Lecture 15

Performer, Variational Autoencoders

Rethinking Attention with Performers

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• "We introduce the first Transformer architectures, *Performers*, capable of **provably** accurate and practical estimations of regular (softmax) full rank attention, but of only linear space and time complexity and **not relying on any priors** such as sparsity or low-rankness. Performers use the *Fast Attention Via positive Orthogonal Random features* (FAVOR+) mechanism"

- Define three different vectors corresponding to each word.
 - Input $x \in \mathbb{R}^d$

 $x = [\underline{x_1} - -x_n]_{d \times n}$

- Key
- Query
- Value

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$$X = [\underline{x_1} - -x_n]_{d \times n}$$

- Key
- $k \in \mathbb{R}^p$

$$K = \underbrace{W_k^T}_{p \times d} X_{d \times n}$$

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- Query
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Define three different vectors corresponding to each word.

 $K = \underbrace{W_k^T}_{p \times d} X_{d \times n}$

 $Q = \underbrace{W_q^T}_{p \times d} X_{d \times n}$

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$$\mathcal{L} = V softmax \left(\underbrace{\frac{Q^T K}{\sqrt{P}}}_{n \times n} \right)$$

$$p \times n$$

$$O(n^2m)$$

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$$\mathcal{L} = V softmax \underbrace{\left(\frac{Q^T K}{\sqrt{P}}\right)}_{n \times n} \qquad \qquad X^T \underbrace{W_q W_k X}_{n \times p}$$

$$O(n^2m)$$

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- Random features has this form:

$$\phi(x) = \frac{h(x)}{\sqrt{r}} \left(f_1\left(\underline{\omega_1^T}x\right), f_1\left(\underline{\omega_2^T}x\right) \dots f_1\left(\underline{\omega_r^T}x\right) \dots f_l\left(\underline{\omega_1^T}x\right) \dots f_l\left(\underline{\omega_1^T}x\right) \right)$$

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$$\phi(y)$$

$$K(x,y) = \phi^{T}(x)\phi(y)$$

$$h(x) = 1$$
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$$K(x,y) = \phi^T \phi(y) = e^{\frac{-|x-y|^2}{\gamma}}$$
Gaussian

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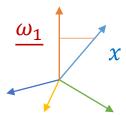
$$K(x,y) = \phi^T \phi(y) = e^{\frac{-|x-y|^2}{\gamma}}$$
Gaussian

$$\frac{\omega_1}{x}$$

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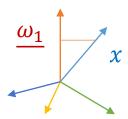


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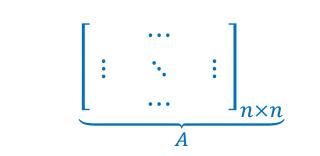
$$softmax\ (\frac{Q^TK}{\sqrt{P}})$$



$$\sigma(\underline{s})_i = a_i = \frac{e^{s_i}}{\sum_j e^{s_j}}$$

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$$A = \exp(\frac{Q^T K}{\sqrt{P}}) \qquad \qquad \underbrace{\begin{bmatrix} \vdots & \cdots & \vdots \\ \vdots & \ddots & \vdots \\ & A \end{bmatrix}_{n \times n}}_{A}$$

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$$diag(\underbrace{A1}_{D}) = \begin{bmatrix} x & 0 & 0 & 0 & - \\ 0 & x & 0 & 0 & - \\ 0 & 0 & x & 0 & - \\ \end{bmatrix}$$

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$$\begin{bmatrix}
\vdots & \ddots & \vdots \\
\vdots & \ddots & \vdots \\
A
\end{bmatrix}_{n \times n}$$

$$A = \exp(\frac{Q^T K}{\sqrt{P}}) \qquad \qquad \underbrace{\begin{bmatrix} & \dots & & 1 & & 0 \\ \vdots & \ddots & \vdots & & \vdots \\ & \dots & & 1 & & 0 \end{bmatrix}}_{n \times n} \qquad 1 \qquad \qquad \vdots \\ & & \dots & 1 \qquad \qquad 0$$

$$diag(\underbrace{A1}_{D}) = \begin{bmatrix} x & 0 & 0 & 0 & - \\ 0 & x & 0 & 0 & - \\ 0 & 0 & x & 0 & - \\ ... & ... & ... & ... \end{bmatrix}$$

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$$e^{-|x-y|^2} = e^{-(x-y)^T(x-y)} = e^{-[x^Tx+y^Ty-2x^Ty]} = e^{-x^Tx} \cdot e^{-y^Ty} \cdot e^{2x^Ty}$$

$$\underbrace{e^{-|x-y|^2}}_{2} = e^{\frac{-(x-y)^T(x-y)}{2}} = e^{\frac{-[x^Tx+y^Ty-2x^Ty]}{2}} = e^{-x^Tx} \cdot e^{-y^Ty} \cdot \underbrace{e^{2x^Ty}}_{2}$$

$$e^{-|x-y|^2} = e^{\frac{-(x-y)^T(x-y)}{2}} = e^{\frac{-[x^Tx+y^Ty-2x^Ty]}{2}} = e^{\frac{-x^Tx}{2}} \cdot e^{\frac{-y^Ty}{2}} \cdot e^{\frac{2x^Ty}{2}}$$

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$$K_{gauss} \cdot e^{\frac{x^Tx}{2}} \cdot e^{\frac{y^Ty}{2}}$$

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$$\underbrace{K_{gauss} \cdot e^{\frac{x^T x}{2}} \cdot e^{\frac{y^T y}{2}}}_{K_{SM} \leftarrow e^{x^T y}}$$

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$$\phi(x) = \frac{h(x)}{\sqrt{r}} \left(f_1\left(\underline{\omega_1^T}x\right), f_1\left(\underline{\omega_2^T}x\right) \dots f_1\left(\underline{\omega_r^T}x\right) \dots f_l\left(\underline{\omega_1^T}x\right) \dots f_l\left(\underline{\omega_1^T}x\right) \dots f_l\left(\underline{\omega_r^T}x\right) \right)$$

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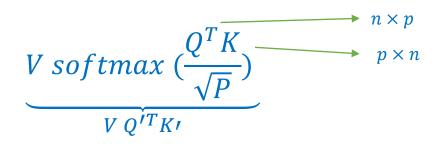
$$h(x) = \frac{x^T x}{2}$$

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$$\phi(\underline{x}) = \frac{x^T x}{2\sqrt{r}} \left(\sin\left(\underline{\omega_1}^T x\right) \sin\left(\underline{\omega_2}^T x\right) \dots \sin\left(\underline{\omega_1}^T x\right) \cos\left(\underline{\omega_1}^T x\right) \dots \cos\left(\underline{\omega_r}^T x\right) \right)$$

$$V softmax \left(\frac{Q^T K}{\sqrt{P}}\right)$$

$$\underbrace{V \, softmax \, (\frac{Q^T K}{\sqrt{P}})}_{V \, Q'^T K'}$$



$$V softmax \left(\frac{Q^{T}K}{\sqrt{P}}\right) \xrightarrow{n \times p} p \times n$$

$$V Q'^{T}K'$$

$$O(mn^{2})$$

$$V softmax \left(\frac{Q^{T}K}{\sqrt{P}}\right) \xrightarrow{p \times n} O(mn^{2})$$

$$V \left(\frac{Q^{T}K}{\sqrt{P}}\right)$$

$$\underbrace{m \times n \quad n \times r'}_{m \times r'} \qquad \qquad r' \times n \qquad \qquad O(mr'n^2)$$

$$r' \times n$$

$$V softmax \left(\frac{Q^{T}K}{\sqrt{P}}\right) \xrightarrow{p \times n} V \left(\frac{Q'^{T}K'}{\sqrt{P}}\right)$$

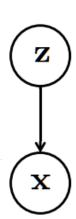
$$O(mn^2)$$

$$\underbrace{m \times n \quad n \times r'}_{m \times r'} \qquad \qquad r' \times n \\ r' \times n$$

$$O(mr'n^2)$$

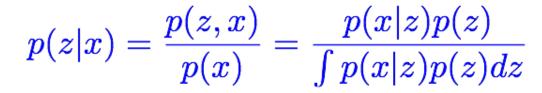
Variational Auto encoder (VEA)

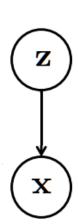
- Problem Definition
 - Observable Data: $x = \{x_1, x_2, ..., x_n\}$
 - Hidden Variable: $z = \{z_1, z_2, ..., z_n\}$



• Problem Definition

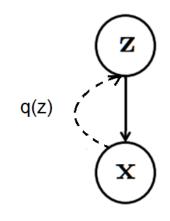
- Observable Data: $x = \{x_1, x_2, ..., x_n\}$
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- Solutions
 - Monte Carlo Sampling
 - Metropolis Hasting
 - Gibbs Sampling
 - Variational Inference

• Approximate p(z|x) by q(z)



• Minimize the KL Divergence:

$$D_{KL}\Big[q(z)||p(z|x)\Big] = -\int q(z)lograc{p(z|x)}{q(z)}dz$$

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 $= -\int q(z)lograc{p(z,x)}{q(z)p(x)}dz$

$$\begin{split} D_{KL}\Big[q(z)||p(z|x)\Big] &= -\int q(z)log\frac{p(z|x)}{q(z)}dz\\ &= -\int q(z)log\frac{p(z,x)}{q(z)p(x)}dz\\ &= -\int q(z)log\frac{p(z,x)}{q(z)}dz + \int q(z)log(p(x))dz \end{split}$$

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$$D_{KL}\Big[q(z)||p(z|x)\Big] = -\underbrace{\left(E_{q(z)}\Big[log\big(p(z,x)\big)\Big] - E_{q(z)}\Big[log\big(q(z)\big)\Big]\right)}_{\text{Evidence Lower Bound (ELBO)}} + log\big(p(x)\big)$$

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$$D_{KL}\Big[q(z)||p(z|x)\Big] = -L\Big[q(z)\Big] + log\Big(p(x)\Big)$$

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$$D_{KL}\Big[q(z)||p(z|x)\Big] = -L\Big[q(z)\Big] + log\Big(p(x)\Big)$$

$$log\Big(p(x)\Big) = D_{KL}\Big[q(z)||p(z|x)\Big] + L\Big[q(z)\Big]$$

$$\begin{split} D_{KL}\Big[q(z)||p(z|x)\Big] &= -\underbrace{\left(E_{q(z)}\Big[log\big(p(z,x)\big)\Big] - E_{q(z)}\Big[log\big(q(z)\big)\Big]\right)}_{\text{Evidence Lower Bound (ELBO)}} + log\big(p(x)\big) \\ D_{KL}\Big[q(z)||p(z|x)\Big] &= -L\Big[q(z)\Big] + log\Big(p(x)\Big) \\ log\Big(p(x)\Big) &= D_{KL}\Big[q(z)||p(z|x)\Big] + L\Big[q(z)\Big] \\ \text{Minimizing } D_{KL}\Big[q(z)||p(z|x)\Big] \\ \text{is equal to Maximizing } L\Big[q(z)\Big] \end{split}$$