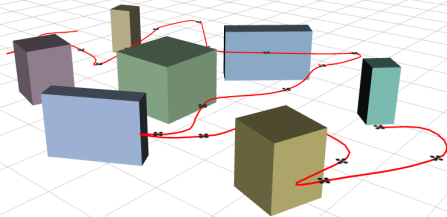


a) Time-Optimal Ergodic Trajectory



b) Trajectory Execution on Drone

00:00:00 TIME: 03:50

