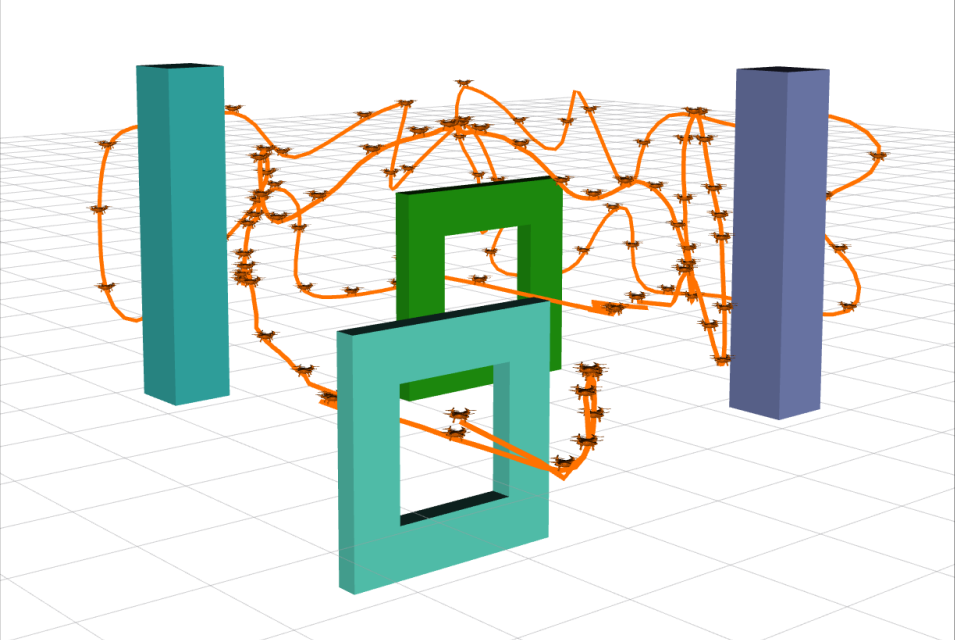


a) Time-Optimal Ergodic Trajectory in Complex Clutter



b) Trajectory Execution on Drone

ELAPSED TIME: 25.64

