

Originally presented at IEEE - Data Compression Conference - 2017

Semantic Perceptual Image Compression

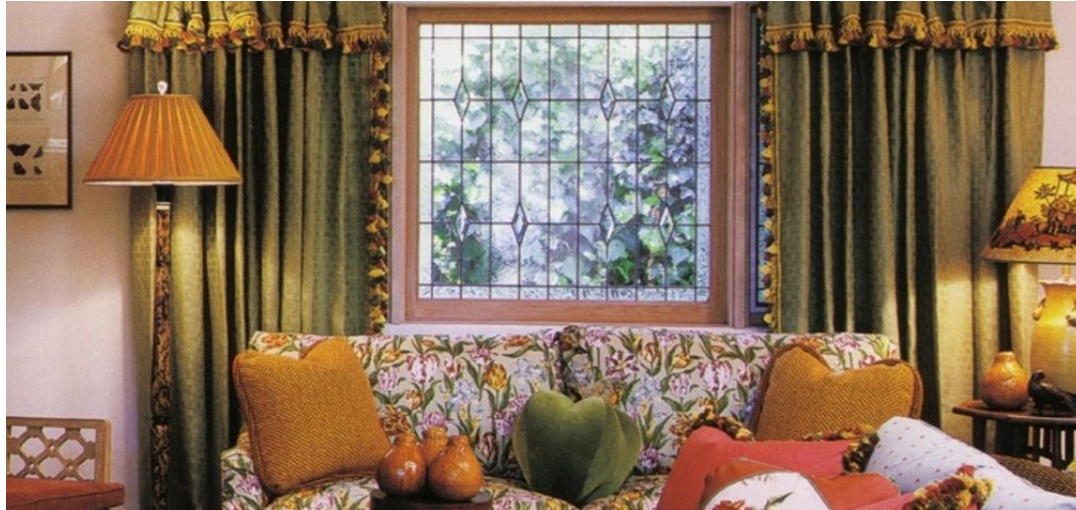
Using Deep
Convolutional Networks

Aaditya Prakash, Nick Moran, Solomon Garber,
Antonella DiLillo and James Storer

Brandeis University

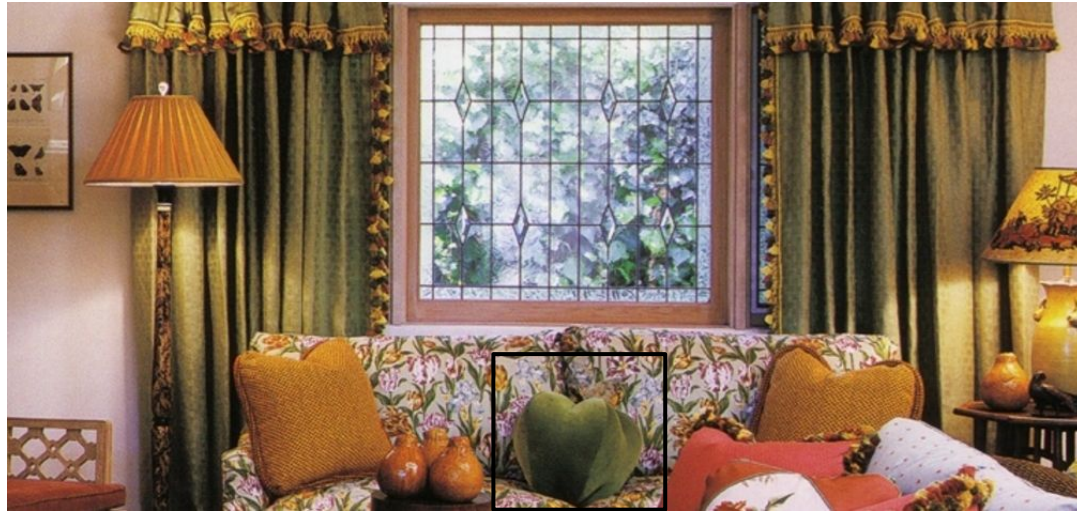
Perceptual Image Compression

JPEG treats all blocks as equally important



Perceptual Image Compression

Humans perceive some regions as more important



Perceptual Image Compression

We use convolutional neural networks to identify 'salient' regions

Standard
JPEG



Our
method



Our work

- Develop novel CNN architecture to find [all salient objects](#)
- Specifically designed towards compression applications

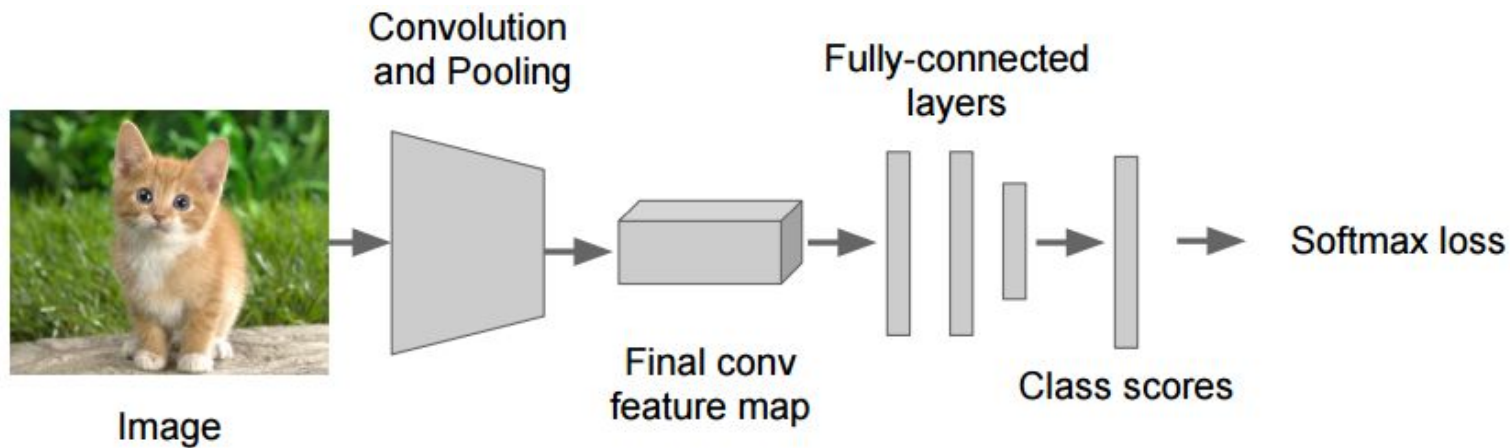
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- Develop novel CNN architecture to find **all salient objects**
- Specifically designed towards compression applications
- Achieves higher visual quality for the same PSNR and compressed size

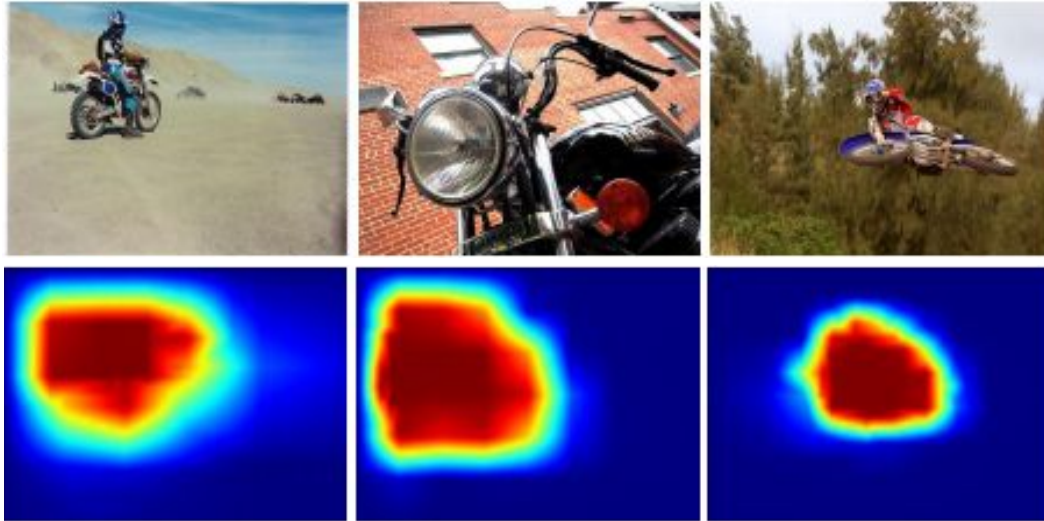
Our work

- Develop novel CNN architecture to find **all salient objects**
- Specifically designed towards compression applications
- Achieves higher visual quality for the same PSNR and compressed size
- Final image is encoded as **standard JPEG**
- Use any **off-the-shelf JPEG decoder** to decode

Convolutional Neural Network



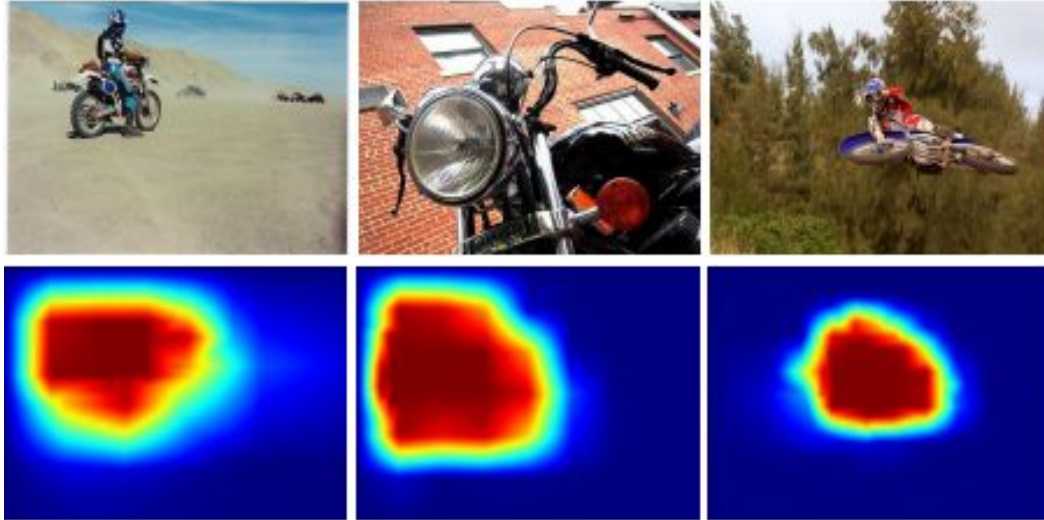
CNN filter response



- Higher activations -> Object Location

See: [Interactive visualization with MNIST](#)

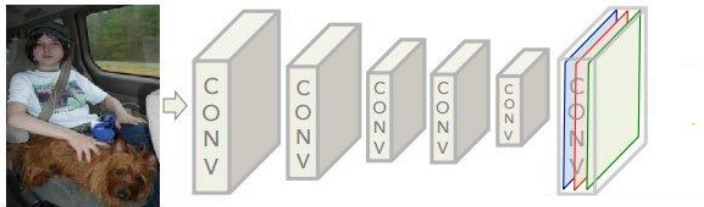
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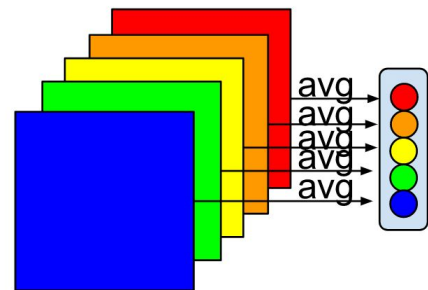
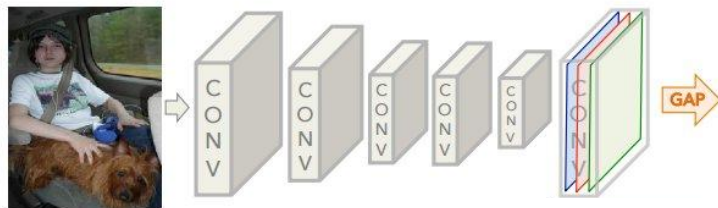
- Higher activations -> Object Location
- Problem: Does not capture object structure

See: [Interactive visualization with MNIST](#)

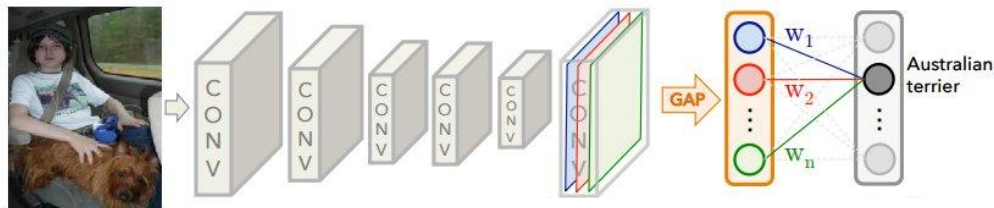
Class activation map



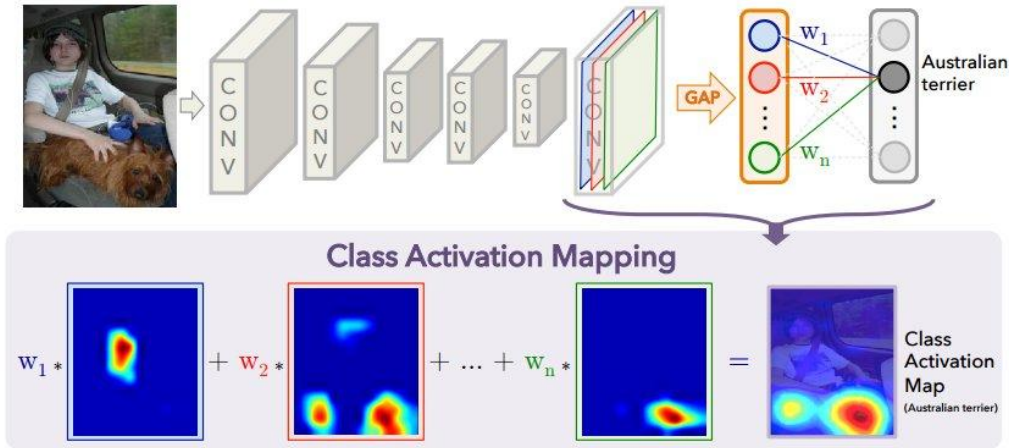
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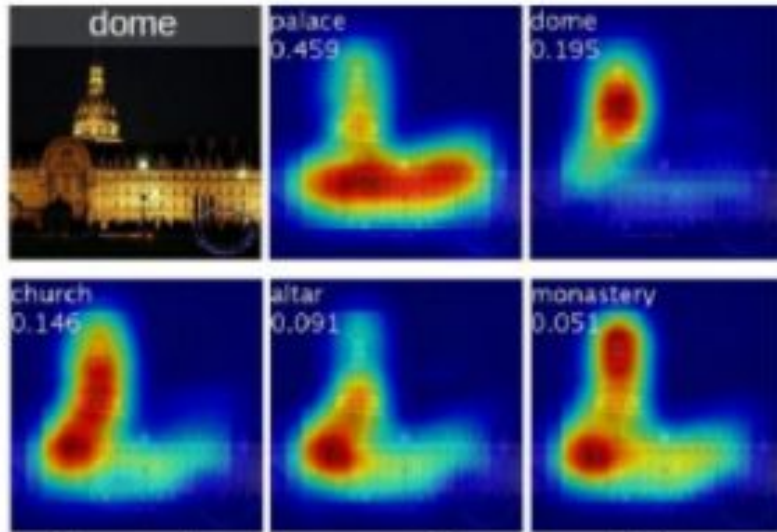


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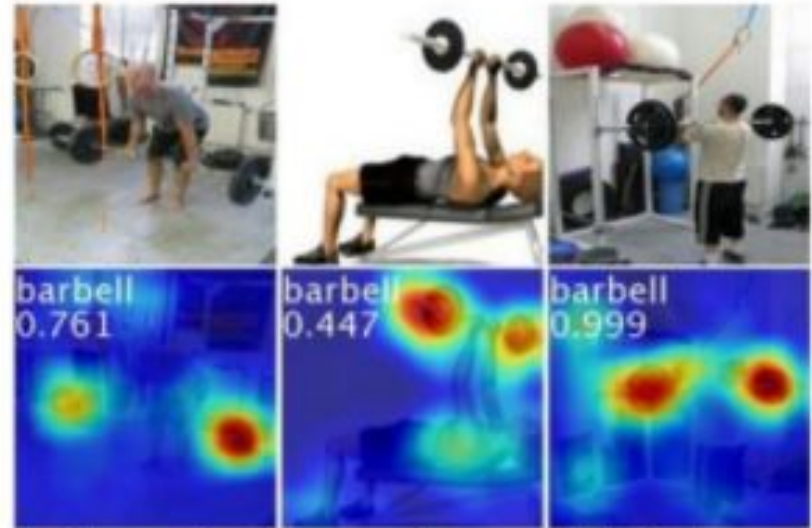


- Class activation map is the obtained by taking the output of GAP and learning weights that maximize the discriminative activations for a given class.

Class activation map



Class activation maps of top 5 predictions



Class activation maps for one object class

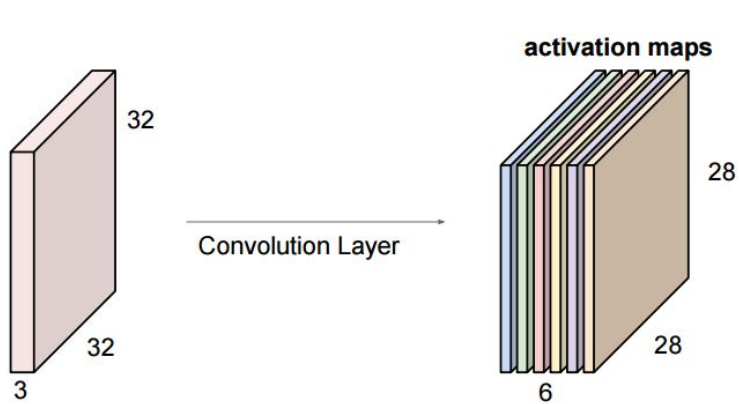
- Problem: Identifies only one object.

Our work

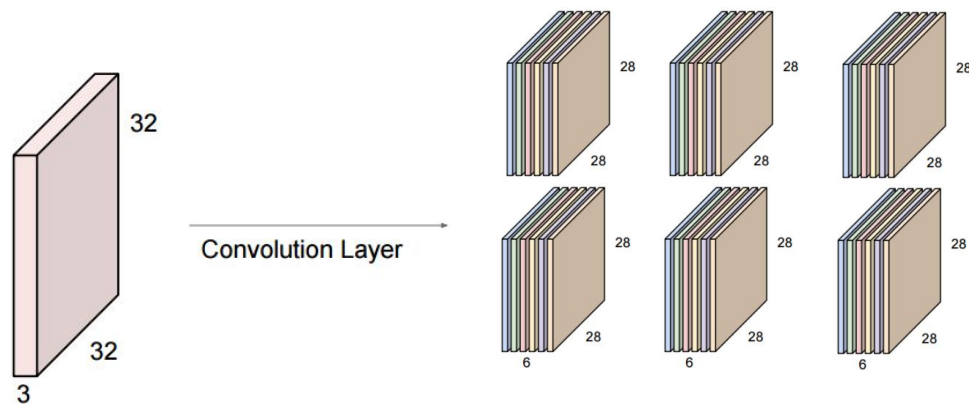
Multi-Structure Region of Interest (MSROI)

Perform weak localization like CAM, but detect multiple salient objects.

Multi-Structure Region of Interest



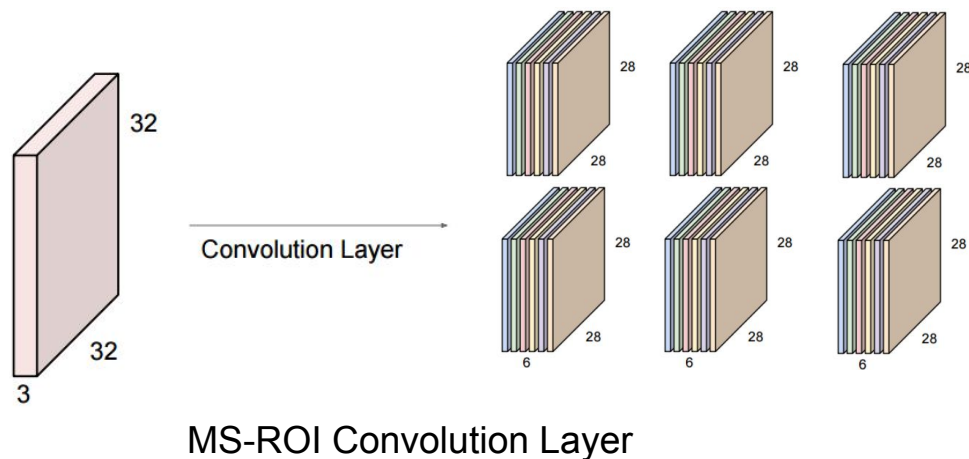
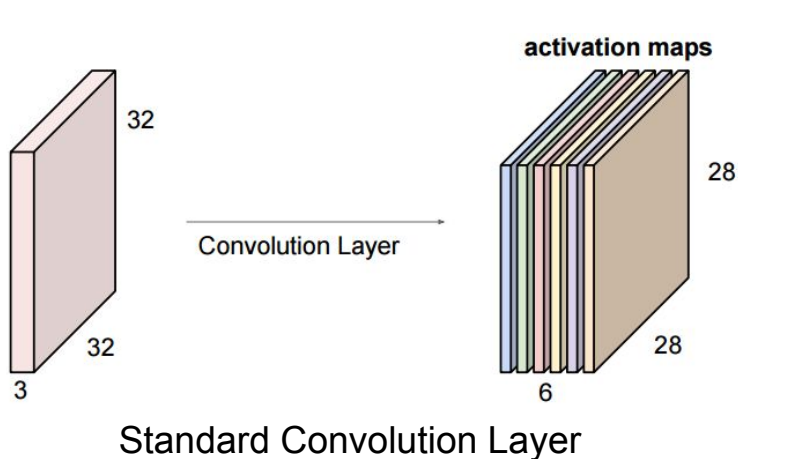
Standard Convolution Layer



MS-ROI Convolution Layer

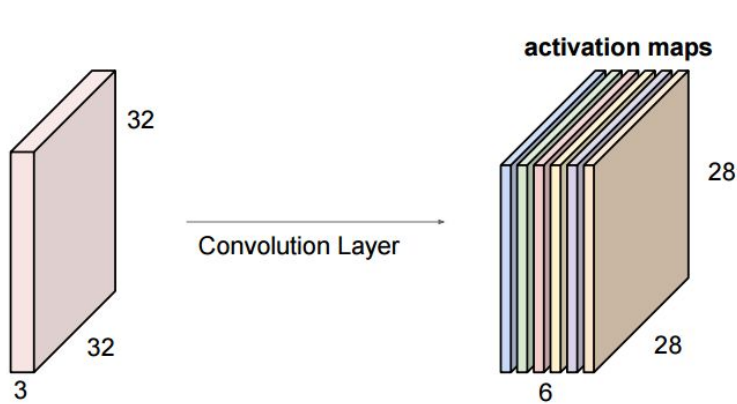
- Add one more dimension to feature maps - **classes**.

Multi-Structure Region of Interest

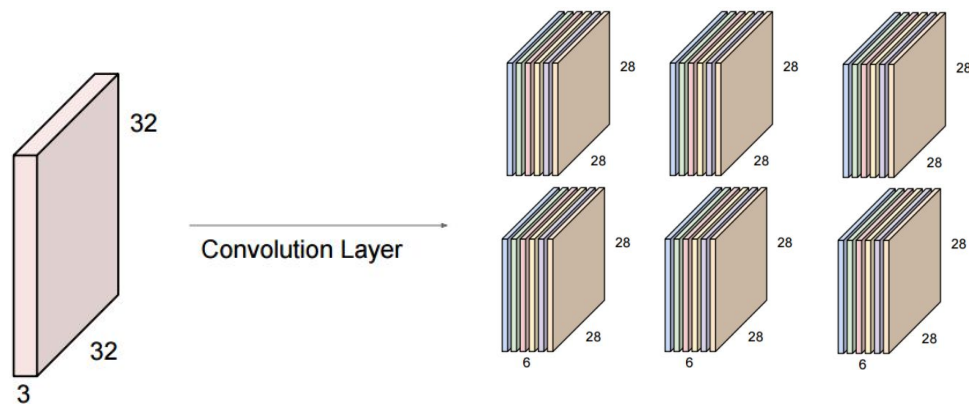


- Add one more dimension to feature maps - **classes**.
- Learns class invariant feature maps.

Multi-Structure Region of Interest



Standard Convolution Layer



MS-ROI Convolution Layer

- Add one more dimension to feature maps - **classes**.
- Learns class invariant feature maps.
- For training, replace softmax with **sigmoid** in order to prevent "squeezing" of the probabilities of classes that are not 'ground-truth'.

MSROI - No Free Lunch

For \mathbf{L} layers, where each layer l contains d_l features, k is the max pooling stride size, an image of size $n \times n$, and with \mathbf{C} classes

$$\sum_{l \in \mathbf{L}} d_l \times \mathbf{C} \times \frac{n}{k^l} \times \frac{n}{k^l}$$

- For a color image of decent size and with many filters per layer and several layers deep, this number is huge.

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Solution

- Make number of **classes very small** by using Synsets - hierarchy of classes in Imagenet
- **Share feature maps** across classes to jointly learn lower level features

MSROI - Fine-grained is overkill

- Most CNN models, including CAM, are trained on Imagenet, which has 1000 classes.
- Some of the classes are **fine-grained** like different breeds of dog.

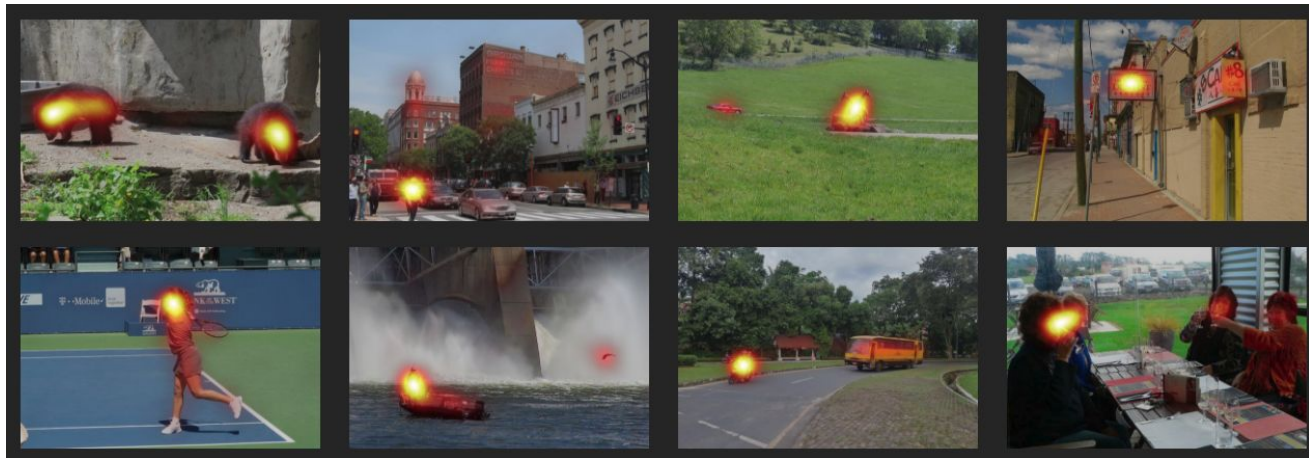


MSROI - Fine-grained is overkill

- Most CNN models, including CAM, are trained on Imagenet, which has 1000 classes.
- Some of the classes are **fine-grained** like different breeds of dog.
- Intuition, they will have **similar “semantic” map**, because of similar object structure.

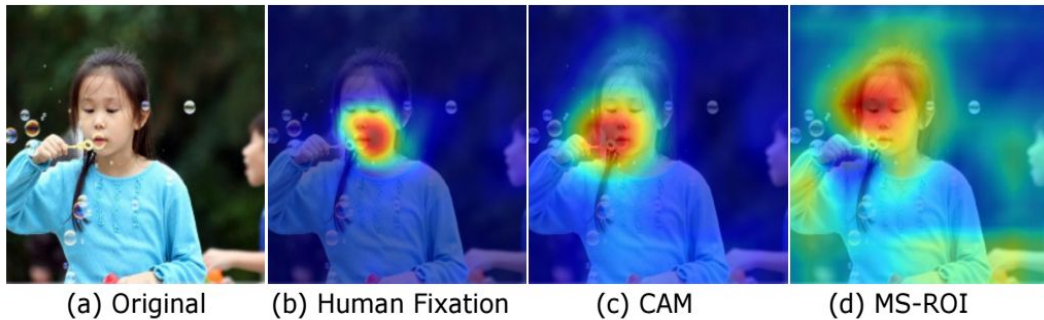


Where do we look?

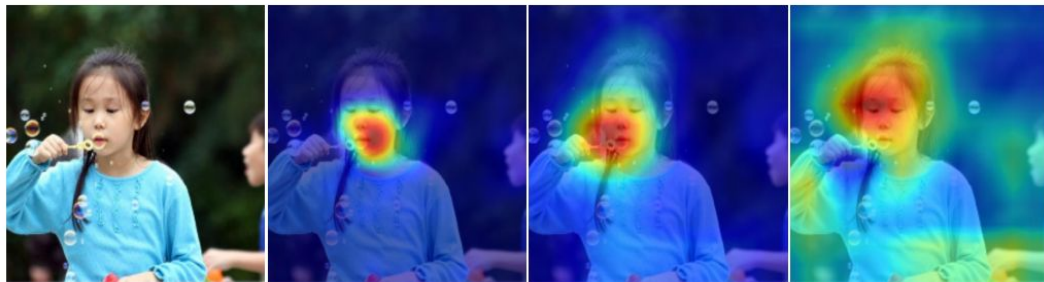


SALICON
Dataset

Where do we look?



Class Activation Map (CAM)



(a) Original

(b) Human Fixation

(c) CAM

(d) MS-ROI

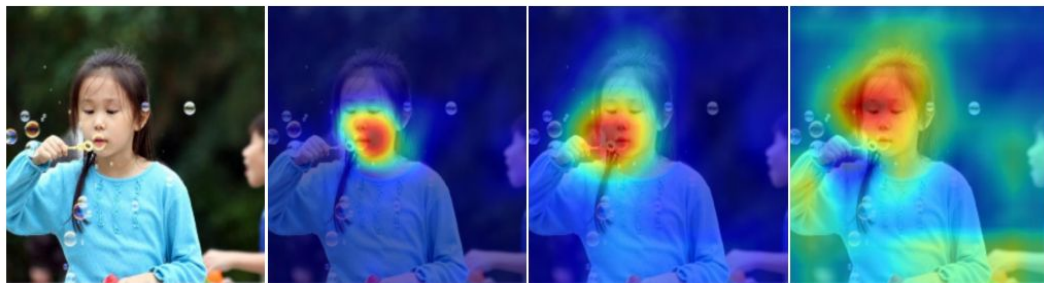
CAM

$$M_c(x, y) = \sum_{d \in \mathbf{D}} w_d^c f_d(x, y)$$

where w_d^c is learned for every class c and for layer 'd'

$$P(c) = \frac{\exp(\sum_{xy} M_c(x, y))}{\sum_c \exp(\sum_{xy} M_c(x, y))}$$

Multi-Structure Region of Interest



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- Z_l^c denotes threshold which signifies 'presence' of a class

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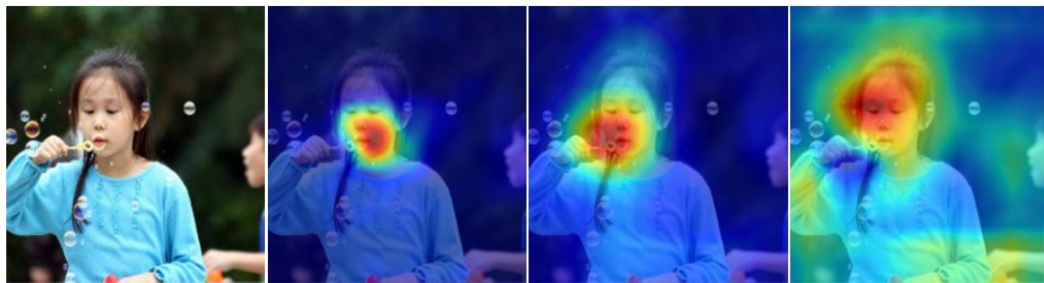
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MSROI Map

$$Z_l^c = \sum_{d \in \mathbf{D}} \sum_{x, y} f_d^c(x, y)$$

MSROI - Details



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- Z_l^c denotes threshold which signifies 'presence' of a class
- \widehat{M} denotes Multi-structure map generated using MSROI. Compare this with CAM map (M)
- It is sum over all classes with total activations Z_l^c beyond some threshold.

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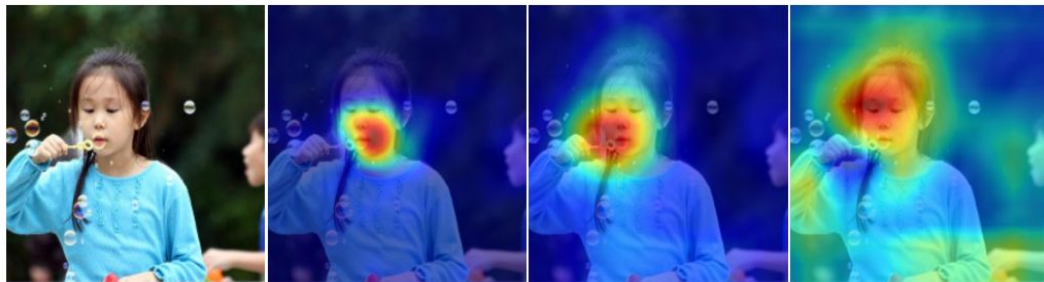
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$$Z_l^c = \sum_{d \in \mathbf{D}} \sum_{x, y} f_d^c(x, y)$$

$$\widehat{M}(x, y) = \sum_{c \in \mathbf{C}} \begin{cases} \sum_d f_d^c(x, y), & \text{if } Z_l^c > T \\ 0 & \text{otherwise} \end{cases}$$

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- Z_l^c denotes threshold which signifies 'presence' of a class
- \widehat{M} denotes Multi-structure map generated using MSROI. Compare this with CAM map (M)
- It is sum over all classes with total activations Z_l^c beyond some threshold.
- For training use sigmoid instead of softmax to prevent losing information about 'other objects'

CAM

$$M_c(x, y) = \sum_{d \in \mathbf{D}} w_d^c f_d(x, y)$$

where w_d^c is learned for every class c and for layer ' d '

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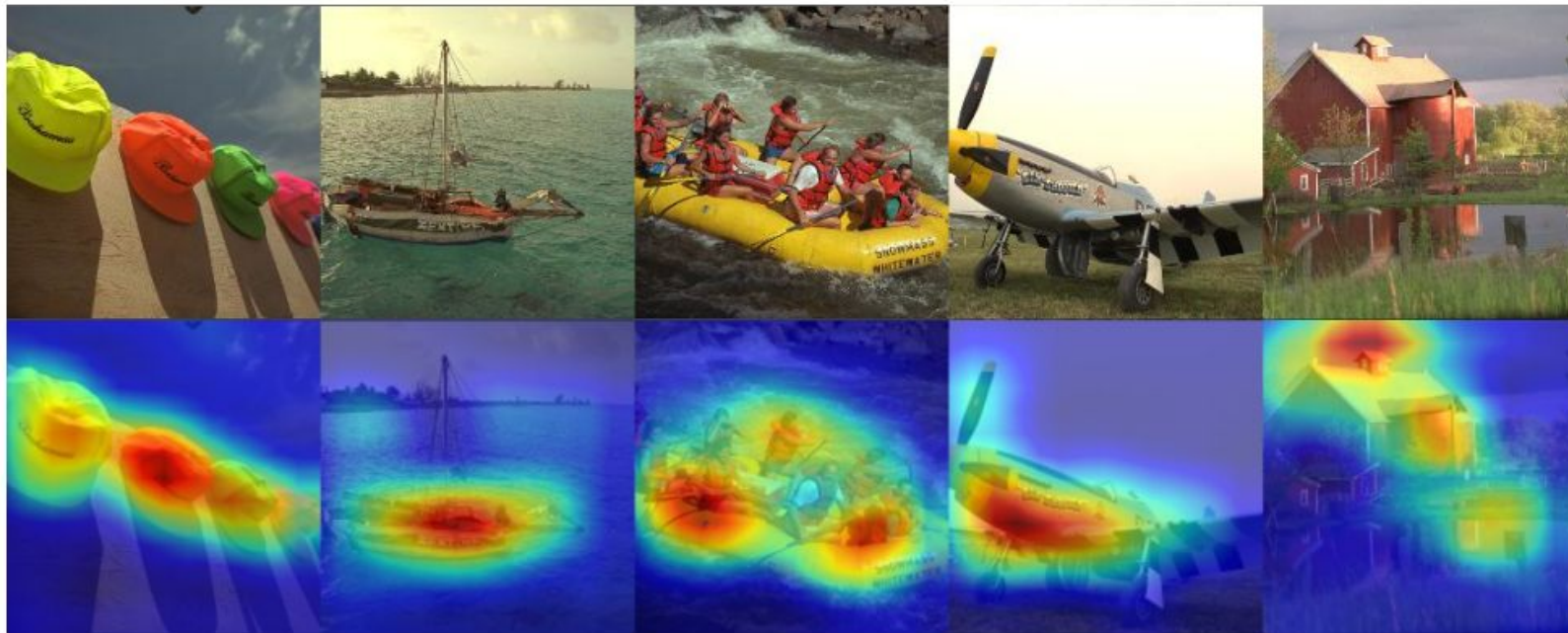
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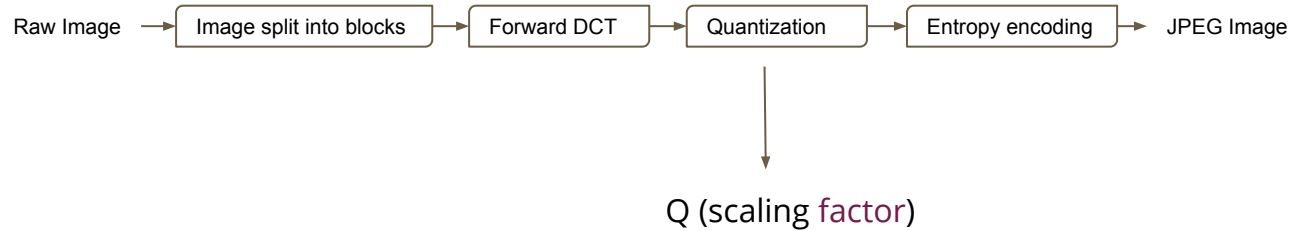
$$P(c) = \frac{1}{1 + \exp(Z_l^c)}$$

MSROI - examples on Kodak images



JPEG

- Traditional JPEG coders apply a fixed scaling factor to the Quantization matrices.

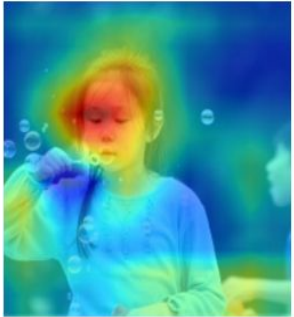


- Our method employs a variable scaling factor.

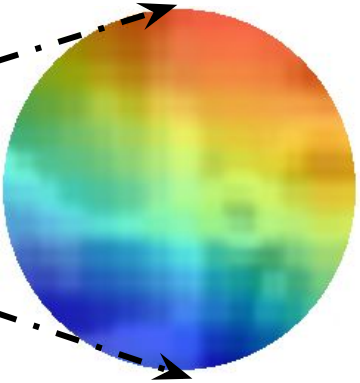
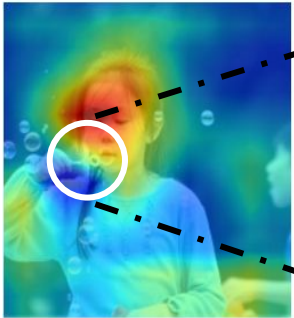
Variable 'Q' JPEG



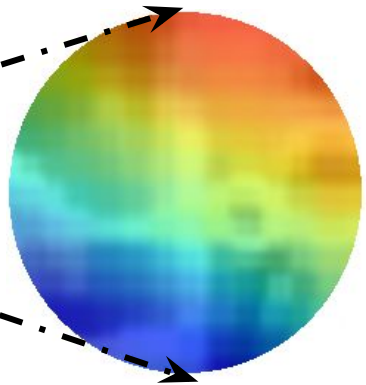
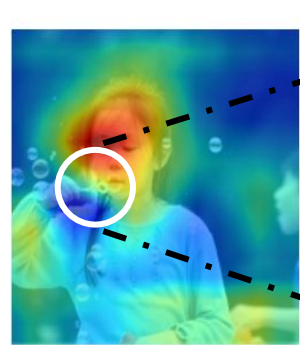
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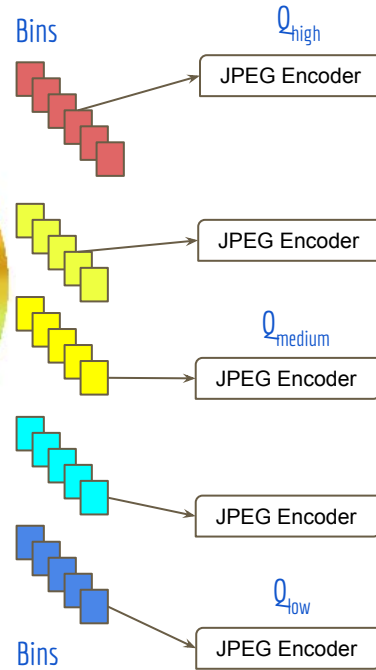
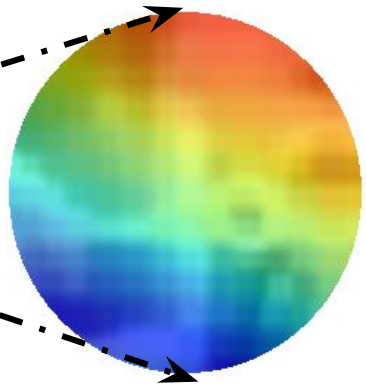
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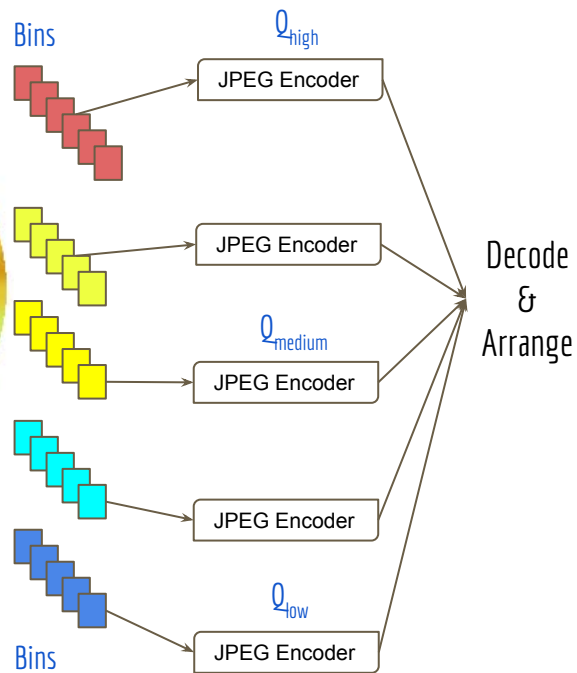
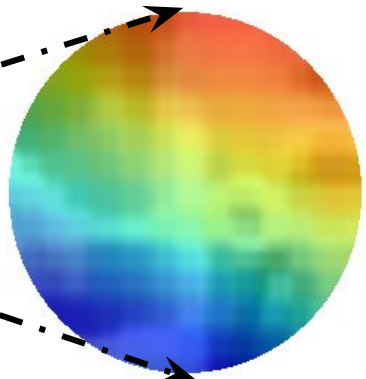
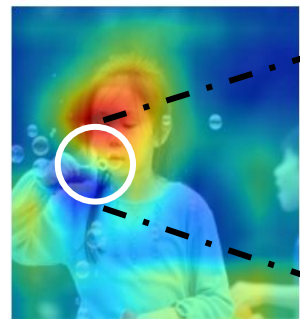
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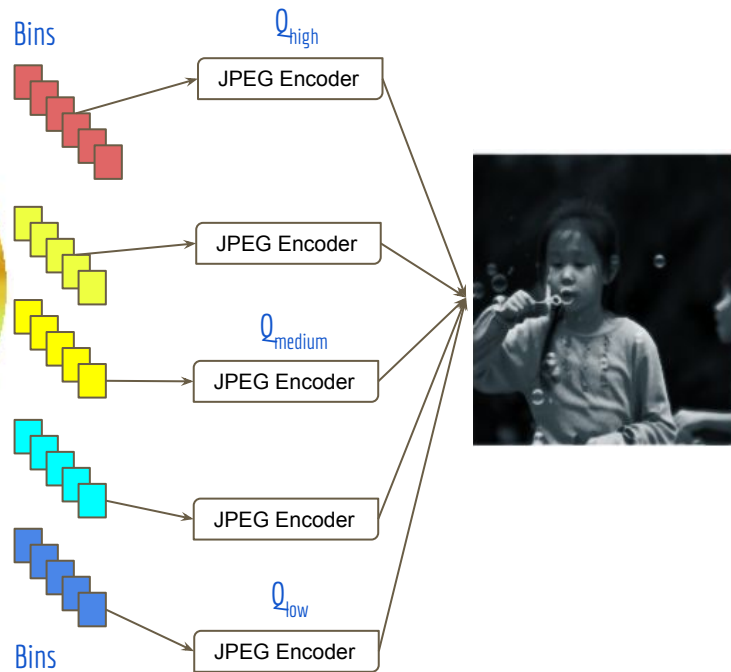
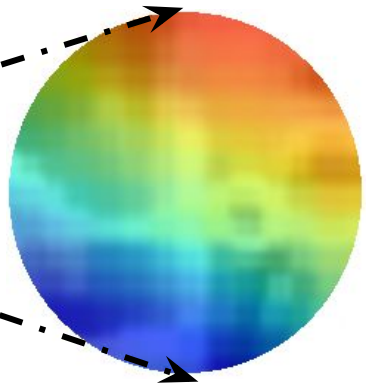
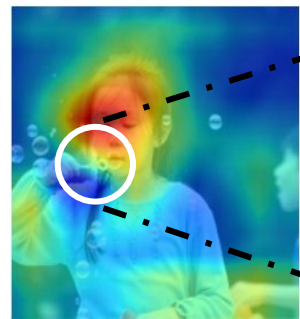
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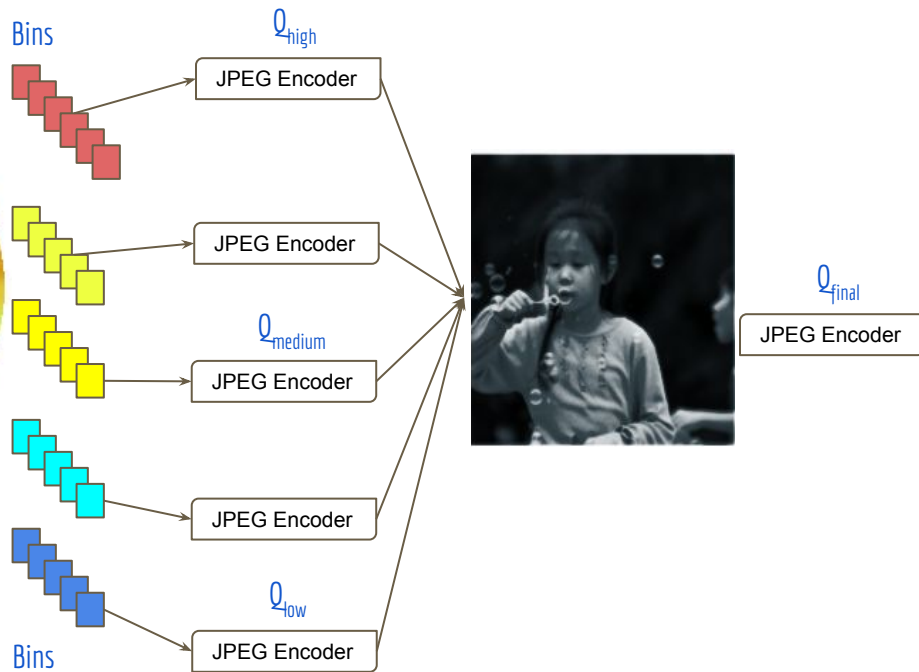
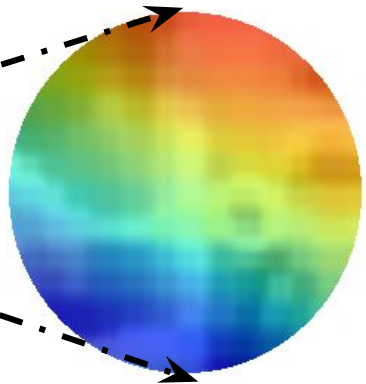
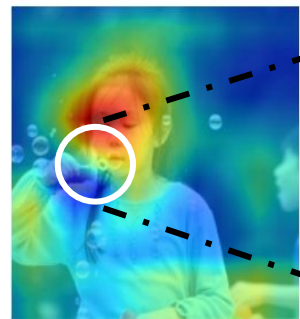
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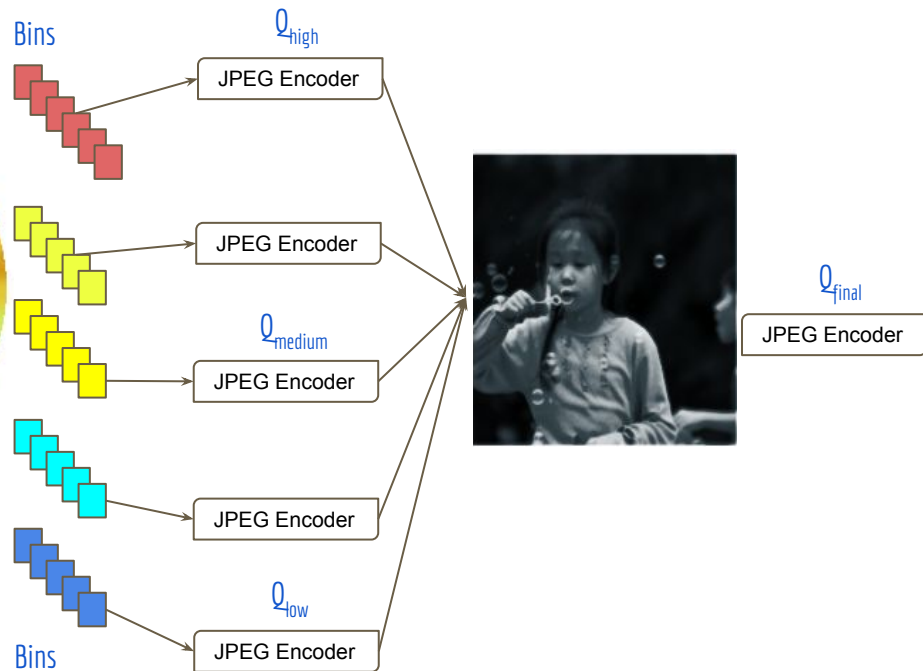
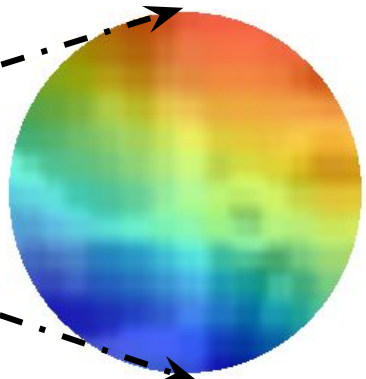
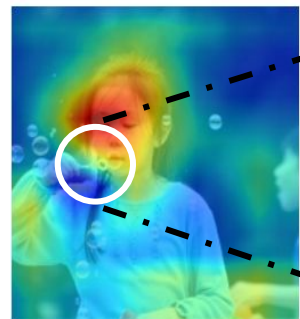
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End-to-End Steps

Train a MSROI model - **only once** for all the images !

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- Decode these blocks and arrange them in the same position from where they were extracted.
- Encode this using **standard JPEG** at a uniform Q level.

Results

PSNR-S is the PSNR of the 'salient' regions as identified by MSROI

	PSNR-S	PSNR	PSNR-HVS	PSNR-HVSM	SSIM	MS-SSIM	VIFP
Kodak PhotoCD [24 images]							
Std JPEG	33.91	34.70	34.92	42.19	0.969	0.991	0.626
Our model	39.16	34.82	35.05	42.33	0.969	0.991	0.629
MIT Saliency Benchmark [Outdoor Man-made + Natural, 200 images]							
Std JPEG	36.9	31.84	35.91	45.37	0.893	0.982	0.521
Our model	40.8	32.16	36.32	45.62	0.917	0.990	0.529
Re-sized images of a very large image, see fig: 4 [20 images]							
Std JPEG	35.4	27.46	33.12	43.26	0.912	0.988	0.494
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- Our model always maintains the PSNR and other perceptual metrics

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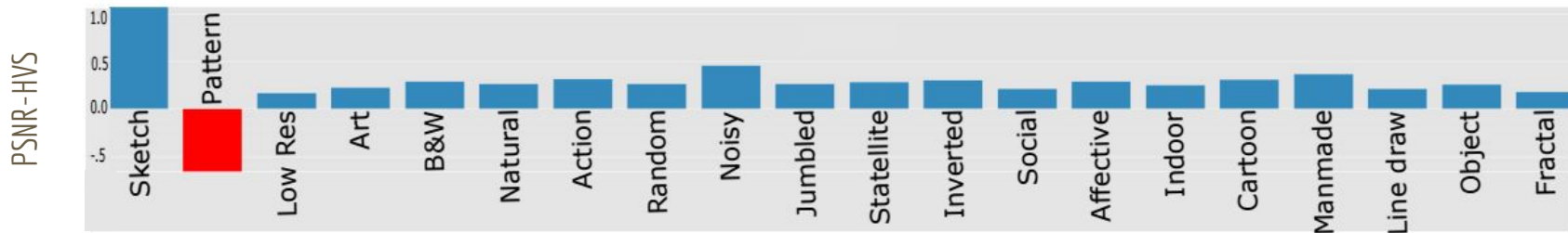
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- For all these experiments - size of images is same ($\pm 1\%$) on both methods
- Our model always maintains the PSNR and other perceptual metrics
- Effective on images much different than the training set

Results - comparison of different categories

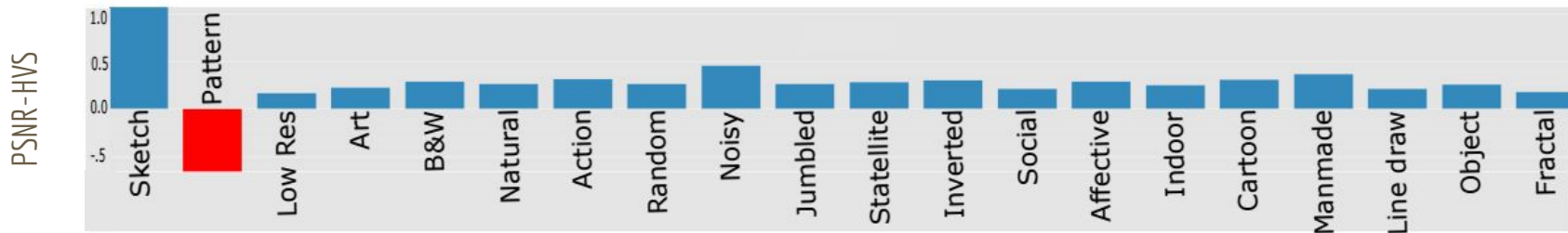
Text in the bar represents categories of object represented in the image



PSNR-HVS of our model minus standard JPEG
Positive values (blue color) means our model is better.

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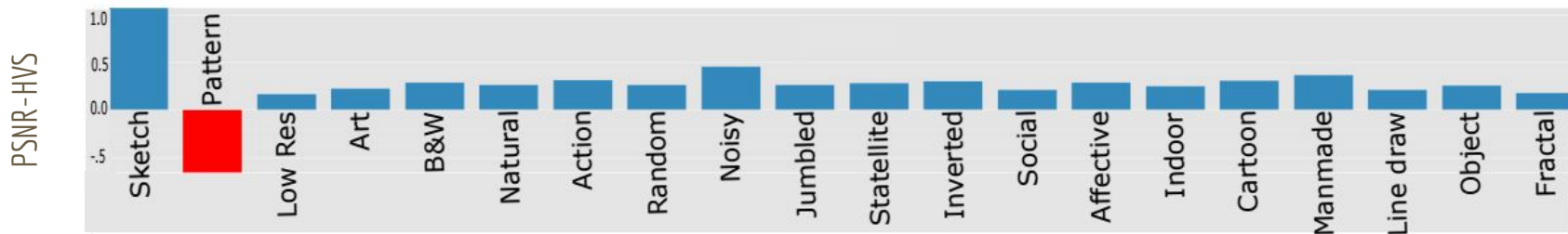


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- Performs better on all 'categories' except 'Pattern'

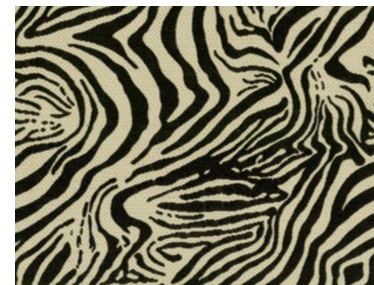
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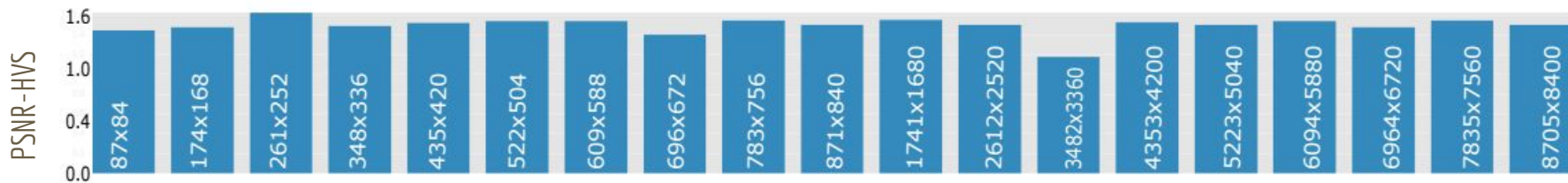
- Performs better on all 'categories' except 'Pattern'
- Patterns have no semantic content and thus model is not able to determine any 'regions-of-interest'.



Sample from pattern category

Results - comparison of different resolutions

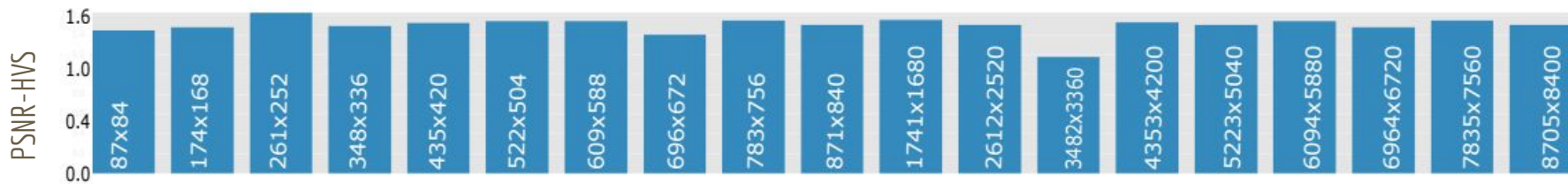
Numbers in the bar represents resolution of image (height x width)



PSNR-HVS of our model minus standard JPEG
Positive values (blue color) means our model is better.

Results - comparison of different resolutions

Numbers in the bar represents resolution of image (height x width)



PSNR-HVS of our model minus standard JPEG
Positive values (blue color) means our model is better.

- Performs equally well on different size images and with many objects.
- This signifies that our model is able to extract object at different scales.

Summary

- MSROI: A new CNN design for salient region detection:
 - Avoids precise object boundary (not needed for image compression).
 - Is able to detect multiple salient regions.
- Encoding is slower than standard JPEG but reasonable (90 images/sec on GPU).
- Decoding employs standard off-the-shelf decoder, thus there is no added cost.
- Technique is agnostic to the kind of 'encoder-decoder' used. Thus can be expanded to JPEG-2000.

Code:

github.com/iamaaditya/image-compression-cnn

References

Object localization/detection

1. Tools for efficient Object Detection [\[pdf\]](#)
2. R-CNN for Object Detection [\[pdf\]](#)
3. Segmentation as Selective Search (Poster) [\[pdf\]](#)
4. Faster R-CNN: Towards real-time object detection [\[pdf\]](#)

Weak localization

5. Is localization for free? - *Original paper which investigated weakly supervised localization.* [\[pdf\]](#)
6. Learning Deep Features for Discriminative Localization - *Subsequent paper, which proposed CAM.* [\[pdf\]](#)
7. Semantic Perceptual Image Compression using Deep Convolution Networks - *Paper this presentation is about.* [\[pdf\]](#)

JPEG Perceptual Quality Metrics

8. Multi-scale Structural Similarity for Image Quality Assessment - *MSSIM* [\[pdf\]](#)
9. A Modified PSNR Metric based on HVS for Quality Assessment of Color Images - *PSNR-HVS* [\[pdf\]](#)
10. On Between-Coefficient Contrast Masking of DCT Basis Functions - *PSNR-HVS-M* [\[pdf\]](#)
11. Image Information and Visual Quality - *VIFP* [\[pdf\]](#)

Image compression using deep learning

12. Variable Rate Image Compression with Recurrent Neural Networks [\[pdf\]](#)
13. Full Resolution Image Compression with Recurrent Neural Networks [\[pdf\]](#)
14. End-to-end Optimized Image Compression [\[pdf\]](#)