

# CENG501 Deep Learning Homework 1

İsmail Karabaş  
Student ID: 2375186

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## Q1.1

$$L1(w, b) = \frac{1}{N} \sum_{i=1}^N |y_i - f(x_i; w, b)|$$

Let  $d_i = y_i - f(x_i; w, b)$ .

### Case 1 when $d_i > 0$

So  $|d_i| = d_i$

Now, the loss function becomes:

$$L1(w, b) = \frac{1}{N} \sum_{i=1}^N d_i$$

Partial Derivative with Respect to  $w$ :

$$\frac{\partial L1(w, b)}{\partial w} = \frac{1}{N} \sum_{i=1}^N \frac{\partial d_i}{\partial w}$$

Now,  $d_i = y_i - f(x_i; w, b)$ , so we need to find  $\frac{\partial d_i}{\partial w}$ . Using the chain rule:

$$\frac{\partial d_i}{\partial w} = \frac{\partial}{\partial w}(y_i - f(x_i; w, b))$$

In the context of the linear function  $f(x_i; w, b) = \sigma(w^T x_i + b)$ , where  $\sigma(t)$  is a step function, the expression  $w^T x_i$  is a dot product between the weight vector  $w$  and the input vector  $x_i$ .

Now, when finding the partial derivative of  $f(x_i; w, b)$  with respect to  $w$ , we consider the term  $w^T x_i$ . The derivative of a dot product of vectors is computed with respect to each component of the vectors, and the result is the vector itself. Therefore,  $\frac{\partial}{\partial w}(w^T x_i) = x_i$ .

In simpler terms, when we vary a single component  $w_j$  in  $w$ , the change in  $w^T x_i$  is precisely  $x_{ij}$ , the corresponding component of the input vector  $x_i$ . This leads to the derivative being  $x_i$ .

Substituting this back into the expression for the partial derivative:

$$\frac{\partial L1(w, b)}{\partial w} = -\frac{1}{N} \sum_{i=1}^N x_i$$

$$\frac{\partial L1(w, b)}{\partial b} = -\frac{1}{N} \sum_{i=1}^N 1$$

**Case 2 When  $|d_i| = 0$ :**

it implies  $d_i = 0$ . In this case, the absolute value does not contribute to the loss. The partial derivatives become:

$$\frac{\partial L1(w, b)}{\partial w} = 0$$

$$\frac{\partial L1(w, b)}{\partial b} = 0$$

**Case 3: When  $d_i < 0$ :**

In this case,  $|d_i| = -d_i$ . The loss function becomes:

$$L1(w, b) = \frac{1}{N} \sum_{i=1}^N -d_i$$

Now, let's find the partial derivatives for this case:

$$\frac{\partial L1(w, b)}{\partial w} = \frac{1}{N} \sum_{i=1}^N \frac{\partial d_i}{\partial w}$$

$$\frac{\partial L1(w, b)}{\partial b} = \frac{1}{N} \sum_{i=1}^N 1$$

Substituting the derivative of  $d_i$  with respect to  $w$ :

$$\frac{\partial d_i}{\partial w} = -x_i$$

We get:

$$\frac{\partial L1(w, b)}{\partial w} = \frac{1}{N} \sum_{i=1}^N x_i$$

$$\frac{\partial L1(w, b)}{\partial b} = \frac{1}{N} \sum_{i=1}^N 1$$

**Overall Solution:**

The partial derivatives can be expressed in a concise manner using the sign function:

$$\frac{\partial L1(w, b)}{\partial w} = -\frac{1}{N} \sum_{i=1}^N \text{sign}(d_i) \cdot x_i$$

$$\frac{\partial L1(w, b)}{\partial b} = -\frac{1}{N} \sum_{i=1}^N \text{sign}(d_i)$$

## Q1.3 Plots of the Model

For the following two plots, the used command is: `python main.py data/linear_data_train.pickle.gz data/linear_data_test.pickle.gz 35 .1`

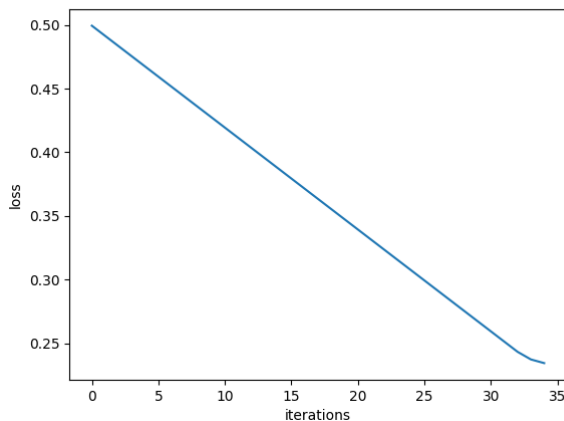


Figure 1: Loss vs Iterations

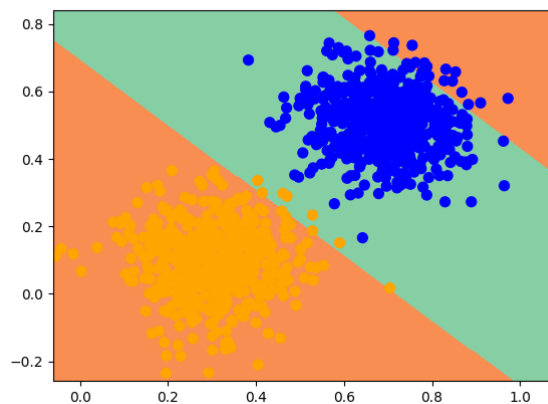


Figure 2: Weights Distribution

For the following two plots, the used command is: `python main.py data/mnist_01_train.pickle.gz data/mnist_01_test.pickle.gz 50 .001`

I changed parameters till finding a good Learning behaviour just like described in the homework text.

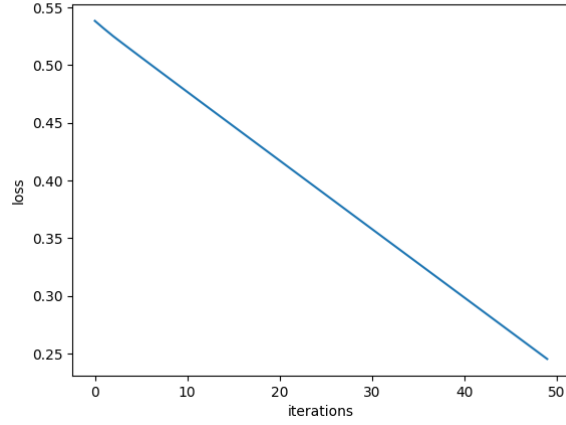


Figure 3: Loss vs Iterations

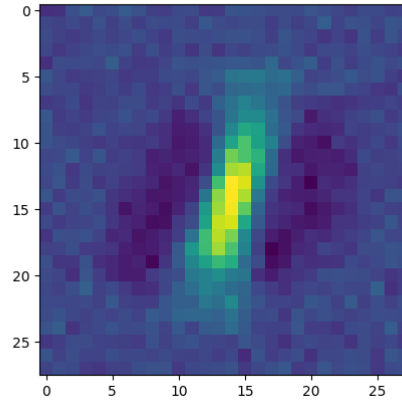


Figure 4: Weights Distribution

## Q1.4

Given the definition of the L1 loss function in:

$$L1(w, b) = \frac{1}{N} \sum_{i=1}^N |y_i - f(x_i; w, b)|$$

$$\text{where } f(x_i; w, b) = \sigma(w^T x_i + b) \text{ and } \sigma(t) = \begin{cases} 0 & \text{if } t \leq 0 \text{ or } t > 1 \\ t & \text{otherwise} \end{cases}$$

Let's use the properties of convex functions and operations according to the lecture slides.

1. **Convexity of Absolute Value:** - The absolute value function  $|z|$  is convex, but not differentiable at  $z = 0$ .

2. **Convexity of Piecewise Function:** - For  $t \leq 0$  and  $t > 1$ ,  $\sigma(t)$  is constant (0 and  $t$  respectively), and constant functions are convex. - For  $0 < t \leq 1$ ,  $\sigma(t) = t$ , which is also a linear function which is convex in piecewise manner. However, Overall function is not continuous. Therefore it is not a convex function

3. **Convexity of L1 Loss:** - The L1 loss is a sum of not convex functions which remains as not convex.

In conclusion, based on the provided definition, the L1 loss function is **not convex** in terms of the parameters of the classifier ( $w$  and  $b$ ). The non-convexity of the L1 loss is attributed to the non-convexity of the piecewise function  $\sigma(t)$ .

If  $\sigma(t)$  was convex, we could say that the loss function is convex because functions obtained from convex functions and convexity preserving operations are convex.

## Q1.5

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### Algorithm 1 Using K-Fold Cross-Validation for Best Parameter Selection

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1: Set best_accuracy to 0
2: Divide the dataset  $D$  into  $k$  folds
3: for each possible hyperparameter  $C$  do
4:   Set total_accuracy to 0
5:   for each fold in the dataset do
6:     Use the current fold as the validation set
7:     By combining the remaining  $k - 1$  folds create the training set
8:     Train the classifier with hyperparameter  $C$  using the training set
9:     Test the classifier on the validation set and calculate accuracy
    current_accuracy
10:    Update total_accuracy by adding current_accuracy
11:  end for
12:  Calculate average accuracy: average_accuracy =  $\frac{\text{total\_accuracy}}{k}$ 
13:  if average_accuracy is better than best_accuracy then
14:    Update best_accuracy and best_hyperparameter
15:  end if
16: end for
17: best_hyperparameter is the best hyperparameter for best performance

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## Q1.6

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**Algorithm 2** Using Cross-Validation for Future Performance Estimation

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- 1: Divide the dataset  $D$  into  $k$  folds
  - 2: Set `total_performance` to 0
  - 3: **for** each fold in the dataset **do**
  - 4:   Use the current fold as the validation set
  - 5:   By combining the remaining  $k - 1$  folds create the training set
  - 6:   Train the model  $M$  using the training set
  - 7:   Test performance of the model on the validation set
  - 8:   Calculate the accuracy of the model `current_performance`
  - 9:   Accumulate `total_performance` by adding the `current_performance`
  - 10: **end for**
  - 11: Calculate the average performance:  $\text{average\_performance} = \frac{\text{total\_performance}}{k}$
  - 12: Represent the estimated future performance of the model  $M$  with `average_performance`
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