

# Google Landmarks Dataset v2

## A Large-Scale Benchmark for Instance-Level Recognition and Retrieval

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### Abstract

While image retrieval and instance recognition techniques are progressing rapidly, there is a need for challenging datasets to accurately measure their performance – while posing novel challenges that are relevant for practical applications. We introduce the Google Landmarks Dataset v2 (GLDv2), a new benchmark for large-scale, fine-grained instance recognition and image retrieval in the domain of human-made and natural landmarks. GLDv2 is the largest such dataset to date by a large margin, including over 5M images and 200k distinct instance labels. Its test set consists of 118k images with ground truth annotations for both the retrieval and recognition tasks. The ground truth construction involved over 800 hours of human annotator work. Our new dataset has several challenging properties inspired by real-world applications that previous datasets did not consider: An extremely long-tailed class distribution, a large fraction of out-of-domain test photos and large intra-class variability. The dataset is sourced from Wikimedia Commons, the world’s largest crowdsourced collection of landmark photos. We provide baseline results for both recognition and retrieval tasks based on state-of-the-art methods as well as competitive results from a public challenge. We further demonstrate the suitability of the dataset for transfer learning by showing that image embeddings trained on it achieve competitive retrieval performance on independent datasets. The dataset images, ground-truth and metric scoring code are available at <https://github.com/cvdfoundation/google-landmark>.

### 1. Introduction

Image retrieval and instance recognition are fundamental research topics which have been studied for decades. The task of image retrieval [42, 29, 22, 44] is to rank images in an index set w.r.t. their relevance to a query image. The task of instance recognition [31, 16, 38] is to identify which specific instance of an object class (e.g. the instance “Mona Lisa” of the object class “painting”) is shown in a query image.

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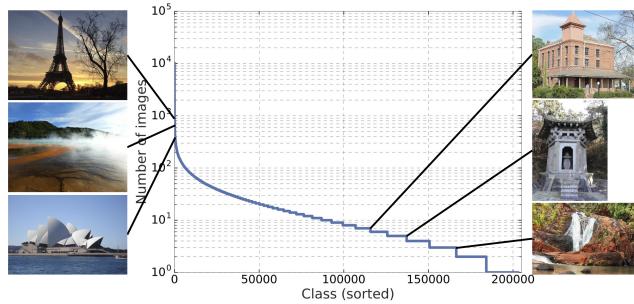


Figure 1: The Google Landmarks Dataset v2 contains a variety of natural and human-made landmarks from around the world. Since the class distribution is very long-tailed, the dataset contains a large number of lesser-known local landmarks.<sup>1</sup>

As techniques for both tasks have evolved, approaches have become more robust and scalable and are starting to “solve” early datasets. Moreover, while increasingly large-scale classification datasets like ImageNet [48], COCO [37] and OpenImages [35] have established themselves as standard benchmarks, image retrieval is still commonly evaluated on very small datasets. For example, the original Oxford5k [42] and Paris6k [43] datasets that were released in 2007 and 2008, respectively, have only 55 query images of 11 instances each, but are still widely used today. Because both datasets only contain images from a single city, results may not generalize to larger-scale settings.

Many existing datasets also do not present real-world challenges. For instance, a landmark recognition system that is applied in a generic visual search app will be queried with a large fraction of non-landmark queries, like animals, plants, or products, which it is not expected to yield any results for. Yet, most instance recognition datasets have only “on-topic” queries and do not measure the false-positive rate on out-of-domain queries. Therefore, larger, more challenging datasets are necessary to fairly benchmark these techniques while providing enough challenges to motivate further research.

A possible reason that small-scale datasets have been the

<sup>1</sup>Photo attributions, top to bottom, left to right: 1 by fyepo, CC-BY, 2 by C24winagain, CC-BY-SA, 3 by AwOjSoAk KaOsloWa, CC-BY-SA, 4 by Jud McCranie, CC-BY-SA; 5 by Shi.fachuang, CC-BY-SA; 6 by Nhi Dang, CC-BY.

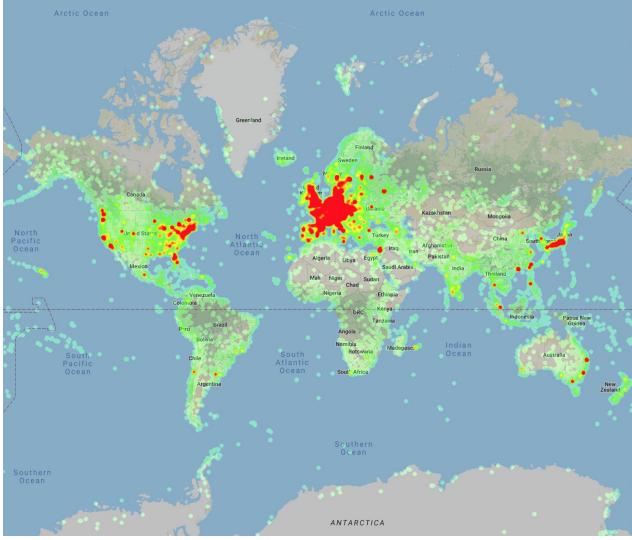


Figure 2: Heatmap of the places in the Google Landmarks Dataset v2.

dominant benchmarks for a long time is that it is hard to collect instance-level labels at scale. Annotating millions of images with hundreds of thousands of fine-grained instance labels is not easy to achieve when using labeling services like Amazon Mechanical Turk, since taggers need expert knowledge of a very fine-grained domain.

We introduce the Google Landmarks Dataset v2 (GLDv2), a new large-scale dataset for instance-level recognition and retrieval. GLDv2 includes over 5M images of over 200k human-made and natural landmarks that were contributed to Wikimedia Commons by local experts. Fig. 1 shows a selection of images from the dataset and Fig. 2 shows its geographical distribution. The dataset includes 4M labeled training images for the instance recognition task and 762k index images for the image retrieval task. The test set consists of 118k query images with ground truth labels for both tasks. To mimic a realistic setting, only 1% of the test images are within the target domain of landmarks, while 99% are out-of-domain images. While the Google Landmarks Dataset v2 focuses on the task of recognizing landmarks, approaches that solve the challenges it poses should readily transfer to other instance-level recognition tasks, like logo, product or artwork recognition.

The Google Landmarks Dataset v2 is designed to simulate real-world conditions and thus poses several hard challenges. It is *large scale* with millions of images of hundreds of thousands of classes. The distribution of these classes is very long-tailed (Fig. 1), making it necessary to deal with extreme *class imbalance*. The test set has a large fraction of *out-of-domain images*, emphasizing the need for low false-positive recognition rates. The *intra-class variability* is very high, since images of the same class can include indoor and outdoor views, as well as images of indirect relevance to a class, such as paintings in a museum. The goal of the Google Landmarks Dataset v2 is to become a new bench-

mark for instance-level recognition and retrieval. In addition, the recognition labels can be used for training image descriptors or pre-training approaches for related domains where less data is available. We show that the dataset is suitable for transfer learning by applying learned descriptors on independent datasets where they achieve competitive performance.

The dataset was used in two public challenges on Kaggle<sup>2</sup>, where researchers and hobbyists competed to develop models for instance recognition and image retrieval. We discuss the results of the challenges in Sec. 5.

The dataset images, instance labels for training, the ground truth for retrieval and recognition and the metric computation code are publicly available<sup>3</sup>.

## 2. Related Work

Image recognition problems range from basic categorization (“cat”, “shoe”, “building”), through fine-grained tasks involving distinction of species/models/styles (“Persian cat”, “running shoes”, “Roman Catholic church”), to instance-level recognition (“Oscar the cat”, “Adidas Duramo 9”, “Notre-Dame cathedral in Paris”). Our new dataset focuses on tasks that are at the end of this continuum: identifying individual human-made and natural landmarks. In the following, we review image recognition and retrieval datasets, focussing mainly on those which are most related to our work.

**Landmark recognition/retrieval datasets.** We compare existing datasets for landmark recognition and retrieval against our newly-proposed dataset in Tab. 1. The Oxford [42] and Paris [43] datasets contain tens of query images and thousands of index images from landmarks in Oxford and Paris, respectively. They have consistently been used in image retrieval for more than a decade, and were re-annotated recently, with the addition of 1M worldwide distractor index images [44]. Other datasets also focus on imagery from a single city: Rome 16k [1]; Geotagged Streetview Images [32] containing 17k images from Paris; San Francisco Landmarks [14] containing 1.7M images; 24/7 Tokyo [56] containing 1k images under different illumination conditions and Paris500k [61], containing 501k images.

More recent datasets contain images from a much larger variety of locations. The European Cities (EC) 50k dataset [5] contains images from 9 cities, with a total of 20 landmarks; unannotated images from other 5 cities are used as distractors. This dataset also has a version with 1M images from 22 cities where the annotated images come from a single city [4]. The Landmarks dataset by Li *et al.* [36] contains 205k images of 1k famous landmarks. Two other recent landmark datasets, by Gordo *et al.* [22] and Radenovic *et al.* [45], have become popular for training image retrieval models,

<sup>2</sup><https://www.kaggle.com/c/landmark-recognition-2019>,  
<https://www.kaggle.com/c/landmark-retrieval-2019>

<sup>3</sup><https://github.com/cvdfoundation/google-landmark>

Dataset name	Year	# Landmarks	# Test images	# Train images	# Index images	Annotation collection	Coverage	Stable
Oxford [42]	2007	11	55	-	5k	Manual	City	Y
Paris [43]	2008	11	55	-	6k	Manual	City	Y
Holidays [28]	2008	500	500	-	1.5k	Manual	Worldwide	Y
European Cities 50k [5]	2010	20	100	-	50k	Manual	Continent	Y
Geotagged StreetView [32]	2010	-	200	-	17k	StreetView	City	Y
Rome 16k [1]	2010	69	1k	-	15k	GeoTag + SfM	City	Y
San Francisco [14]	2011	-	80	-	1.7M	StreetView	City	Y
Landmarks-PointCloud [36]	2012	1k	10k	-	205k	Flickr label + SfM	Worldwide	Y
24/7 Tokyo [56]	2015	125	315	-	1k	Smartphone + Manual	City	Y
Paris500k [61]	2015	13k	3k	-	501k	Manual	City	N
Landmark URLs [7, 22]	2016	586	-	140k	-	Text query + Feature matching	Worldwide	N
Flickr-SfM [45]	2016	713	-	120k	-	Text query + SfM	Worldwide	Y
Google Landmarks [40]	2017	30k	118k	1.2M	1.1M	GPS + semi-automatic	Worldwide	N
Revisited Oxford [44]	2018	11	70	-	5k + 1M	Manual + semi-automatic	Worldwide	Y
Revisited Paris [44]	2018	11	70	-	6k + 1M	Manual + semi-automatic	Worldwide	Y
Google Landmarks Dataset v2	2019	<b>200k</b>	<b>118k</b>	<b>4.1M</b>	762k	Crowdsourced + semi-automatic	Worldwide	Y

Table 1: Comparison of our dataset against existing landmark recognition/retrieval datasets. “Stable” denotes if the dataset can be retained indefinitely. Our Google Landmarks Dataset v2 is larger than all existing datasets in terms of total number of images and landmarks, besides being stable.

containing hundreds of landmarks and approximately 100k images each; note that these do not contain test images, but only training data. The original Google Landmarks Dataset [40] contains 2.3M images from 30k landmarks, but due to copyright restrictions this dataset is not stable: it shrinks over time as images get deleted by the users who uploaded them. The Google Landmarks Dataset v2 dataset surpasses all existing datasets in terms of the number of images and landmarks, and uses images only with licenses that allow free reproduction and indefinite retention.

**Instance-level recognition datasets.** Instance-level recognition refers to a very fine-grained identification problem, where the goal is to visually recognize a single (or indistinguishable) occurrence of an entity. This problem is typically characterized by a large number of classes, with high imbalance, and small intra-class variation. Datasets for such problems have been introduced in the community, besides the landmark datasets mentioned previously. For example: logos [19, 30, 31, 47], cars [8, 63, 65], products [38, 21, 59, 51], artwork [2, 16], among others [11].

**Other image recognition datasets.** There are numerous computer vision datasets for other types of image recognition problems. Basic image categorization is addressed by datasets such as Caltech 101 [20], Caltech 256 [23], ImageNet [48] and more recently OpenImages [35]. Popular fine-grained recognition datasets include CUB-200-2011 [57], iNaturalist [26], Stanford Cars [33], Places [66].

### 3. Dataset Overview

#### 3.1. Goals

The Google Landmarks Dataset v2 aims to mimic the following challenges of industrial landmark recognition systems: *Large scale*: To cover the entire world, a corpus of millions of photos is necessary. *Intra-class variability*: Photo-

tos are taken under varying lighting conditions and from different views, including indoor and outdoor views of buildings. There will also be photos related to the landmark, but not showing the landmark itself, *e.g.* floor plans, portraits of architects, or views *from* the landmark. *Long-tailed class distribution*: There are much more photos of famous landmarks than of lesser-known ones. *Out-of-domain queries*: The query stream that these systems receive may come from various applications such as photo album apps or visual search apps and often contains only a small fraction of landmarks among many photos of other object categories. This poses a significant challenge for the robustness of the recognition algorithm. We designed our dataset to capture these challenges. An additional goal was to use only images whose licenses permit indefinite retention and reproduction in publications.

**Non-goals.** In contrast to many other datasets, we explicitly did not design GLDv2 to have clean query and index sets for the reasons mentioned above. Also, the dataset does not aim to measure generalization of embedding models to unseen data – therefore, the index and training sets do not have disjoint class sets. Finally, we do not aim to provide an image-level retrieval ground truth at this point due to very expensive annotation costs. Instead, the retrieval ground truth is on a class-level, *i.e.* all index images that belong to the same class as a query image will be marked as relevant in the ground truth.

#### 3.2. Scale and Splits

The Google Landmarks Dataset v2 consists of over 5M images and over 200k distinct instance labels, making it the largest instance recognition dataset to date. It is divided into three subsets: (i) 118k *query* images with ground truth annotations, (ii) 4.1M *training* images of 203k landmarks with labels that can be used for training, and (iii) 762k *index* images of 101k landmarks. We also make available a cleaner,

reduced training set of 1.2M images and 15k landmarks (see Sec. 5.1). While the index and training set do not share images, their label space is highly overlapping, with 92k common classes. The query set is randomly split into 1/3 validation and 2/3 testing data. The validation data was used for the “Public” leaderboard in the Kaggle competition, which allowed participants to submit solutions and view their scores in real-time. The test set was used for the “Private” leaderboard, which was used for the final ranking and was only revealed at the end of the competition.

### 3.3. Challenges

Besides its scale, the Google Landmarks Dataset v2 presents practically relevant challenges, as motivated above. **Class distribution.** The class distribution is extremely long-tailed, as illustrated in Fig. 1. 57% of classes have at most 10 images and 38% of classes have at most 5 images. The dataset therefore contains a wide variety of landmarks, from world-famous ones to lesser-known, local ones.

**Intra-class variation.** As is typical for an image dataset collected from the web, the Google Landmarks Dataset v2 has large intra-class variability, including views from different vantage points and of different details of the landmarks, as well as both indoor and outdoor views for buildings.

**Out-of-domain query images.** To simulate a realistic query stream, the query set consists of only 1.1% images of landmarks and 98.9% out-of-domain images, for which no result is expected. This puts a strong emphasis on the importance of robustness in a practical instance recognition system.

### 3.4. Metrics

The Google Landmarks Dataset v2 uses well-established metrics, which we now introduce. Reference implementations are available on the dataset website.

**Recognition** is evaluated using micro Average Precision ( $\mu\text{AP}$ ) [41] with one prediction per query. This is also known as Global Average Precision (GAP). It is calculated by sorting all predictions in descending order of their confidence and computing:

$$\mu\text{AP} = \frac{1}{M} \sum_{i=1}^N P(i)\text{rel}(i), \quad (1)$$

where  $N$  is the total number of predictions across all queries;  $M$  is the total number of queries with at least one landmark from the training set visible in it (note that most queries do not depict landmarks);  $P(i)$  is the precision at rank  $i$ ; and  $\text{rel}(i)$  is a binary indicator function denoting the correctness of prediction  $i$ . Note that this metric penalizes a system that predicts a landmark for an out-of-domain query image; overall, it measures both ranking performance as well as the ability to set a common threshold across different queries.

**Retrieval** is evaluated using mean Average Precision@100 (mAP@100), which is a variant of the standard mAP metric

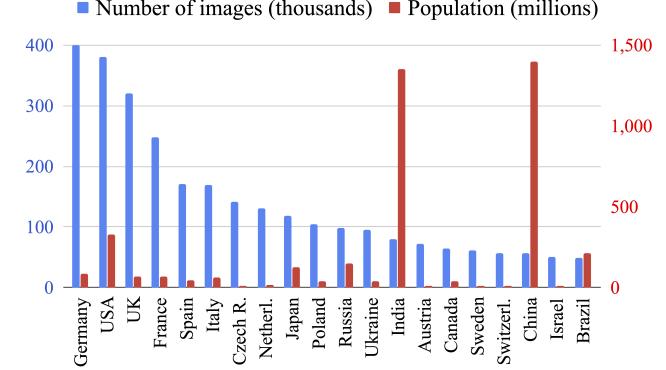


Figure 3: Histogram of the number of images from the top-20 countries (blue) compared to their populations (red).

that only considers the top-100 ranked images. We chose this limitation since exhaustive retrieval of every matching image is not necessary in most applications, like image search. The metric is computed as follows:

$$\text{mAP}@100 = \frac{1}{Q} \sum_{q=1}^Q \text{AP}@100(q), \quad (2)$$

where

$$\text{AP}@100(q) = \frac{1}{\min(m_q, 100)} \sum_{k=1}^{\min(n_q, 100)} P_q(k) \text{rel}_q(k) \quad (3)$$

where  $Q$  is the number of query images that depict landmarks from the index set;  $m_q$  is the number of index images containing a landmark in common with the query image  $q$  (note that this is only for queries which depict landmarks from the index set, so  $m_q \neq 0$ );  $n_q$  is the number of predictions made by the system for query  $q$ ;  $P_q(k)$  is the precision at rank  $k$  for the  $q$ -th query; and  $\text{rel}_q(k)$  is a binary indicator function denoting the relevance of prediction  $k$  for the  $q$ -th query. Some query images will have no associated index images to retrieve; these queries are ignored in scoring, meaning this metric does not penalize the system if it retrieves landmark images for out-of-domain queries.

### 3.5. Data Distribution

The Google Landmarks Dataset v2 is a truly world-spanning dataset, containing landmarks from 246 of the 249 countries in the ISO 3166-1 country code list. Fig. 3 shows the number of images in the top-20 countries and Fig. 4 shows the number of images by continent. We can see that even though the dataset is world-spanning, it is by no means a representative sample of the world, because the number of images per country depends heavily on the activity of the local Wikimedia Commons community.

Fig. 5 shows the distribution of the dataset images by landmark category, as obtained from the Google Knowledge Graph. By far the most frequent category is churches,

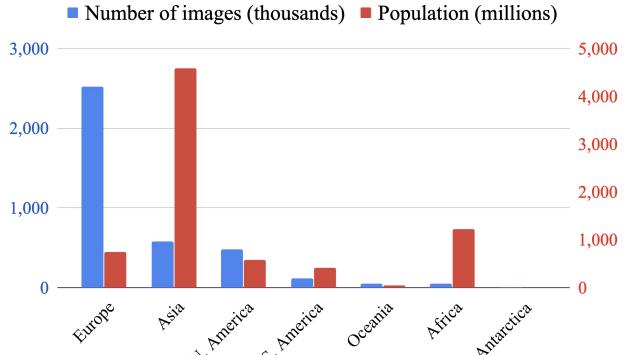


Figure 4: Histogram of the number of images per continent (blue) compared to their populations (red).

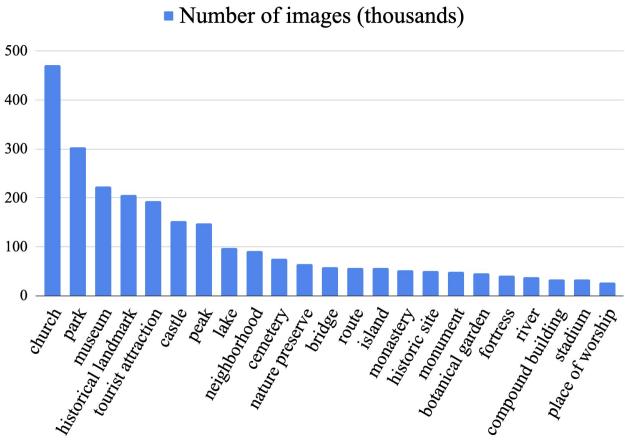


Figure 5: Histogram of the number of images by landmark category. This includes only categories with more than 25k images.

followed by parks and museums. Counting only those categories with over 25k images, roughly 28% are natural landmarks while 72% are human-made.

### 3.6. Image Licenses

All images in GLDv2 are freely licensed, so that the dataset is indefinitely retainable and does not shrink over time, allowing recognition and retrieval approaches to be compared over a long period of time. All images can be freely reproduced in publications, as long as proper attribution is provided. The image licenses are either Creative Commons<sup>4</sup> or Public Domain. We provide a list of attributions for those images that require it so dataset users can easily give attribution when using the images in print or on the web.

## 4. Dataset Construction

This section details the data collection process and the construction of the ground truth.

<sup>4</sup><https://creativecommons.org>

### 4.1. Data Collection

**Data sources.** The main data source of the Google Landmarks Dataset v2 is *Wikimedia Commons*<sup>5</sup>, the media repository behind Wikipedia. Wikimedia Commons hosts millions of photos of landmarks licensed under Creative Commons and Public Domain licenses, contributed by an active community of photographers as well as partner organizations such as libraries, archives and museums. Its large coverage of the world’s landmarks is partly thanks to *Wiki Loves Monuments*<sup>6</sup>, an annual world-wide contest with the goal to upload high-quality, freely licensed photos of landmarks to the site and to label them within a fine-grained taxonomy of the world’s cultural heritage sites. In addition to Wikimedia Commons, we collected realistic query images by crowdsourcing. Operators were sent out to take photos of selected landmarks around the world with smartphones.

**Training and index sets.** Fig. 6 shows the process we used to mine landmark images from Wikimedia Commons. Wikimedia Commons is organized into a hierarchy of categories that form its taxonomy. Each category has a unique URL where all its associated images are listed. We found that the Wikimedia Commons hierarchy does not have a suitable set of top-level categories that map to human-made and natural landmarks. Instead, we found the Google Knowledge Graph<sup>7</sup> to be useful to obtain an exhaustive list of the landmarks of the world. To obtain a list of Wikimedia Commons categories for landmarks, we queried the Google Knowledge Graph with terms like “landmarks”, “tourist attractions”, “points of interest”, *etc.* For each returned knowledge graph entity, we obtained its associated Wikipedia articles. We then followed the link to the Wikimedia Commons Category page in the Wikipedia article. Note that while Wikipedia may have articles about the same landmark in different languages, Wikimedia Commons only has one category per subject. We then downloaded all images contained in the Wikimedia Commons pages we obtained. To avoid ambiguities, we enforced the restriction that each mined image be associated to a single Wikimedia category or Knowledge Graph entity. We use the Wikimedia Commons category URLs as the canonical class labels. The training and index sets are collected in this manner.

**Query set.** The query set consists of “positive” query images of landmarks and “negative” query images not showing landmarks. For collecting the “positive” query set, we selected a subset of the landmarks we collected from Wikimedia Commons and asked crowdsourcing operators to take photos of them. For the “negative” query data collection, we used the same process as for the index and training data, but queried the Knowledge Graph only with terms that are

<sup>5</sup><https://commons.wikimedia.org>

<sup>6</sup><https://www.wikilovesmonuments.org>

<sup>7</sup><https://developers.google.com/knowledge-graph>

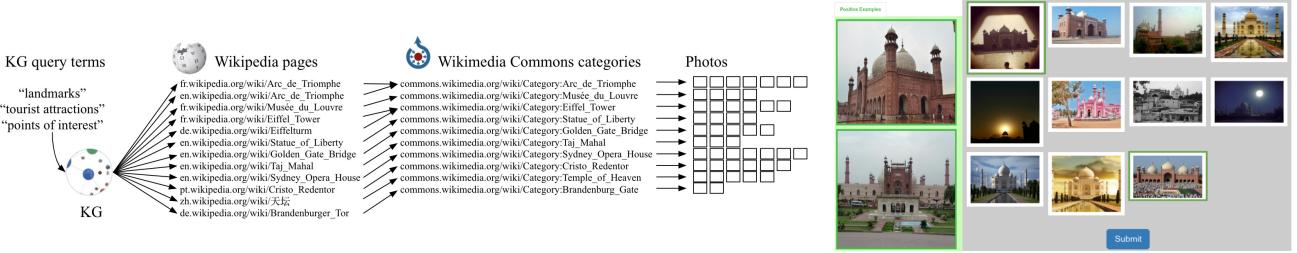


Figure 6: Left: pipeline for mining images from Wikimedia Commons. Right: the user interface of the re-annotation tool.

unrelated to landmarks. We also removed any negative query images that had near-duplicates in the index or training sets.

**Dataset partitioning.** The landmark images from Wikimedia Commons were split into training and index sets based on their licenses. We used CC0 and Public Domain photos for the index set while photos with “Creative Commons By” licenses that did not have a “No Derivatives” clause were used for the training set. As a result, the label spaces of index and training sets have a large, but not complete, overlap.

## 4.2. Test Set Re-Annotation

Visual inspection of retrieval and recognition results showed that many errors were due to missing ground truth annotations, which was due to the following reasons: (i) Crowdsourced labels from Wikimedia Commons can contain errors and omissions. (ii) Some query images contain multiple landmarks, but only one of them was present in the ground truth. (iii) There are sometimes multiple valid labels for an image on different hierarchical levels. For example, for a picture of a mountain in a park, both the mountain and the park would be appropriate labels. (iv) Some of the “negative” query images do actually depict landmarks.

We therefore amend the ground truth with human annotations. However, the large number of instance labels makes this a challenging problem: Each query image would need to be annotated with one out of 200k landmark classes, which is infeasible for human raters. We therefore used the model predictions of the top-ranked teams from the challenges to propose potential labels to the raters. To avoid bias in the new annotation towards any particular method, we used the top-10 submissions which represent a wide range of methods (see Sec. 5.4). A similar idea was used to construct the distractor set of the revisited Oxford and Paris datasets [44], where hard distractors were mined using a combination of different retrieval methods.

Fig. 6 shows the user interface of the re-annotation tool. On the left side, we show a sample of index/train images of a given landmark label. On the right, we show the query images that are proposed for this label and ask raters to click on the correct images. This way, we simplified the question of “which landmark is it?” as “is it this landmark?”, which is a simple “yes” or “no” question. Grouping the query images associated with the same landmark class together

further improved the re-annotation efficiency, since raters do not need to switch context between landmark classes. To make efficient use of rater time, we only selected the highest-confidence candidates from the top submissions, since those are more likely to be missing annotations rather than model errors. In total, we sent out  $\sim 10k$  recognition query images and  $\sim 90k$  retrieval query images for re-annotation. To ensure the re-annotation quality, we sent each image to 3 human raters and assigned the label based on majority voting. In total, we leveraged  $\sim 800$  rater hours on the re-annotation process. This re-annotation increased the number of recognition annotations by 72% and the number of retrieval annotations by 30%. If a “negative” query image was verified to contain a landmark, it was moved to the “positive” query set. We will continue to improve the ground truth and will make future versions available on the dataset website. For comparability, past versions will stay available and each ground truth will receive a version number that we ask dataset users to state when publishing results.

## 5. Experiments

We demonstrate usage of the dataset and present several baselines that can be used as reference results for future research, besides discussing results from the public challenge. All results presented in this section are w.r.t. version 2.1 of the dataset ground truth.

### 5.1. Training Set Pre-Processing

The Google Landmarks Dataset v2 training set presents a realistic crowdsourced setting with diverse types of images for each landmark: *e.g.*, for a specific museum there may be outdoor images showing the building facade, but also indoor images of paintings and sculptures that are on display. Such diversity within a class may pose challenges to the training process, so we consider the pre-processing steps proposed in [64] in order to make each class more visually coherent. Within each class, each image is queried against all others by global descriptor similarity, followed by geometric verification of the top-100 most similar images using local features. The global descriptor is a ResNet-101 [25] embedding and the local features are DELF [40], both trained on the first Google Landmarks Dataset version (GLDv1) [40]. If an image is successfully matched to at least 3 other images, each

Training set	# Images	# Labels
GLDv1-train [40]	1, 225, 029	14, 951
GLDv2-train	4, 132, 914	203, 094
GLDv2-train-clean	1, 580, 470	81, 313
GLDv2-train-no-tail	1, 223, 195	27, 756

Table 2: Number of images and labels for the different training datasets used in our experiments.

Technique	Training Dataset	Medium		Hard	
		$\mathcal{R}\text{Oxf}$	$\mathcal{R}\text{Par}$	$\mathcal{R}\text{Oxf}$	$\mathcal{R}\text{Par}$
ResNet101+ArcFace	Landmarks-full [22]	50.8	70.4	24.3	47.1
	Landmarks-clean [22]	54.2	70.7	28.3	46.0
	GLDv1-train [40]	68.9	83.4	45.3	67.2
	GLDv2-train-clean	74.2	<b>84.9</b>	51.6	<b>70.3</b>
	GLDv2-train-no-tail	73.5	84.4	50.7	69.1
DELF-ASMK*+SP [44]	-	67.8	76.9	43.1	55.4
DELF-R-ASMK* [54]	-	73.3	80.7	47.6	61.3
DELF-R-ASMK*+SP [54]	-	<b>76.0</b>	80.2	52.4	58.6
ResNet152+Triplet [45]	GLDv1-train [40]	68.7	79.7	44.2	60.3
ResNet101+AP [46]	-	66.3	80.2	42.5	60.8
DELG global-only [10]	-	69.7	81.6	45.1	63.4
DELG global+SP [10]	-	75.4	82.2	<b>53.7</b>	63.7
HesAff-rSIFT-ASMK*+SP [44]	-	60.6	61.4	36.7	35.0

Table 3: Retrieval results (% mAP) on  $\mathcal{R}\text{Oxf}$  and  $\mathcal{R}\text{Par}$  of baseline models (ResNet-101 + ArcFace loss) learned on different training sets, compared to other techniques. All global descriptors use GeM pooling [45].

with at least 30 inliers, it is selected; otherwise discarded.

We refer to the resulting dataset version as GLDv2-train-clean and make it available on the dataset website. Tab. 2 presents the number of selected images and labels: 1.6M training images (38%) and 81k labels (40%). Even if this version only contains less than half of the data from GLDv2-train, it is still much larger than the training set of any other landmark recognition dataset. We also experiment with another variant where classes with lower than 15 images are removed, referred to as GLDv2-train-no-tail; it has approximately the same number of images as GLDv1-train, but  $2 \times$  the number of classes.

## 5.2. Comparing Training Datasets

We assess the utility of our dataset’s training split for transfer learning, by using it to learn global descriptor models and evaluating them on independent landmark retrieval datasets: Revisited Oxford ( $\mathcal{R}\text{Oxf}$ ) and Revisited Paris ( $\mathcal{R}\text{Par}$ ) [44]. A ResNet-101 [25] model is used, with GeM [45] pooling, trained with ArcFace loss [18]. Results are presented in Tab. 3, where we compare against models trained on other datasets, as well as recent state-of-the-art results – including methods based on global descriptors [45, 46], local feature aggregation [44, 54] and unified global-local features [10]. Note that “SP” denotes methods using local feature-based spatial verification for re-ranking.

Model training on GLDv2-train-clean provides a substantial boost in performance, compared to training on GLDv1-train: mean average precision (mAP) improves by up to 5%. We also compare with models trained on the Landmarks-full

Technique	Training Dataset	Testing	Validation
ResNet101+ArcFace	Landmarks-full [22]	23.20	20.07
	Landmarks-clean [22]	22.23	20.48
	GLDv1-train [40]	33.25	33.21
	GLDv2-train-clean	27.34	26.40
DELF-KD-tree [40]	-	44.84	41.07
DELG global-only [10]	GLDv1-train [40]	32.37	32.02
DELG global+SP [10]	-	<b>56.35</b>	<b>55.01</b>

Table 4: Baseline results (%  $\mu\text{AP}$ ) for the GLDv2 recognition task.

Technique	Training Dataset	Testing	Validation
ResNet101+ArcFace	Landmarks-full [22]	13.27	10.75
	Landmarks-clean [22]	13.55	11.95
	GLDv1-train [40]	20.67	18.82
	GLDv2-train-clean	<b>24.15</b>	<b>22.20</b>
DELF-R-ASMK* [54]	-	18.21	16.32
DELF-R-ASMK*+SP [54]	GLDv1-train [40]	18.78	17.38
DELG global-only [10]	-	20.44	18.25
DELG global+SP [10]	-	22.30	20.43
ResNet101+AP [46]	-	18.71	16.30
ResNet101+Triplet [60]	GLDv1-train [40]	18.94	17.14
ResNet101+CosFace [58]	-	21.35	18.41

Table 5: Baseline results (% mAP@100) for the GLDv2 retrieval task. The bottom three results were reported in [64].

and Landmarks-clean datasets [22]: performance is significantly lower, which is likely due to their much smaller scale. Our simple global descriptor baseline even outperforms all methods on the  $\mathcal{R}\text{Par}$  dataset, and comes close to the state-of-the-art in  $\mathcal{R}\text{Oxf}$ . Results in the GLDv2-train-no-tail variant show high performance, although a little lower than GLDv2-train-clean in all cases.

## 5.3. Benchmarking

Tab. 4 and Tab. 5 show results of baseline methods for the recognition and retrieval tasks, respectively. The methods shown use deep local and global features extracted with models that were trained using different datasets and loss functions. All global descriptors use GeM [45] pooling. For recognition with global descriptors, all methods compose landmark predictions by aggregating the sums of cosine distances of the top-5 retrieved images; the landmark with the highest sum is used as the predicted label and its sum of cosine distances is used as the confidence score. For DELG with SP, we first find the global descriptor nearest neighbors; then spatially verify the top 100 images; sort images based on the number of inliers; and aggregate scores over the top-5 images to compose the final prediction, where the score of each image is given by  $\frac{\min(l, 70)}{70} + g$ , where  $l$  is the number of inliers and  $g$  the global descriptor cosine similarity. For DELF-KD-tree, we use the system proposed in [40] to obtain the top prediction for each query (if any).

In all cases, training on GLDv1 or GLDv2 improves performance substantially when compared to training on Landmarks-full/clean; for the retrieval task, GLDv2 train-

Team Name	Technique			Before re-annotation	
		Testing	Validation	Testing	Validation
smyaka [64]	GF ensemble → LF → category filter	69.39	65.85	35.54	30.96
JL [24]	GF ensemble → LF → non-landmark filter	66.53	61.86	37.61	32.10
GLRunner [15]	GF → non-landmark detector → GF+classifier	53.08	52.07	35.99	37.14

Table 6: Top 3 results on recognition challenge (%  $\mu$ AP). GF = global feature similarity search; LF = local feature matching re-ranking.

Team Name	Technique			Before re-annotation		Precision@100	
		Testing	Validation	Testing	Validation	After	Before
smyaka [64]	GF ensemble → DBA/QE → C	37.19	35.69	37.25	35.68	6.09	4.73
GLRunner [15]	GF ensemble → LF → DBA/QE → C	34.38	32.04	34.75	32.09	6.42	4.83
Layer 6 AI [12]	GF ensemble → LF → QE → EGT	32.10	29.92	32.18	29.64	5.13	3.97

Table 7: Top 3 results on retrieval challenge (% mAP@100). GF = global feature similarity search; LF = local feature matching re-ranking; DBA = database augmentation; QE = query expansion; C = re-ranking based on classifier predictions; EGT = Explore-Exploit Graph Traversal. The last two columns show the effect of the re-annotation on the retrieval precision on the testing set (% Precision@100).

ing performs better, while for the recognition task, GLDv1 performs better. In the recognition case, a system purely based on local feature matching with DELF-KD-tree outperforms global descriptors; the best performance is obtained when combining both local and global features, as done with DELG. In the retrieval task, our global descriptor approach trained on GLDv2 outperforms all others; in this case, we also report results from [64] comparing different loss functions; CosFace and ArcFace perform similarly, while Triplet and AP losses perform worse.

#### 5.4. Challenge Results

Tab. 6 and Tab. 7 present the top 3 results from the public challenges, for the recognition and retrieval tracks, respectively. These results are obtained with complex techniques involving ensembling of multiple global and/or local features, usage of trained detectors/classifiers to filter queries, and several query/database expansion techniques.

The most important building block in these systems is the global feature similarity search, which is the first stage in all successful approaches. These were learned with different backbones such as ResNet [25], ResNeXt [62], Squeeze-and-Excitation [27], FishNet [52] and Inception-V4 [53]; pooling methods such as SPoC [6], RMAC [55] or GeM [45]; loss functions such as ArcFace [18], CosFace [58], N-pairs [50] and triplet [49]. Database-side augmentation [3] is also often used to improve image representations.

The second most widely used type of method is local feature matching re-ranking, with DELF [40], SURF [9] or SIFT [39]. Other re-ranking techniques which are especially important for retrieval tasks, such as query expansion (QE) [17, 45] and graph traversal [13], were also employed.

These challenge results can be useful as references for future research. Even with such complex methods, there is still substantial room for improvement in both tasks, indicating that landmark recognition and retrieval are far from solved.

#### 5.5. Effect of Re-annotation

The goal of the re-annotation (Sec. 4.2) was to fill gaps in the ground truth where index images showing the same

landmark as a query were not marked as relevant, or where relevant class annotations were missing. To show the effect of this on the metrics, Tab. 6 and 7 also list the scores of the top methods from the challenge before re-annotation. There is a clear improvement in  $\mu$ AP for the recognition challenge, which is due to a large number of correctly recognized instances that were previously not counted as correct. However, a similar improvement cannot be observed for the retrieval results. This is because by the design of the dataset, the retrieval annotations are on the class level rather than the image level. Therefore, if a class is marked as relevant for a query, all of its images are, regardless of whether they have shared content with the query image. So, while the measured *precision* of retrieval increases, the measured *recall* decreases, overall resulting in an almost unchanged mAP score. This is illustrated in the last two columns of Tab. 7, which shows that Precision@100 consistently increases as an effect of the re-annotation.

## 6. Conclusion

We have presented the Google Landmarks Dataset v2, a new large-scale benchmark for image retrieval and instance recognition. It is the largest such dataset to date and presents several real-world challenges that were not present in previous datasets, such as extreme class imbalance and out-of-domain test images. We hope that the Google Landmarks Dataset v2 will help advance the state of the art and foster research that deals with these novel challenges for instance recognition and image retrieval.

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