There are a lot of papers to analyze users by their web cites visits while more than half of digital traffic online now comes from mobile devices and through mobile apps (based on comScore report).

The goal is to predict the demographic and life style profiles of users based on their previous locations and past behavior at a certain hour of a day.

In case if we have additional context (like any truth set, or application used, user's tweets, etc.) we could tune the model.

As a first step, let's imagine we have a data set that contains user id, timestamp and location (latitude/longitude pair).

- 1. Detect "frequent spots":
 - cluster data using KMeans algorithm (represent users trajectories as fixed-length vectors of coordinates and then compare such vectors by means of Euclidean distance) or (as another approach) using Hidden Markov models
 - detect multiple interleaved periods using Fourier Transform and autocorrelation

record	user	timestamp	latitude	longitude
r1	u1	2016-05-09 09:00:00	37.786137	-122.409143
r2	u1	2016-05-09 09:30:00	37.785737	-122.410922
r3	u1	2016-05-09 13:00:00	37.787011	-122.406039
r4	u2	2016-03-26 12:45:00	37.786200	-122.409600
r5	u3	2016-03-01 17:15:00	37.785934	-122.411144

2. Label the spots based on timestamps and external context available (like type of location from GooglePlacesAPI): "Office", "Home", "Shopping Mall" etc.

record	annotation			
r1	San Francisco, Starbucks, coffeehouse,			
	working hours			
r2	San Francisco, Hilton, hotel, working hours			
r3	San Francisco, Macy's, department store,			
	lunch time			
r4	San Francisco, road			
r5	San Francisco, FedEx			

3. Predict user profiles using decision trees with generative grammar component (associative rules, NLP are applicable).

High-level examples:

Frequent visits to "Victoria Secret" => Gender: female

Frequent visits to Chinese, Japanese restaurants => Food interest: Asian

Let's consider a finite set of users V_A (inspired by <u>a formal grammar</u>), a finite set of profiles V_T and describe a finite set of rules $A{\to}\phi$, where $A{\in}V_A$, $\phi{\in}V_T$.

Example:

Suppose we have users $(A_1, A_2, A_3, A_4, A_5)$ and the following rules:

Conditional rules	Decision rules
$A_1 \mid (s_1 = "+" \land s_2 = "-") \rightarrow \phi_{11}$	$A_1 \mid (\phi_1 = \phi_{11}) \Rightarrow (s_3 := "+")$
$A_1 \mid (s_1 = "+" \land s_2 = "+") \rightarrow \phi_{12}$	$A_1 \mid (\phi_1 = \phi_{12}) \Rightarrow (s_3 := "-")$
$A_2 \mid (s_3 = "+" \land s_4 = "+") \rightarrow \phi_{21}$	$A_2 \mid \phi_2 = \phi_{21}) \Rightarrow (s_5 = "+")$
$A_3 \mid (s_4 = "+") \rightarrow \phi_{31}$ $A_3 \mid (s_4 = "-") \rightarrow \phi_{32}$	$A_3 \mid (\phi_3 = \phi_{31}) \Rightarrow (s_2 := "-")$
$A_4 \mid (s_6 = "+") \rightarrow \phi_{41}$	$A_4 \mid (\phi_4 = \phi_{41}) \Rightarrow (s_1 := "-")$
$A_4 \mid (s_6 = "-") \rightarrow \phi_{42}$	$A_4 \mid (\phi_4 = \phi_{42}) \Rightarrow (s_1 := "+" \land s_4 := "+")$
$A_5 \mid (s_1 = "+") \rightarrow \phi_{51}$	$A_5 \mid (\phi_5 = \phi_{51}) \Rightarrow (s_6 := "-")$
$A_5 \mid (s_1 = "-") \rightarrow \phi_{52}$	$A_5 \mid (\phi_5 = \phi_{52}) \Rightarrow (s_6 := "+")$

Then the algorithm is as follows:

Setting					Profile A _i , Rule type	Hypothesis	
S ₁	s_2	s_3	S ₄	S ₅	S 6	1	
				-	-	-	
+	-			-	-	1, cond.	$H_1: s_1="+" \land s_2="-"$
+	1	+	-	-		1, cond.	
+	ı	+	+			2, cond.	H ₂ : s ₄ ="+"
+	1	+	+	+	-	2, cond.	
+	ı	+	+	+		3, cond.	
+	-	+	+	+		3, cond.	Confirmation for $s_2=$ "-" in H_1
+	-	+	+	+	+	4, cond.	H ₃ : s ₆ ="+"
-	-	+	+	+	+	4, cond.	Rejection for s ₁ ="+" in H ₁
+	ı	+	+	+	-	4, cond.	H ₃ : s ₆ ="-"
+	-	+	+	+	-	4, cond.	Confirmation for s_1 ="+" in H_1 and s_4 ="+" in H_2
+	-	+	+	+	-	5, cond.	_
+	-	+	+	+	-	5, cond.	Confirmation for $s_6=$ "-" in H_3

Therefore we obtain the following classification:

A ₁	A ₂	A ₃	A ₄	A ₅
Φ11	Φ21	Φ31	Φ42	Φ51

Improvements and known issues:

- GPS accuracy: The United States government currently <u>claims</u> 4 meter RMS (**7.8** meter **95%** Confidence Interval) horizontal accuracy for civilian (SPS) GPS. Vertical accuracy is worse. So in step 2, we need to use not latitude/longitude pair, but a circle with radius at least 8 meters (we choose 10 meters).
- For demographic profiles some open data sets can be used as the truth sets like:

 <u>http://proximityone.com/location_based_demographics.htm</u>
 <u>http://www.census.gov/topics/income-poverty/income.html</u>
- To smooth our probabilities in case of high deviations it worst to add some weights to every profile. As a first approach, for this step we need to estimate the overall population in the area using deep learning model.