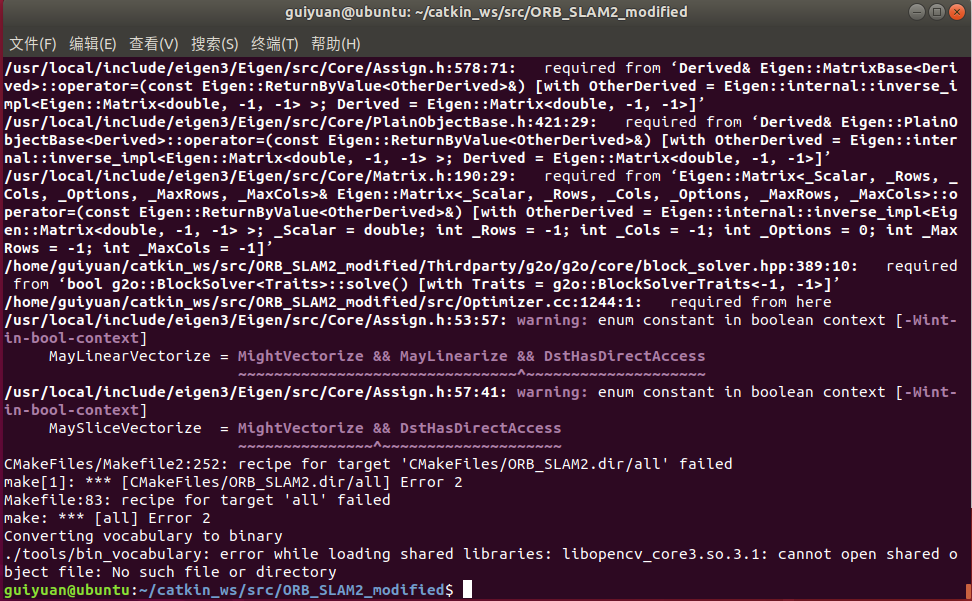
教程：<https://blog.csdn.net/m0_60355964/article/details/124735742>

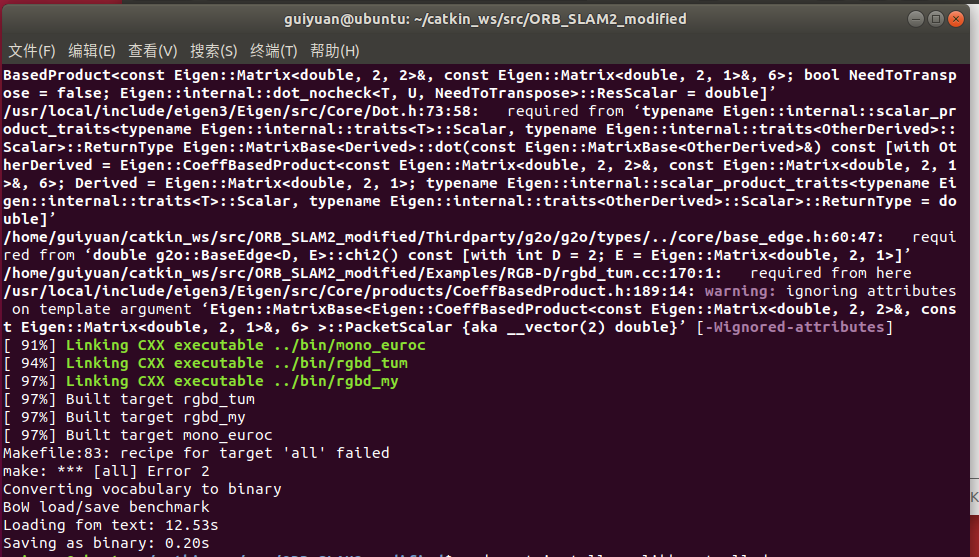
./build报错



https://blog.csdn.net/m0\_60355964/article/details/124735742，参照下图（怀疑这步都不用，就是多build几次）



先加了-lboost\_system



多./build几遍就过了，可能是内存不足。

./build\_ros.sh时，看ORBSLAM2构建稠密点云图及小觅相机的使用.html

#roslaunch realsense2\_camera rs\_camera.launch

roslaunch realsense2\_camera rs\_rgbd.launch

rosrun ORB\_SLAM2 RGBD Vocabulary/ORBvoc.txt Examples/ROS/ORB\_SLAM2/MyD435i2.yaml

https://blog.csdn.net/m0\_60355964/article/details/124850849?spm=1001.2014.3001.5502



roslaunch realsense2\_camera rs\_rgbd.launch

rosrun ORB\_SLAM2 RGBD Vocabulary/ORBvoc.txt Examples/ROS/ORB\_SLAM2/MyD435i2.yaml

（配置用MyD435i2.yaml）

在终端查看pcd文件

pcl\_viewer vslam.pcd