Assignment #3

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C. MORPH VIDEO

1. Determine Image Correspondences

To obtain corresponding points, dlib (http://dlib.net/) was used. For each image, dlib detects 68 facial feature points in order (as Figure 1 shows). I added the corners of the image and half way points between those corners as corresponding points as well.

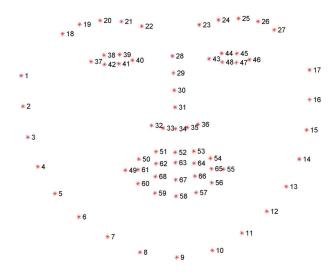


Figure 1: Visualizing the 68 facial landmark coordinates.

2. Compute a Triangulation

Delauney Triangulation was applied to the corresponding points acquired from the previous step. The result of Delaunay triangulation is a list of triangles represented by the indices of points in the 76 points array.

3. Locally Warp and Align Images

We first find the locations of all 76 points (x_m, y_m) in the morphed image based on the source (x_i, y_i) and target (x_j, y_j) images, using Equation 1.

$$x_m = (1 - \alpha)x_i + \alpha x_j$$

$$y_m = (1 - \alpha)y_i + \alpha y_j$$
(1)

Then we can find the corresponding triangle in the morphed image for each triangle in source image and calculate the affine transform that maps the three corners of the triangle in source image to the three corners of the corresponding triangle in the morphed image. Finally, repeat the process for target image and the morphed image.

$$\begin{bmatrix} t_1 & t_2 & t_3 \\ t_4 & t_5 & t_6 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \\ 1 & 1 & 1 \end{bmatrix}$$
(2)

or

$$TA = X (3)$$

SO

$$\mathbf{T} = \mathbf{X}\mathbf{A}^{-1} \tag{4}$$

where T is the affine transformation matrix we want.

For each triangle in source image, use the affine transform calculated in the previous step to transform all pixels inside the triangle to the morphed image. Similarly, obtain a warped version for target image.

4. Color Interpolating

Blend the warped version of source and target images, we obtained in the previous step, using Equation 5, we get our final morphed image.

$$M(x_m, y_m) = (1 - \alpha)I(x_i, y_i) + \alpha J(x_j, y_j)$$

$$\tag{5}$$

In this task we produced 58 intermediate representations for each source and target image pair by setting α to $\{1, 2, ..., 57, 58\}/59$.

5. Save the Image Sequence as a Video

The program was run on all the images provided under the alphabetical order of the filenames. The whole image sequence is then saved as a video file by calling OpenCV.

The output video can be viewed here https://d.iyuyue.net/share/users/yue/out.mp4 or https://www.youtube.com/watch?v=P5Dvpz-RBVg.

```
1 import sys, cv2, dlib, os, math, scipy.ndimage
2 import numpy as np
3 from scipy.spatial import Delaunay
4 import matplotlib.pyplot as plt
5 from PIL import Image
7 def shape to np(shape, dtype="int"):
8
9
       # initialize the list of (x, y)-coordinates
       coords = np.zeros((68, 2), dtype=dtype)
10
11
       # loop over the 68 facial landmarks and convert them
12
       # to a 2-tuple of (x, y)-coordinates
13
       for i in range (0, 68):
14
15
           coords[i] = (shape.part(i).x, shape.part(i).y)
16
       # return the list of (x, y)-coordinates
17
       return coords
18
19
   def triangulation(landmarks):
20
21
22
       tri = Delaunay(landmarks)
       # The result is a list of triangles represented by the
23
          indices of landmark points
24
       return tri
25
   def plot(path, landmarks):
26
27
       # Apply Delaunay Triangulation
28
       tri = triangulation(landmarks)
29
30
31
       if tri is not None:
           # if len(landmarks) == 0:
32
                 print("No face found in", path)
33
34
           # else:
35
                  landmarks = stasm.force_points_into_image(
              landmarks, img)
                  for point in landmarks:
36
                      img[int(round(point[1]))][int(round(point[0])
37
              ) ] = 0
38
39
           # cv2.imshow("stasm minimal", img)
40
           # cv2.waitKey(0)
41
```

```
# Read original image in RGB
42
           img = cv2.imread(path, cv2.IMREAD COLOR)
43
44
           img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
           # add image to the plot
45
           plt.imshow(img)
46
           # add triangles to the plot
47
           plt.triplot(landmarks[:,0], landmarks[:,1], tri.
48
              simplices.copy(), 'w-')
           # add landmarks to the plot
49
           plt.plot(landmarks[:,0], landmarks[:,1], 'm.')
50
51
           # show the plot and close it
           plt.show()
52
           # plt.savefig(os.path.splitext(path)[0]+' tri'+os.path.
53
              splitext(path)[1])
           plt.close()
54
       else:
55
           print("Delaunay Triangulation failed on", path)
56
57
   def landmarkPredictor(path, detector, predictor):
58
59
       # Read original image in grayscale
60
       img = cv2.imread(path, cv2.IMREAD_GRAYSCALE)
61
62
63
       if img is None:
           print("Cannot load", path)
64
           raise SystemExit
65
66
       ## Use stasm to predict landmark
67
       # landmarks = stasm.search_single(img)
68
69
70
       ## Use dlib to predict landmark
       # detect faces in the grayscale image
71
72
       rects = detector(img, 1)
73
74
       if not rects:
75
           return None
76
       # Only predict the landmarks for the first face
       landmarks = predictor(img, rects[0])
77
       landmarks = shape to np(landmarks)
78
79
       return landmarks
80
81
   def image2landmarks(imageDir):
82
83
84
       # directory of images
```

```
directory = os.fsencode(imageDir)
85
86
87
        # dlib initializing
        detector = dlib.get frontal face detector()
88
        predictor = dlib.shape predictor()
89
           shape predictor 68 face landmarks.dat')
90
        # Go through everything in the directory
91
        for file in os.listdir(directory):
92
93
94
            filename = os.fsdecode(file)
95
            if filename.endswith(".jpg") or filename.endswith(".png
96
               "):
97
                # path to the image file
98
                path = imageDir+filename
99
                # get landmarks from predictor
100
                landmarks = landmarkPredictor(path, detector,
101
                   predictor)
102
                if landmarks is not None:
103
                     f = open(path, 'rb')
104
105
                     width, height = Image.open(f).size
                     width = width - 1
106
                     height = height - 1
107
108
                     # Add the corners of the image and half way
109
                       points between those corners as
                        corresponding points as well
                     landmarks = np.append(landmarks, [[0, 0], [0,
110
                       math.floor(width/2)], [0, width], [math.
                       floor(height/2), 0], [math.floor(height/2),
                       width], [height, 0], [height, math.floor(
                       width/2)], [height, width]], axis=0)
111
                     # save the landmarks to seperated txt files
112
113
                     np.savetxt(os.path.splitext(path)[0]+'.txt',
                       landmarks, fmt='%d')
114
                else:
                     print("Landmark Prediction failed on", path)
115
                continue
116
            else:
117
118
                continue
119
```

```
120 # Visualize the result of Triangulation
121 def plotTriangulation(imageDir):
122
123
        directory = os.fsencode(imageDir)
124
125
        for file in os.listdir(directory):
126
127
            filename = os.fsdecode(file)
128
            if filename.endswith(".jpg") or filename.endswith(".png
129
130
131
                # path to the image file
                path = imageDir+filename
132
                # load landmarks from txt files
133
                landmarks = np.loadtxt(os.path.splitext(path)[0]+'.
134
                   txt')
135
                # print(landmarks)
                if landmarks is not None:
136
                     plot(path, landmarks)
137
                else:
138
139
                     print("Landmark Prediction failed on", path)
                continue
140
141
            else:
142
                continue
143
144 # Calculate the affine transformation matrix for each triangle
      pair
   def getAffineMatrice(src tri, dest tri):
145
146
        amat = np.dot(src tri, np.linalg.inv(dest tri))[:2, :]
147
        return amat
148
149
   def warp_to(src_img, src_landmarks, dest_landmarks):
150
151
        width, height, colors = src img.shape
152
153
154
        # initialize the array to store the resulted image
        result img = np.zeros((height, width, 3), np.uint8)
155
156
157
        # construct an array of all coordinates in the resulted
           image
        coor = np.asarray([(x, y) for y in range(0, height)
158
                          for x in range(0, width)], np.uint8)
159
160
```

```
# triangulation on morphed image
161
        dest tri = triangulation(dest landmarks)
162
163
164
        ones = [1, 1, 1]
165
        # find the triangle each coordinate, in the resulted image,
166
            belongs to
        tri index = dest tri.find simplex(coor)
167
168
        # go through each triangle
169
170
        for i in range(len(dest_tri.simplices)):
            # triangle indices
171
            tri = dest tri.simplices[i]
172
            # points within the triangle
173
            points = coor[tri index == i]
174
            # number of points within the triangle
175
            count = len(points)
176
            # get affine matrice for this pair of triangle
177
            amat = getAffineMatrice(np.vstack((src_landmarks[tri,
178
               :].T, ones)), np.vstack((dest landmarks[tri, :].T,
               ones)))
            # use the affine matrice to transform every pixel
179
               inside the triangle to the morphed image
            morphed = np.dot(amat, np.vstack((points.T, np.ones(
180
               count))))
            # coordinates in the original image
181
182
            x, y = points.T
            # coordinates in the morphed image
183
            u, v = np.int32(morphed)
184
            # copy the color of pixels
185
            result img[y, x] = src img[v, u]
186
187
188
        return result_img
189
190
    def warp images(src path, dest path):
191
192
        # saving path
193
        save_path = os.path.splitext(src_path)[0]+'_'+filename(
           dest path)+'/'
        save ext = os.path.splitext(src path)[1]
194
195
        # number of images to generate, including two original
196
           images and morphed images
197
        frames = 60
198
```

```
199
        if not os.path.exists(save path):
200
201
            os.makedirs(save_path)
202
            # read in images
203
            src img = scipy.ndimage.imread(src path)[:, :, :3]
204
            dest img = scipy.ndimage.imread(dest path)[:, :, :3]
205
206
            # predict landmarks for both images
207
            src landmarks = np.loadtxt(os.path.splitext(src path)
208
               [0]+'.txt')
            dest landmarks = np.loadtxt(os.path.splitext(dest path)
209
               [0]+'.txt')
210
            # save the first image (original one)
211
            scipy.misc.imsave(save path+int2filename(0)+save ext,
212
               src img)
213
214
            for x in range(1, frames-1):
                alpha = x/(frames-1)
215
216
                # landmarks for the morphed image
217
                morphed_landmarks = (src_landmarks * (1 - alpha) +
218
                   dest landmarks * alpha)
219
                s2m = warp_to(src_img, src_landmarks,
220
                   morphed landmarks)
                d2m = warp to(dest img, dest landmarks,
221
                   morphed landmarks)
222
223
                # blend two warped images into one
                morphed_img = np.uint8(np.mean(np.array([s2m *
224
                   - alpha), d2m * alpha]), axis=(0)) * 2)
225
226
                # save the morphed image
                scipy.misc.imsave(save path+int2filename(x)+
227
                   save ext, morphed img)
228
            # save the last image (original one)
229
            scipy.misc.imsave(save path+int2filename(frames)+
230
               save_ext, dest_img)
231
        else:
232
            print(save_path, " already exists. Skip this one.")
233
234
```

```
235
        return save path
236
237
   # http://docs.opencv.org/3.1.0/dd/d43/tutorial_py_video_display
   def images2video(dir path, save path):
238
239
        output = save_path + "out.mp4"
240
        images = []
241
242
        if isinstance(dir path, list):
243
244
            for d in dir_path:
                for f in os.listdir(d):
245
                     if f.endswith(".jpg") or f.endswith(".png"):
246
                         images.append(os.path.join(d, f))
247
        else:
248
            for f in os.listdir(dir path):
249
250
                 if f.endswith(".jpg") or f.endswith(".png"):
                     images.append(os.path.join(dir path, f))
251
252
        # Determine the width and height from the first image
253
254
        frame = cv2.imread(images[0])
        cv2.imshow('video',frame)
255
        height, width, channels = frame.shape
256
257
        # Define the codec and create VideoWriter object
258
        fourcc = cv2.VideoWriter fourcc(*'mp4v') # Be sure to use
259
           lower case
        out = cv2. VideoWriter(output, fourcc, 20.0, (width, height)
260
           )
261
262
        for image in images:
263
264
            frame = cv2.imread(image)
265
266
            out.write(frame) # Write out frame to video
267
            cv2.imshow('video',frame)
268
            if (cv2.waitKey(1) & 0xFF) == ord('q'): # Hit 'q' to
269
               exit
270
                break
271
        # Release everything if job is finished
272
        out.release()
273
274
        cv2.destroyAllWindows()
275
```

```
276 def int2filename(n):
        return '{0:06d}'.format(n)
277
278
279
   def filename(path):
        return os.path.splitext(os.path.basename(path))[0]
280
281
282 def main(argv):
283
        imageDir = './csFaculty/'
284
        # image2landmarks(imageDir)
285
        # plotTriangulation(imageDir)
286
287
288
        mList = []
        previousFile = ''
289
290
291
        # Go through every images to make a video
        for f in os.listdir(imageDir):
292
            if f.endswith(".jpg") or f.endswith(".png"):
293
                 if previousFile:
294
                     mList.append(warp images(imageDir+previousFile,
295
                         imageDir+f))
                 previousFile = f
296
297
        images2video(mList, imageDir)
298
299
        # imgdir = warp_images(imageDir+'bala_0.jpg', imageDir+'
300
           mahe.jpg')
        # images2video(imgdir)
301
302
        # plt.imshow(img)
303
        # plt.show()
304
305
        # img = cv2.imread(imageDir+'mahe.jpg', cv2.IMREAD_COLOR)
306
        # img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
307
        # plt.imshow(img)
308
        # plt.show()
309
310
311
   if __name__ == "__main__":
        # execute only if run as a script
312
        main(sys.argv)
313
```