Ignacio Alzugaray

Curriculum Vitae

Birthdate: 10/11/1992 | Nationality: Spanish
Zürich, Switzerland
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Education

Feb'17-Present **PhD. Candidate**, *Vision for Robotics Lab (V4RL), ETH Zürich*.
Thesis: *Event-driven Feature Detection and Tracking for Visual SLAM*.
- Advisor: Prof. Dr. Margarita Chli.
- Examiners: Prof. Dr. Andrew Davison, Prof. Dr. Davide Scaramuzza, Prof. Dr. Lauren Kneip.

2016 **M.Sc. Automatic Control and Robotics**, *Polytechnic University of Catalonia (UPC)*.
Top student in Master's program (2014-2016), GPA – 8.70/10.
Graduate Thesis: *Path planning for MAVs with vision in the loop*.
- Advisor: Prof. Dr. Margarita Chli. Grade: 5.75/6. ETH Zürich – International student exchange.
- Accepted as a paper in the *International Conference on Robotics and Automation* (ICRA 2017).

2014 **B.Sc. Industrial Engineering**, *University of Malaga (UMA)*.
Top student in Bachelor's program (2010-2014). GPA – 8.49/10.
Undergraduate Thesis: *Teleoperation of Robotic Manipulators applied to Laparoscopic Surgery*.
- Advisor: Dr. Carlos Perez del Pulgar. Grade: 9.5/10.

Experience

Sep'21 - Dec'21 **Research Scientist Intern**, *Facebook/Meta Reality Labs*.
- Designing of a NeRF-based pipeline for image-based visual relocalization.
- PyTorch implementation trained with real egocentric footage for AR applications.
- Supervisor: Dr. Vasileios Balntas.

Sep'19 - Dec'19 **Software Engineer Intern**, *Disney Research Zurich*.
- Development of VR animation tools with hand tracking and gesture recognition within Unity.
- Close collaboration with Disney Animation Studio on PoseVR project.
- Supervisors: Dr. Jakob Buhmann and Dr. Martin Guay.

Sep'16 - Feb'17 **Research Assistant**, *Vision for Robotics Lab (V4RL), ETH Zürich*.
- Implementation of probabilistic event-based scene mapping.
- Design of active monocular-inertial SLAM pipeline for UAVs.
- Supervisor: Prof. Dr. Margarita Chli.

Jun'15 - Feb'16 **Research Assistant Intern**, *Institute of Robotics and Industrial Informatics (IRI-CSIC)*.
- Design of path planning algorithms for UAVs embedding the experience of expert pilots.
- Accepted paper in the International Conference on Intelligent Robots and Systems (IROS 2016).
- Supervisor: Prof. Dr. Alberto Sanfeliu.

Oct'13 - Jul'14 **Undergraduate Research Assistant**, *Instituto Andaluz de Automática Avanzada y Robótica*.
- Design of trajectory control algorithms for robotic manipulators applied to laparoscopic surgery.
- Supervisor: Dr. Carlos Perez del Pulgar.

Research and Dissemination Activities

Jun'21 **Invited Speaker** at the *Event-based Vision* workshop, CVPR 2021. Presentation title: "Towards Asynchronous SLAM with Event Cameras."

Oct'18 **Invited Speaker** at the *Unconventional Sensing and Processing for Robotic Visual Perception* workshop, IROS 2018. Presentation title: "Asynchronous Vision."

Awards and Scholarships

2016 **Award for Academic Performance in Master's**, *Polytechnic University of Catalonia (UPC)*.
Granted to the top performing student in postgraduate programme (2014–2016). The recipient is granted with an internship sponsored by KUKA AG.

2016 **International Student Scholarship**, *ETH Zürich, Swiss-European Mobility Programme*.
Competitive scholarship granted to students in an international exchange programme.

2014 **Excellence Scholarship in Master's Programme**, *Catalunya-La Pedrera Foundation*.
Two-years scholarship granted to the Master's program applicant with the best academic record.

2014 **Award for Academic Performance in Bacherlor's**, *University of Malaga (UMA)*.
Granted to the top performing student in undergraduate programme (2010–2014).

2013 **Undergraduate Research Scholarship**, *University of Malaga, Spanish Ministry of Education*.
Nationally competitive six-months scholarship to conduct short research projects.

Skills

Languages **Spanish:** Native **English:** Professional Proficiency **German:** Basic

Programming C++, Matlab, Python, C#, Simulink, LaTeX

Frameworks PyTorch, ROS, Unity, OpenCV, Unreal Engine, Gazebo, Git

Peer-reviewed Publications

[C7] I. Alzugaray and M. Chli.
HASTE: multi-Hypothesis Asynchronous Speeded-up Tracking of Events.
British Machine Vision Conference (BMVC), Virtual, 2020.

[J2] Z. Lai, I. Alzugaray, M. Chli and E. Chatzi.
Full-field structural monitoring using event cameras and physics-informed sparse identification.
Mechanical Systems and Signal Processing, 2020.

[C6] C. Le Gentil, F. Tschopp, I. Alzugaray, T. Vidal-Calleja, R. Siegwart and J. Nieto.
IDOL: A framework for IMU-DVS odometry using lines.
IEEE/RSJ Conference on Intelligent Robots and Systems (IROS), Las Vegas, NV, USA, 2020.

[C5] I. Alzugaray and M. Chli.
Asynchronous Multi-hypothesis Tracking of features with Event Cameras.
International Conference on 3D Vision (3DV), Quebec, Canada, 2019. Oral presentation.

[C4] I. Alzugaray and M. Chli.
ACE: An Efficient Asynchronous Corner Tracker for Event Cameras.
International Conference on 3D Vision (3DV), Verona, Italy, 2018.

[J1] I. Alzugaray and M. Chli.
Asynchronous Corner Detection and Tracking for Event Cameras in Real Time.
IEEE Robotics and Automation Letters (RA-L), 2018.

[C3] L. Texeira, I. Alzugaray and M. Chli.
Autonomous Aerial Inspection Using Visual-Inertial Robust Localization and Mapping.
Conference on Field and Service Robotics (FSR), Zurich, Switzerland, 2017.

[C2] I. Alzugaray, L. Texeira and M. Chli.
Short-term UAV Path-Planning with Monocular-Inertial SLAM in the Loop.
IEEE International Conference on Robotics and Automation (ICRA), Singapore, 2017.

[C1] I. Alzugaray and A. Sanfeliu.
Learning the Hidden Human Knowledge of UAV Pilots when navigating in a cluttered environment for improving Path Planning.
IEEE/RSJ Conference on Intelligent Robots and Systems (IROS), Daejeon, Korea, 2016.