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Performance Evaluation of Computer Systems

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Performance Modeling and Design of Computer Systems

3- PROBABILITY REVIEW

Probability Space

- (Ω, Σ, p)
- An event : $E \in \Sigma$ is any subset of the sample space, Ω
- $|\Sigma| = 2^{|\Omega|}$
- $p : \Sigma \rightarrow [0 \ 1]$

Probability Space

- $E1$ and $E2$ are mutually exclusive
 - $E1 \cap E2 = \emptyset$
- E_1, E_2, \dots, E_n are events such that
 - $\forall i, j \ E_i \cap E_j = \emptyset$
 - $\cup_{i=1}^n E_i = F$

\Rightarrow Events E_1, E_2, \dots, E_n **partition** set F .

Conditional Probability & Independent Events

- Conditional probability of event E given event F :
 - $P\{E|F\}$
 - $P\{E|F\} = \frac{P\{E \cap F\}}{P\{F\}}$
- Events E and F are independent if :
 - $P\{E \cap F\} = P\{E\} \times P\{F\}$
 - $P\{E|F\} = \frac{P\{E \cap F\}}{P\{F\}} = P\{E\}$
- Events E and F are conditionally independent given event G , where $P\{G\} > 0$, if :
 - $P\{E \cap F|G\} = P\{E|G\} \times P\{F|G\}$

Law of Total Probability

- Let F_1, \dots, F_n **partition** the state space Ω Then,

$$\begin{aligned} - P\{E\} &= \sum_{i=1}^n P\{E \cap F_i\} \\ &= \sum_{i=1}^n P\{E|F_i\} \times P\{F_i\} \end{aligned}$$

Bayes Law

- $P\{F|E\} = \frac{P\{E \cap F\}}{P\{E\}} = \frac{P\{E|F\}.P\{F\}}{P\{E\}}$
- **Extended Bayes Law**
 - Let F, F_2, \dots, F_n **partition** the state space Ω . Then,
 - $P\{F|E\} = \frac{P\{E \cap F\}}{P\{E\}} = \frac{P\{E|F\}.P\{F\}}{P\{E\}} = \frac{P\{E|F\}.P\{F\}}{\sum_{i=1}^n P\{E|F_i\} \times P\{F_i\}}$

Random Variable

- $X : \Omega \rightarrow R$
 - Real-valued function of the outcome of an experiment
 - All the theorems that we learned about events apply to random variables as well
 - e.g. Total probability

Probabilities and Densities : Discrete

- Probability mass function (**p.m.f.**)
 - $P_X(a) = P\{X = a\}$, where $\sum_x P_X(a) = 1$
- Cumulative distribution function
 - $F_X(a) = P\{X \leq a\} = \sum_{x \leq a} P_X(x)$
 - $\overline{F}_X(a) = P\{X > a\} = \sum_{x > a} P_X(x) = 1 - F_X(a)$
- Samples
 - Bernoulli (p)
 - Binomial (n, p)
 - Geometric (p)
 - Poisson (λ)

Probabilities and Densities : Continuous

- Probability density function (**p.d.f.**)
 - $P(a \leq X \leq b) = \int_a^b f_X(x)dx$, and where $\int_{-\infty}^{\infty} f_X(x)dx = 1$
 - $f_X(x) \neq P\{X = x\}$
 - $f_X(x)dx = P\{x \leq X \leq x + dx\}$
- Cumulative distribution function
 - $F_X(a) = P\{-\infty \leq X \leq a\} = \int_{-\infty}^a f_X(x)dx$
 - $\overline{F}_X(a) = P\{X > a\} = 1 - F_X(a)$
 - $f_X(x) = \frac{d}{dx} \int_{-\infty}^x f(t)dt = \frac{d}{dx} F_X(x)$
- Samples
 - Uniform (a, b)
 - Exp (λ)
 - Pareto (α)

Expectation and Variance

- Discrete random variable : X
 - $E[X] = \sum_x x \cdot p_X(x)$
 - $E[X^i] = \sum_x x^i \cdot p_X(x)$
- Continuous random variable : X
 - $E[X] = \int_{-\infty}^{\infty} x \cdot f_X(x) dx$
 - $E[X^i] = \int_{-\infty}^{\infty} x^i \cdot f_X(x) dx$

Expectation of a Function

- Discrete random variable : X
 - $E[g(X)] = \sum_x g(x) \cdot p_X(x)$
- Continuous random variable : X
 - $E[g(X)] = \int_{-\infty}^{\infty} g(x) \cdot f_X(x) dx$

Variance

- Expected squared difference of X from its mean
 - $Var(X) = E[(X - E[X])^2]$
 - $Var(X) = E[X^2] - (E(X))^2$

Table 3.2. *Discrete and continuous distributions*

Distribution	p.m.f. $p_X(x)$	Mean	Variance
Bernoulli(p)	$p_X(0) = 1 - p ; p_X(1) = p$	p	$p(1 - p)$
Binomial(n, p)	$p_X(x) = \binom{n}{x} p^x (1 - p)^{n-x},$ $x = 0, 1, \dots, n$	np	$np(1 - p)$
Geometric(p)	$p_X(x) = (1 - p)^{x-1} p, \quad x = 1, 2, \dots$	$\frac{1}{p}$	$\frac{1-p}{p^2}$
Poisson(λ)	$p_X(x) = e^{-\lambda} \cdot \frac{\lambda^x}{x!}, \quad x = 0, 1, 2, \dots$	λ	λ
Distribution	p.d.f. $f_X(x)$	Mean	Variance
Exp(λ)	$f_X(x) = \lambda e^{-\lambda x}$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$
Uniform(a, b)	$f_X(x) = \frac{1}{b-a}, \quad \text{if } a \leq x \leq b$	$\frac{b+a}{2}$	$\frac{(b-a)^2}{12}$
Pareto(α), $0 < \alpha < 2$	$f_X(x) = \alpha x^{-\alpha-1}, \quad \text{if } x > 1$	$\begin{cases} \infty & \text{if } \alpha \leq 1 \\ \frac{\alpha}{\alpha-1} & \text{if } \alpha > 1 \end{cases}$	∞
Normal(μ, σ^2)	$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2},$ $-\infty < x < \infty$	μ	σ^2

Joint Probabilities and Independence

- Discrete random variables X and Y
- Joint probability mass function
 - $p_{X,Y}(x, y) = P\{X = x \text{ \& } Y = y\}$
 - $p_X(x) = \sum_y p_{X,Y}(x, y)$
 - $p_Y(y) = \sum_x p_{X,Y}(x, y)$
- X and Y are independent
 - $X \perp Y$
 - $p_{X,Y}(x, y) = p_X(x) \cdot p_Y(y)$

Joint Probabilities and Independence

- Continuous random variables X and Y
- Joint probability density function
 - $\int_c^d \int_a^b f_{X,Y}(x, y) = \mathbf{P}\{a < X < b \text{ \& } c < Y < d\}$
 - $f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dy$
 - $f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dx$
- X and Y are independent
 - $X \perp Y$
 - $f_{X,Y}(x, y) = f_x(x) \cdot f_y(y), \forall x, y$

Theorem 3.20

Theorem 3.20 If $X \perp Y$, then $\mathbf{E}[XY] = \mathbf{E}[X] \cdot \mathbf{E}[Y]$.

Proof

$$\begin{aligned}\mathbf{E}[XY] &= \sum_x \sum_y xy \cdot \mathbf{P}\{X = x, Y = y\} \\ &= \sum_x \sum_y xy \cdot \mathbf{P}\{X = x\} \mathbf{P}\{Y = y\} \quad (\text{by definition of } \perp) \\ &= \sum_x x \mathbf{P}\{X = x\} \cdot \sum_y y \mathbf{P}\{Y = y\} \\ &= \mathbf{E}[X] \mathbf{E}[Y]\end{aligned}$$

The same argument works for continuous r.v.'s. ■

- We also have,
- $E[g(X)f(Y)] = E[g(X)] \times E[f(Y)]$

Question?

- $E[XY] = E[X]E[Y] \stackrel{?}{\Rightarrow} X \perp Y$
- No, see Exercise 3.10

Conditional Probabilities : Discrete

- Conditional *p.m.f.* of X given event A
 - $p_{X|A}(x) = P\{X = x \mid A\} = \frac{P\{(X=x) \cap A\}}{P\{A\}}$
- Conditional expectation of X given event A
 - $E(X|A) = \sum_x x \cdot p_{X|A}(x) = \sum_x x \cdot \frac{P\{(X=x) \cap A\}}{P\{A\}}$

Conditional Probabilities : Continuous

- Conditional **p. d. f.** of X given event A

$$- f_{X|A}(x) = \begin{cases} \frac{f_X(x)}{P\{X \in A\}}, & \text{if } x \in A \\ 0, & \text{otherwise} \end{cases}$$

- Conditional expectation of X given event A

$$\begin{aligned} - E(X|A) &= \int_{-\infty}^{\infty} x f_{X|A}(x) dx \\ &= \int_A x f_{X|A}(x) dx = \frac{1}{P\{X \in A\}} \int_A x f_X(x) dx \end{aligned}$$

Probabilities and Expectations via Conditioning

- Let F, F_2, \dots, F_n **partition** the state space Ω
 - $P\{E\} = \sum_{i=1}^n P\{E|F_i\}P\{F_i\}$
- Law of Total Probability for Discrete Random Variables
 - $P\{X = k\} = \sum_y P\{X = k | Y = y\} \cdot P\{Y = y\}$

Theorem 3.25 For discrete random variables,

$$E[X] = \sum_y E[X | Y = y] P\{Y = y\}.$$

Similarly for continuous random variables,

$$E[X] = \int E[X | Y = y] f_Y(y) dy.$$


$$- E[g(X)] = \sum_y E[g(X)|Y = y] \cdot P\{Y = y\}$$

Linearity of Expectation

Theorem 3.26 (Linearity of Expectation) For random variables X and Y ,

$$\mathbf{E}[X + Y] = \mathbf{E}[X] + \mathbf{E}[Y].$$

Proof Here is a proof in the case where X and Y are continuous. The discrete case is similar: Just replace $f_{X,Y}(x, y)$ with $p_{X,Y}(x, y)$.

$$\begin{aligned}\mathbf{E}[X + Y] &= \int_{y=-\infty}^{\infty} \int_{x=-\infty}^{\infty} (x + y) f_{X,Y}(x, y) dx dy \\&= \int_{y=-\infty}^{\infty} \int_{x=-\infty}^{\infty} x f_{X,Y}(x, y) dx dy + \int_{y=-\infty}^{\infty} \int_{x=-\infty}^{\infty} y f_{X,Y}(x, y) dx dy \\&= \int_{x=-\infty}^{\infty} \int_{y=-\infty}^{\infty} x f_{X,Y}(x, y) dy dx + \int_{y=-\infty}^{\infty} \int_{x=-\infty}^{\infty} y f_{X,Y}(x, y) dx dy \\&= \int_{x=-\infty}^{\infty} x \int_{y=-\infty}^{\infty} f_{X,Y}(x, y) dy dx + \int_{y=-\infty}^{\infty} y \int_{x=-\infty}^{\infty} f_{X,Y}(x, y) dx dy \\&= \int_{x=-\infty}^{\infty} x f_X(x) dx + \int_{y=-\infty}^{\infty} y f_Y(y) dy \\&= \mathbf{E}[X] + \mathbf{E}[Y]\end{aligned}$$


Linearity of Expectation

Theorem 3.27 *Let X and Y be random variables where $X \perp Y$. Then*

$$\mathbf{Var}(X + Y) = \mathbf{Var}(X) + \mathbf{Var}(Y).$$

Proof

$$\begin{aligned}\mathbf{Var}(X + Y) &= \mathbf{E} \left[(X + Y)^2 \right] - (\mathbf{E} [(X + Y)])^2 \\ &= \mathbf{E} [X^2] + \mathbf{E} [Y^2] + 2\mathbf{E} [XY] \\ &\quad - (\mathbf{E} [X])^2 - (\mathbf{E} [Y])^2 - 2\mathbf{E} [X] \mathbf{E} [Y] \\ &= \mathbf{Var}(X) + \mathbf{Var}(Y) \\ &\quad + \underbrace{2\mathbf{E} [XY] - 2\mathbf{E} [X] \mathbf{E} [Y]}_{\text{equals 0 if } X \perp Y}\end{aligned}$$

Normal Distribution

Definition 3.28 A continuous r.v. X is said to be *Normal* (μ, σ^2) or *Gaussian* (μ, σ^2) if it has p.d.f. $f_X(x)$ of the form

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}, \quad -\infty < x < \infty$$

where $\sigma > 0$. The parameter μ is called the *mean*, and the parameter σ is called the *standard deviation*.

Definition 3.29 A Normal $(0, 1)$ r.v. Y is said to be a *standard Normal*. Its c.d.f. is denoted by

$$\Phi(y) = F_Y(y) = \mathbf{P}\{Y \leq y\} = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^y e^{-t^2/2} dt.$$

Theorem 3.30 Let $X \sim \text{Normal}(\mu, \sigma^2)$, then $\mathbf{E}[X] = \mu$ and $\mathbf{Var}(X) = \sigma^2$.

Linear Transformation Property

Theorem 3.31 (Linear Transformation Property) *Let $X \sim \text{Normal}(\mu, \sigma^2)$. Let $Y = aX + b$, where $a > 0$ and b are scalars. Then $Y \sim \text{Normal}(a\mu + b, a^2\sigma^2)$.*

- Thus,
- $X \sim \text{Normal}(\mu, \sigma^2) \Leftrightarrow Y = \frac{X - \mu}{\sigma} \sim \text{Normal}(0, 1)$
- $P\{X < K\} = P\left\{\frac{X - \mu}{\sigma} < \frac{K - \mu}{\sigma}\right\} = P\left\{Y < \frac{K - \mu}{\sigma}\right\} = \Phi\left(\frac{K - \mu}{\sigma}\right)$

Linear Transformation Property

Theorem 3.32 *If $X \sim \text{Normal}(\mu, \sigma^2)$, then the probability that X deviates from its mean by less than k standard deviations is the same as the probability that the standard Normal deviates from its mean by less than k .*

Proof Let $Y \sim \text{Normal}(0, 1)$. Then,

$$\mathbf{P}\{-k\sigma < X - \mu < k\sigma\} = \mathbf{P}\left\{-k < \frac{X - \mu}{\sigma} < k\right\} = \mathbf{P}\{-k < Y < k\} \quad \blacksquare$$

Theorem 3.32 illustrates why it is often easier to think in terms of standard deviations than in absolute values.

Central Limit Theorem

Theorem 3.33 (Central Limit Theorem (CLT)) Let X_1, X_2, \dots, X_n be a sequence of i.i.d. r.v.'s with common mean μ and variance σ^2 , and define

$$Z_n = \frac{X_1 + \dots + X_n - n\mu}{\sigma\sqrt{n}}.$$

Then the c.d.f. of Z_n converges to the standard normal c.d.f.; that is,

$$\lim_{n \rightarrow \infty} \mathbf{P}\{Z_n \leq z\} = \Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z e^{-x^2/2} dx$$

for every z .

- **Binomial**(n, p) distribution, which is a sum of **i. i. d.** **Bernoulli**(p) r.v.'s, converges to a Normal distribution when n is high.
- **Poisson**(λ) distribution is also well approximated by a **Normal** distribution with mean λ and variance λ .

Sum of a Random Number of Random Variables

- Number of these variables is itself a random variable
- N : non-negative integer-valued random variable
- $S = \sum_{i=1}^N X_i, N \perp X_i$
- $E[S], E[S^2], \dots?$
 - Linearity equations only apply when N is a constant
 - ?

$$E[S]$$

- Condition on the value of N , and then apply linearity of expectation

$$\begin{aligned} \mathbf{E}[S] &= \mathbf{E}\left[\sum_{i=1}^N X_i\right] = \sum_n \mathbf{E}\left[\sum_{i=1}^N X_i \middle| N = n\right] \cdot \mathbf{P}\{N = n\} \\ &= \sum_n \mathbf{E}\left[\sum_{i=1}^n X_i\right] \cdot \mathbf{P}\{N = n\} \\ &= \sum_n n \mathbf{E}[X] \cdot \mathbf{P}\{N = n\} \\ &= \mathbf{E}[X] \cdot \mathbf{E}[N] \end{aligned}$$

$$E[S^2]$$

- ?

Theorem 3.34 *Let X_1, X_2, X_3, \dots be i.i.d. random variables. Let*

$$S = \sum_{i=1}^N X_i, \quad N \perp X_i.$$

Then

$$\begin{aligned}\mathbf{E}[S] &= \mathbf{E}[N] \mathbf{E}[X], \\ \mathbf{E}[S^2] &= \mathbf{E}[N] \mathbf{Var}(X) + \mathbf{E}[N^2] (\mathbf{E}[X])^2, \\ \mathbf{Var}(S) &= \mathbf{E}[N] \mathbf{Var}(X) + \mathbf{Var}(N) (\mathbf{E}[X])^2.\end{aligned}$$