

Iqraq's Note

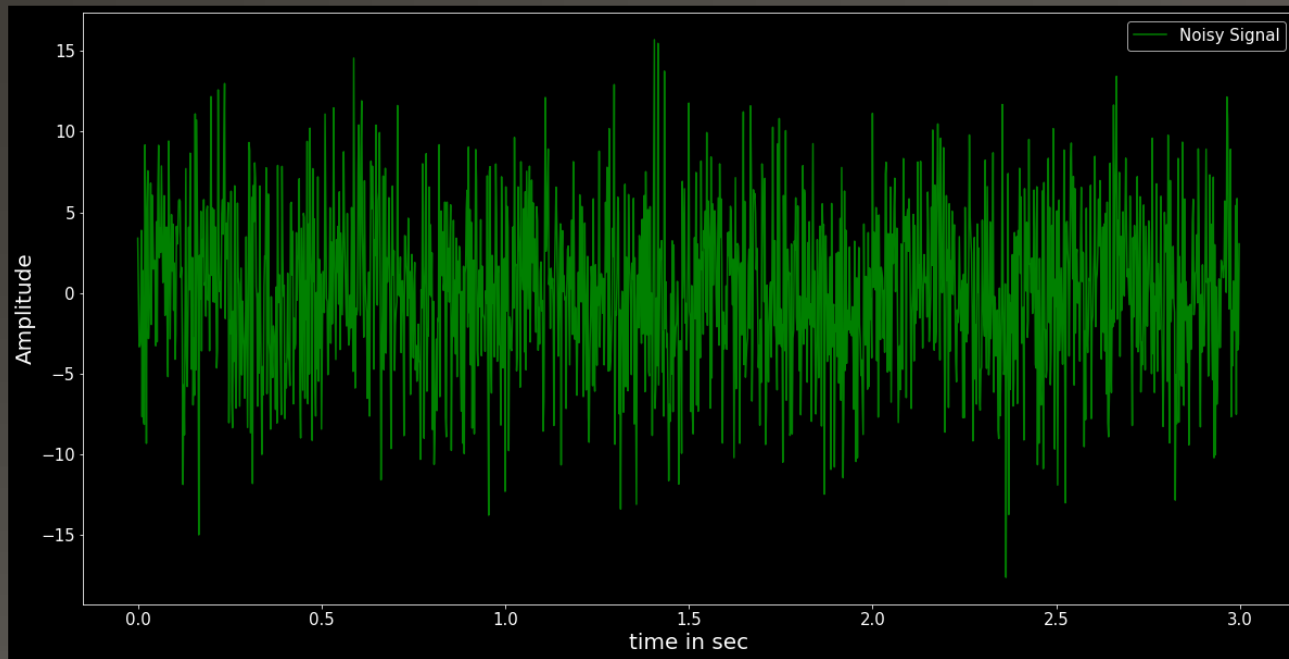
# Signal Denoising

# Moving average filter

- $y(n) = \frac{1}{M} \sum_{i=0}^{M-1} x(n + i)$
- Where M is number of interval(average)
- $X(n)$  = discrete signal value at that particular point
- Assuming you are trying to find the average value at 10<sup>th</sup> point/interval of a signal with the average of 4 interval (M = 5), you could either
- 1.  $y[10] = \frac{y[10] + y[11] + y[12] + y[13] + y[14]}{5}$  or
- 2.  $y[10] = \frac{y[8] + y[9] + y[10] + y[11] + y[12]}{5}$

# Example

- Let say you have a 3(s) signal with 256 hz sampling rate of generated noise



Remember that

$$T = 1/f_s$$

So if sampling rate is 256 hz

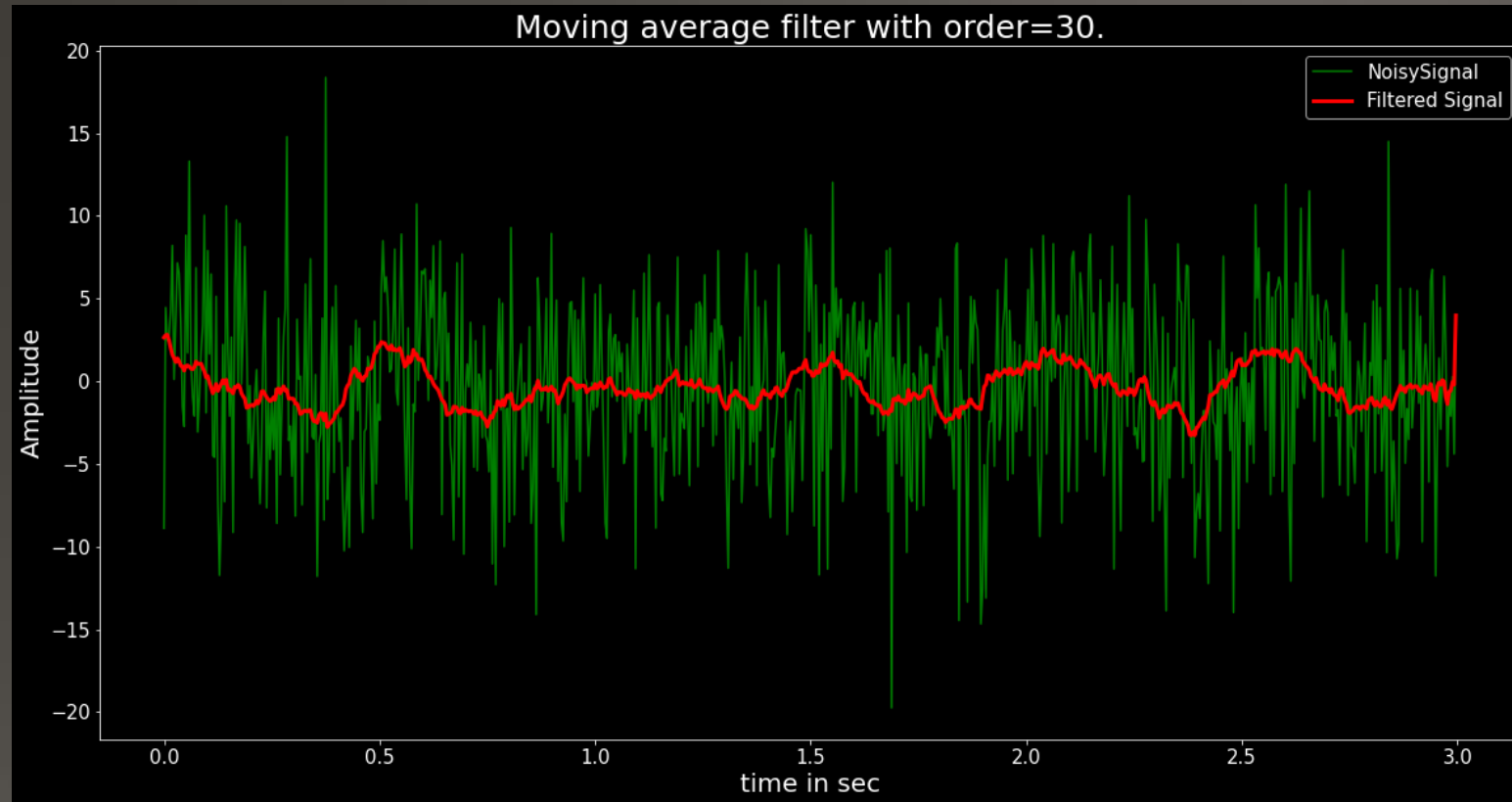
$$T = 1/256 = 0.004$$

$$3 \text{ seconds} / 0.004 = 750 \text{ intervals/points}$$

And we can use this formula to find the average  
At every points

$$y(n) = \frac{1}{M} \sum_{i=0}^{M-1} x(n + i)$$

If we set the  $M = 30$ , this will be our graph



\*the higher the  $M$  – the smoother and less accurate the graph will be

# Median Filter

- Assuming you have following data sequence

1,2,3,4,5,6,7 – the median of this sequence = 4'

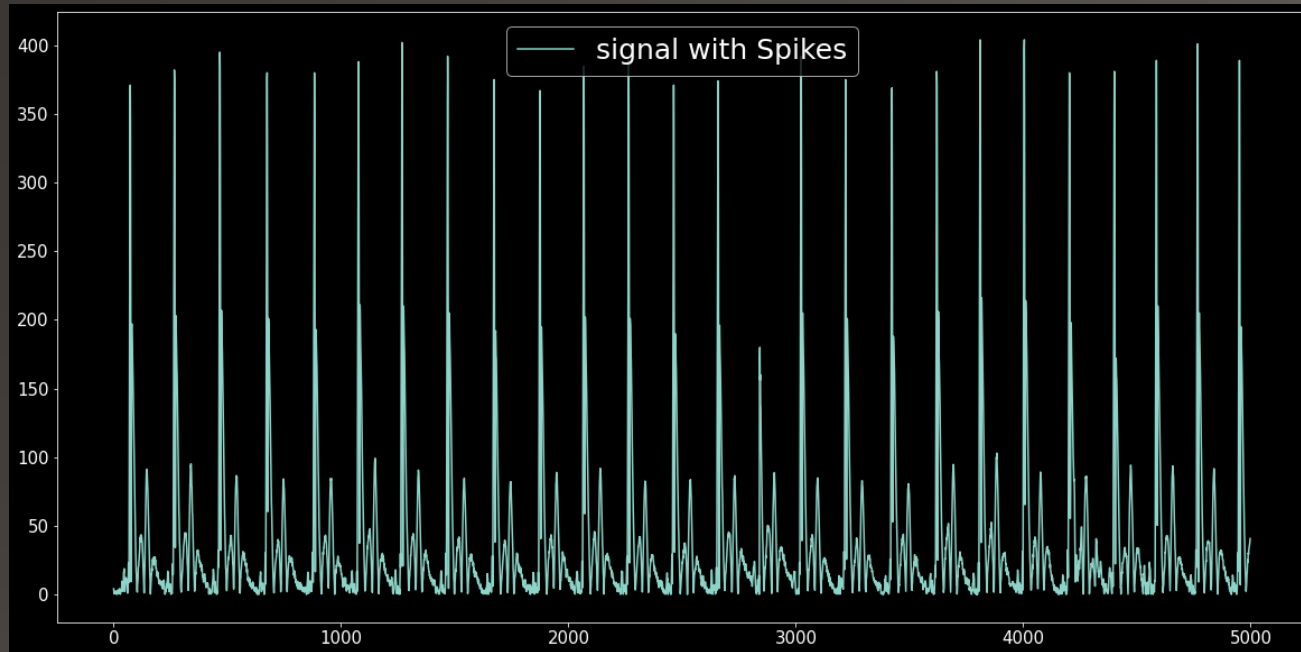
If the data sequence is even

1,2,3,4,5,6,7,8- the median would be  $\frac{4+5}{2} = 4.5$

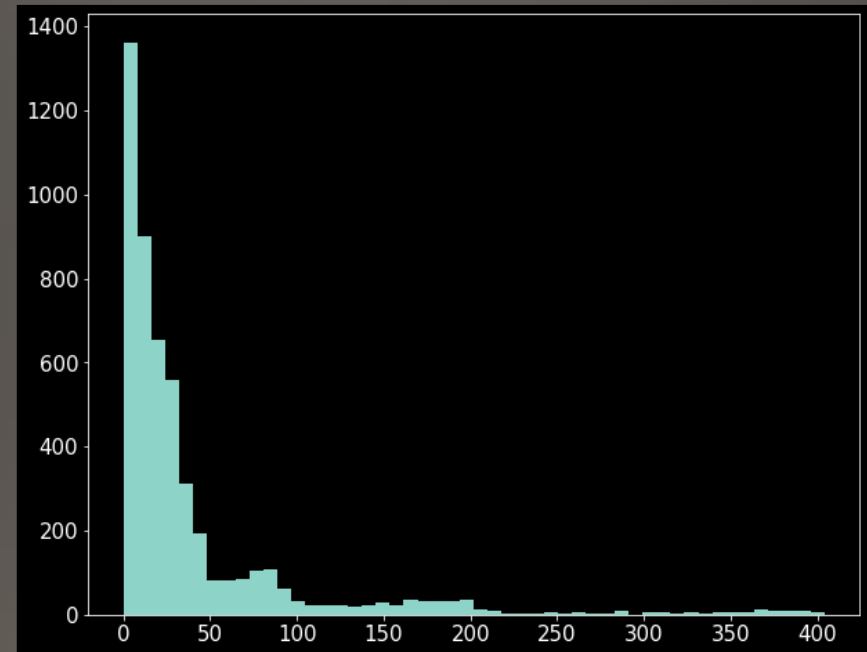
If it is unsorted – you 'll need to sort it first before figuring out the median

Same concept as average filter, but instead of averaging M amount of data points, you are finding the median of M amount of data point

# Example – removing noisy spikes filter

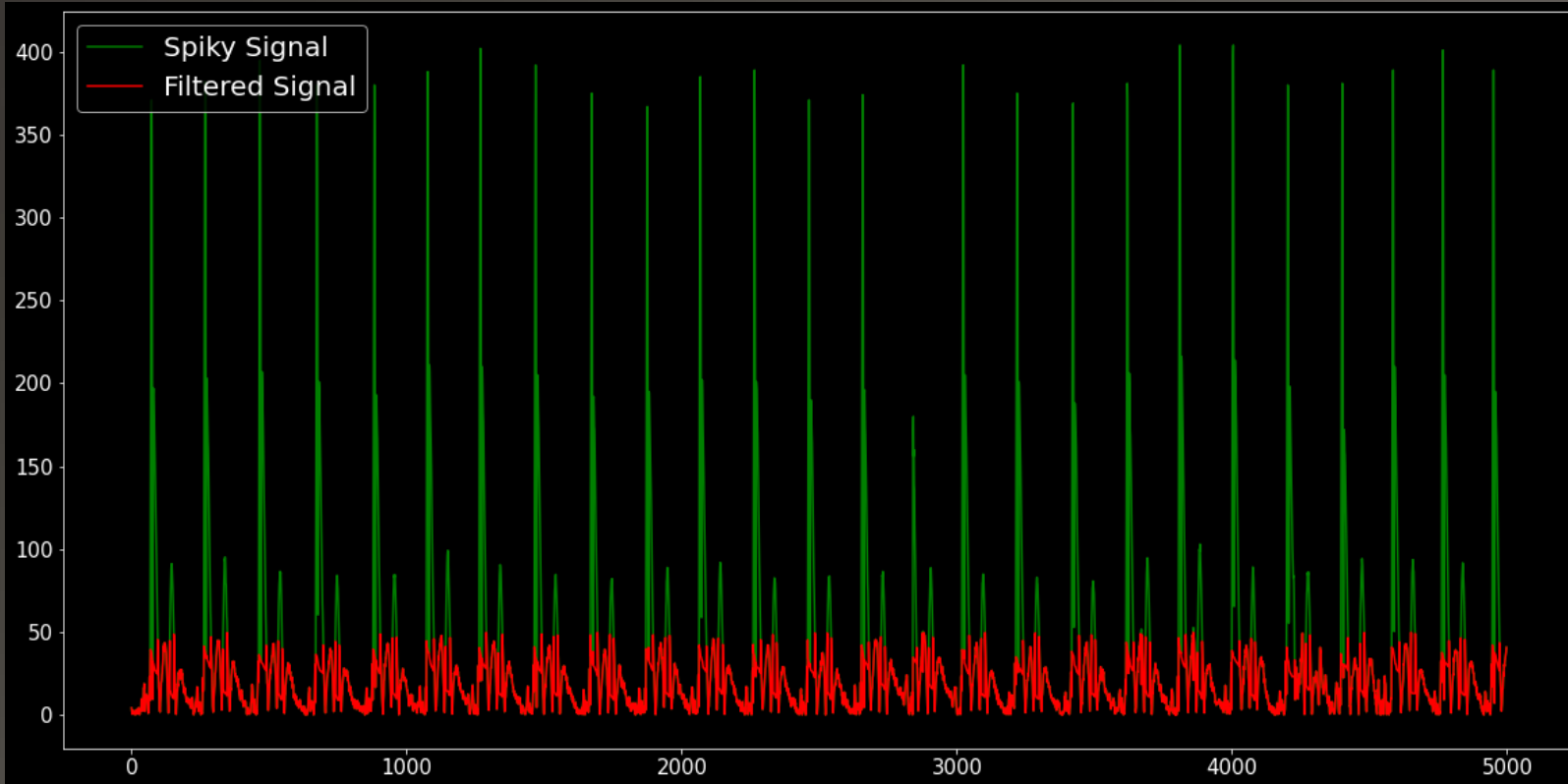


Spikes signal



Signal representation within M

# Final product



Good with repetitive noise where else  
If mean filter is applied, the final product  
Will be less accurate