

Escena14_ST

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1|      10|      20|      30|      40|      50|      60|      70|      80|      90|     100|     110|
1  R_TRIG_0 (CLK := start);
2  if em_stop and stop and not reseteo and R_TRIG_0.Q then
3      start_light:=1;
4      stop_light:=0;
5      reset_light:=0;
6      %M50:=0;
7  end_if;
8  if not stop and not auto then
9      entry_conveyor:=0;
10     exit_conveyor:=0;
11     start_light:=0;
12     stop_light:=1;
13 end_if;
14 (*-----modo automático*)
15 if start_light and em_stop and auto then
16     if R_TRIG_0.Q and (vision <> 0 or vision =0) then
17         reset_light:=0;
18         entry_conveyor:=1;
19         exit_conveyor:=0;
20     end_if;
21     if cont1<3 or cont2<3 or cont3<3 then
22         reseteo:=0;
23 (*-----primera cinta*)
24     if (vision = 2 or vision = 5) then
25         aux1:= 1;
26         exit_conveyor:=1;
27     end_if;
28
29     if aux1 and (not aux2 and not aux3) and entry_conveyor then
30         sorter1_turn := 1;
31         sorter1_belt:=1;
32         aux2:=0;
33         aux3:=0;
34     end_if;
35 (*-----segunda cinta*)
36     if (vision = 3 or vision = 6) then
37         aux2:= 1;
38         exit_conveyor:=1;
39     end_if;
40     if aux2 and (not aux1 and not aux3) and entry_conveyor then
41         sorter2_turn := 1;
42         sorter2_belt:=1;
43         aux1:=0;
44         aux3:=0;
45     end_if;
46 (*-----tercera cinta*)
47     if (vision = 1 or vision = 4) then
48         aux3:= 1;
49         exit_conveyor:=1;
50     end_if;
51     if aux3 and (not aux1 and not aux2) and entry_conveyor then
52         sorter3_turn := 1;
53         sorter3_belt:=1;
54         aux2:=0;
55         aux1:=0;
56     end_if;
57 else
58     sorter1_turn := 0;
59     sorter1_belt:=0;
60     sorter2_turn := 0;
61     sorter2_belt:=0;
62     sorter3_turn := 0;
63     sorter3_belt:=0;
64     exit_conveyor:=0;
65     entry_conveyor:=0;
66     temp:=0;
67     start_light:=0;
68     reset_light:=1;
69 end_if;
70
71
72 TON_3 (IN := exit_conveyor,
73       PT := t#1.5s);
74 if TON_3.Q then
75     entry_conveyor:=0;
76 end_if;
77
78 r_trig_1(clk := not at_exit);
79 if r_trig_1.q then
80     temp:=1;
81 end_if;
82
83 TON_1 (IN := temp,
84       PT := t#0.5s);
85 if TON_1.Q then
86     sorter1_turn := 0;
87     sorter1_belt:=0;
88     sorter2_turn := 0;
89     sorter2_belt:=0;
90     sorter3_turn := 0;
91     sorter3_belt:=0;
92     exit_conveyor:=0;
93     aux1:= 0;
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1|      10|      20|      30|      40|      50|      60|      70|      80|      90|      100|      110|
94          aux2:= 0;
95          aux3:= 0;
96          entry_conveyor:=1;
97          temp:=0;
98          end_if;
99
100
101
102      end_if;
103
104
105      CTU_0 (CU := aux1,
106            R := reseteo,
107            CV => cont1);
108      CTU_1 (CU := aux2,
109            R := reseteo,
110            CV => cont2);
111      CTU_2 (CU := aux3,
112            R := reseteo,
113            CV => cont3);
114
115      (*Reseteo-----*)
116
117      R_TRIG_3 (CLK := reseteo);
118      if r_trig_3.q then
119          %M51:=0;
120      end_if;
121      if (R_TRIG_3.Q and not start_light) or not em_stop then
122          sorter1_turn := 0;
123          sorter1_belt:=0;
124          sorter2_turn := 0;
125          sorter2_belt:=0;
126          sorter3_turn := 0;
127          sorter3_belt:=0;
128          exit_conveyor:=0;
129          entry_conveyor:=0;
130          temp:=0;
131          start_light:=0;
132          reset_light:=1;
133      end_if;
134
135      if %M51 and %s6 then
136          reset_light:=1;
137      end_if;
138      if %M51 and not %s6 then
139          reset_light:=0;
140      end_if;
141
142      F_TRIG_3 (CLK := stop);
143      if F_TRIG_3.Q then
144          stop_light:=1;
145          %M50:=1;
146      end_if;
147      F_TRIG_4 (CLK := em_stop);
148      if F_TRIG_4.Q then
149          %M51:=1;
150      end_if;
151
152
153
154      (*-----modo manual*)
155      R_TRIG_12 (CLK := start);
156      if R_TRIG_12.Q then
157          start_light:=1;
158      end_if;
159      if start_light and em_stop and manual then
160          R_TRIG_4 (CLK := start);
161          if R_TRIG_4.Q then
162              reset_light:=0;
163              entry_conveyor:=1;
164              exit_conveyor:=0;
165          end_if;
166
167      (*-----primera cinta*)
168          if (vision = 2 or vision = 5) then
169              aux1:= 1;
170              exit_conveyor:=1;
171          end_if;
172          R_TRIG_9 (CLK := exit_conveyor);
173          if aux1 and (not aux2 and not aux3) and r_trig_9.Q then
174              sorter1_turn := 1;
175              sorter1_belt:=1;
176              aux2:=0;
177              aux3:=0;
178              entry_conveyor:=1;
179          end_if;
180
181          R_TRIG_6 (CLK := at_exit);
182          if R_TRIG_6.Q then
183              start_light:=0;
184              sorter1_turn := 0;
185              sorter1_belt:=0;
186              aux2:=0;

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1|      10|      20|      30|      40|      50|      60|      70|      80|      90|     100|     110|
187      aux3:=0;
188      aux1:=0;
189      exit_conveyor:=0;
190      end_if;
191      (*-----segunda cinta*)
192      if (vision = 3 or vision = 6) then
193          aux2:= 1;
194          exit_conveyor:=1;
195      end_if;
196
197      R_TRIG_10 (CLK := exit_conveyor);
198      if aux2 and (not aux1 and not aux3) and r_trig_10.Q then
199          sorter2_turn := 1;
200          sorter2_belt:=1;
201          aux1:=0;
202          aux3:=0;
203      end_if;
204
205
206      R_TRIG_7 (CLK := at_exit);
207      if R_TRIG_7.Q then
208          start_light:=0;
209          sorter2_turn := 0;
210          sorter2_belt:=0;
211          aux2:=0;
212          aux3:=0;
213          aux1:=0;
214          exit_conveyor:=0;
215      end_if;
216      (*-----tercera cinta*)
217      if (vision = 1 or vision = 4) then
218          aux3:= 1;
219          exit_conveyor:=1;
220      end_if;
221      R_TRIG_11 (CLK := exit_conveyor);
222      if aux3 and (not aux1 and not aux2) and r_trig_11.Q then
223          sorter3_turn := 1;
224          sorter3_belt:=1;
225          aux2:=0;
226          aux1:=0;
227      end_if;
228
229
230
231      R_TRIG_8 (CLK := at_exit);
232      if R_TRIG_8.Q then
233          start_light:=0;
234          sorter3_turn := 0;
235          sorter3_belt:=0;
236          aux2:=0;
237          aux3:=0;
238          aux1:=0;
239          exit_conveyor:=0;
240      end_if;
241
242
243
244      TON_9 (IN := exit_conveyor,
245            PT := t#0.8s);
246      if TON_9.Q then
247          entry_conveyor:=0;
248      end_if;
249
250
251
252
253      end_if;
```