

Escena14_ST

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1|      10|      20|      30|      40|      50|      60|      70|      80|      90|     100|     110|
1 R_TRIGGER (CLK := start);
2 if em_stop and stop and not reseteo and R_TRIGGER.Q then
3   start_light:=1;
4   stop_light:=0;
5   reset_light:=0;
6   %M50:=0;
7 end_if;
8 if not stop and not auto then
9   entry_conveyor:=0;
10  exit_conveyor:=0;
11  start_light:=0;
12  stop_light:=1;
13 end_if;
14 (*-----modo automático*)
15 if start_light and em_stop and auto then
16   if R_TRIGGER.Q and (vision >> 0 or vision = 0) then
17     reset_light:=0;
18     entry_conveyor:=1;
19     exit_conveyor:=0;
20   end_if;
21   if cont1<3 or cont2<3 or cont3<3 then
22     reseteo:=0;
23 (*-----primera cinta*)
24   if (vision = 2 or vision = 5) then
25     aux1:= 1;
26     exit_conveyor:=1;
27   end_if;
28
29   if aux1 and (not aux2 and not aux3) and entry_conveyor then
30     sorter1_turn := 1;
31     sorter1_belt:=1;
32     aux2:=0;
33     aux3:=0;
34   end_if;
35 (*-----segunda cinta*)
36   if (vision = 3 or vision = 6) then
37     aux2:= 1;
38     exit_conveyor:=1;
39   end_if;
40   if aux2 and (not aux1 and not aux3) and entry_conveyor then
41     sorter2_turn := 1;
42     sorter2_belt:=1;
43     aux1:=0;
44     aux3:=0;
45   end_if;
46 (*-----tercera cinta*)
47   if (vision = 1 or vision = 4) then
48     aux3:= 1;
49     exit_conveyor:=1;
50   end_if;
51   if aux3 and (not aux1 and not aux2) and entry_conveyor then
52     sorter3_turn := 1;
53     sorter3_belt:=1;
54     aux2:=0;
55     aux1:=0;
56   end_if;
57 else
58   sorter1_turn := 0;
59   sorter1_belt:=0;
60   sorter2_turn := 0;
61   sorter2_belt:=0;
62   sorter3_turn := 0;
63   sorter3_belt:=0;
64   exit_conveyor:=0;
65   entry_conveyor:=0;
66   temp:=0;
67   start_light:=0;
68   reset_light:=1;
69 end_if;
70
71 TON_3 (IN := exit_conveyor,
72         PT := t#1.5s);
73   if TON_3.Q then
74     entry_conveyor:=0;
75   end_if;
76
77 r_trig_1(clk := not at_exit);
78   if r_trig_1.q then
79     temp:=1;
80   end_if;
81
82 TON_1 (IN := temp,
83         PT := t#0.5s);
84   if TON_1.Q then
85     sorter1_turn := 0;
86     sorter1_belt:=0;
87     sorter2_turn := 0;
88     sorter2_belt:=0;
89     sorter3_turn := 0;
90     sorter3_belt:=0;
91     exit_conveyor:=0;
92     aux1:= 0;
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1|      10|      20|      30|      40|      50|      60|      70|      80|      90|     100|     110|
94          aux2:= 0;
95          aux3:= 0;
96          entry_conveyor:=1;
97          temp:=0;
98      end_if;
99
100
101 end_if;
102
103
104
105 CTU_0 (CU := aux1,
106         R := reseteo,
107         CV => cont1);
108 CTU_1 (CU := aux2,
109         R := reseteo,
110         CV => cont2);
111 CTU_2 (CU := aux3,
112         R := reseteo,
113         CV => cont3);
114
115 (*Reseteo-----*)
116
117 R_TRIG_3 (CLK := reseteo);
118 if r_trig_3.q then
119     %M51:=0;
120 end_if;
121 if (R_TRIG_3.Q and not start_light) or not em_stop then
122     sorter1_turn := 0;
123     sorter1_belt:=0;
124     sorter2_turn := 0;
125     sorter2_belt:=0;
126     sorter3_turn := 0;
127     sorter3_belt:=0;
128     exit_conveyor:=0;
129     entry_conveyor:=0;
130     temp:=0;
131     start_light:=0;
132     reset_light:=1;
133 end_if;
134
135 if %M51 and %s6 then
136     reset_light:=1;
137 end_if;
138 if %M51 and not %s6 then
139     reset_light:=0;
140 end_if;
141
142 F_TRIG_3 (CLK := stop);
143 if F_TRIG_3.Q then
144     stop_light:=1;
145     %M50:=1;
146 end_if;
147 F_TRIG_4 (CLK := em_stop);
148 if F_TRIG_4.Q then
149     %M51:=1;
150 end_if;
151
152
153
154 (*-----modo manual*)
155 R_TRIG_12 (CLK := start);
156 if R_TRIG_12.Q then
157     start_light:=1;
158 end_if;
159 if start_light and em_stop and manual then
160     R_TRIG_4 (CLK := start);
161     if R_TRIG_4.Q then
162         reset_light:=0;
163         entry_conveyor:=1;
164         exit_conveyor:=0;
165     end_if;
166
167 (*-----primera cinta*)
168     if (vision = 2 or vision = 5) then
169         aux1:= 1;
170         exit_conveyor:=1;
171     end_if;
172     R_TRIG_9 (CLK := exit_conveyor);
173     if aux1 and (not aux2 and not aux3) and r_trig_9.Q then
174         sorter1_turn := 1;
175         sorter1_belt:=1;
176         aux2:=0;
177         aux3:=0;
178         entry_conveyor:=1;
179     end_if;
180
181     R_TRIG_6 (CLK := at_exit);
182     if R_TRIG_6.Q then
183         start_light:=0;
184         sorter1_turn := 0;
185         sorter1_belt:=0;
186         aux2:=0;
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1|      10|      20|      30|      40|      50|      60|      70|      80|      90|     100|     110|
187                         aux3:=0;
188                         aux1:=0;
189                         exit_conveyor:=0;
190         end_if;
191 (*-----segunda cinta*)
192         if (vision = 3 or vision = 6) then
193             aux2:= 1;
194             exit_conveyor:=1;
195         end_if;
196
197     R_TRIG_10 (CLK := exit_conveyor);
198         if aux2 and (not aux1 and not aux3) and r_trig_10.Q then
199             sorter2_turn := 1;
200             sorter2_belt:=1;
201             aux1:=0;
202             aux3:=0;
203         end_if;
204
205
206     R_TRIG_7 (CLK := at_exit);
207     if R_TRIG_7.Q then
208         start_light:=0;
209         sorter2_turn := 0;
210         sorter2_belt:=0;
211         aux2:=0;
212         aux3:=0;
213         aux1:=0;
214         exit_conveyor:=0;
215     end_if;
216 (*-----tercera cinta*)
217     if (vision = 1 or vision = 4) then
218         aux3:= 1;
219         exit_conveyor:=1;
220     end_if;
221     R_TRIG_11 (CLK := exit_conveyor);
222         if aux3 and (not aux1 and not aux2) and r_trig_11.Q then
223             sorter3_turn := 1;
224             sorter3_belt:=1;
225             aux2:=0;
226             aux1:=0;
227         end_if;
228
229
230     R_TRIG_8 (CLK := at_exit);
231     if R_TRIG_8.Q then
232         start_light:=0;
233         sorter3_turn := 0;
234         sorter3_belt:=0;
235         aux2:=0;
236         aux3:=0;
237         aux1:=0;
238         exit_conveyor:=0;
239     end_if;
240
241
242
243
244     TON_9 (IN := exit_conveyor,
245             PT := t#0.8s);
246     if TON_9.Q then
247         entry_conveyor:=0;
248     end_if;
249
250
251
252
253 end_if;
```