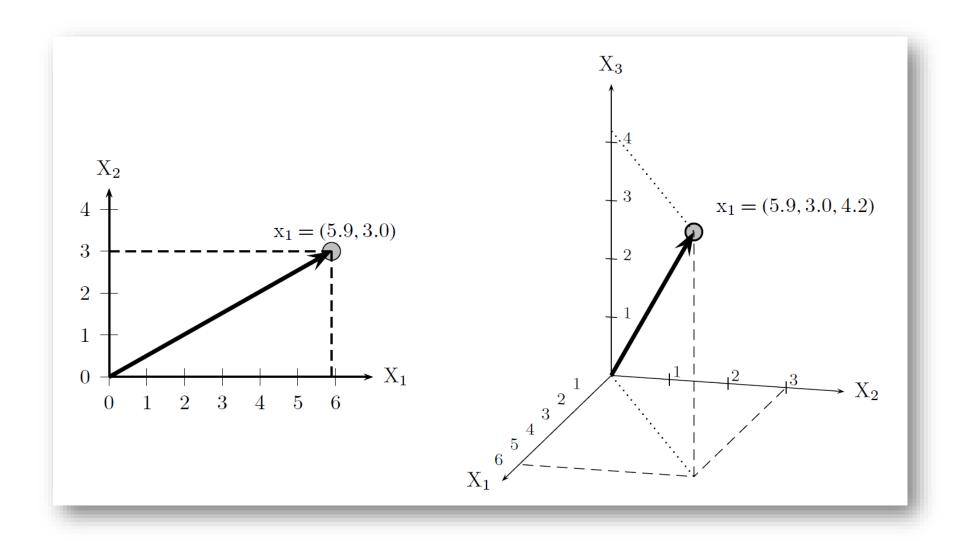
### Cartesian Coordinate Space

- The *d*-dimensional *Cartesian coordinate space* is specified via the d unit vectors, called the standard basis vectors, along each of the axes.
- Any other vector in R<sup>d</sup> can be written as linear combination of the standard basis vectors.

$$e_j = (0, ..., 1_j, ..., 0)^T$$

$$x_i = x_{i1}e_1 + x_{i2}e_2 + \dots + x_{id}e_d = \sum_{j=1}^d x_{ij}e_j$$

# Examples



### Data Matrix: Example

 An extract of the Iris dataset; the complete data forms a 150×5 data matrix.

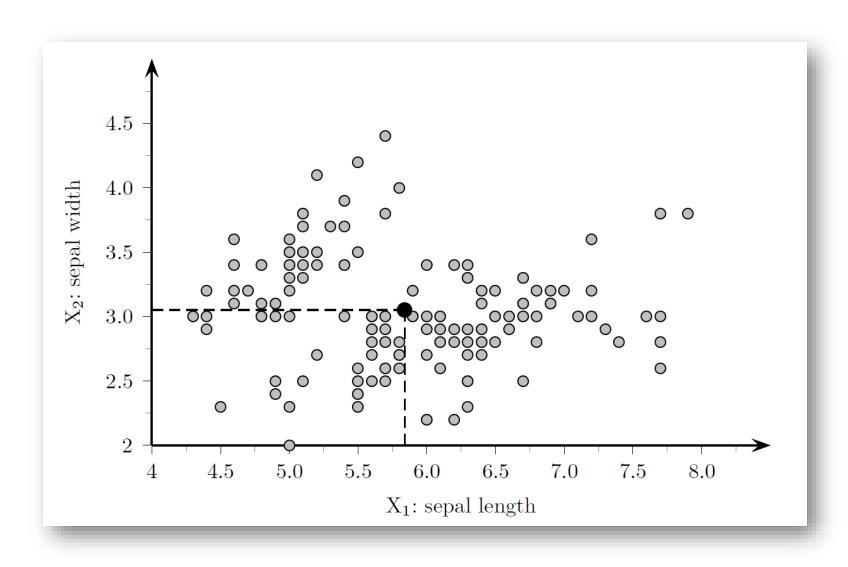
• Each entity is an Iris flower, and the attributes include sepal length, sepal width, petal length, and petal width in centimeters, and the type or class of the Iris flower.

### Data Matrix

	Sepal length	Sepal width	Petal length	Petal width	Class
	$X_1$	$X_2$	$X_3$	$X_4$	$X_5$
$\mathbf{x}_1$	5.9	3.0	4.2	1.5	Iris-versicolor
$x_2$	6.9	3.1	4.9	1.5	Iris-versicolor
$x_3$	6.6	2.9	4.6	1.3	Iris-versicolor
$x_4$	4.6	3.2	1.4	0.2	Iris-setosa
X5	6.0	2.2	4.0	1.0	Iris-versicolor
$x_6$	4.7	3.2	1.3	0.2	Iris-setosa
X7	6.5	3.0	5.8	2.2	Iris-virginica
X8	5.8	2.7	5.1	1.9	Iris-virginica
:	÷	÷	÷	:	i i
X <sub>149</sub>	7.7	3.8	6.7	2.2	Iris-virginica
$\chi_{150}$	5.1	3.4	1.5	0.2	Iris-setosa /

https://archive.ics.uci.edu/ml/machine-learning-databases/iris/iris.data

### Geometric Representation



### Distance and Angle

• **Vectors**: Treating data objects and attributes as vectors, and the entire dataset as a matrix, enables to apply both geometric and algebraic methods to aid in the data mining and analysis tasks.

What is a distance / similarity?

### Dot Product

$$\mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{pmatrix} \qquad \mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

$$\mathbf{a}^{\mathrm{T}}\mathbf{b} = \begin{pmatrix} a_1 & a_2 & \cdots & a_m \end{pmatrix} \times \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$
$$= a_1b_1 + a_2b_2 + \cdots + a_mb_m$$
$$= \sum_{i=1}^m a_ib_i$$

#### Euclidean Norm

$$\|\mathbf{a}\| = \sqrt{\mathbf{a}^{\mathrm{T}}\mathbf{a}} = \sqrt{a_1^2 + a_2^2 + \dots + a_m^2} = \sqrt{\sum_{i=1}^{m} a_i^2}$$

• The Euclidean norm is a special case of a general class of norms, known as  $L_p$ -norm (p=2), defined as

$$\|\mathbf{a}\|_{p} = (|a_{1}|^{p} + |a_{2}|^{p} + \dots + |a_{m}|^{p})^{\frac{1}{p}} = (\sum_{i=1}^{m} |a_{i}|^{p})^{\frac{1}{p}}$$

#### Euclidean Distance

• Euclidean distance is the distance in Euclidean space.

$$\delta(\mathbf{a}, \mathbf{b}) = \|\mathbf{a} - \mathbf{b}\| = \sqrt{(\mathbf{a} - \mathbf{b})^{\mathrm{T}}(\mathbf{a} - \mathbf{b})} = \sqrt{\sum_{i=1}^{m} (a_i - b_i)^2}$$

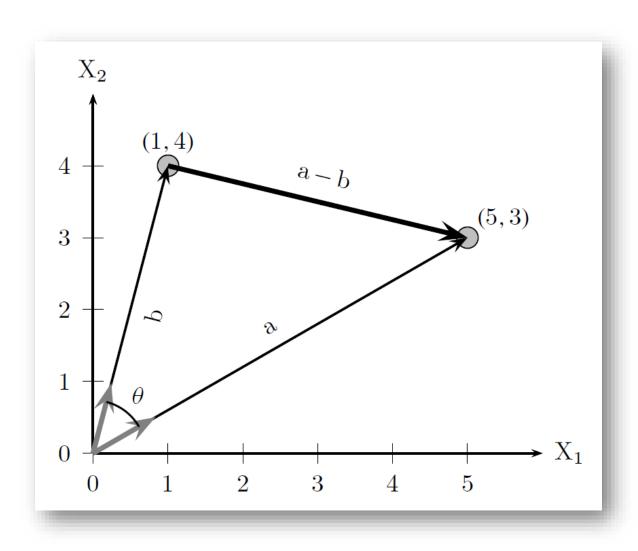
### Cosine Similarity

• **Cosine similarity** is the cosine of the smallest angle between vectors *a* and *b*.

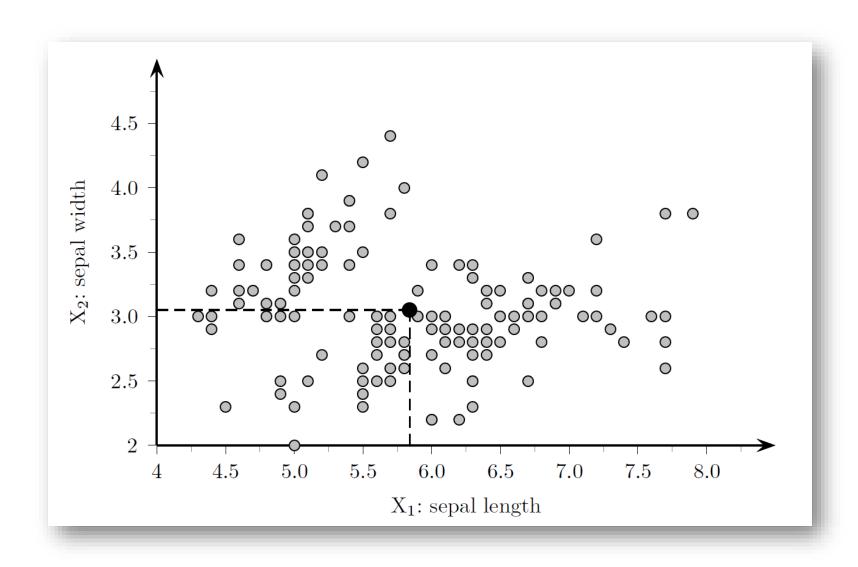
$$\cos \theta = \frac{\mathbf{a}^{\mathrm{T}} \mathbf{b}}{\|\mathbf{a}\| \|\mathbf{b}\|} = \left(\frac{\mathbf{a}}{\|\mathbf{a}\|}\right)^{\mathrm{T}} \left(\frac{\mathbf{b}}{\|\mathbf{b}\|}\right)$$

• The cosine of the angle between a and b is given as the dot product of the unit vectors a / ||a|| a b / ||b||.

# Distance and Angle



### Mean and Total Variance



#### Mean

• The **Mean** of the data matrix D is the vector obtained as the average of all the points.

$$mean(D) = \mu = \frac{1}{n} \sum_{i=1}^{n} x_i$$

#### Total Variance

• The **Total Variance** of the data matrix *D* is the average squared distance of each point from the mean.

$$var(D) = \frac{1}{n} \sum_{i=1}^{n} \delta(\mathbf{x}_i, \boldsymbol{\mu})^2 = \frac{1}{n} \sum_{i=1}^{n} \|\mathbf{x}_i - \boldsymbol{\mu}\|^2$$

#### Centered Data Matrix

- Often we need to center the data matrix by making the mean coincide with the origin of the data space.
- The centered data matrix is obtained by subtracting the mean from all the points.

$$\mathbf{Z} = \mathbf{D} - 1 \cdot \boldsymbol{\mu}^{\mathrm{T}} = \begin{pmatrix} \mathbf{x}_{1}^{\mathrm{T}} \\ \mathbf{x}_{2}^{\mathrm{T}} \\ \vdots \\ \mathbf{x}_{n}^{\mathrm{T}} \end{pmatrix} - \begin{pmatrix} \boldsymbol{\mu}^{\mathrm{T}} \\ \boldsymbol{\mu}^{\mathrm{T}} \\ \vdots \\ \boldsymbol{\mu}^{\mathrm{T}} \end{pmatrix} = \begin{pmatrix} \mathbf{x}_{1}^{\mathrm{T}} - \boldsymbol{\mu}^{\mathrm{T}} \\ \mathbf{x}_{2}^{\mathrm{T}} - \boldsymbol{\mu}^{\mathrm{T}} \\ \vdots \\ \mathbf{x}_{n}^{\mathrm{T}} - \boldsymbol{\mu}^{\mathrm{T}} \end{pmatrix} = \begin{pmatrix} \mathbf{z}_{1}^{\mathrm{T}} \\ \mathbf{z}_{2}^{\mathrm{T}} \\ \vdots \\ \mathbf{z}_{n}^{\mathrm{T}} \end{pmatrix}$$

#### Linear Independence

• The vectors  $v_1, \ldots, v_k$  are linearly dependent if at least one vector can be written as a linear combination of the others.

 A set of vectors is linearly independent if none of them can be written as a linear combination of the other vectors in the dataset.

• Basis: It is a minimum set of vectors in the dataset that are linearly independent. Any two bases must have the same number of vectors.

### Dimensionality

• **Dimension (rank)**: For any matrix, the *dimension* of its row and column space is the same, and this dimension is also called the *rank* of the matrix. Rank gives an indication about the intrinsic dimensionality of the data.

• **Dimensionality reduction**: It is often possible to approximate dataset (matrix) *D* with a derived data matrix D', which has much lower dimensionality.