

OS LAB TASK

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CODE 1:

```
GNU nano 7.2
 include <sys/types.h>
include <unistd.h>
include <stdio.h>
int main()
    pid_t pid, mypid, myppid;
    pid = getpid();
printf("Before fork: Process id is %d\n", pid);
    pid = fork();
     if (pid < 0) {
         perror("fork() failure\n");
         printf("This is child process\n");
         mypid = getpid();
         myppid = getppid();
printf("Process id is %d and PPID is %d\n", mypid, myppid);
     } else {
         sleep(2);
         printf("This is parent process\n");
         mypid = getpid();
         myppid = getppid();
         printf("Process id is %d and PPID is %d\n", mypid, myppid);
printf("Newly created process id or child pid is %d\n", pid);
```

OUTPUT:

```
(kali® kali)-[~/Documents]
$ ./lab
Before fork: Process id is 4144
This is child process
Process id is 4148 and PPID is 4144
This is parent process
Process id is 4144 and PPID is 1792
Newly created process id or child pid is 4148
```

CODE EXPLANATION:

This C program uses the **fork ()** system call to create a child process from the parent process. The parent and child processes then print their respective process IDs **(PID)** and the parent's parent process **ID (PPID)**. The child process prints its own **PID** and the **PPID** of its parent (which is the original process). The parent process additionally sleeps for 2 seconds before printing the process information to illustrate a delay between parent and child execution.

CODE 2:

```
GNU nano 7.2
ginclude <stdio.h>
#include <stdib.h>
#include <sys/wait.h>
#include <unistd.h>

int main() {
    pid_t cpid;

    if (fork() = 0) {
        exit(0);
    } else {
        cpid = wait(NULL);
        printf("Parent pid = %d\n", getpid());
        printf("Child pid = %d\n", cpid);
    }

    return 0;
}
```

OUTPUT:

```
(kali@ kali)-[~/Documents]
$ ./lab
Parent pid = 8890
Child pid = 8891
```

CODE EXPLANATION:

This C program uses the **fork ()** system call to create a child process. In the child process, it immediately exits, terminating the child. The parent process waits for the child to complete using **wait ()**, capturing the child's process ID. Finally, both the parent and child processes print their respective process **IDs**, demonstrating the creation and termination of the child process.

TASK 01:

```
GNU nano 7.2
#include <stdib.h>
#include <systdib.h>
#include <sys/types.h>
#include <sys/types.h>
#include <unistd.h>
int main()

{
    pid_t child_pid;
    child_pid = fork();
    if (child_pid < 0)
    {
        perror("fork() failure");
        exit(EXIT_FAELURE);
    }
    else if (child_pid = 0)
    {
        printf("Child process (PID=%d) is created and becomes a zombie.\n", getpid());
        exit(0);
    }
    else
    {
        printf("Parent process (PID=%d) created a child with PID=%d.\n", getpid(), child_pid);
        sleep(10);
        printf("Parent process exits.\n");
    }
}</pre>
```

OUTPUT:

```
(kali® kali)-[~/Documents]
$ ./lab
Parent process (PID=19706) created a child with PID=19710.
Child process (PID=19710) is created and becomes a zombie.
Parent process exits.
```

Now when we use the command **ps -I** it will enlist all the current running processes and we will check our respective process ID from the list as shown and highlighted below.

```
kali)-[~/Documents]
 💲 Parent process exits.
[1] + done
                 ./lab
  -(kali@kali)-[~/Documents]
[1] 22718
Child process (PID=22720) is created and becomes a zombie.
Parent process (PID=22718) created a child with PID=22720.
  -(kali@kali)-[~/Documents]
FS
     UID
             PID
                   PPID C PRI NI ADDR SZ WCHAN TTY
                                                               TIME CMD
    1000
            1792
                    1781
                         0 80
                                 0 - 3406 sigsus pts/0
                                                           00:00:05 zsh
                    1792 0
           22718
                                                          00:00:00 lab
    1000
                                       616 hrtime pts/0
    1000
           22720
                   22718 0 85
                                        0 -
                                                  pts/0
                                                           00:00:00 lab
1 Z
           22751
                    1792 0 80 0 - 2824 -
   1000
                                                  pts/0
                                                           00:00:00 ps
```

When you append an **ampersand (&)** at the end of a command in the shell, it runs the command in the background.

CODE EXPLANATION:

- The C program initiates a child process using the **fork ()** system call, creating a new process in which the child immediately exits, becoming a zombie.
- The parent process, upon successfully creating the child, prints information about both the parent and child processes, including their respective process IDs (PIDs).
- The parent process then sleeps for **10** seconds using the sleep () function, allowing the child process to persist as a zombie during this period.
- After the sleep duration, the parent process exits, leaving the child process in a zombie state as the parent did not wait for the child's termination using functions like wait().
- When running the program in the background and checking the process status using ps I, the child process with a state of 'Z' (zombie) should be visible, confirming its existence
 in the system.

TASK 02:

```
p[i].wtime = (i > 0) ? p[i-1].wtime + p[i-1].btime : 0; // Waiting time calculation
int turnaround_time = p[i].wtime + p[i].btime;
printf(" %d\t\t %d\t\t %d\t\t %d\t\t %d\n", p[i].pno, p[i].btime, p[i].wtime, turnaround_time)
total_waiting_time += p[i].wtime;
}

float avg_waiting_time = (float)total_waiting_time / n;
float avg_turnaround_time = (float)(total_burst_time + total_waiting_time) / n;
printf("\nTotal Waiting Time: %d\n", total_waiting_time);
printf("Average Waiting Time: %d\n", total_burst_time + total_waiting_time);
printf("Total Turnaround Time: %d\n", total_burst_time + total_waiting_time);
printf("Average Turnaround Time: %.2f\n", avg_turnaround_time);

// Free allocated memory
free(p);
return 0;
```

OUTPUT:

```
PRIORITY SCHEDULING.

enter the no of processes: 2
enter the burst time and priority:
process1:1

2
process2:2
3

process burstime waiting time turnaround time
1 1 0 1
2 2 1 3

total waiting time: 1
average waiting time: 0.500000
total turnaround time: 3
average turnaround time: 1.500000
```
