Introduction to Graphs

Graph is a non-linear data structure. It contains a set of points known as nodes (or vertices) and a set of links known as edges (or Arcs). Here edges are used to connect the vertices. A graph is defined as follows...

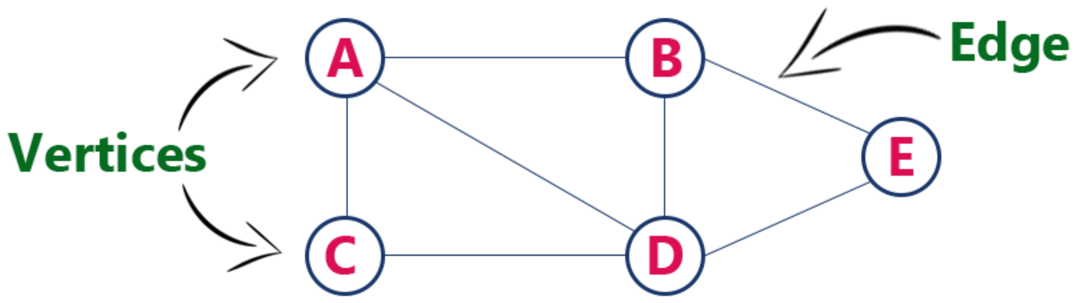
Graph is a collection of vertices and arcs in which vertices are connected with arcs

Graph is a collection of nodes and edges in which nodes are connected with edges

Generally, a graph **G** is represented as **G = (V , E)**, where **V is set of vertices** and **E is set of edges**.

Example

The following is a graph with 5 vertices and 6 edges.
This graph G can be defined as G = (V , E)
Where V = {A,B,C,D,E} and E = {(A,B),(A,C)(A,D),(B,D),(C,D),(B,E),(E,D)}.



Graph Terminology

We use the following terms in graph data structure...

Vertex

Individual data element of a graph is called as Vertex. **Vertex** is also known as **node**. In above example graph, A, B, C, D & E are known as vertices.

Edge

An edge is a connecting link between two vertices. **Edge** is also known as **Arc**. An edge is represented as (startingVertex, endingVertex). For example, in above graph the link between vertices A and B is represented as (A,B). In above example graph, there are 7 edges (i.e., (A,B), (A,C), (A,D), (B,D), (B,E), (C,D), (D,E)).

Edges are three types.

1. **Undirected Edge -** An undirected egde is a bidirectional edge. If there is undirected edge between vertices A and B then edge (A , B) is equal to edge (B , A).
2. **Directed Edge -** A directed egde is a unidirectional edge. If there is directed edge between vertices A and B then edge (A , B) is not equal to edge (B , A).
3. **Weighted Edge -** A weighted egde is a edge with value (cost) on it.

Undirected Graph

A graph with only undirected edges is said to be undirected graph.

Directed Graph

A graph with only directed edges is said to be directed graph.

Mixed Graph

A graph with both undirected and directed edges is said to be mixed graph.

End vertices or Endpoints

The two vertices joined by edge are called end vertices (or endpoints) of that edge.

Origin

If a edge is directed, its first endpoint is said to be the origin of it.

Destination

If a edge is directed, its first endpoint is said to be the origin of it and the other endpoint is said to be the destination of that edge.

Adjacent

If there is an edge between vertices A and B then both A and B are said to be adjacent. In other words, vertices A and B are said to be adjacent if there is an edge between them.

Incident

Edge is said to be incident on a vertex if the vertex is one of the endpoints of that edge.

Outgoing Edge

A directed edge is said to be outgoing edge on its origin vertex.

Incoming Edge

A directed edge is said to be incoming edge on its destination vertex.

Degree

Total number of edges connected to a vertex is said to be degree of that vertex.

Indegree

Total number of incoming edges connected to a vertex is said to be indegree of that vertex.

Outdegree

Total number of outgoing edges connected to a vertex is said to be outdegree of that vertex.

Parallel edges or Multiple edges

If there are two undirected edges with same end vertices and two directed edges with same origin and destination, such edges are called parallel edges or multiple edges.

Self-loop

Edge (undirected or directed) is a self-loop if its two endpoints coincide with each other.

Simple Graph

A graph is said to be simple if there are no parallel and self-loop edges.

Path

A path is a sequence of alternate vertices and edges that starts at a vertex and ends at other vertex such that each edge is incident to its predecessor and successor vertex.

Graph Representations

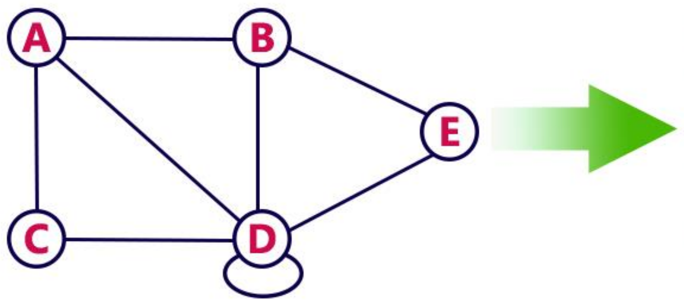
Graph data structure is represented using following representations...

1. **Adjacency Matrix**
2. **Adjacency List**

Adjacency Matrix

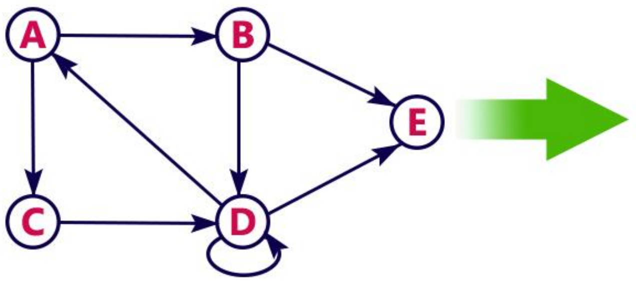
In this representation, the graph is represented using a matrix of size total number of vertices by a total number of vertices. That means a graph with 4 vertices is represented using a matrix of size 4X4. In this matrix, both rows and columns represent vertices. This matrix is filled with either 1 or 0. Here, 1 represents that there is an edge from row vertex to column vertex and 0 represents that there is no edge from row vertex to column vertex.

For example, consider the following undirected graph representation...



$$\begin{array}{c|ccccc} & A & B & C & D & E \\ \hline A & 0 & 1 & 1 & 1 & 0 \\ B & 1 & 0 & 0 & 1 & 1 \\ C & 1 & 0 & 0 & 1 & 0 \\ D & 1 & 1 & 1 & 1 & 1 \\ E & 0 & 1 & 0 & 1 & 0 \end{array}$$

Directed graph representation...

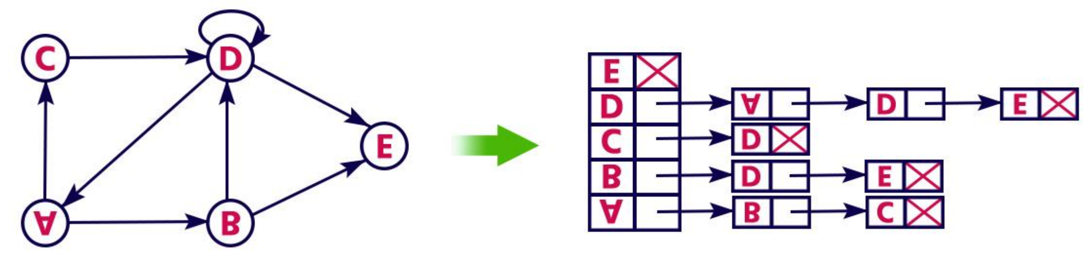


$$\begin{array}{c|ccccc} & A & B & C & D & E \\ \hline A & 0 & 1 & 1 & 0 & 0 \\ B & 0 & 0 & 0 & 1 & 1 \\ C & 0 & 0 & 0 & 1 & 0 \\ D & 1 & 0 & 0 & 1 & 1 \\ E & 0 & 0 & 0 & 0 & 0 \end{array}$$

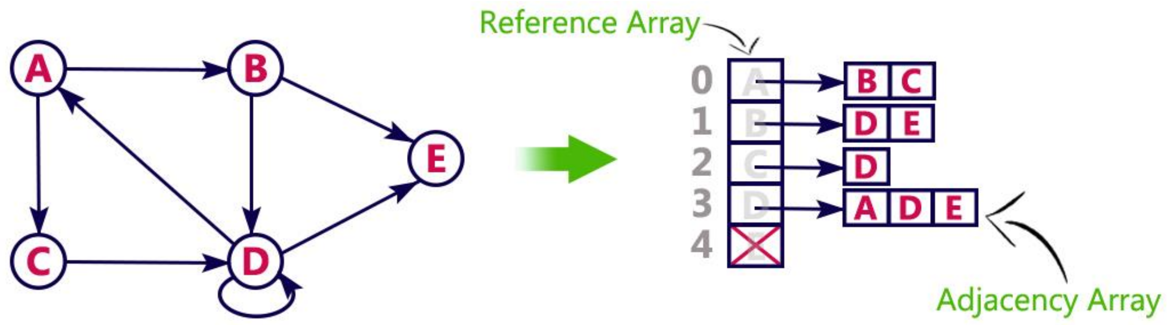
Adjacency List

In this representation, every vertex of a graph contains list of its adjacent vertices.

For example, consider the following directed graph representation implemented using linked list...



This representation can also be implemented using an array as follows..



Linear Search Algorithm

What is Search?

Search is a process of finding a value in a list of values. In other words, searching is the process of locating given value position in a list of values.

Linear Search Algorithm (Sequential Search Algorithm)

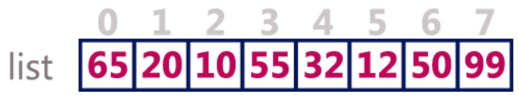
Linear search algorithm finds a given element in a list of elements with **O(n)** time complexity where **n** is total number of elements in the list. This search process starts comparing search element with the first element in the list. If both are matched then result is element found otherwise search element is compared with the next element in the list. Repeat the same until search element is compared with the last element in the list, if that last element also doesn't match, then the result is "Element not found in the list". That means, the search element is compared with element by element in the list.

Linear search is implemented using following steps...

- **Step 1 -** Read the search element from the user.
- **Step 2 -** Compare the search element with the first element in the list.
- **Step 3 -** If both are matched, then display "Given element is found!!!" and terminate the function
- **Step 4 -** If both are not matched, then compare search element with the next element in the list.
- **Step 5 -** Repeat steps 3 and 4 until search element is compared with last element in the list.
- **Step 6 -** If last element in the list also doesn't match, then display "Element is not found!!!" and terminate the function.

Example

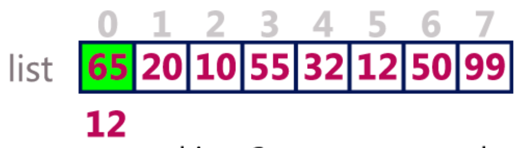
Consider the following list of elements and the element to be searched...



search element **12**

Step 1:

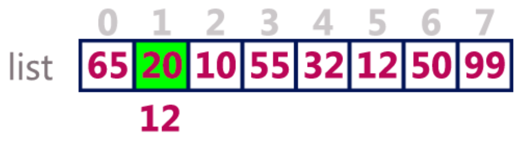
search element (12) is compared with first element (65)



Both are not matching. So move to next element

Step 2:

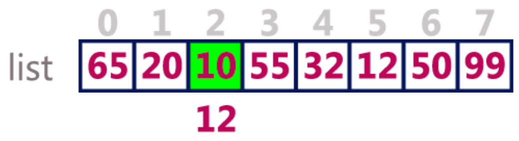
search element (12) is compared with next element (20)



Both are not matching. So move to next element

Step 3:

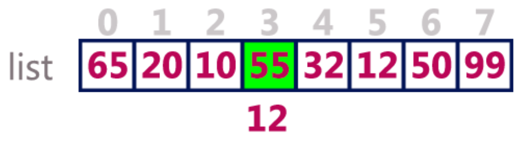
search element (12) is compared with next element (10)



Both are not matching. So move to next element

Step 4:

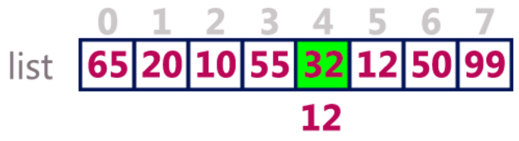
search element (12) is compared with next element (55)



Both are not matching. So move to next element

Step 5:

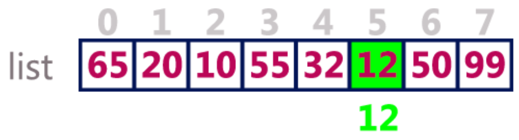
search element (12) is compared with next element (32)



Both are not matching. So move to next element

Step 6:

search element (12) is compared with next element (12)



Both are matching. So we stop comparing and display element found at index 5.

Implementation of Linear Search Algorithm using C Programming Language

```
#include<stdio.h>
#include<conio.h>

void main(){
  int list[20],size,i,sElement;

  printf("Enter size of the list: ");
  scanf("%d",&size);

  printf("Enter any %d integer values: ",size);
  for(i = 0; i < size; i++)
    scanf("%d",&list[i]);

  printf("Enter the element to be Search: ");
  scanf("%d",&sElement);

  // Linear Search Logic
  for(i = 0; i < size; i++)
  {
     if(sElement == list[i])
     {
        printf("Element is found at %d index", i);
        break;
     }
  }
  if(i == size)
     printf("Given element is not found in the list!!!");
  getch();
}
```

Binary Search Algorithm

What is Search?

Search is a process of finding a value in a list of values. In other words, searching is the process of locating given value position in a list of values.

Binary Search Algorithm

Binary search algorithm finds a given element in a list of elements with **O(log n)** time complexity where **n** is total number of elements in the list. The binary search algorithm can be used with only a sorted list of elements. That means the binary search is used only with a list of elements that are already arranged in an order. The binary search can not be used for a list of elements arranged in random order. This search process starts comparing the search element with the middle element in the list. If both are matched, then the result is "element found". Otherwise, we check whether the search element is smaller or larger than the middle element in the list. If the search element is smaller, then we repeat the same process for the left sublist of the middle element. If the search element is larger, then we repeat the same process for the right sublist of the middle element. We repeat this process until we find the search element in the list or until we left with a sublist of only one element. And if that element also doesn't match with the search element, then the result is "Element not found in the list".

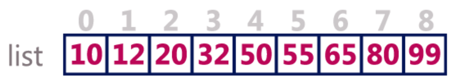
Binary search is implemented using following steps...

- **Step 1 -** Read the search element from the user.
- **Step 2 -** Find the middle element in the sorted list.
- **Step 3 -** Compare the search element with the middle element in the sorted list.
- **Step 4 -** If both are matched, then display "Given element is found!!!" and terminate the function.

- **Step 5 -** If both are not matched, then check whether the search element is smaller or larger than the middle element.
- **Step 6 -** If the search element is smaller than middle element, repeat steps 2, 3, 4 and 5 for the left sublist of the middle element.
- **Step 7 -** If the search element is larger than middle element, repeat steps 2, 3, 4 and 5 for the right sublist of the middle element.
- **Step 8 -** Repeat the same process until we find the search element in the list or until sublist contains only one element.
- **Step 9 - If that element also doesn't match with the search element, then display "Element is not found in the list!!!" and terminate the function.**

Example

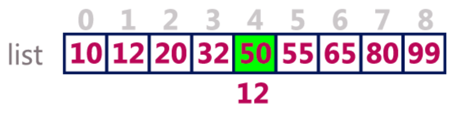
Consider the following list of elements and the element to be searched...



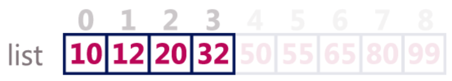
search element **12**

Step 1:

search element (12) is compared with middle element (50)

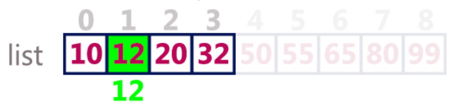


Both are not matching. And 12 is smaller than 50. So we search only in the left sublist (i.e. 10, 12, 20 & 32).



Step 2:

search element (12) is compared with middle element (12)

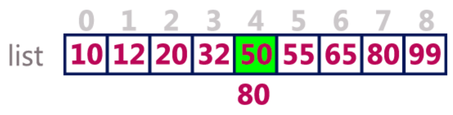


Both are matching. So the result is "Element found at index 1"

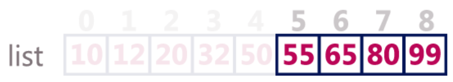
search element **80**

Step 1:

search element (80) is compared with middle element (50)

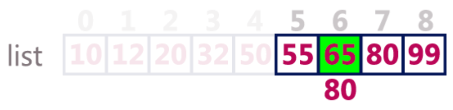


Both are not matching. And 80 is larger than 50. So we search only in the right sublist (i.e. 55, 65, 80 & 99).

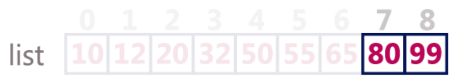


Step 2:

search element (80) is compared with middle element (65)

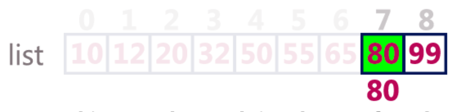


Both are not matching. And 80 is larger than 65. So we search only in the right sublist (i.e. 80 & 99).



Step 3:

search element (80) is compared with middle element (80)



Both are not matching. So the result is "Element found at index 7"

Implementation of Binary Search Algorithm using C Programming Language

```
#include<stdio.h>
#include<conio.h>

void main()
{
   int first, last, middle, size, i, sElement, list[100];
   clrscr();

   printf("Enter the size of the list: ");
   scanf("%d",&size);

   printf("Enter %d integer values in Assending order\n", size);

   for (i = 0; i < size; i++)
      scanf("%d",&list[i]);

   printf("Enter value to be search: ");
   scanf("%d", &sElement);

   first = 0;
   last = size - 1;
   middle = (first+last)/2;

   while (first <= last) {
      if (list[middle] < sElement)
         first = middle + 1;
      else if (list[middle] == sElement) {
         printf("Element found at index %d.\n",middle);
         break;
      }
      else
```

```
         last = middle - 1;

      middle = (first + last)/2;
   }
   if (first > last)
      printf("Element Not found in the list.");
   getch();
}
```

Tree - Terminology

In linear data structure data is organized in sequential order and in non-linear data structure data is organized in random order. A tree is a very popular non-linear data structure used in a wide range of applications. A tree data structure can be defined as follows...

Tree is a non-linear data structure which organizes data in hierarchical structure and this is a recursive definition.

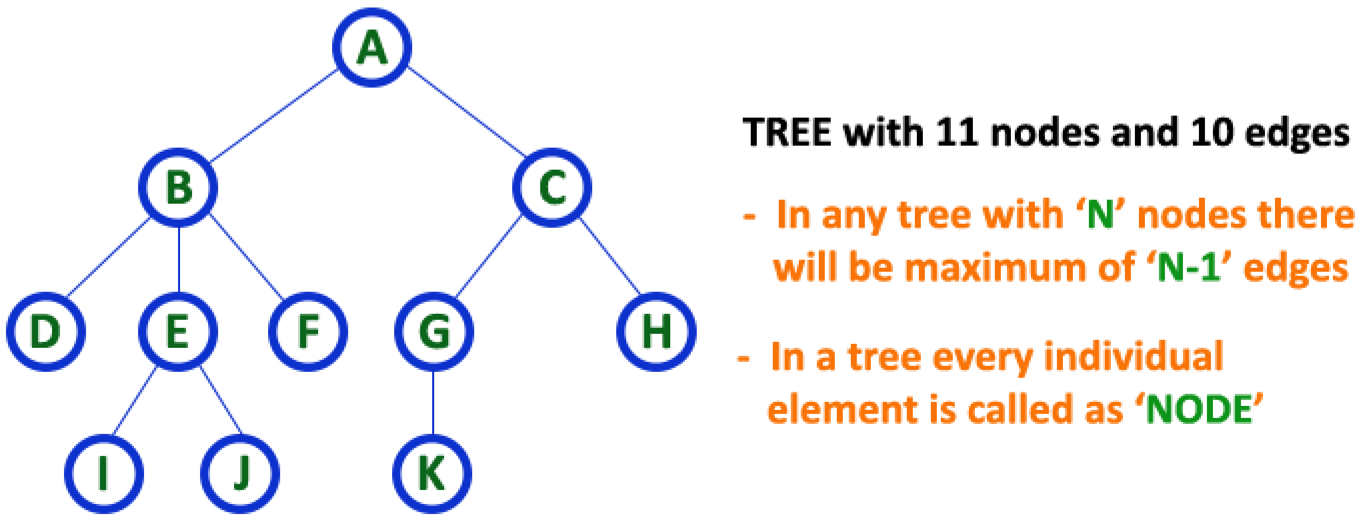
A tree data structure can also be defined as follows...

Tree data structure is a collection of data (Node) which is organized in hierarchical structure recursively

In tree data structure, every individual element is called as **Node**. Node in a tree data structure stores the actual data of that particular element and link to next element in hierarchical structure.

In a tree data structure, if we have **N** number of nodes then we can have a maximum of **N-1** number of links.

Example



TREE with 11 nodes and 10 edges

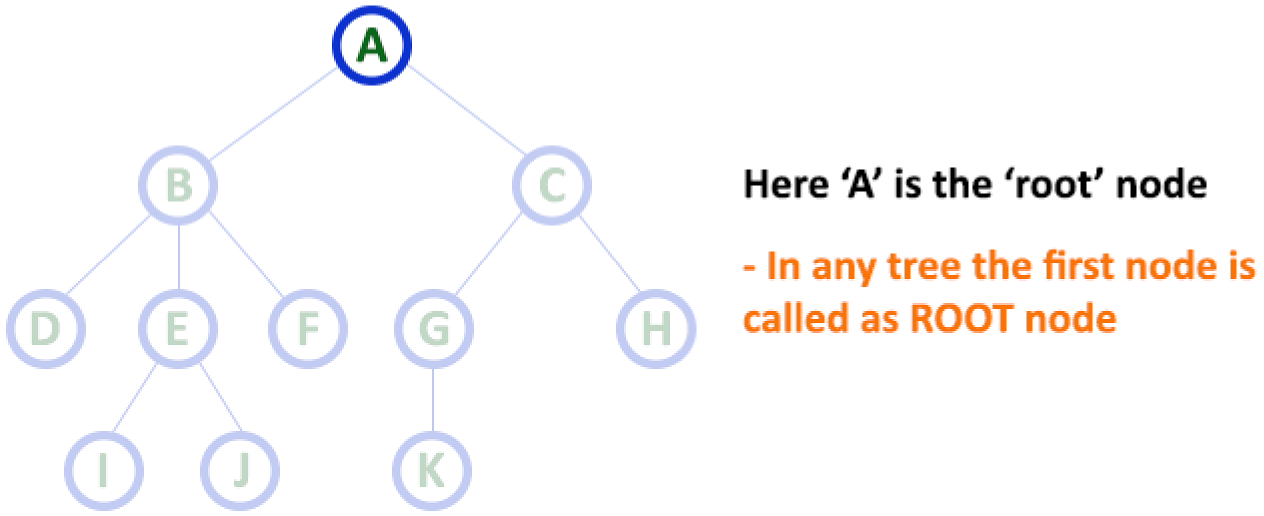
- In any tree with 'N' nodes there will be maximum of 'N-1' edges
- In a tree every individual element is called as 'NODE'

Terminology

In a tree data structure, we use the following terminology...

1. Root

In a tree data structure, the first node is called as **Root Node**. Every tree must have a root node. We can say that the root node is the origin of the tree data structure. In any tree, there must be only one root node. We never have multiple root nodes in a tree.

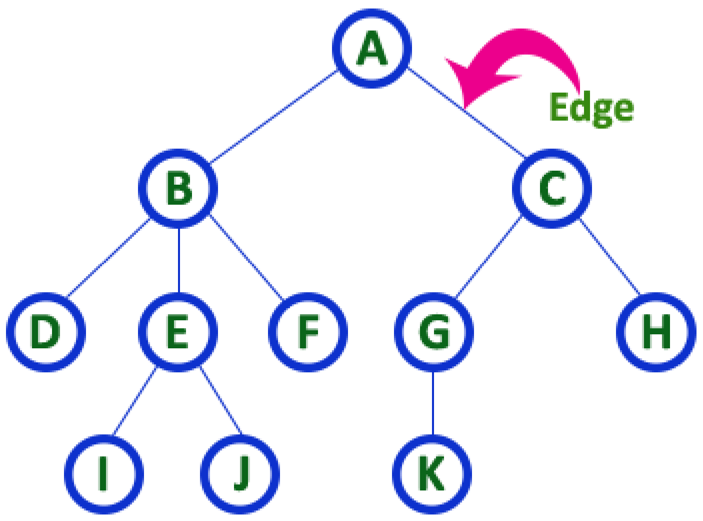


Here 'A' is the 'root' node

- In any tree the first node is called as ROOT node

2. Edge

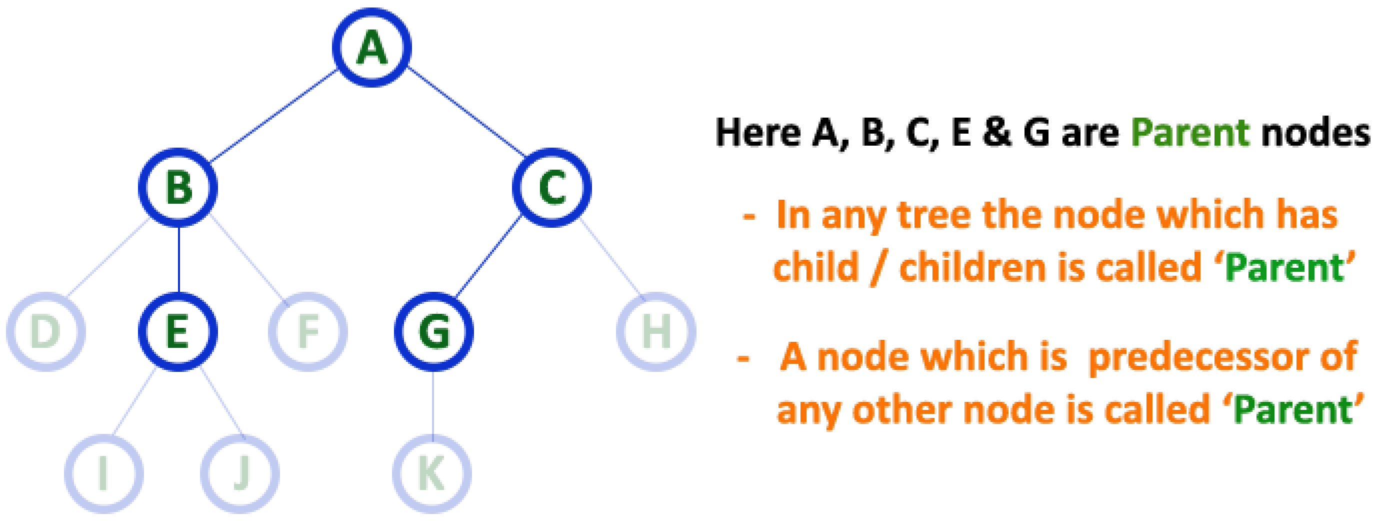
In a tree data structure, the connecting link between any two nodes is called as **EDGE**. In a tree with '**N**' number of nodes there will be a maximum of '**N-1**' number of edges.



- In any tree, 'Edge' is a connecting link between two nodes.

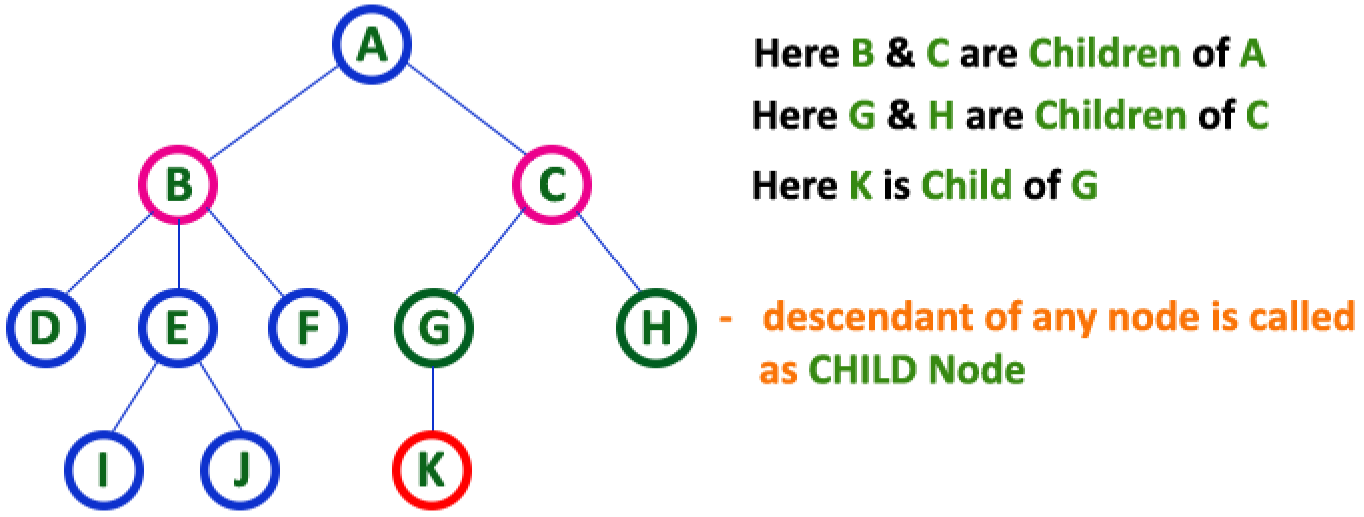
3. Parent

In a tree data structure, the node which is a predecessor of any node is called as **PARENT NODE**. In simple words, the node which has a branch from it to any other node is called a parent node. Parent node can also be defined as "**The node which has child / children**".


A
B
C
D
E
F
G
H
I
J
K
Here A, B, C, E & G are Parent nodes
- In any tree the node which has child / children is called 'Parent'
- A node which is predecessor of any other node is called 'Parent'

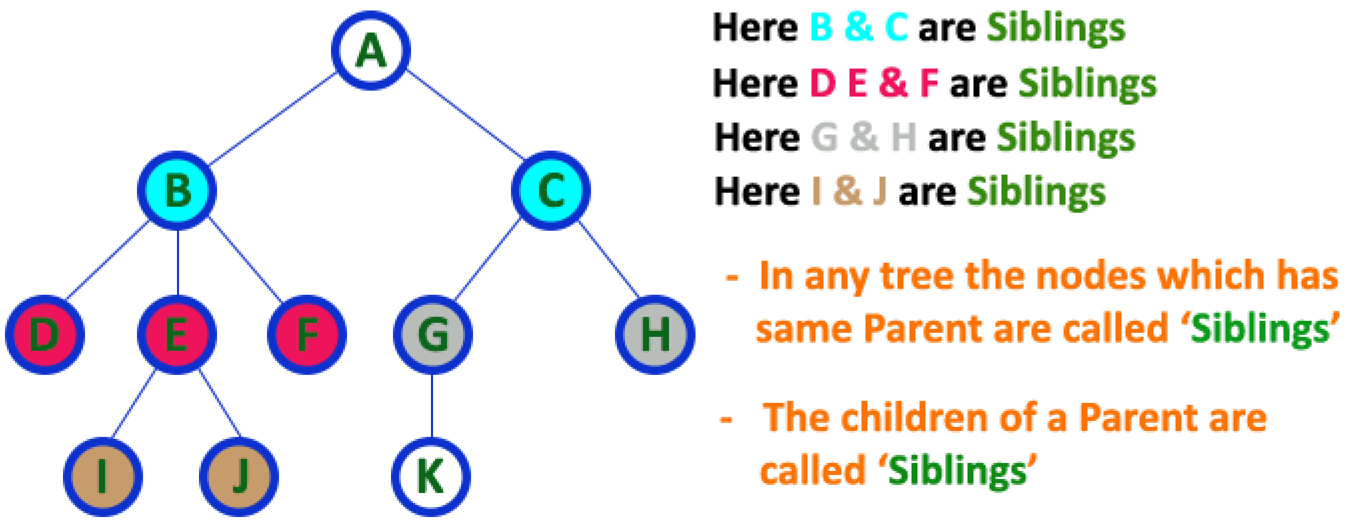
4. Child

In a tree data structure, the node which is descendant of any node is called as **CHILD Node**. In simple words, the node which has a link from its parent node is called as child node. In a tree, any parent node can have any number of child nodes. In a tree, all the nodes except root are child nodes.


A
B
C
D
E
F
G
H
I
J
K
Here B & C are Children of A
Here G & H are Children of C
Here K is Child of G
- descendant of any node is called as CHILD Node

5. Siblings

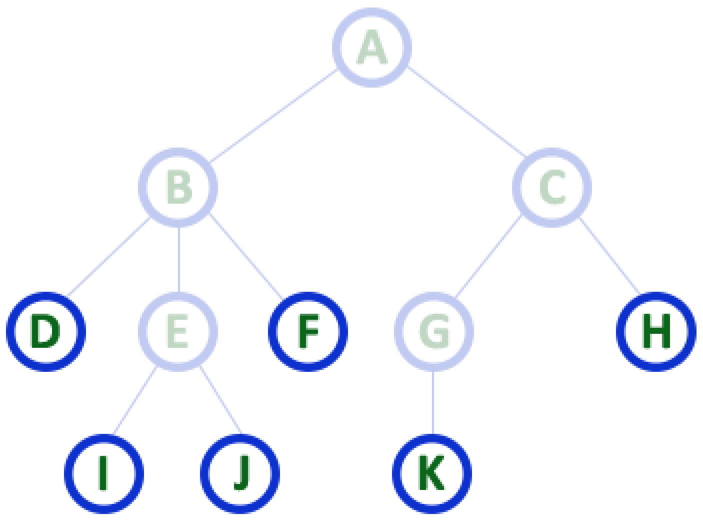
In a tree data structure, nodes which belong to same Parent are called as **SIBLINGS**. In simple words, the nodes with the same parent are called Sibling nodes.


A
B
C
D
E
F
G
H
I
J
K
Here B & C are Siblings
Here D E & F are Siblings
Here G & H are Siblings
Here I & J are Siblings
- In any tree the nodes which has same Parent are called 'Siblings'
- The children of a Parent are called 'Siblings'

6. Leaf

In a tree data structure, the node which does not have a child is called as **LEAF Node**. In simple words, a leaf is a node with no child.

In a tree data structure, the leaf nodes are also called as **External Nodes**. External node is also a node with no child. In a tree, leaf node is also called as '**Terminal**' node.



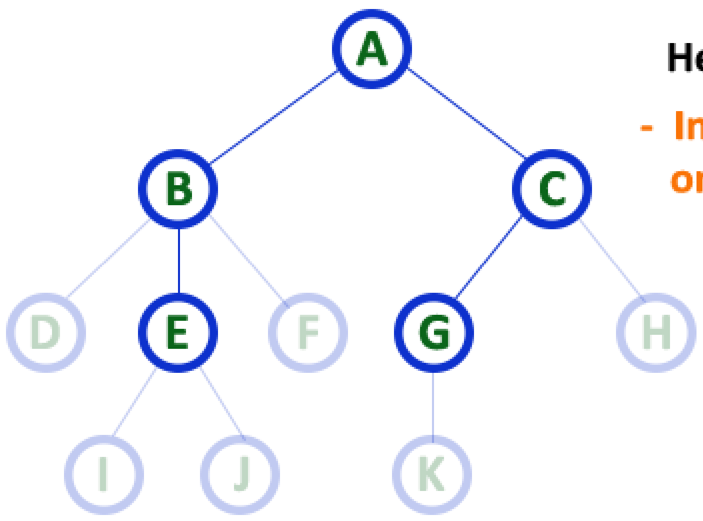
Here D, I, J, F, K & H are Leaf nodes

- In any tree the node which does not have children is called 'Leaf'
- A node without successors is called a 'leaf' node

7. Internal Nodes

In a tree data structure, the node which has atleast one child is called as **INTERNAL Node**. In simple words, an internal node is a node with atleast one child.

In a tree data structure, nodes other than leaf nodes are called as **Internal Nodes**. **The root node is also said to be Internal Node** if the tree has more than one node. Internal nodes are also called as '**Non-Terminal**' nodes.

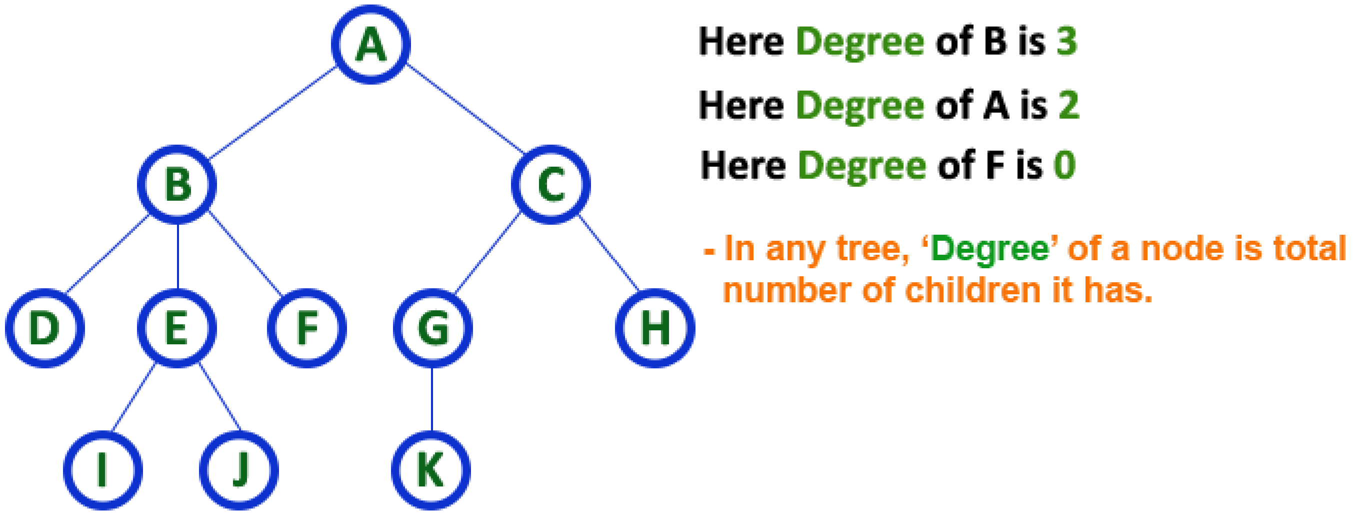


Here A, B, C, E & G are Internal nodes

- In any tree the node which has atleast one child is called 'Internal' node
- Every non-leaf node is called as 'Internal' node

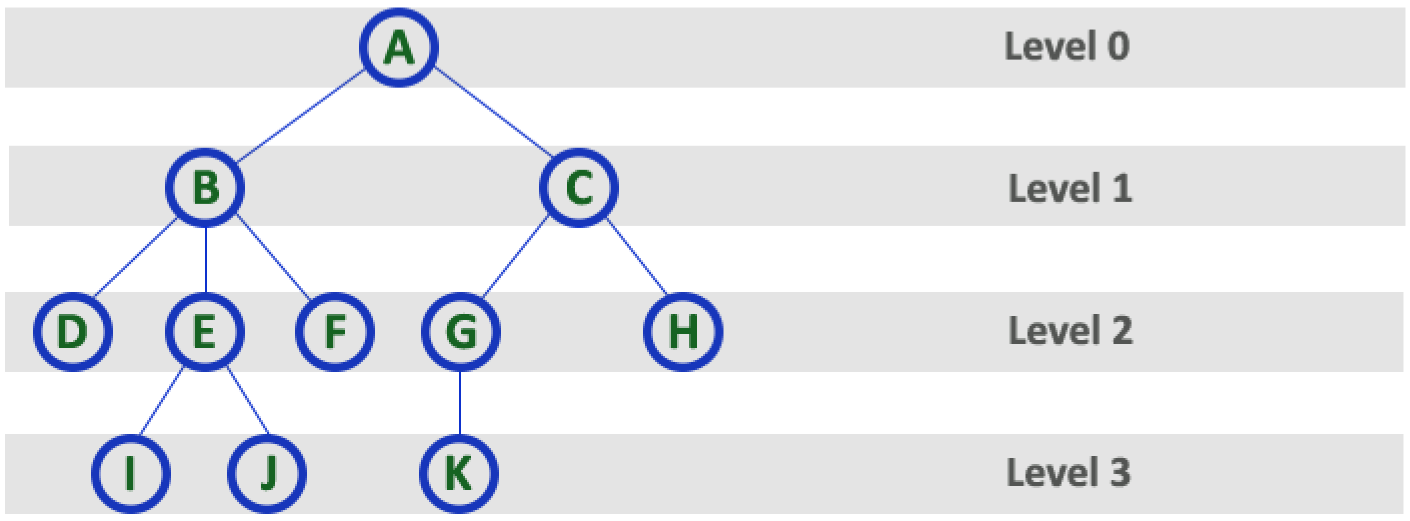
8. Degree

In a tree data structure, the total number of children of a node is called as **DEGREE** of that Node. In simple words, the Degree of a node is total number of children it has. The highest degree of a node among all the nodes in a tree is called as '**Degree of Tree**'



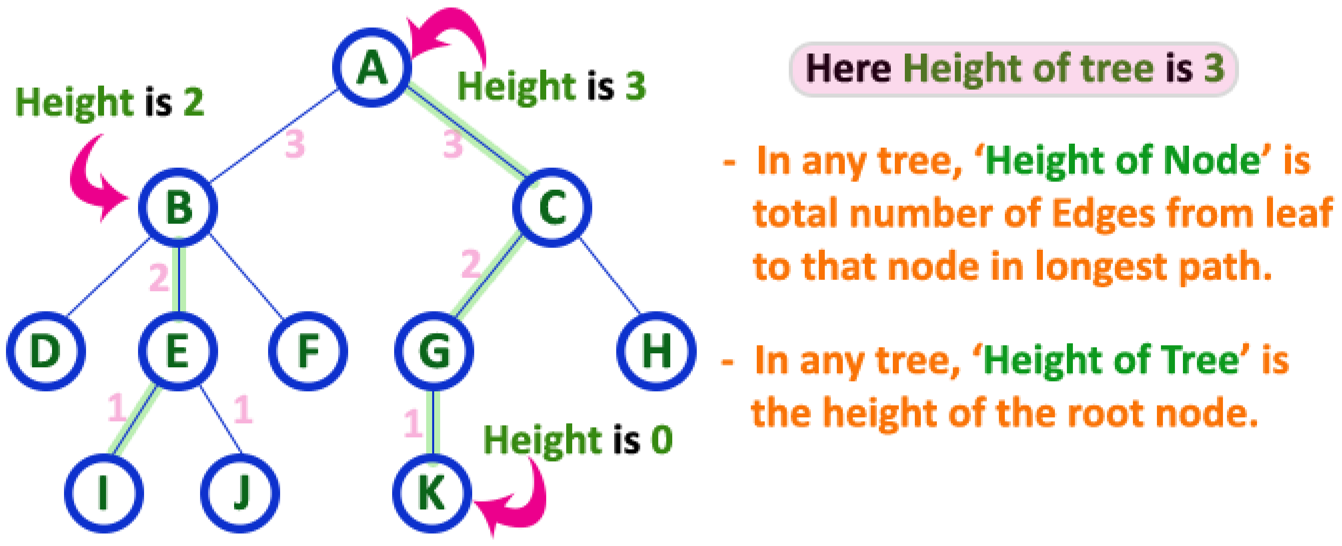
9. Level

In a tree data structure, the root node is said to be at Level 0 and the children of root node are at Level 1 and the children of the nodes which are at Level 1 will be at Level 2 and so on... In simple words, in a tree each step from top to bottom is called as a Level and the Level count starts with '0' and incremented by one at each level (Step).



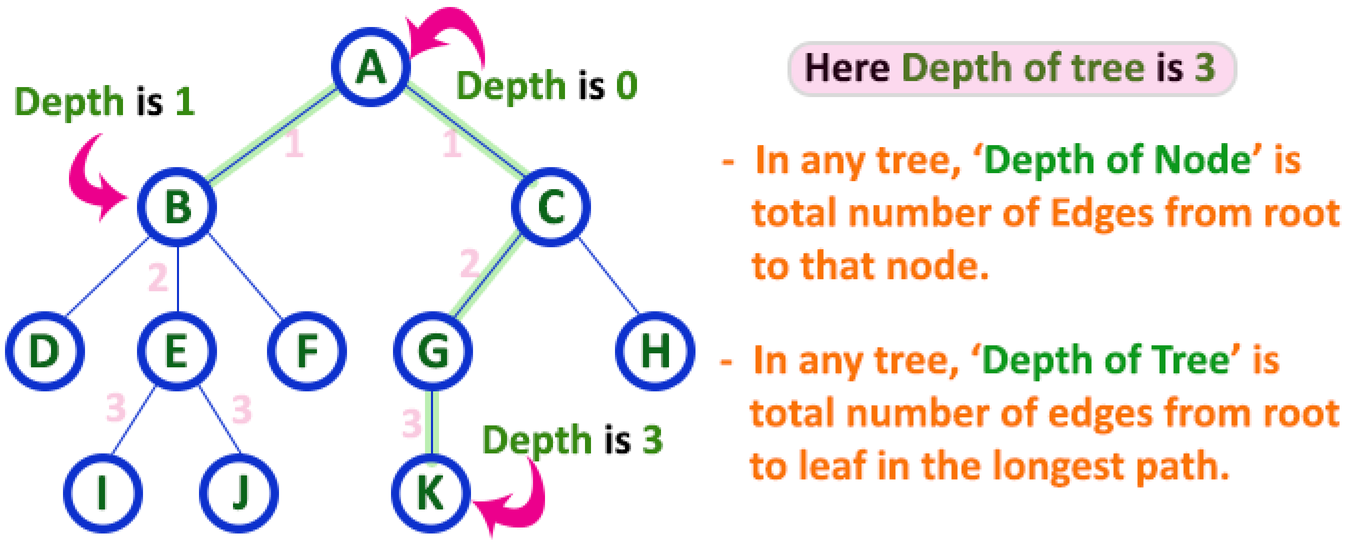
10. Height

In a tree data structure, the total number of edges from leaf node to a particular node in the longest path is called as **HEIGHT** of that Node. In a tree, height of the root node is said to be **height of the tree**. In a tree, **height of all leaf nodes is '0'.**


Here Height of tree is 3
Height is 2
Height is 3
Height is 0
- In any tree, 'Height of Node' is total number of Edges from leaf to that node in longest path.
- In any tree, 'Height of Tree' is the height of the root node.
A
B
C
D
E
F
G
H
I
J
K
3
3
2
2
1
1
1

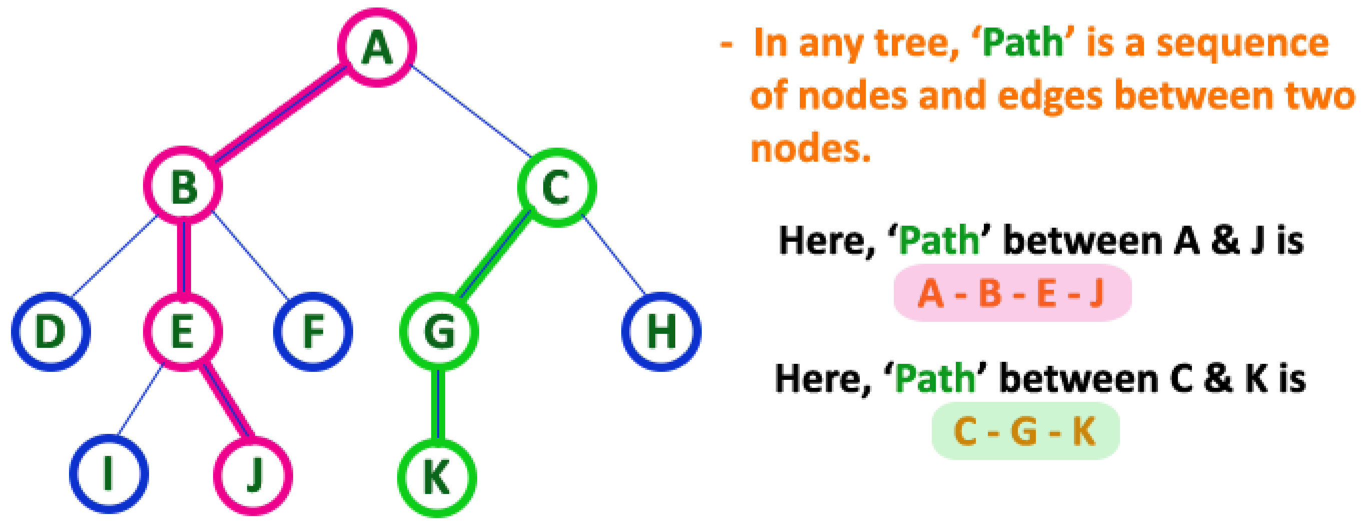
11. Depth

In a tree data structure, the total number of egdes from root node to a particular node is called as **DEPTH** of that Node. In a tree, the total number of edges from root node to a leaf node in the longest path is said to be **Depth of the tree**. In simple words, the highest depth of any leaf node in a tree is said to be depth of that tree. In a tree, **depth of the root node is '0'.**


Depth is 1
Depth is 0
Depth is 3
Here Depth of tree is 3
A
B
C
D
E
F
G
H
I
J
K
1
1
2
2
3
3
3
- In any tree, 'Depth of Node' is total number of Edges from root to that node.
- In any tree, 'Depth of Tree' is total number of edges from root to leaf in the longest path.

12. Path

In a tree data structure, the sequence of Nodes and Edges from one node to another node is called as **PATH** between that two Nodes. **Length of a Path** is total number of nodes in that path. In below example **the path A - B - E - J has length 4**.



- In any tree, 'Path' is a sequence of nodes and edges between two nodes.

Here, 'Path' between A & J is

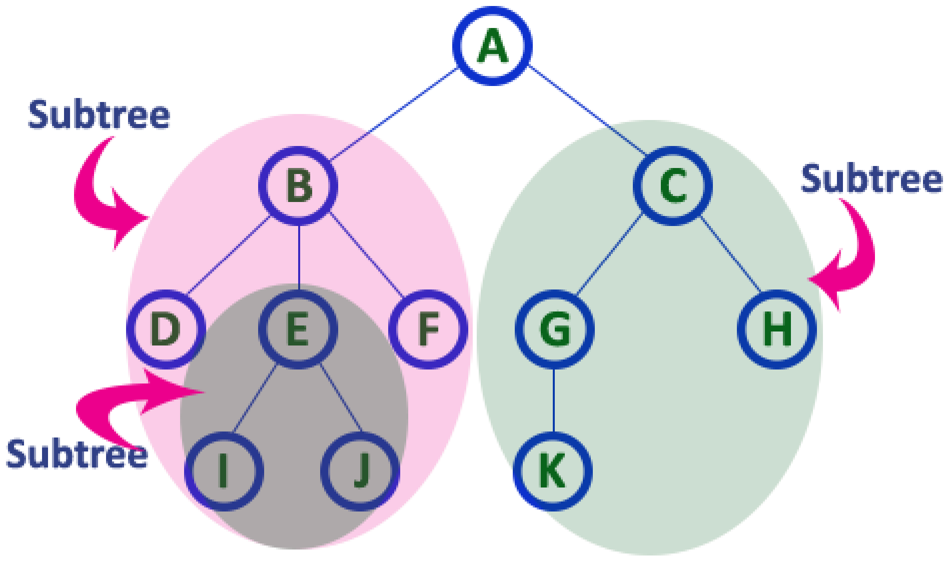
A - B - E - J

Here, 'Path' between C & K is

C - G - K

13. Sub Tree

In a tree data structure, each child from a node forms a subtree recursively. Every child node will form a subtree on its parent node.

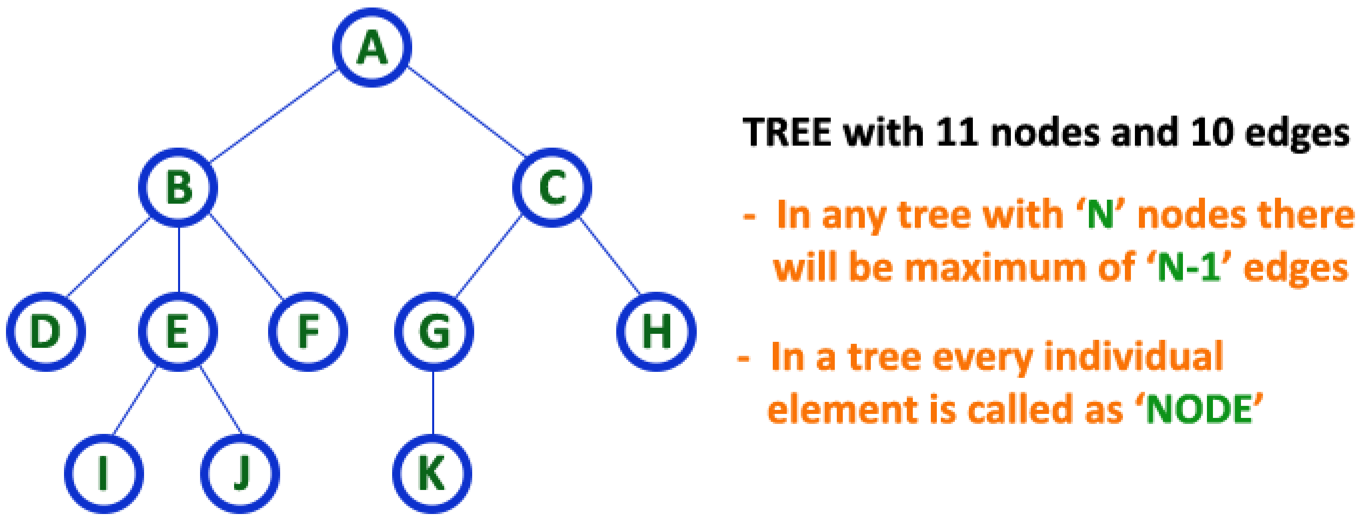


Tree Representations

A tree data structure can be represented in two methods. Those methods are as follows...

1. **List Representation**
2. **Left Child - Right Sibling Representation**

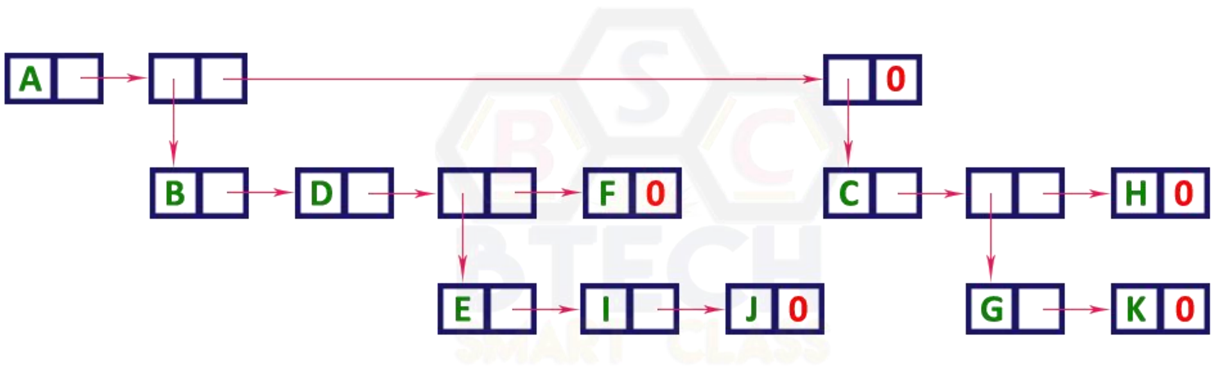
Consider the following tree...


A
B
C
D
E
F
G
H
I
J
K
TREE with 11 nodes and 10 edges
- In any tree with 'N' nodes there will be maximum of 'N-1' edges
- In a tree every individual element is called as 'NODE'

1. List Representation

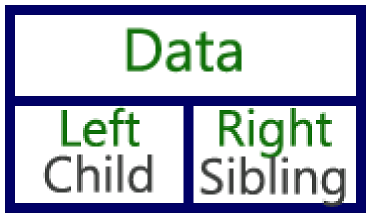
In this representation, we use two types of nodes one for representing the node with data called 'data node' and another for representing only references called 'reference node'. We start with a 'data node' from the root node in the tree. Then it is linked to an internal node through a 'reference node' which is further linked to any other node directly. This process repeats for all the nodes in the tree.

The above example tree can be represented using List representation as follows...



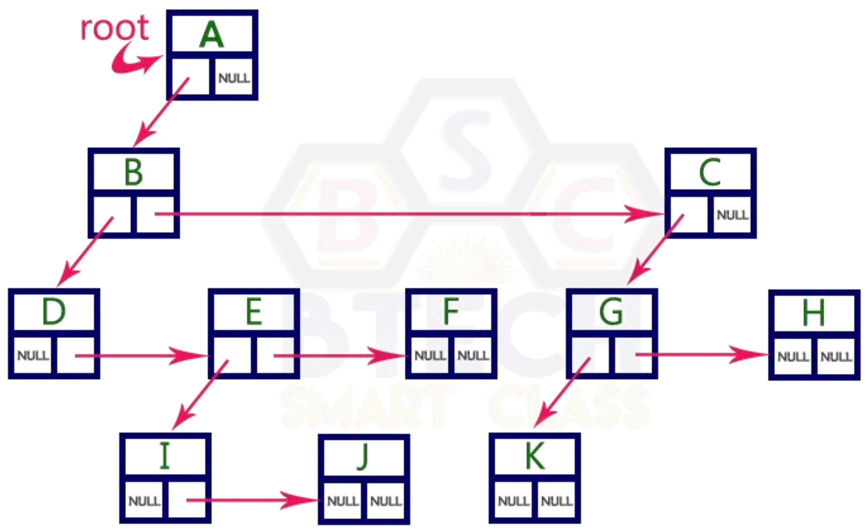
2. Left Child - Right Sibling Representation

In this representation, we use a list with one type of node which consists of three fields namely Data field, Left child reference field and Right sibling reference field. Data field stores the actual value of a node, left reference field stores the address of the left child and right reference field stores the address of the right sibling node. Graphical representation of that node is as follows...



In this representation, every node's data field stores the actual value of that node. If that node has left a child, then left reference field stores the address of that left child node otherwise stores NULL. If that node has the right sibling, then right reference field stores the address of right sibling node otherwise stores NULL.

The above example tree can be represented using Left Child - Right Sibling representation as follows...



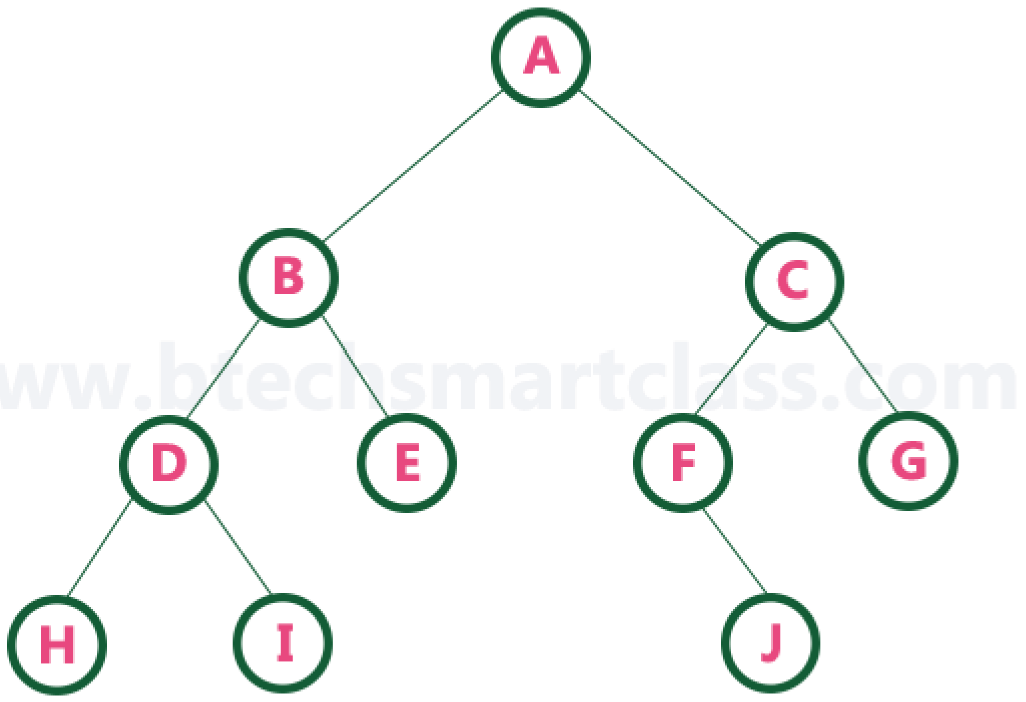
Binary Tree Datastructure

In a normal tree, every node can have any number of children. A binary tree is a special type of tree data structure in which every node can have a **maximum of 2 children**. One is known as a left child and the other is known as right child.

A tree in which every node can have a maximum of two children is called Binary Tree.

In a binary tree, every node can have either 0 children or 1 child or 2 children but not more than 2 children.

Example



There are different types of binary trees and they are...

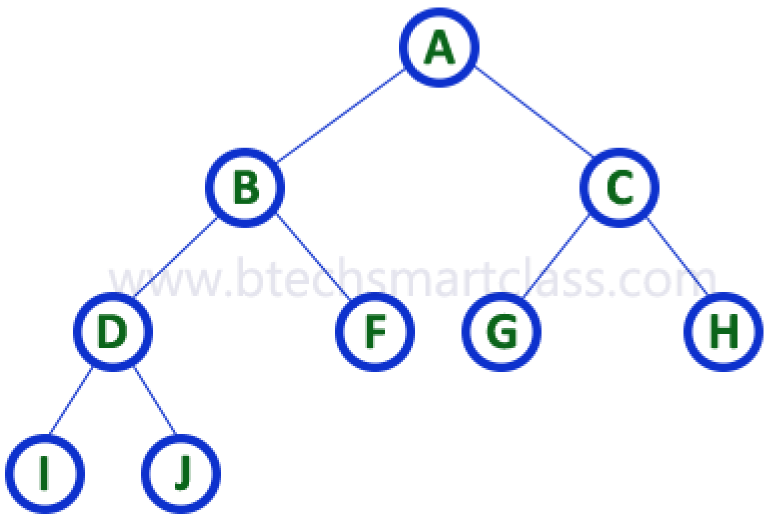
1. Strictly Binary Tree

In a binary tree, every node can have a maximum of two children. But in strictly binary tree, every node should have exactly two children or none. That means every internal node must have exactly two children. A strictly Binary Tree can be defined as follows...

A binary tree in which every node has either two or zero number of children is called Strictly Binary Tree

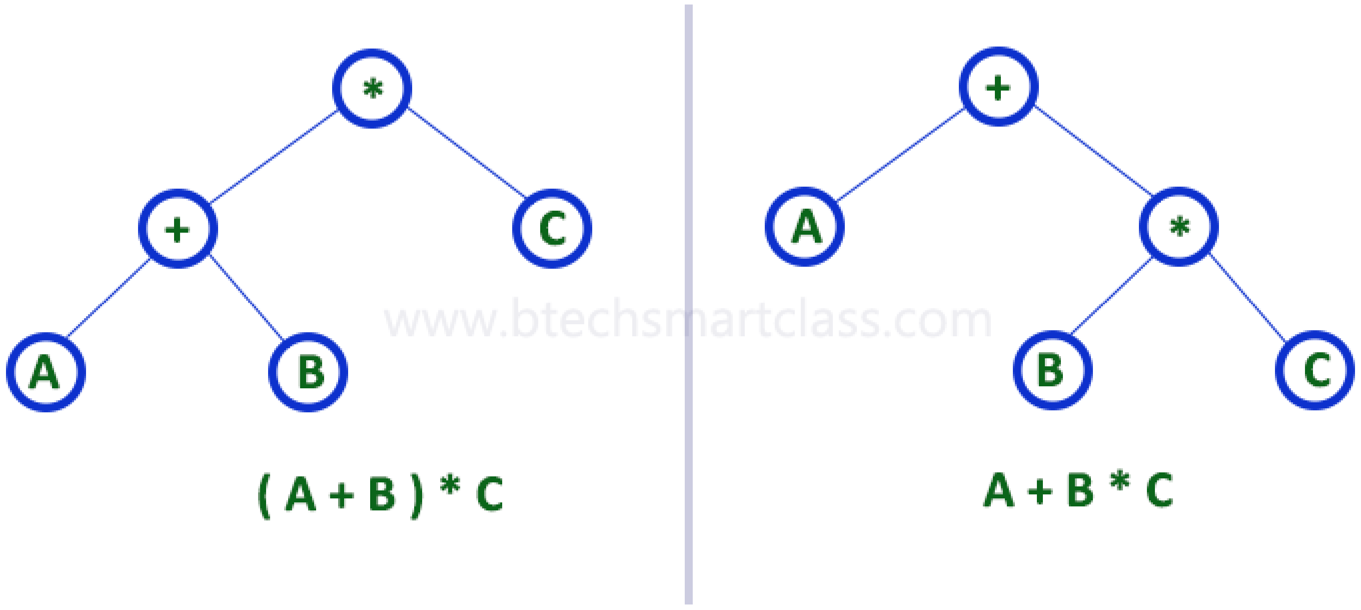
---

Strictly binary tree is also called as **Full Binary Tree** or **Proper Binary Tree** or **2-Tree**



Strictly binary tree data structure is used to represent mathematical expressions.

Example

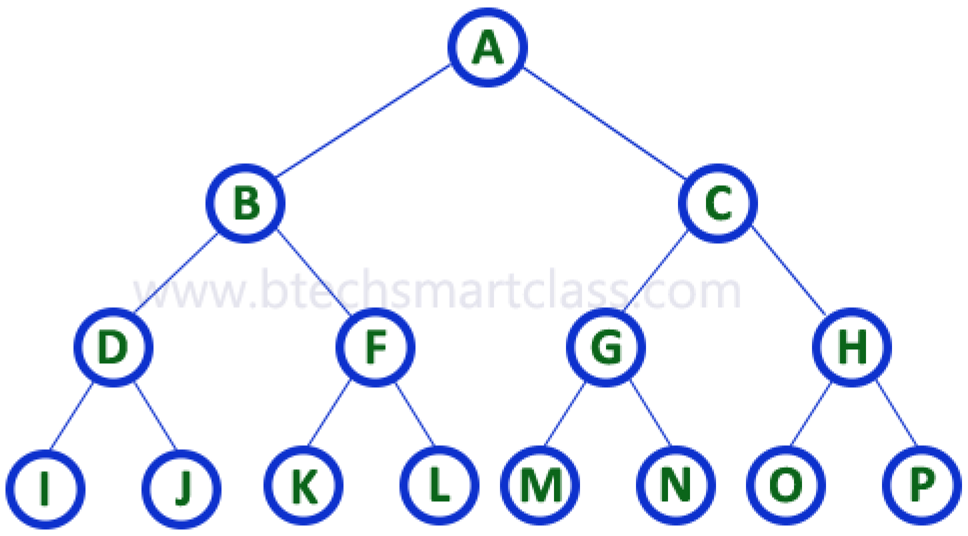


2. Complete Binary Tree

In a binary tree, every node can have a maximum of two children. But in strictly binary tree, every node should have exactly two children or none and in complete binary tree all the nodes must have exactly two children and at every level of complete binary tree there must be 2^{level} number of nodes. For example at level 2 there must be $2^2 = 4$ nodes and at level 3 there must be $2^3 = 8$ nodes.

A binary tree in which every internal node has exactly two children and all leaf nodes are at same level is called Complete Binary Tree.

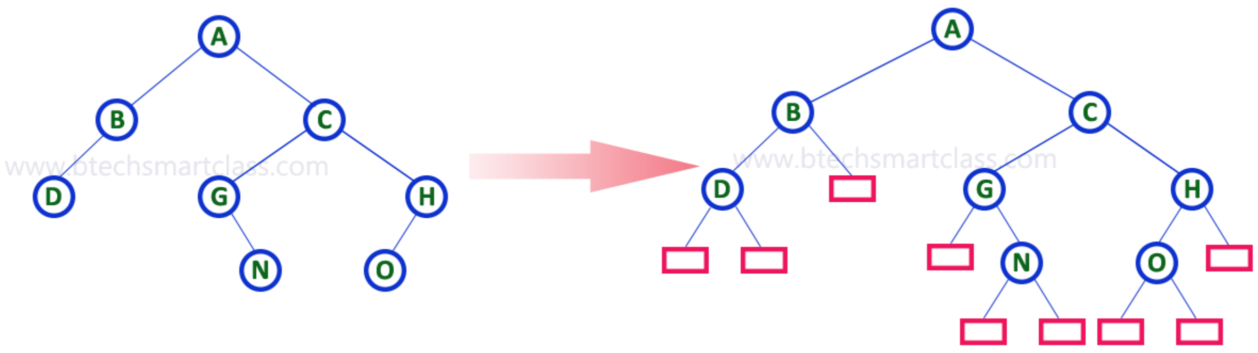
Complete binary tree is also called as **Perfect Binary Tree**



3. Extended Binary Tree

A binary tree can be converted into Full Binary tree by adding dummy nodes to existing nodes wherever required.

The full binary tree obtained by adding dummy nodes to a binary tree is called as Extended Binary Tree.



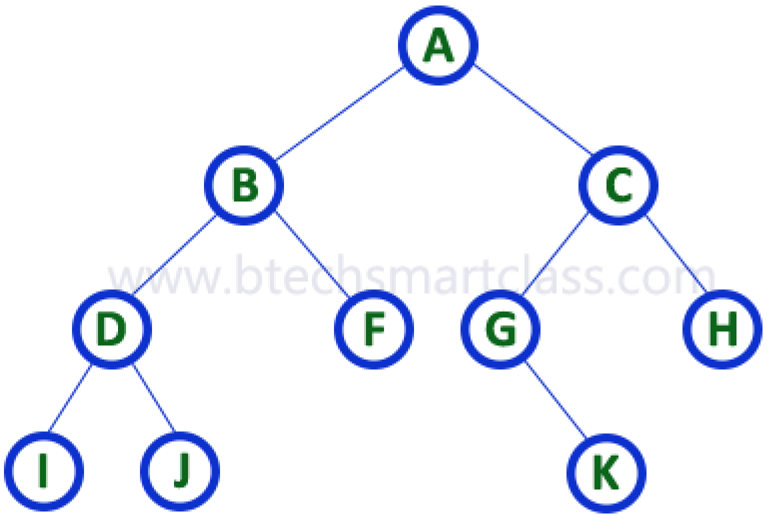
In above figure, a normal binary tree is converted into full binary tree by adding dummy nodes (In pink colour).

Binary Tree Representations

A binary tree data structure is represented using two methods. Those methods are as follows...

1. **Array Representation**
2. **Linked List Representation**

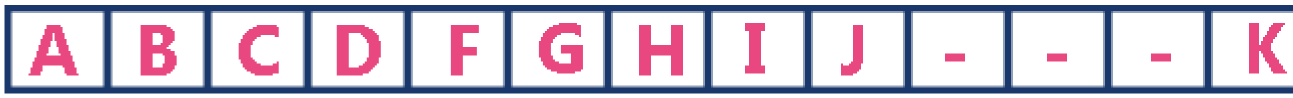
Consider the following binary tree...



1. Array Representation of Binary Tree

In array representation of a binary tree, we use one-dimensional array (1-D Array) to represent a binary tree.

Consider the above example of a binary tree and it is represented as follows...

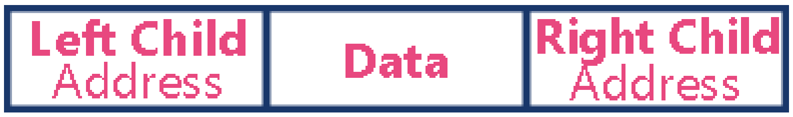


To represent a binary tree of depth **'n'** using array representation, we need one dimensional array with a maximum size of **2n + 1**.

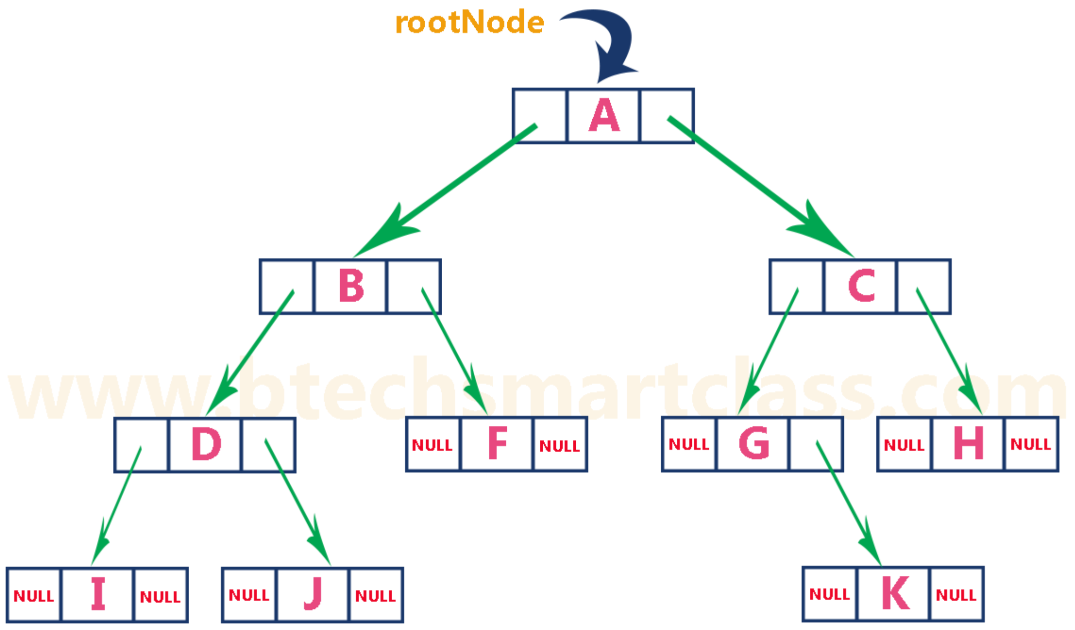
2. Linked List Representation of Binary Tree

We use a double linked list to represent a binary tree. In a double linked list, every node consists of three fields. First field for storing left child address, second for storing actual data and third for storing right child address.

In this linked list representation, a node has the following structure...



The above example of the binary tree represented using Linked list representation is shown as follows...



Binary Tree Traversals

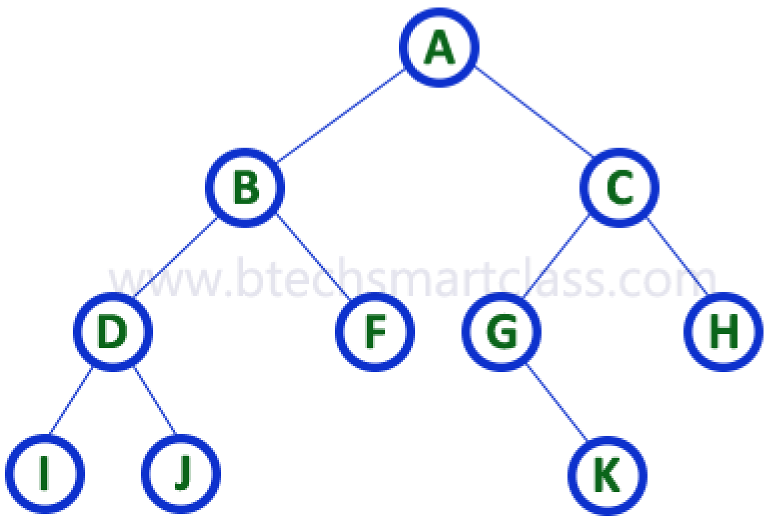
When we wanted to display a binary tree, we need to follow some order in which all the nodes of that binary tree must be displayed. In any binary tree, displaying order of nodes depends on the traversal method.

Displaying (or) visiting order of nodes in a binary tree is called as Binary Tree Traversal.

There are three types of binary tree traversals.

1. **In - Order Traversal**
2. **Pre - Order Traversal**
3. **Post - Order Traversal**

Consider the following binary tree...



1. In - Order Traversal (leftChild - root - rightChild)

In In-Order traversal, the root node is visited between the left child and right child. In this traversal, the left child node is visited first, then the root node is visited and later we go for visiting the right child node. This in-order traversal is applicable for every root node of all subtrees in the tree. This is performed recursively for all nodes in the tree.
In the above example of a binary tree, first we try to visit left child of root node 'A', but A's left child 'B' is a root node for left subtree. so we try to visit its (B's) left child 'D' and again D is a root for subtree with nodes D, I and J. So we try to visit its left child 'I' and it is the leftmost child. So first we visit **'I'** then go for its root node **'D'** and later we visit D's right child **'J'**. With this we have completed the left part of node B. Then visit **'B'** and next B's right child **'F'** is visited. With this we have completed left part of node A. Then visit root node **'A'**. With this we have completed left and root parts of node A. Then we go for the right part of the node A. In right of A again there is a subtree with root C. So go for left child of C and again it is a subtree with root G. But G does not have left part so we visit **'G'** and then visit G's right child K. With this we have completed the left part of node C. Then visit root node **'C'** and next visit C's right child **'H'** which is the rightmost child in the tree. So we stop the process.

That means here we have visited in the order of **I - D - J - B - F - A - G - K - C - H** using In-Order Traversal.

In-Order Traversal for above example of binary tree is

$$I - D - J - B - F - A - G - K - C - H$$

2. Pre - Order Traversal (root - leftChild - rightChild)

In Pre-Order traversal, the root node is visited before the left child and right child nodes. In this traversal, the root node is visited first, then its left child and later its right child. This pre-order traversal is applicable for every root node of all subtrees in the tree. In the above example of binary tree, first we visit root node **'A'** then visit its left child **'B'** which is a root for D and F. So we visit B's left child **'D'** and again D is a root for I and J. So we visit D's left child **'I'** which is the leftmost child. So next we go for visiting D's right child **'J'**. With this we have completed root, left and right parts of node D and root, left parts of node B. Next visit B's right child **'F'**. With this we have completed root and left parts of node A. So we go for A's right child **'C'** which is a root node for G and H. After visiting C, we go for its left child **'G'** which is a root for node K. So next we visit left of G, but it does not have left child so we go for G's right child **'K'**. With this, we have completed node C's root and left parts. Next visit C's right child **'H'** which is the rightmost child in the tree. So we stop the process.

That means here we have visited in the order of **A-B-D-I-J-F-C-G-K-H** using Pre-Order Traversal.

Pre-Order Traversal for above example binary tree is

$$A - B - D - I - J - F - C - G - K - H$$

3. Post - Order Traversal (leftChild - rightChild - root)

In Post-Order traversal, the root node is visited after left child and right child. In this traversal, left child node is visited first, then its right child and then its root node. This is recursively performed until the right most node is visited.

Here we have visited in the order of **I - J - D - F - B - K - G - H - C - A** using Post-Order Traversal.

Post-Order Traversal for above example binary tree is

$$I - J - D - F - B - K - G - H - C - A$$

Program to Create Binary Tree and display using In-Order Traversal - C Programming

```
#include<stdio.h>
#include<conio.h>

struct Node{
   int data;
   struct Node *left;
   struct Node *right;
};

struct Node *root = NULL;
int count = 0;

struct Node* insert(struct Node*, int);
void display(struct Node*);
void main(){
   int choice, value;
   clrscr();
   printf("\n----- Binary Tree -----\n");
   while(1){
      printf("\n***** MENU *****\n");
      printf("1. Insert\n2. Display\n3. Exit");
      printf("\nEnter your choice: ");
      scanf("%d",&choice);
      switch(choice){
         case 1: printf("\nEnter the value to be insert: ");
                 scanf("%d", &value);
                 root = insert(root,value);
                 break;
         case 2: display(root); break;
         case 3: exit(0);
         default: printf("\nPlease select correct operations!!!\n");
      }
   }
}

struct Node* insert(struct Node *root,int value){
   struct Node *newNode;
   newNode = (struct Node*)malloc(sizeof(struct Node));
   newNode->data = value;
   if(root == NULL){
      newNode->left = newNode->right = NULL;
      root = newNode;
      count++;
   }
   else{
      if(count%2 != 0)
         root->left = insert(root->left,value);
      else
         root->right = insert(root->right,value);
   }
   return root;
}
// display is performed by using Inorder Traversal
void display(struct Node *root)
{
   if(root != NULL){
      display(root->left);
      printf("%d\t",root->data);
      display(root->right);
   }
}
```

Threaded Binary Trees

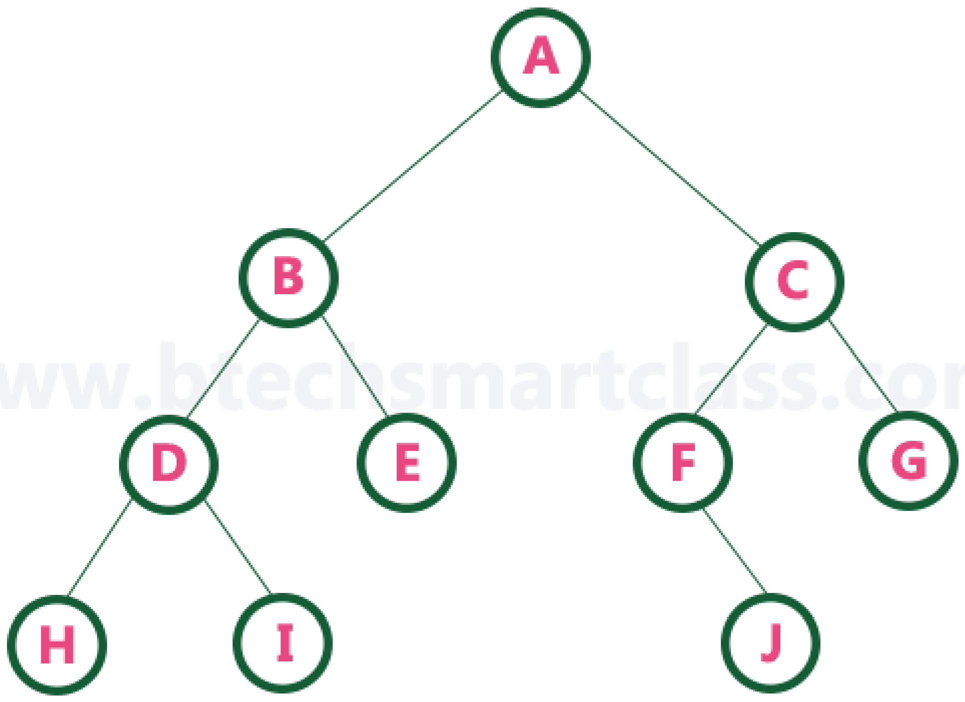
A binary tree can be represented using array representation or linked list representation. When a binary tree is represented using linked list representation, the reference part of the node which doesn't have a child is filled with a NULL pointer. In any binary tree linked list representation, there is a number of NULL pointers than actual pointers. Generally, in any binary tree linked list representation, if there are **2N** number of reference fields, then **N+1** number of reference fields are filled with NULL (**N+1 are NULL out of 2N**). This NULL pointer does not play any role except indicating that there is no link (no child).

A. J. Perlis and C. Thornton have proposed new binary tree called "***Threaded Binary Tree***", which makes use of NULL pointers to improve its traversal process. In a threaded binary tree, NULL pointers are replaced by references of other nodes in the tree. These extra references are called as ***threads***.

Threaded Binary Tree is also a binary tree in which all left child pointers that are NULL (in Linked list representation) points to its in-order predecessor, and all right child pointers that are NULL (in Linked list representation) points to its in-order successor.

If there is no in-order predecessor or in-order successor, then it points to the root node.

Consider the following binary tree...



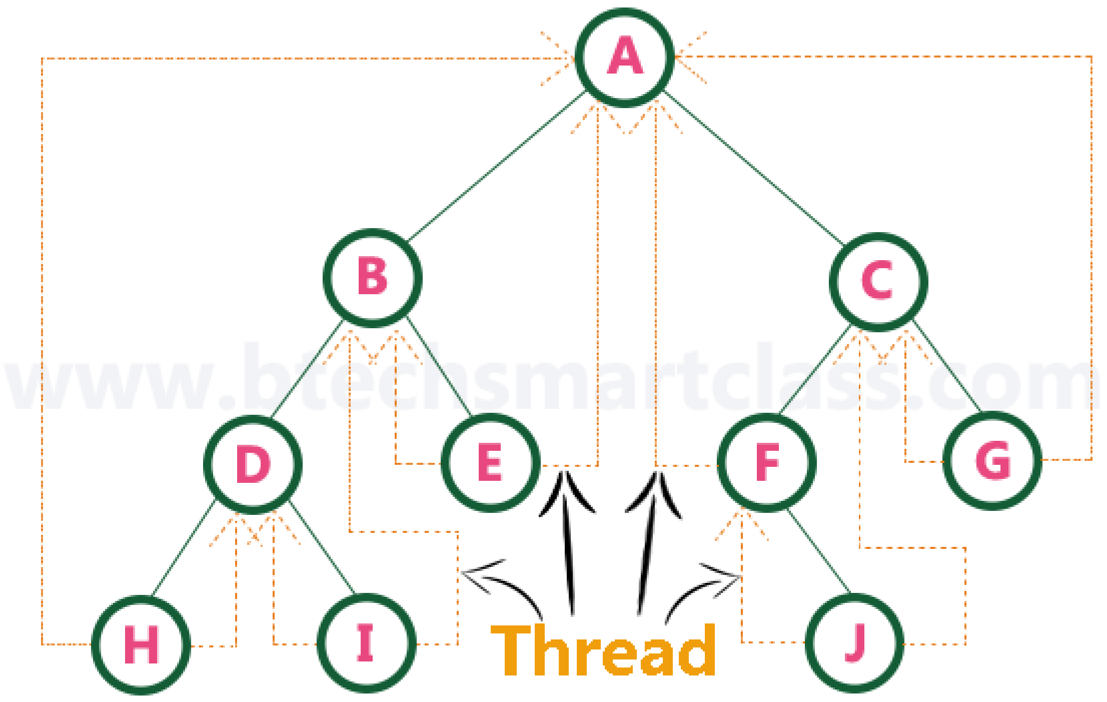
To convert the above example binary tree into a threaded binary tree, first find the in-order traversal of that tree...

In-order traversal of above binary tree...

$$H - D - I - B - E - A - F - J - C - G$$

When we represent the above binary tree using linked list representation, nodes **H, I, E, F, J** and **G** left child pointers are NULL. This NULL is replaced by address of its in-order predecessor respectively (I to D, E to B, F to A, J to F and G to C), but here the node H does not have its in-order predecessor, so it points to the root node A. And nodes **H, I, E, J** and **G** right child pointers are NULL. These NULL pointers are replaced by address of its in-order successor respectively (H to D, I to B, E to A, and J to C), but here the node G does not have its in-order successor, so it points to the root node A.

Above example binary tree is converted into threaded binary tree as follows.



In the above figure, threads are indicated with dotted links.

Binary Search Tree

In a binary tree, every node can have a maximum of two children but there is no need to maintain the order of nodes basing on their values. In a binary tree, the elements are arranged in the order they arrive at the tree from top to bottom and left to right.

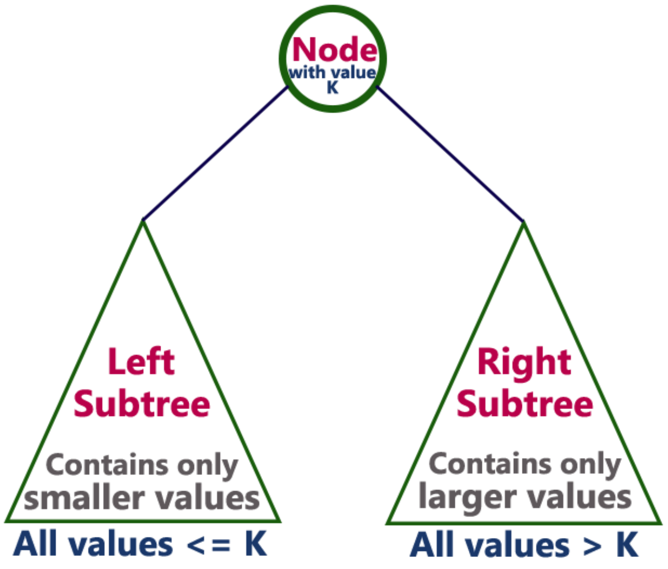
A binary tree has the following time complexities...

1. **Search Operation - O(n)**
2. **Insertion Operation - O(1)**
3. **Deletion Operation - O(n)**

To enhance the performance of binary tree, we use a special type of binary tree known as **Binary Search Tree**. Binary search tree mainly focuses on the search operation in a binary tree. Binary search tree can be defined as follows...

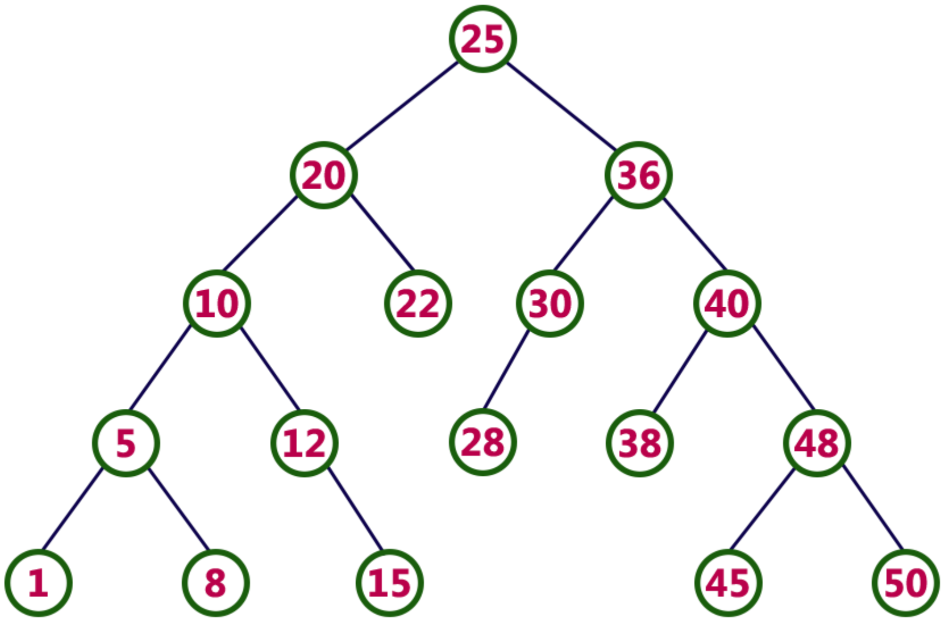
Binary Search Tree is a binary tree in which every node contains only smaller values in its left subtree and only larger values in its right subtree.

In a binary search tree, all the nodes in the left subtree of any node contains smaller values and all the nodes in the right subtree of any node contains larger values as shown in the following figure...



Example

The following tree is a Binary Search Tree. In this tree, left subtree of every node contains nodes with smaller values and right subtree of every node contains larger values.



Every binary search tree is a binary tree but every binary tree need not to be binary search tree.

Operations on a Binary Search Tree

The following operations are performed on a binary search tree...

1. **Search**
2. **Insertion**
3. **Deletion**

Search Operation in BST

In a binary search tree, the search operation is performed with **O(log n)** time complexity. The search operation is performed as follows...

- **Step 1 -** Read the search element from the user.
- **Step 2 -** Compare the search element with the value of root node in the tree.
- **Step 3 -** If both are matched, then display "Given node is found!!!" and terminate the function
- **Step 4 -** If both are not matched, then check whether search element is smaller or larger than that node value.
- **Step 5 -** If search element is smaller, then continue the search process in left subtree.
- **Step 6-** If search element is larger, then continue the search process in right subtree.
- **Step 7 -** Repeat the same until we find the exact element or until the search element is compared with the leaf node
- **Step 8 -** If we reach to the node having the value equal to the search value then display "Element is found" and terminate the function.

- **Step 9 -** If we reach to the leaf node and if it is also not matched with the search element, then display "Element is not found" and terminate the function.

Insertion Operation in BST

In a binary search tree, the insertion operation is performed with **O(log n)** time complexity. In binary search tree, new node is always inserted as a leaf node. The insertion operation is performed as follows...

- **Step 1 -** Create a newNode with given value and set its **left** and **right** to **NULL**.
- **Step 2 -** Check whether tree is Empty.
- **Step 3 -** If the tree is **Empty**, then set **root** to **newNode**.
- **Step 4 -** If the tree is **Not Empty**, then check whether the value of newNode is **smaller** or **larger** than the node (here it is root node).
- **Step 5 -** If newNode is **smaller** than **or equal** to the node then move to its **left** child. If newNode is **larger** than the node then move to its **right** child.
- **Step 6-** Repeat the above steps until we reach to the **leaf** node (i.e., reaches to NULL).
- **Step 7 -** After reaching the leaf node, insert the newNode as **left child** if the newNode is **smaller or equal** to that leaf node or else insert it as **right child**.

Deletion Operation in BST

In a binary search tree, the deletion operation is performed with **O(log n)** time complexity. Deleting a node from Binary search tree includes following three cases...

- **Case 1: Deleting a Leaf node (A node with no children)**
- **Case 2: Deleting a node with one child**
- **Case 3: Deleting a node with two children**

Case 1: Deleting a leaf node

We use the following steps to delete a leaf node from BST...

- **Step 1 - Find** the node to be deleted using **search operation**
- **Step 2 -** Delete the node using **free** function (If it is a leaf) and terminate the function.

Case 2: Deleting a node with one child

We use the following steps to delete a node with one child from BST...

- **Step 1 - Find** the node to be deleted using **search operation**
- **Step 2 -** If it has only one child then create a link between its parent node and child node.
- **Step 3 -** Delete the node using **free** function and terminate the function.

Case 3: Deleting a node with two children

We use the following steps to delete a node with two children from BST...

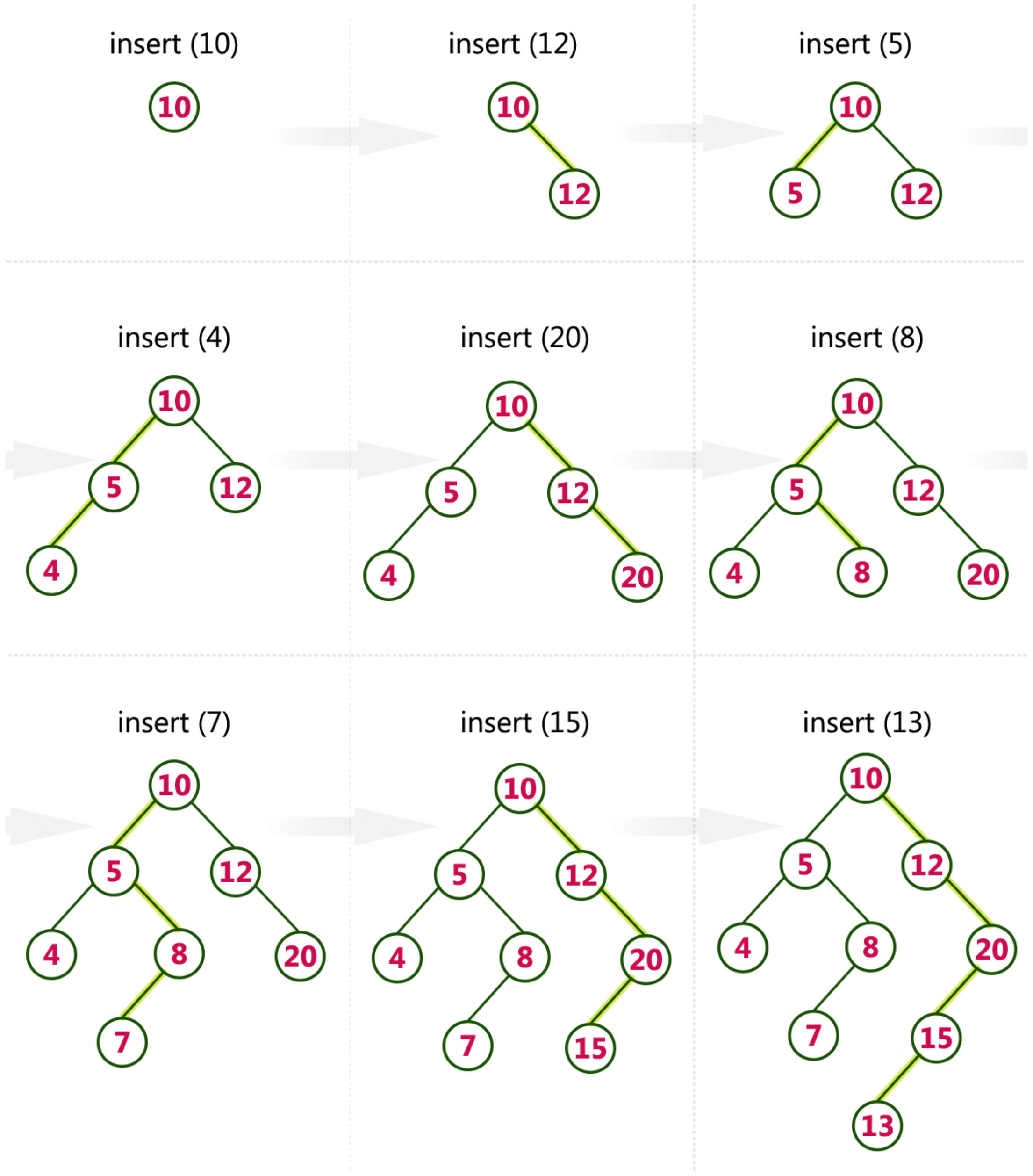
- **Step 1 - Find** the node to be deleted using **search operation**
- **Step 2 -** If it has two children, then find the **largest** node in its **left subtree** (OR) the **smallest** node in its **right subtree**.
- **Step 3 - Swap** both **deleting node** and node which is found in the above step.
- **Step 4 -** Then check whether deleting node came to **case 1** or **case 2** or else goto step 2
- **Step 5 -** If it comes to **case 1**, then delete using case 1 logic.
- **Step 6-** If it comes to **case 2**, then delete using case 2 logic.
- **Step 7 -** Repeat the same process until the node is deleted from the tree.

Example

Construct a Binary Search Tree by inserting the following sequence of numbers...

10,12,5,4,20,8,7,15 and 13

Above elements are inserted into a Binary Search Tree as follows...



Implementaion of Binary Search Tree using C Programming Language

```
#include<stdio.h>

#include<conio.h>

#include<stdlib.h>


struct node

{
        int data;
        struct node *left;
        struct node *right;
};


void inorder(struct node *root)
{
        if(root)
        {
                inorder(root->left);
                printf("  %d",root->data);
                inorder(root->right);
        }
}

int main()
{
        int n , i;
        struct node *p , *q , *root;
        printf("Enter the number of nodes to be insert: ");
        scanf("%d",&n);

        printf("\nPlease enter the numbers to be insert: ");

        for(i=0;i<i++)
        {
                p = (struct node*)malloc(sizeof(struct node));
                scanf("%d",&p->data);
                p->left = NULL;
                p->right = NULL;
                if(i == 0)
                {
                        root = p; // root always point to the root node
                }
                else
                {
                        q = root;   // q is used to traverse the tree
                        while(1)
                        {
                                if(p->data > q->data)
                                {
                                        if(q->right == NULL)
                                                {
                                                q->right = p;
                                                break;
                                                }
                                        else
                                                q = q->right;
                                }
                                else
                                {
                                        if(q->left == NULL)
                                                {
                                                q->left = p;
                                                break;
                                                }
                                        else
                                                q = q->left;
                                }
                        }

                }

        }

printf("\nBinary Search Tree nodes in Inorder Traversal: ");
inorder(root);
```

```
printf("\n");

return 0;
}
```

AVL Tree Datastructure

AVL tree is a height-balanced binary search tree. That means, an AVL tree is also a binary search tree but it is a balanced tree. A binary tree is said to be balanced if, the difference between the heights of left and right subtrees of every node in the tree is either -1, 0 or +1. In other words, a binary tree is said to be balanced if the height of left and right children of every node differ by either -1, 0 or +1. In an AVL tree, every node maintains an extra information known as **balance factor**. The AVL tree was introduced in the year 1962 by G.M. Adelson-Velsky and E.M. Landis.

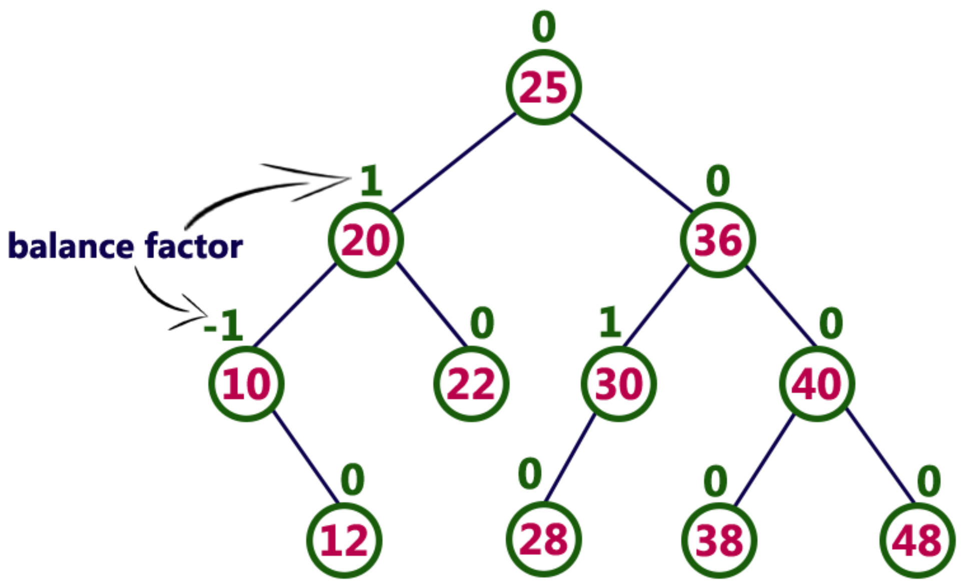
An AVL tree is defined as follows...

An AVL tree is a balanced binary search tree. In an AVL tree, balance factor of every node is either -1, 0 or +1.

Balance factor of a node is the difference between the heights of the left and right subtrees of that node. The balance factor of a node is calculated either **height of left subtree - height of right subtree** (OR) **height of right subtree - height of left subtree**. In the following explanation, we calculate as follows...

Balance factor = heightOfLeftSubtree - heightOfRightSubtree

Example of AVL Tree



The above tree is a binary search tree and every node is satisfying balance factor condition. So this tree is said to be an AVL tree.

Every AVL Tree is a binary search tree but every Binary Search Tree need not be AVL tree.

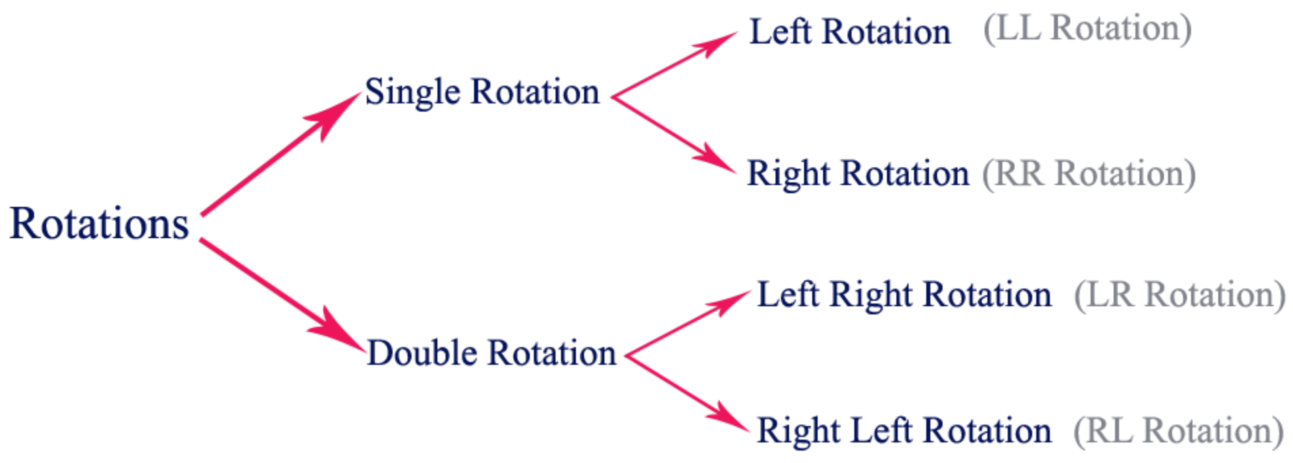
AVL Tree Rotations

In AVL tree, after performing operations like insertion and deletion we need to check the **balance factor** of every node in the tree. If every node satisfies the balance factor condition then we conclude the operation otherwise we must make it balanced. Whenever the tree becomes imbalanced due to any operation we use **rotation** operations to make the tree balanced.

Rotation operations are used to make the tree balanced.

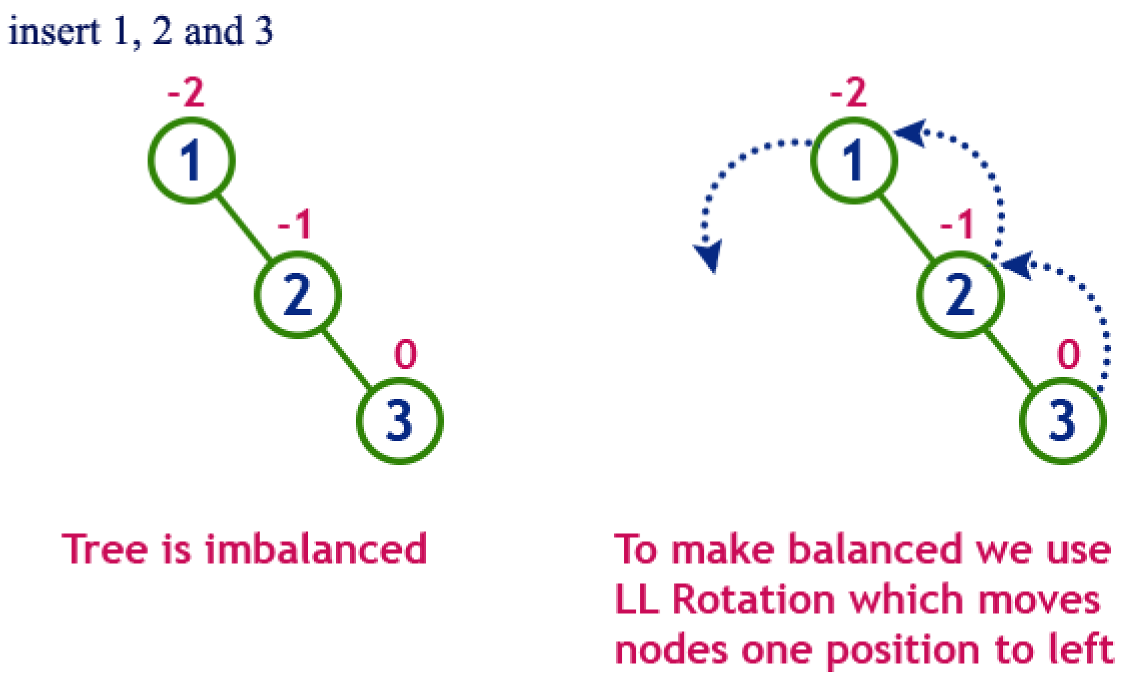
Rotation is the process of moving nodes either to left or to right to make the tree balanced.

There are **four** rotations and they are classified into **two** types.


Rotations
Single Rotation
Double Rotation
Left Rotation (LL Rotation)
Right Rotation (RR Rotation)
Left Right Rotation (LR Rotation)
Right Left Rotation (RL Rotation)

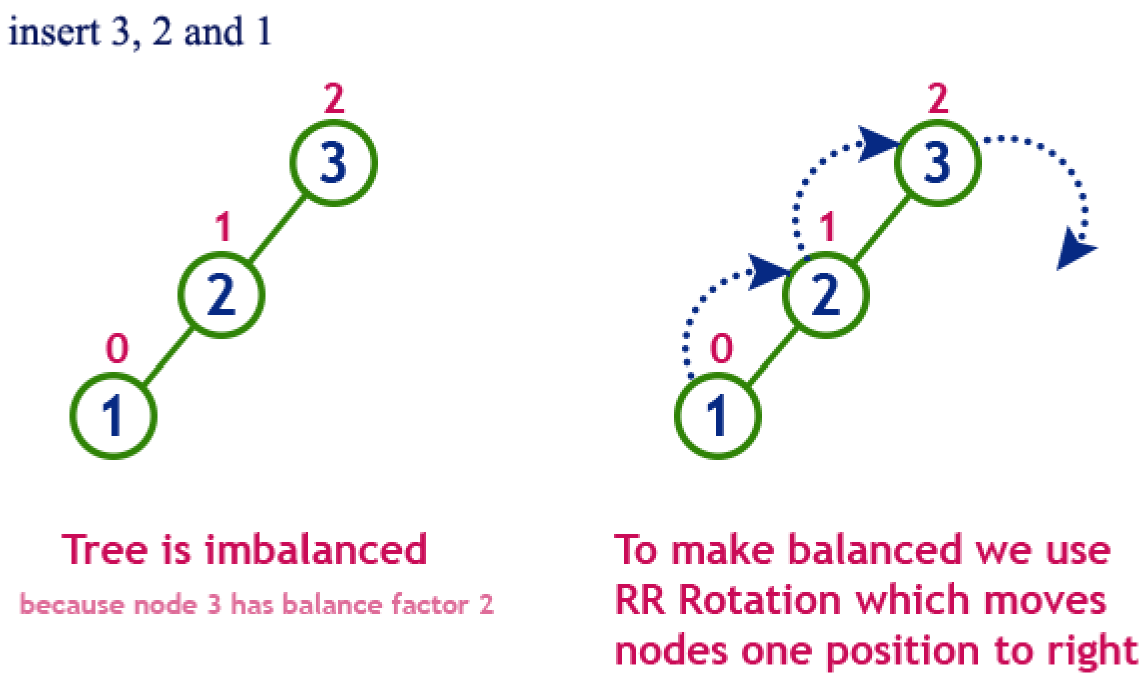
Single Left Rotation (LL Rotation)

In LL Rotation, every node moves one position to left from the current position. To understand LL Rotation, let us consider the following insertion operation in AVL Tree...


insert 1, 2 and 3
-2
1
-1
2
0
3
Tree is imbalanced
-2
1
-1
2
0
3
To make balanced we use LL Rotation which moves nodes one position to left

Single Right Rotation (RR Rotation)

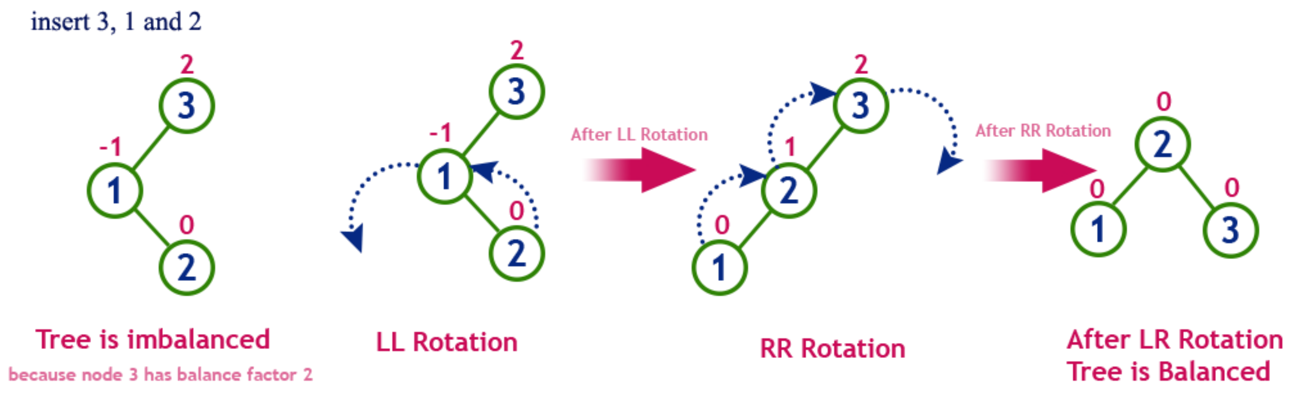
In RR Rotation, every node moves one position to right from the current position. To understand RR Rotation, let us consider the following insertion operation in AVL Tree...



insert 3, 2 and 1
2
3
1
2
0
1
Tree is imbalanced
because node 3 has balance factor 2
To make balanced we use RR Rotation which moves nodes one position to right

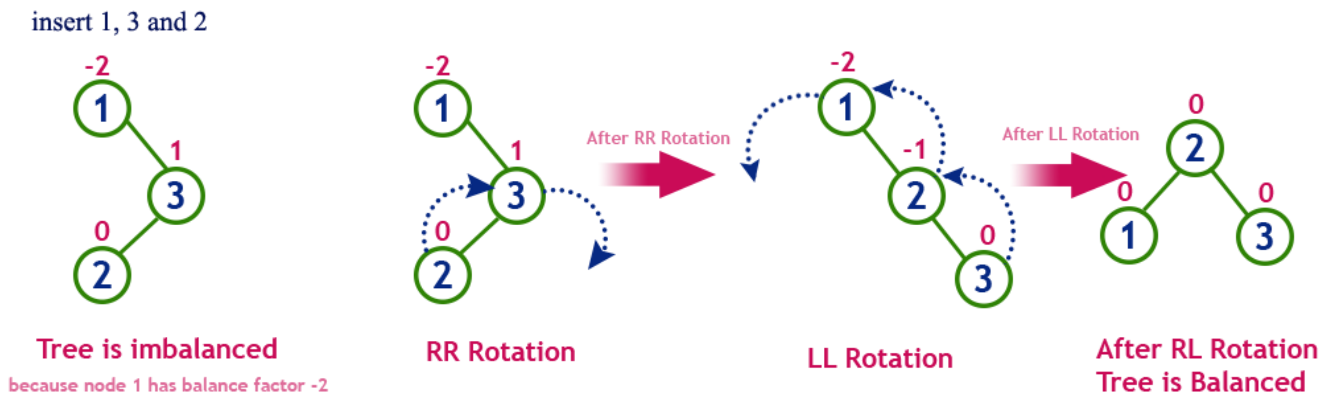
Left Right Rotation (LR Rotation)

The LR Rotation is a sequence of single left rotation followed by a single right rotation. In LR Rotation, at first, every node moves one position to the left and one position to right from the current position. To understand LR Rotation, let us consider the following insertion operation in AVL Tree...



Right Left Rotation (RL Rotation)

The RL Rotation is sequence of single right rotation followed by single left rotation. In RL Rotation, at first every node moves one position to right and one position to left from the current position. To understand RL Rotation, let us consider the following insertion operation in AVL Tree...



Operations on an AVL Tree

The following operations are performed on AVL tree...

1. **Search**
2. **Insertion**

3. **Deletion**

Search Operation in AVL Tree

In an AVL tree, the search operation is performed with **O(log n)** time complexity. The search operation in the AVL tree is similar to the search operation in a Binary search tree. We use the following steps to search an element in AVL tree...

- **Step 1 -** Read the search element from the user.
- **Step 2 -** Compare the search element with the value of root node in the tree.
- **Step 3 -** If both are matched, then display "Given node is found!!!" and terminate the function
- **Step 4 -** If both are not matched, then check whether search element is smaller or larger than that node value.
- **Step 5 -** If search element is smaller, then continue the search process in left subtree.
- **Step 6 -** If search element is larger, then continue the search process in right subtree.
- **Step 7 -** Repeat the same until we find the exact element or until the search element is compared with the leaf node.
- **Step 8 -** If we reach to the node having the value equal to the search value, then display "Element is found" and terminate the function.
- **Step 9 -** If we reach to the leaf node and if it is also not matched with the search element, then display "Element is not found" and terminate the function.

Insertion Operation in AVL Tree

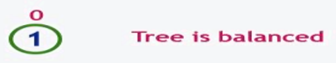
In an AVL tree, the insertion operation is performed with **O(log n)** time complexity. In AVL Tree, a new node is always inserted as a leaf node. The insertion operation is performed as follows...

- **Step 1 -** Insert the new element into the tree using Binary Search Tree insertion logic.
- **Step 2 -** After insertion, check the **Balance Factor** of every node.
- **Step 3 -** If the **Balance Factor** of every node is **0 or 1 or -1** then go for next operation.

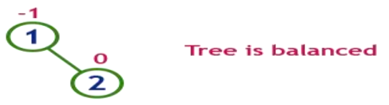
- **Step 4 -** If the **Balance Factor** of any node is other than **0 or 1 or -1** then that tree is said to be imbalanced. In this case, perform suitable **Rotation** to make it balanced and go for next operation.

Example: Construct an AVL Tree by inserting numbers from 1 to 8.

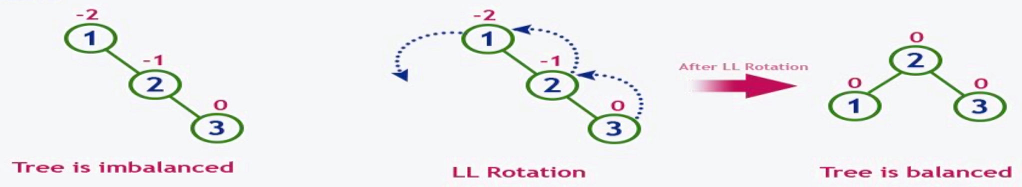
insert 1



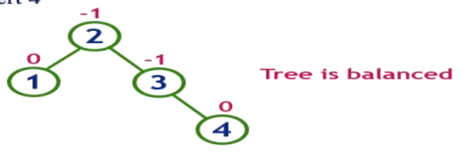
insert 2



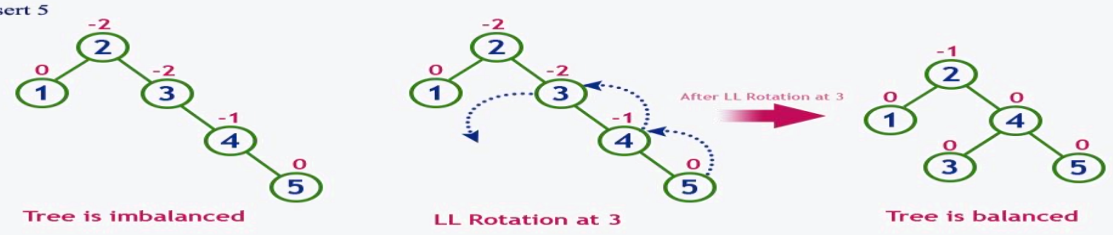
insert 3



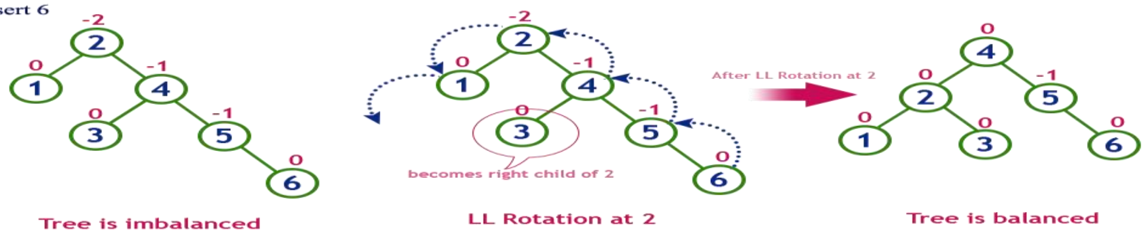
insert 4



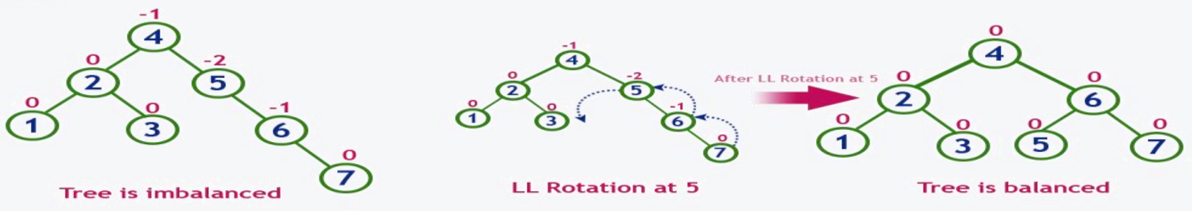
insert 5



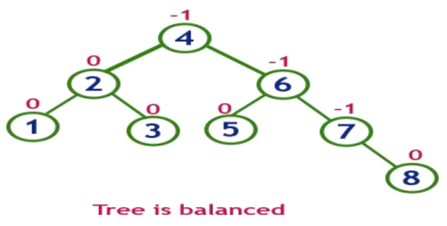
insert 6



insert 7



insert 8



Deletion Operation in AVL Tree

The deletion operation in AVL Tree is similar to deletion operation in BST. But after every deletion operation, we need to check with the Balance Factor condition. If the tree is balanced after deletion go for next operation otherwise perform suitable rotation to make the tree Balanced.

B - Tree Datastructure

In search trees like binary search tree, AVL Tree, Red-Black tree, etc., every node contains only one value (key) and a maximum of two children. But there is a special type of search tree called B-Tree in which a node contains more than one value (key) and more than two children. B-Tree was developed in the year 1972 by **Bayer and McCreight** with the name ***Height Balanced m-way Search Tree***. Later it was named as B-Tree.

B-Tree can be defined as follows...

B-Tree is a self-balanced search tree in which every node contains multiple keys and has more than two children.

Here, the number of keys in a node and number of children for a node depends on the order of B-Tree. Every B-Tree has an order.

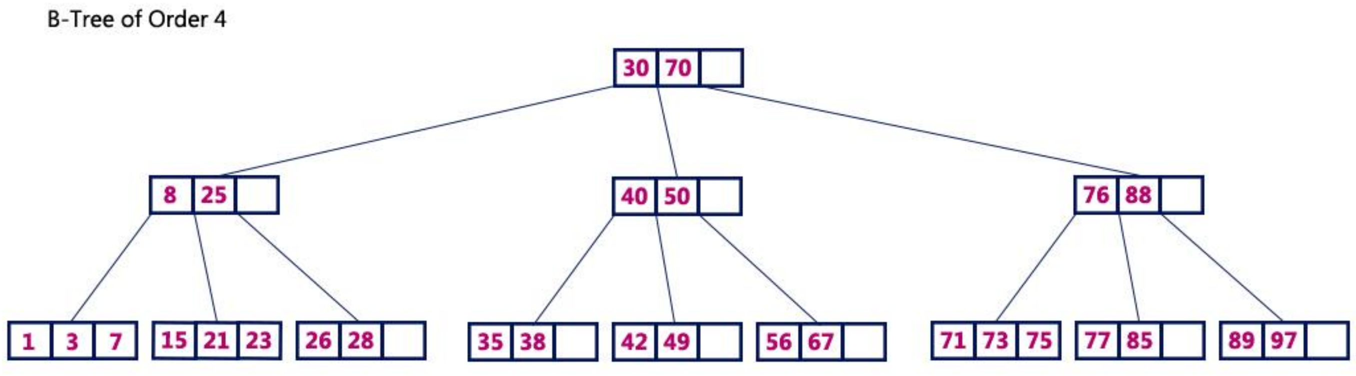
B-Tree of Order m has the following properties...

- **Property #1** - All **leaf nodes** must be **at same level**.
- **Property #2** - All nodes except root must have at least **[m/2]-1** keys and maximum of **m-1** keys.

- **Property #3** - All non leaf nodes except root (i.e. all internal nodes) must have at least **m/2** children.
- **Property #4** - If the root node is a non leaf node, then it must have **atleast 2** children.
- **Property #5** - A non leaf node with **n-1** keys must have **n** number of children.
- **Property #6** - All the **key values in a node** must be in **Ascending Order**.

For example, B-Tree of Order 4 contains a maximum of 3 key values in a node and maximum of 4 children for a node.

Example



Operations on a B-Tree

The following operations are performed on a B-Tree...

1. **Search**
2. **Insertion**
3. **Deletion**

Search Operation in B-Tree

The search operation in B-Tree is similar to the search operation in Binary Search Tree. In a Binary search tree, the search process starts from the root node and we make a 2-way decision every time (we go to either left subtree or right subtree). In B-Tree also search process starts from the root node but here we make an n-way decision every time. Where 'n' is the total number of children the node has. In a B-Tree, the search operation is performed with **O(log n)** time complexity. The search operation is performed as follows...

- **Step 1 -** Read the search element from the user.
- **Step 2 -** Compare the search element with first key value of root node in the tree.
- **Step 3 -** If both are matched, then display "Given node is found!!!" and terminate the function
- **Step 4 -** If both are not matched, then check whether search element is smaller or larger than that key value.
- **Step 5 -** If search element is smaller, then continue the search process in left subtree.
- **Step 6 -** If search element is larger, then compare the search element with next key value in the same node and repeate steps 3, 4, 5 and 6 until we find the exact match or until the search element is compared with last key value in the leaf node.
- **Step 7 -** If the last key value in the leaf node is also not matched then display "Element is not found" and terminate the function.

Insertion Operation in B-Tree

In a B-Tree, a new element must be added only at the leaf node. That means, the new keyValue is always attached to the leaf node only. The insertion operation is performed as follows...

- **Step 1 -** Check whether tree is Empty.
- **Step 2 -** If tree is **Empty**, then create a new node with new key value and insert it into the tree as a root node.
- **Step 3 -** If tree is **Not Empty**, then find the suitable leaf node to which the new key value is added using Binary Search Tree logic.
- **Step 4 -** If that leaf node has empty position, add the new key value to that leaf node in ascending order of key value within the node.

- **Step 5 -** If that leaf node is already full, **split** that leaf node by sending middle value to its parent node. Repeat the same until the sending value is fixed into a node.
- **Step 6 -** If the spilting is performed at root node then the middle value becomes new root node for the tree and the height of the tree is increased by one.

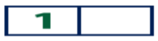
Example

Construct a **B-Tree of Order 3** by inserting numbers from 1 to 10.

Construct a B-Tree of order 3 by inserting numbers from 1 to 10.

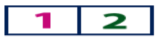
insert(1)

Since '1' is the first element into the tree that is inserted into a new node. It acts as the root node.



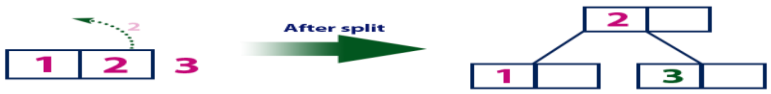
insert(2)

Element '2' is added to existing leaf node. Here, we have only one node and that node acts as root and also leaf. This leaf node has an empty position. So, new element (2) can be inserted at that empty position.



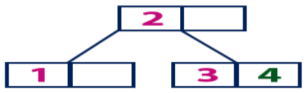
insert(3)

Element '3' is added to existing leaf node. Here, we have only one node and that node acts as root and also leaf. This leaf node doesn't has an empty position. So, we split that node by sending middle value (2) to its parent node. But here, this node doesn't has parent. So, this middle value becomes a new root node for the tree.



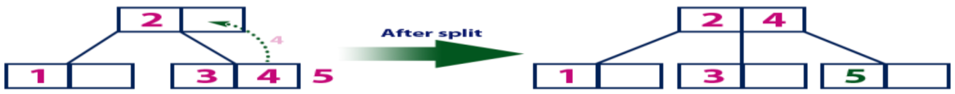
insert(4)

Element '4' is larger than root node '2' and it is not a leaf node. So, we move to the right of '2'. We reach to a leaf node with value '3' and it has an empty position. So, new element (4) can be inserted at that empty position.



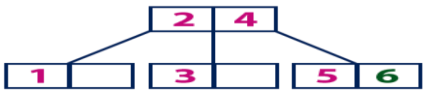
insert(5)

Element '5' is larger than root node '2' and it is not a leaf node. So, we move to the right of '2'. We reach to a leaf node and it is already full. So, we split that node by sending middle value (4) to its parent node (2). There is an empty position in its parent node. So, value '4' is added to node with value '2' and new element '5' added as new leaf node.



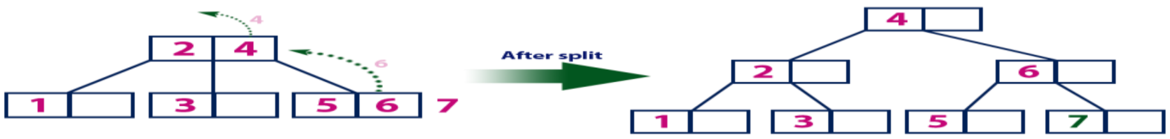
insert(6)

Element '6' is larger than root node '2' & '4' and it is not a leaf node. So, we move to the right of '4'. We reach to a leaf node with value '5' and it has an empty position. So, new element (6) can be inserted at that empty position.



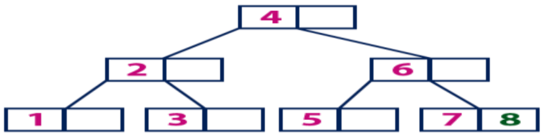
insert(7)

Element '7' is larger than root node '2' & '4' and it is not a leaf node. So, we move to the right of '4'. We reach to a leaf node and it is already full. So, we split that node by sending middle value (6) to its parent node (2&4). But the parent (2&4) is also full. So, again we split the node (2&4) by sending middle value '4' to its parent but this node doesn't have parent. So, the element '4' becomes new root node for the tree.



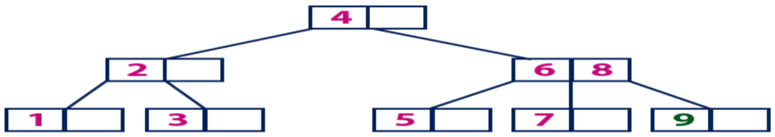
insert(8)

Element '8' is larger than root node '4' and it is not a leaf node. So, we move to the right of '4'. We reach to a node with value '6'. '8' is larger than '6' and it is also not a leaf node. So, we move to the right of '6'. We reach to a leaf node (7) and it has an empty position. So, new element (8) can be inserted at that empty position.



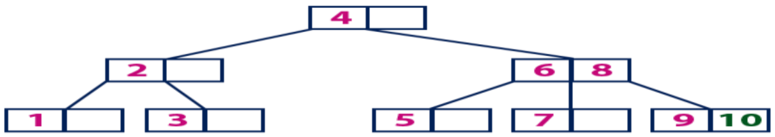
insert(9)

Element '9' is larger than root node '4' and it is not a leaf node. So, we move to the right of '4'. We reach to a node with value '6'. '9' is larger than '6' and it is also not a leaf node. So, we move to the right of '6'. We reach to a leaf node (7 & 8). This leaf node is already full. So, we split this node by sending middle value (8) to its parent node. The parent node (6) has an empty position. So, '8' is added at that position. And new element is added as a new leaf node.



insert(10)

Element '10' is larger than root node '4' and it is not a leaf node. So, we move to the right of '4'. We reach to a node with values '6 & 8'. '10' is larger than '6 & 8' and it is also not a leaf node. So, we move to the right of '8'. We reach to a leaf node (9). This leaf node has an empty position. So, new element '10' is added at that empty position.



Red - Black Tree Datastructure

Red - Black Tree is another variant of Binary Search Tree in which every node is colored either RED or BLACK. We can define a Red Black Tree as follows...

Red Black Tree is a Binary Search Tree in which every node is colored either RED or BLACK.

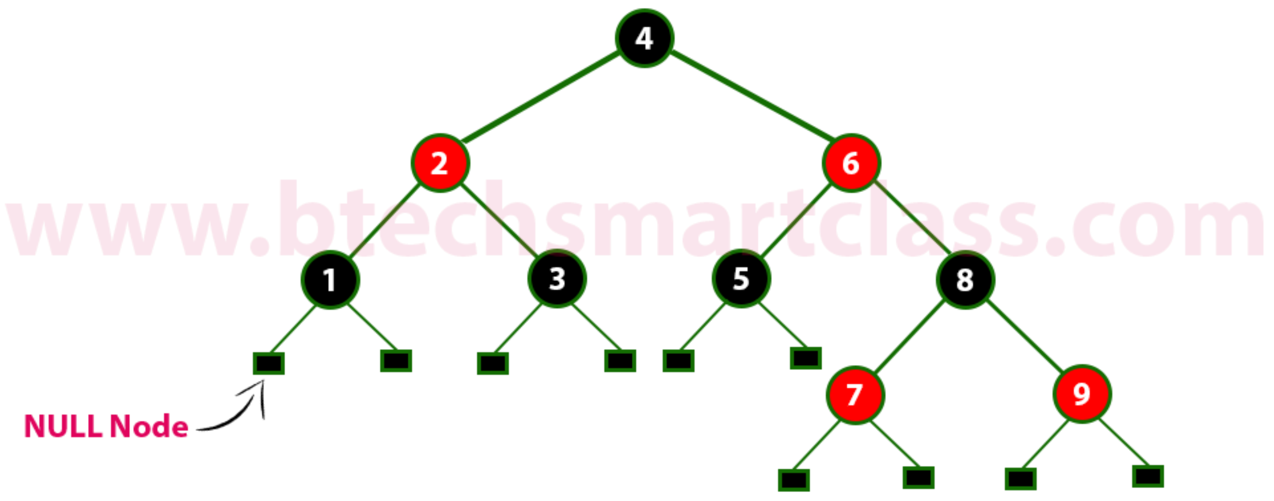
Red Black Tree, the color of a node is decided based on the properties of Red-Black Tree. Every Red Black Tree has the following properties.

Properties of Red Black Tree

- **Property #1:** Red - Black Tree must be a Binary Search Tree.
- **Property #2:** The ROOT node must be colored BLACK.
- **Property #3:** The children of Red colored node must be colored BLACK. (There should not be two consecutive RED nodes).
- **Property #4:** In all the paths of the tree, there should be same number of BLACK colored nodes.
- **Property #5:** Every new node must be inserted with RED color.
- **Property #6:** Every leaf (e.i. NULL node) must be colored BLACK.

Example

Following is a Red-Black Tree which is created by inserting numbers from 1 to 9.



The above tree is a Red-Black tree where every node is satisfying all the properties of Red-Black Tree.

Every Red Black Tree is a binary search tree but every Binary Search Tree need not be Red Black tree.

Insertion into RED BLACK Tree

In a Red-Black Tree, every new node must be inserted with the color RED. The insertion operation in Red Black Tree is similar to insertion operation in Binary Search Tree. But it is inserted with a color property. After every insertion operation, we need to check all the properties of Red-Black Tree. If all the properties are satisfied then we go to next operation otherwise we perform the following operation to make it Red Black Tree.

- **1. Recolor**
- **2. Rotation**
- **3. Rotation followed by Recolor**

The insertion operation in Red Black tree is performed using the following steps...

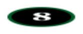
- **Step 1 -** Check whether tree is Empty.
- **Step 2 -** If tree is Empty then insert the **newNode** as Root node with color **Black** and exit from the operation.
- **Step 3 -** If tree is not Empty then insert the newNode as leaf node with color Red.
- **Step 4 -** If the parent of newNode is Black then exit from the operation.
- **Step 5 -** If the parent of newNode is Red then check the color of parentnode's sibling of newNode.
- **Step 6 -** If it is colored Black or NULL then make suitable Rotation and Recolor it.
- **Step 7 -** If it is colored Red then perform Recolor. Repeat the same until tree becomes Red Black Tree.

Example

Create a RED BLACK Tree by inserting following sequence of number
8, 18, 5, 15, 17, 25, 40 & 80.

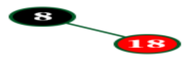
insert (8)

Tree is Empty. So insert newNode as Root node with black color.



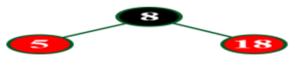
insert (18)

Tree is not Empty. So insert newNode with red color.



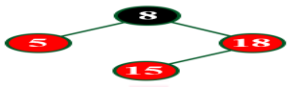
insert (5)

Tree is not Empty. So insert newNode with red color.



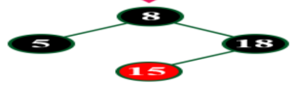
insert (15)

Tree is not Empty. So insert newNode with red color.



Here there are two consecutive Red nodes (18 & 15).
The newnode's parent sibling color is Red
and parent's parent is root node.
So we use RECOLOR to make it Red Black Tree.

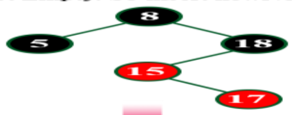
After RECOLOR



After Recolor operation, the tree is satisfying all Red Black Tree properties.

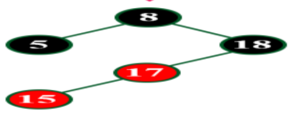
insert (17)

Tree is not Empty. So insert newNode with red color.

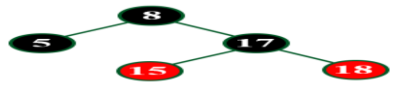


Here there are two consecutive Red nodes (15 & 17).
The newnode's parent sibling is NULL. So we need rotation.
Here, we need LR Rotation & Recolor.

After Left Rotation

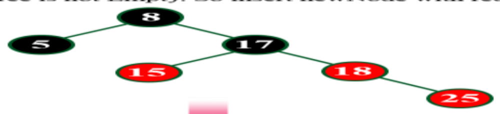


After Right Rotation & Recolor



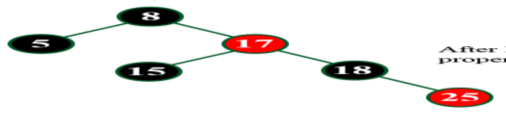
insert (25)

Tree is not Empty. So insert newNode with red color.



Here there are two consecutive Red nodes (18 & 25).
The newnode's parent sibling color is Red
and parent's parent is not root node.
So we use RECOLOR and Recheck.

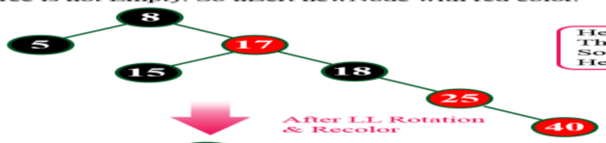
After Recolor



After Recolor operation, the tree is satisfying all Red Black Tree properties.

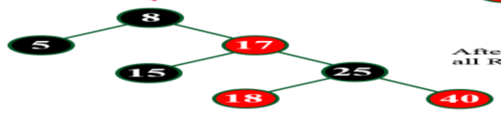
insert (40)

Tree is not Empty. So insert newNode with red color.



Here there are two consecutive Red nodes (25 & 40).
The newnode's parent sibling is NULL
So we need a Rotation & Recolor.
Here, we use LL Rotation and Recheck.

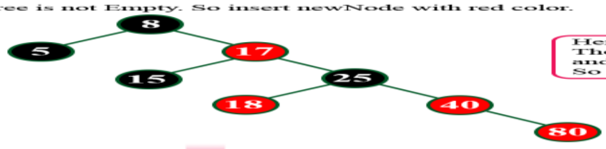
After LL Rotation
& Recolor



After LL Rotation & Recolor operation, the tree is satisfying all Red Black Tree properties.

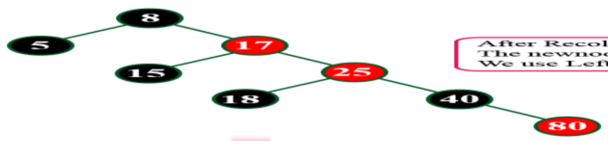
insert (80)

Tree is not Empty. So insert newNode with red color.



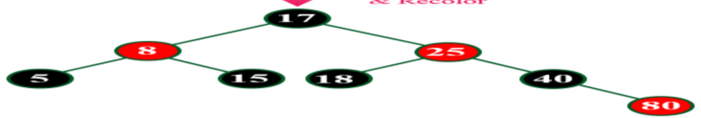
Here there are two consecutive Red nodes (40 & 80).
The newnode's parent sibling color is Red
and parent's parent is not root node.
So we use RECOLOR and Recheck.

After Recolor



After Recolor again there are two consecutive Red nodes (17 & 25).
The newnode's parent sibling color is Black. So we need Rotation.
We use Left Rotation & Recolor.

After Left Rotation
& Recolor



Deletion Operation in Red Black Tree

The deletion operation in Red-Black Tree is similar to deletion operation in BST. But after every deletion operation, we need to check with the Red-Black Tree properties. If any of the properties are violated then make suitable operations like Recolor, Rotation and Rotation followed by Recolor to make it Red-Black Tree.