



$$q_o = \frac{h}{R} \quad C dh = (q_i - q_o) dt$$

$$C_1 dh_1 = (q_{i1} - q_1) dt$$

$$q_1 = \frac{h_1 - h_2}{R_1}$$

$$C_2 dh_2 = (q_{i2} + q_1 - q_o) dt$$

$$q_o = \frac{h_2}{R_2}$$

$$C_2 \frac{dh_2}{dt} = (q_{i2} + q_1 - q_o)$$

$$\frac{dh_2}{dt} = \frac{q_{i2} + q_1 - q_o}{C_2}$$

$$C_1 \frac{dh_1}{dt} = q_{i1} - q_1$$

$$\frac{dh_1}{dt} = \frac{q_{i1} - q_1}{C_1}$$

Variações de estado

$$y_1 = h_1 \quad y_2 = h_2$$

$$\beta_0 = b_0$$

$$\beta_1 = b_1 - a_1 \beta_0$$

$$\beta_2 = b_2 - a_1 \beta_1 - a_2 \beta_0$$

$$\beta_3 = b_3 - a_1 \beta_2 - a_2 \beta_1 - a_3 \beta_0$$

$$\vdots$$

$$\vdots$$

$$\vdots$$

$$\beta_{n-1} = b_{n-1} - a_1 \beta_{n-2} - \dots - a_{n-2} \beta_1 - a_{n-1} \beta_0$$

$$\ddot{y} + a_1 \dot{y} + a_2 y = b_0 \ddot{u} + b_1 \dot{u} + b_2 u$$

$$\dot{h}_1 = \frac{q_{i1} - q_1}{C_1}$$

$$x_1 = y - \beta_0 u$$

$$x_2 = \dot{y} - \beta_0 \dot{u} - \beta_1 u = \dot{x}_1 - \beta_1 u$$

$$x_1 = y_1 = h_1$$

$$x_2 = \dot{h}_1$$

$$x_3 = y_2 = h_2$$

$$x_4 = \dot{h}_2$$

$$\dot{x}_1 = x_2 + \beta_1 u$$

$$\dot{x}_1 = \dot{h}_1$$

$$\dot{x}_2 = \dot{h}_2$$

$$\begin{aligned} \dot{x}_1 &= \frac{q_{i1} - q_1}{C} = \frac{q_{i1} - \frac{h_1 - h_2}{R_1}}{C} \\ &= \frac{q_{i1} R_1 - (h_1 - h_2)}{C R_1} \end{aligned}$$

$$\begin{aligned} q_{i1} &= u_1 \\ q_{i2} &= u_2 \end{aligned}$$

$$\begin{aligned} &= \frac{q_{i1}R_1 - C_1(h_1 - h_2)}{C_1R_1} \\ &= \frac{q_{i1}R_1 - (x_1 - x_3)}{C_1R_1} \end{aligned}$$

$$\dot{x}_1 = \frac{u_1R_1 - (x_1 - x_3)}{C_1R_1}$$

$$\dot{x}_1 = -\frac{1}{R_1C_1}x_1 + \frac{1}{R_1C_1}x_3 + \frac{1}{C_1}u_1$$

$$\frac{dh_2}{dt} = \frac{q_{12} + q_1 - q_0}{C_2}$$

$$q_0 = \frac{h_2}{R_2}, \quad q_1 = \frac{h_1 - h_2}{R_1}$$

$$\dot{x}_2 = \frac{u_2 + \frac{h_1 - h_2}{R_1} - \frac{h_2}{R_2}}{C_2}$$

$$\dot{x}_2 = \frac{u_2R_1R_2 + R_2(x_1 - x_3) - R_1(x_2)}{C_2R_1R_2}$$

$$\dot{x}_2 = \frac{1}{R_1C_2}x_1 - \left(\frac{1}{R_1C_2} + \frac{1}{R_2C_2}\right)x_3 + \frac{1}{C_2}u_2$$