

CS 349: Artificial Intelligence

Uncertainty and Bayes Nets

Uncertainty

- Logical agent performs as per the expectation if
 - Knows enough facts about environment

Unfortunately agents almost never have access to the whole truth of the environment !

Impossible to construct a complete and correct descriptions of how its actions will work

Agents must, therefore, act under uncertainty

Uncertainty

Let action A_t = leave for airport t minutes before flight departs

Will A_t get me there on time?

Problems:

1. partial observability (road state, other drivers' plans, etc.)
2. noisy sensors (traffic reports)
3. uncertainty in action outcomes (flat tire, etc.)
4. immense complexity of modeling and predicting traffic

Hence a purely logical approach either

1. risks falsehood: “ A_{25} will get me there on time”, or
2. leads to conclusions that are too weak for decision making:

“ A_{25} will get me there on time if there's no accident on the bridge and it doesn't rain and my tires remain intact etc etc.”

(A_{1440} might reasonably be said to get me there on time but I'd have to stay overnight in the airport ...)

Methods for handling uncertainty

- Default or non-monotonic logic (*consequences may be derived only because of lack of evidence of the contrary*):
 - Assume my car does not have a flat tire
 - Assume A_{25} works unless contradicted by evidence
- Issues: *What assumptions are reasonable? How to handle contradiction?*
- Probability
 - Model agent's degree of belief
 - Given the available evidence, A_{25} will get me there on time with probability 0.04

Probability

- Expresses uncertainty
- Pervasive in many applications of CS
 - Machine learning, Pattern recognition
 - Information Retrieval (e.g., Web)
 - Computer Vision
 - Robotics
- Based on mathematical calculus
- Disclaimer: We only discuss finite distributions

Probability

Probabilistic assertions **summarize** effects of

- **Laziness**: failure to enumerate exceptions, qualifications, etc.
- **Ignorance**: lack of relevant facts, initial conditions, etc.

Subjective probability:

- Probabilities relate propositions to agent's own state of knowledge
e.g., $P(A_{25} \mid \text{no reported accidents}) = 0.06$

These are **not** assertions about the world

does not imply that whenever there are no accidents will reach the airport with 0.4

***implies**: whenever there are no accidents and no other information is available then reach the airport with 0.4*

Probabilities of propositions change with new evidence:

e.g., $P(A_{25} \mid \text{no reported accidents, 5 a.m.}) = 0.7$

Making decisions under uncertainty

Suppose I believe the following:

$$P(A_{25} \text{ gets me there on time} \mid \dots) = 0.04$$

$$P(A_{90} \text{ gets me there on time} \mid \dots) = 0.70$$

$$P(A_{120} \text{ gets me there on time} \mid \dots) = 0.95$$

$$P(A_{1440} \text{ gets me there on time} \mid \dots) = 0.9999$$

- Which action to choose?

Depends on my preferences for missing flight vs. time spent waiting, etc.

- Utility theory is used to represent and infer preferences
- Decision theory = probability theory + utility theory

Syntax

- Basic element: **random variable**
- Similar to propositional logic: possible worlds defined by assignment of values to random variables
- Boolean random variables
e.g., *Cavity* (do I have a cavity?)
- Discrete random variables
e.g., *Weather* is one of *<unny,rainy,cloudy,snow>*
- Domain values must be exhaustive and mutually exclusive
- Elementary proposition constructed by assignment of a value to a random variable: e.g., *Weather = sunny, Cavity = false* (abbreviated as $\neg cavity$)
- Complex propositions formed from elementary propositions and standard logical connectives e.g., *Weather = sunny \vee Cavity = false*

Syntax

- **Atomic event:** A complete specification of the state of the world about which the agent is uncertain

E.g., if the world consists of only two boolean variables *Cavity* and *Toothache*, then there are 4 distinct atomic events:

Cavity = *false* \wedge *Toothache* = *false*

Cavity = *false* \wedge *Toothache* = *true*

Cavity = *true* \wedge *Toothache* = *false*

Cavity = *true* \wedge *Toothache* = *true*

Properties of atomic events

- Atomic events are mutually exclusive
E.g. $Cavity \wedge Toothache$ and $Cavity \wedge \neg Toothache$
- Set of atomic events is exhaustive-*disjunction of all atomic events is logically equivalent to true*
- Atomic event entails the truth or falsehood of every proposition
e.g. $Cavity \wedge \neg Toothache$ entails the **truth** of cavity and falsehood of *Toothache*
- *Logically equivalent to the disjunction of all atomic events that entail the truth of proposition*
e.g. $cavity = (Cavity \wedge Toothache) \vee (Cavity \wedge \neg Toothache)$

Probability

- Probability of a fair coin

$$P(\text{COIN} = \text{tail}) = \frac{1}{2}$$

$$P(\text{tail}) = \frac{1}{2}$$

Probability

- Probability of cancer

$$P(\text{has cancer}) = 0.02$$

$$\Rightarrow P(\neg \text{has cancer}) = 0.98$$

Joint Probability

- Multiple events: cancer, test result

$P(\text{has cancer, test positive})$

Has cancer?	Test positive?	P(C,TP)
yes	yes	0.018
yes	no	0.002
no	yes	0.196
no	no	0.784

Joint Probability

- The problem with joint distributions

It takes $2^D - 1$ numbers to specify them!

Conditional Probability

- Describes the cancer test:

$$P(\text{test positive} \mid \text{has cancer}) = 0.9$$

$$P(\text{test positive} \mid \neg \text{has cancer}) = 0.2$$

- Put this together with: Prior probability

$$P(\text{has cancer}) = 0.02$$

$$P(A, B) = P(A|B) * P(B) = P(B|A) * P(A)$$

Conditional Probability

- We have:
 $P(C) = 0.02$ $P(\neg C) = 0.98$
 $P(TP \mid C) = 0.9$ $P(\neg TP \mid C) = 0.1$
 $P(TP \mid \neg C) = 0.2$ $P(\neg TP \mid \neg C) = 0.8$
- We can now calculate joint probabilities

Has cancer?	Test positive?	P(TP, C)
yes	yes	0.018
yes	no	0.002
no	yes	0.196
no	no	0.784

Conditional Probability

- “Diagnostic” question: How likely do is cancer given a positive test?

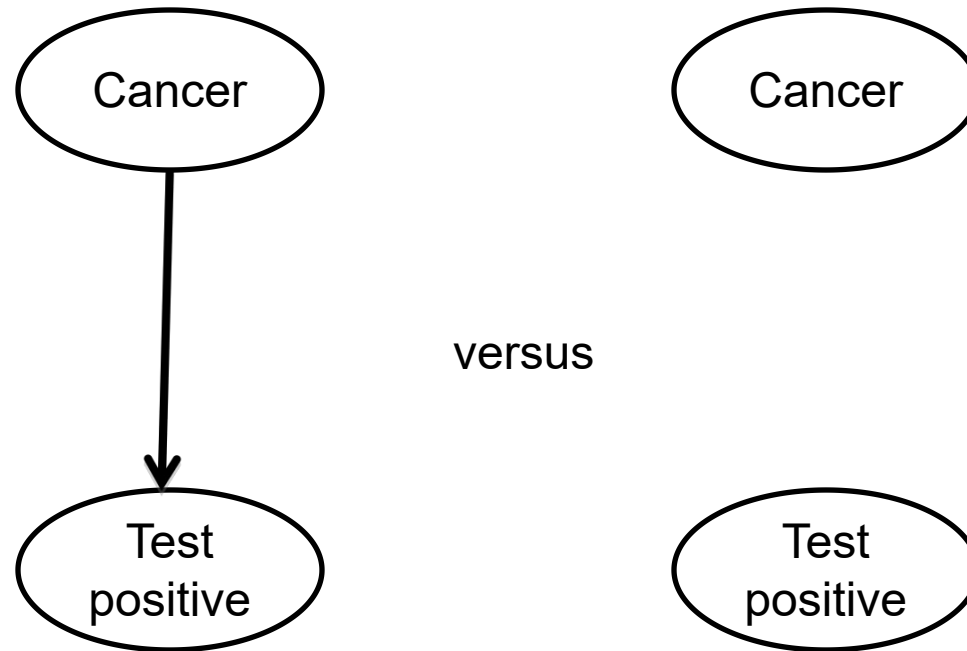
$$P(\text{has cancer} \mid \text{test positive}) = ?$$

Has cancer?	Test positive?	P(TP, C)
yes	yes	0.018
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no	yes	0.196
no	no	0.784

$$P(C \mid TP) = P(C, TP) / P(TP) = 0.018 / 0.214 = 0.084$$

Bayes Network

- We just encountered our first Bayes network:



Conditional Probability

- Chain rule is derived by successive application of product rule:

$$\begin{aligned} P(X_1, \dots, X_n) &= P(X_1, \dots, X_{n-1}) P(X_n \mid X_1, \dots, X_{n-1}) \\ &= P(X_1, \dots, X_{n-2}) P(X_{n-1} \mid X_1, \dots, X_{n-2}) P(X_n \mid X_1, \dots, X_{n-1}) \\ &= \dots \\ &= \prod_{i=1}^n P(X_i \mid X_1, \dots, X_{i-1}) \end{aligned}$$

Inference by enumeration

- Start with the joint probability distribution:

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

- For any proposition ϕ , sum the atomic events where it is true: $P(\phi) = \sum_{\omega: \omega \models \phi} P(\omega)$

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$$P(\text{toothache}) = 0.108 + 0.012 + 0.016 + 0.064 = 0.2$$

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- Can also compute conditional probabilities:

$$\begin{aligned} P(\neg \text{cavity} \mid \text{toothache}) &= \frac{P(\neg \text{cavity} \wedge \text{toothache})}{P(\text{toothache})} \\ &= \frac{0.016 + 0.064}{0.108 + 0.012 + 0.016 + 0.064} \\ &= 0.4 \end{aligned}$$

Normalization

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

- Denominator can be viewed as a normalization constant α

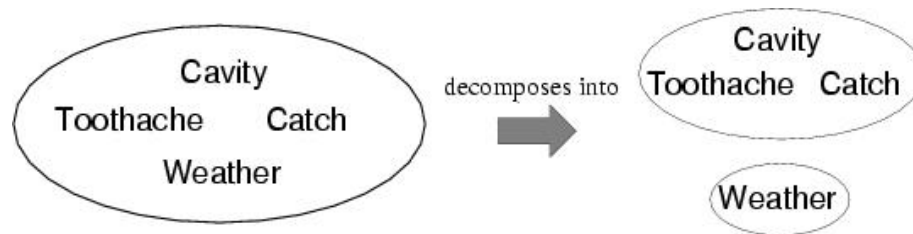
$$\begin{aligned} P(\text{Cavity} \mid \text{toothache}) &= \alpha, P(\text{Cavity}, \text{toothache}) \\ &= \alpha, [P(\text{Cavity}, \text{toothache}, \text{catch}) + P(\text{Cavity}, \text{toothache}, \neg \text{catch})] \\ &= \alpha, [<0.108, 0.016> + <0.012, 0.064>] \\ &= \alpha, <0.12, 0.08> = <0.6, 0.4> \end{aligned}$$

$$\alpha = P(\text{toothache})$$

General idea: compute distribution on query variable by fixing evidence variables and summing over hidden variables

Independence

- A and B are independent iff
 $P(A|B) = P(A)$ or $P(B|A) = P(B)$ or $P(A, B) = P(A) P(B)$



$$P(\textit{Toothache}, \textit{Catch}, \textit{Cavity}, \textit{Weather}) \\ = P(\textit{Toothache}, \textit{Catch}, \textit{Cavity}) P(\textit{Weather})$$

- Absolute independence powerful but rare
- Dentistry is a large field with hundreds of variables, none of which are independent. What to do?

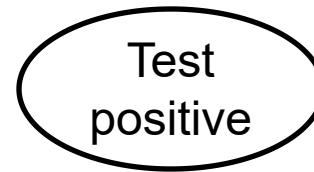
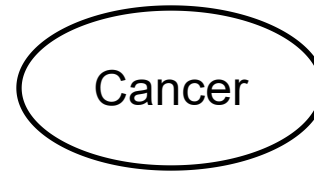
Independence

- Independence

$$P(C, TP) = P(C) \cdot P(TP)$$

- What does this mean for our test?

- Don't take it!



Independence

- Two variables are *independent* if:

$$\forall x, y : P(x, y) = P(x)P(y)$$

- This says that their joint distribution *factors* into a product of two simpler distributions
- This implies:

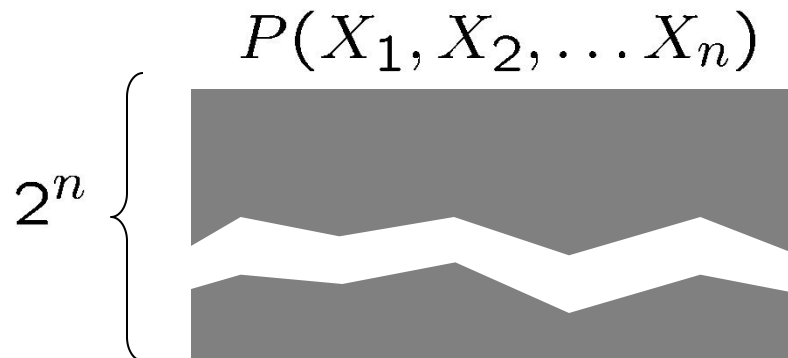
$$\forall x, y : P(x|y) = P(x)$$

- We write: $X \perp\!\!\!\perp Y$
- Independence is a simplifying *modeling assumption*
 - Empirical* joint distributions: at best “close” to independent

Example: Independence

- N fair, independent coin flips:

$P(X_1)$		$P(X_2)$		\dots		$P(X_n)$	
h	0.5	h	0.5			h	0.5
t	0.5	t	0.5			t	0.5



Example: Independence?

$$P(T)$$

T	P
warm	0.5
cold	0.5

$$P(W)$$

W	P
sun	0.6
rain	0.4

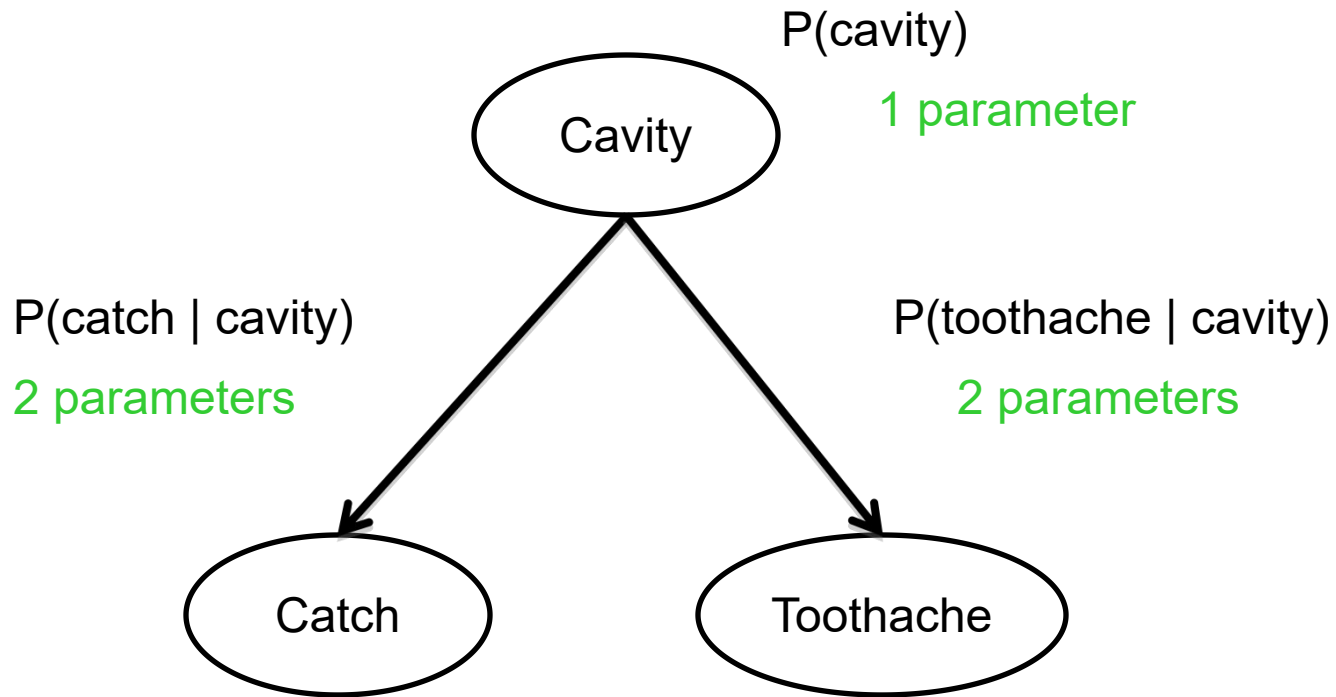
$$P_2(T, W)$$

T	W	P
warm	sun	0.3
warm	rain	0.2
cold	sun	0.3
cold	rain	0.2

Conditional Independence

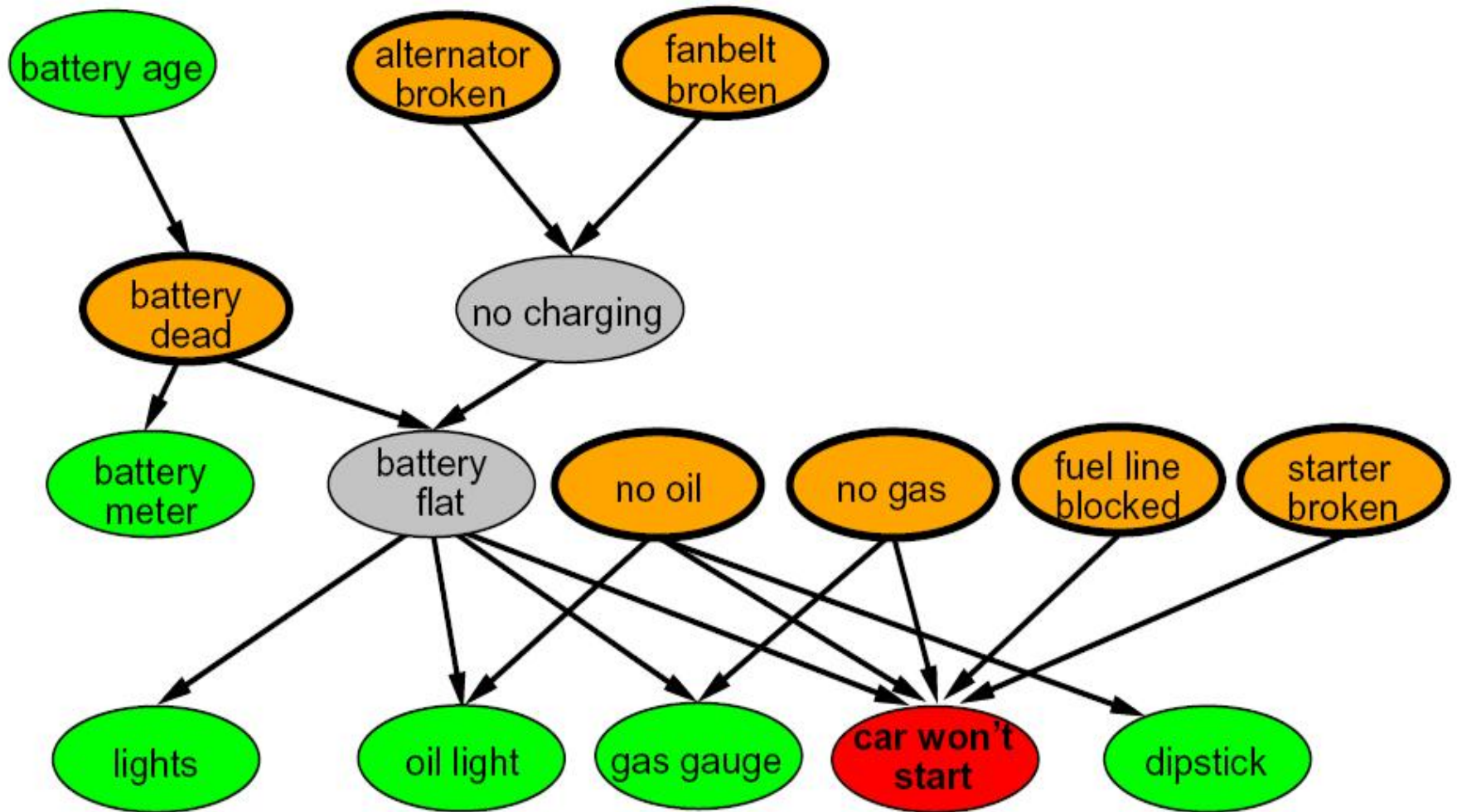
- $P(\text{Toothache}, \text{Cavity}, \text{Catch})$
- If I have a Toothache, a dental probe might be more likely to catch
- But: if I have a cavity, the probability that the probe catches doesn't depend on whether I have a toothache:
 - $P(+\text{catch} \mid +\text{toothache}, +\text{cavity}) = P(+\text{catch} \mid +\text{cavity})$
- The same independence holds if I don't have a cavity:
 - $P(+\text{catch} \mid +\text{toothache}, \neg\text{cavity}) = P(+\text{catch} \mid \neg\text{cavity})$
- Catch is *conditionally independent* of Toothache given Cavity:
 - $P(\text{Catch} \mid \text{Toothache}, \text{Cavity}) = P(\text{Catch} \mid \text{Cavity})$
- Equivalent statements:
 - $P(\text{Toothache} \mid \text{Catch}, \text{Cavity}) = P(\text{Toothache} \mid \text{Cavity})$
 - $P(\text{Toothache}, \text{Catch} \mid \text{Cavity}) = P(\text{Toothache} \mid \text{Cavity}) P(\text{Catch} \mid \text{Cavity})$
 - One can be derived from the other easily
- We write: $X \perp\!\!\!\perp Y \mid Z$

Bayes Network Representation



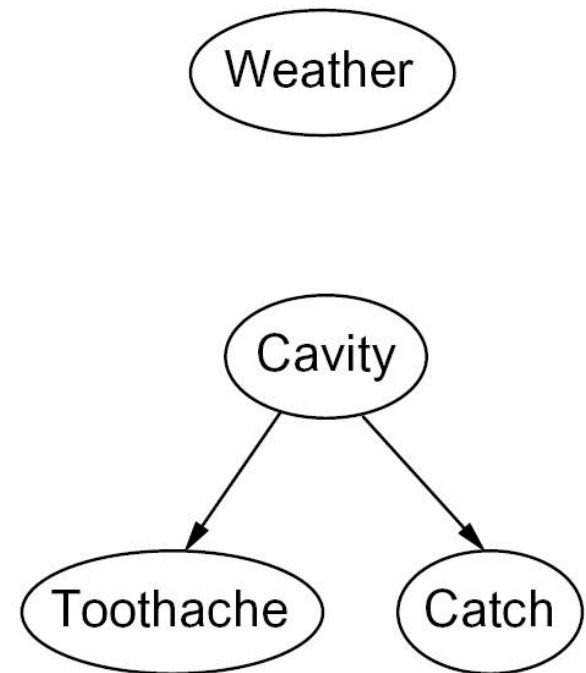
Versus: $2^3 - 1 = 7$ parameters

Example Bayes Network: Car



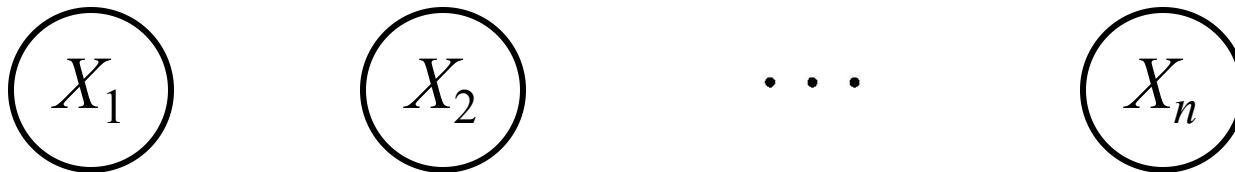
Graphical Model Notation

- **Nodes: variables (with domains)**
 - Can be assigned (observed) or unassigned (unobserved)
- **Arcs: interactions**
 - Indicate “direct influence” between variables
 - Formally: encode conditional independence (more later)
- **For now: imagine that arrows mean direct causation (they may not!)**



Example: Coin Flips

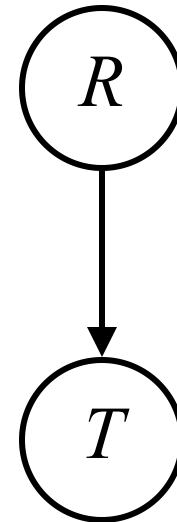
- N independent coin flips



- No interactions between variables:
absolute independence

Example: Traffic

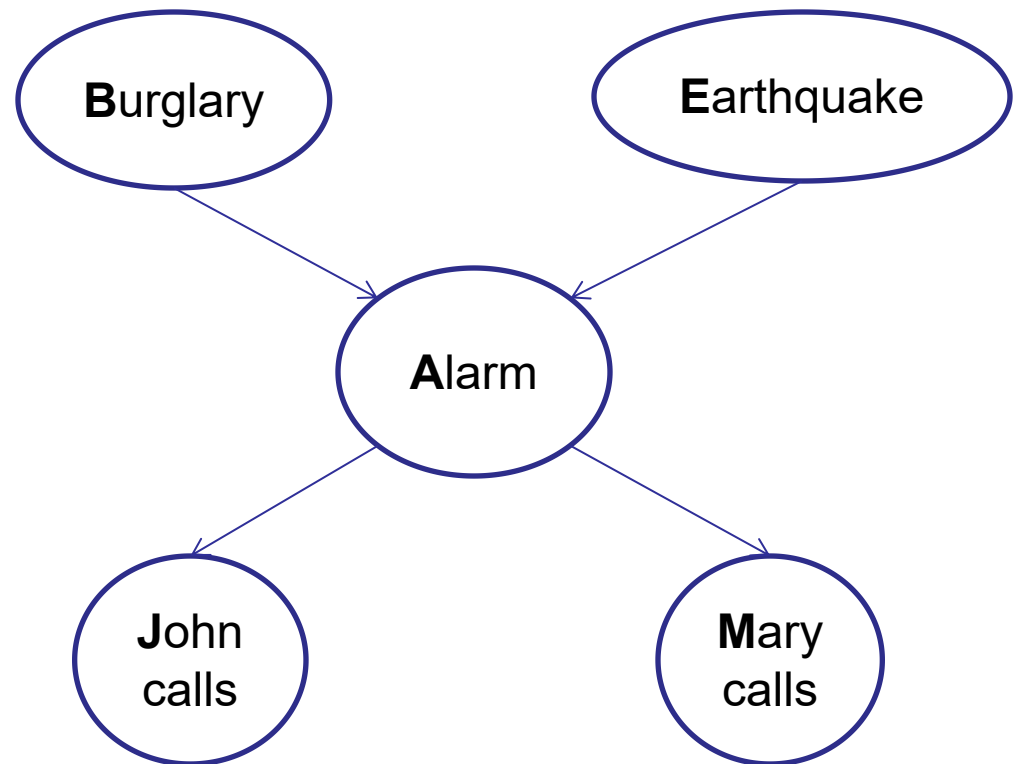
- Variables:
 - R : It rains
 - T : There is traffic
- Model 1: independence
- Model 2: rain causes traffic
- Why is an agent using model 2 better?



Example: Alarm Network

■ Variables

- B: Burglary
- A: Alarm rings
- M: Mary calls
- J: John calls
- E: Earthquake!



Problem Description

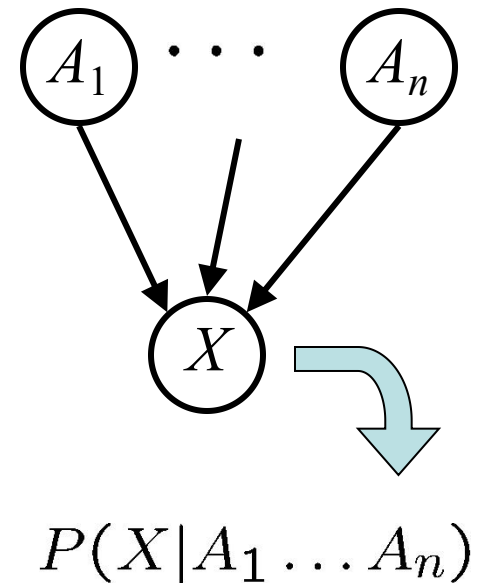
- New burglar alarm installed
- Detects burglary fairly but also responds on occasion to minor earthquake
- John and Mary- two neighbors
 - Calls when they hear the alarm
 - Sometimes confuses the telephone ringing with the alarm and then calls
 - John likes loud music and often misses the alarm together
- Given the evidence of who has or has not called, we would like to estimate the probability of a burglary

Bayes Net Semantics

- A set of nodes, one per variable X
- A directed, acyclic graph
- A conditional distribution for each node
 - A collection of distributions over X , one for each combination of parents' values

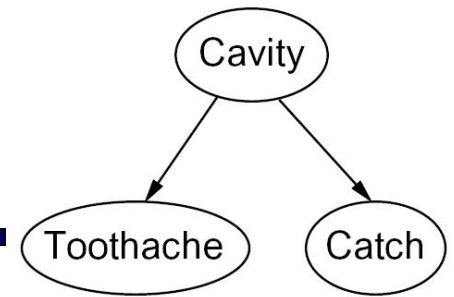
$$P(X|a_1 \dots a_n)$$

- CPT: conditional probability table
- Description of a noisy “causal” process
 - Uncertain relationships



A Bayes net = Topology (graph) + Local Conditional Probabilities

Probabilities in BNs



- Bayes nets **implicitly** encode joint distributions
 - As a product of local conditional distributions
 - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

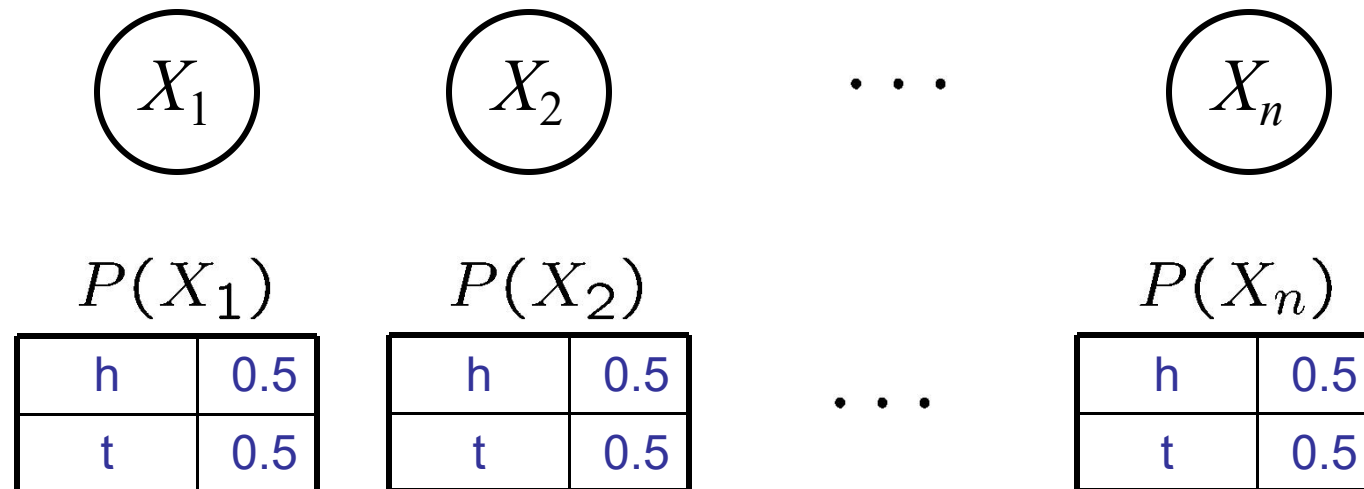
$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

- Example:

$$P(+cavity, +catch, \neg toothache)$$

- This lets us reconstruct any entry of the full joint
- Not every BN can represent every joint distribution
 - The topology enforces certain conditional independencies

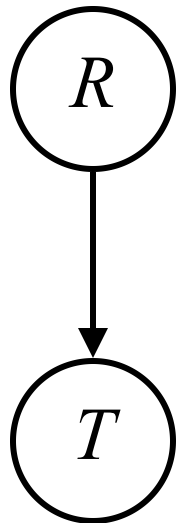
Example: Coin Flips



$$P(h, h, t, h) =$$

Only distributions whose variables are absolutely independent can be represented by a Bayes' net with no arcs.

Example: Traffic



$P(R)$

$+r$	$1/4$
$\neg r$	$3/4$

$$P(+r, \neg t) =$$

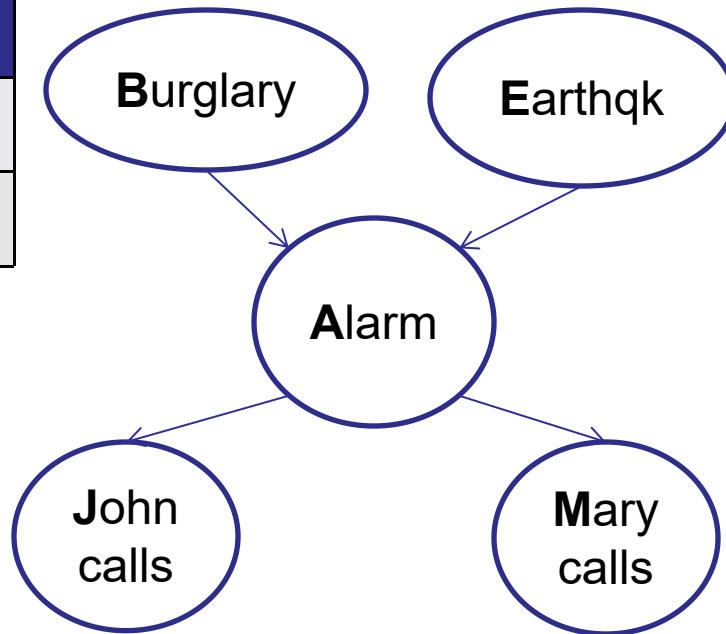
$P(T|R)$

$+r \rightarrow$	$+t$	$3/4$
	$\neg t$	$1/4$

$\neg r \rightarrow$	$+t$	$1/2$
	$\neg t$	$1/2$

Example: Alarm Network

B	P(B)
+b	0.001
¬b	0.999



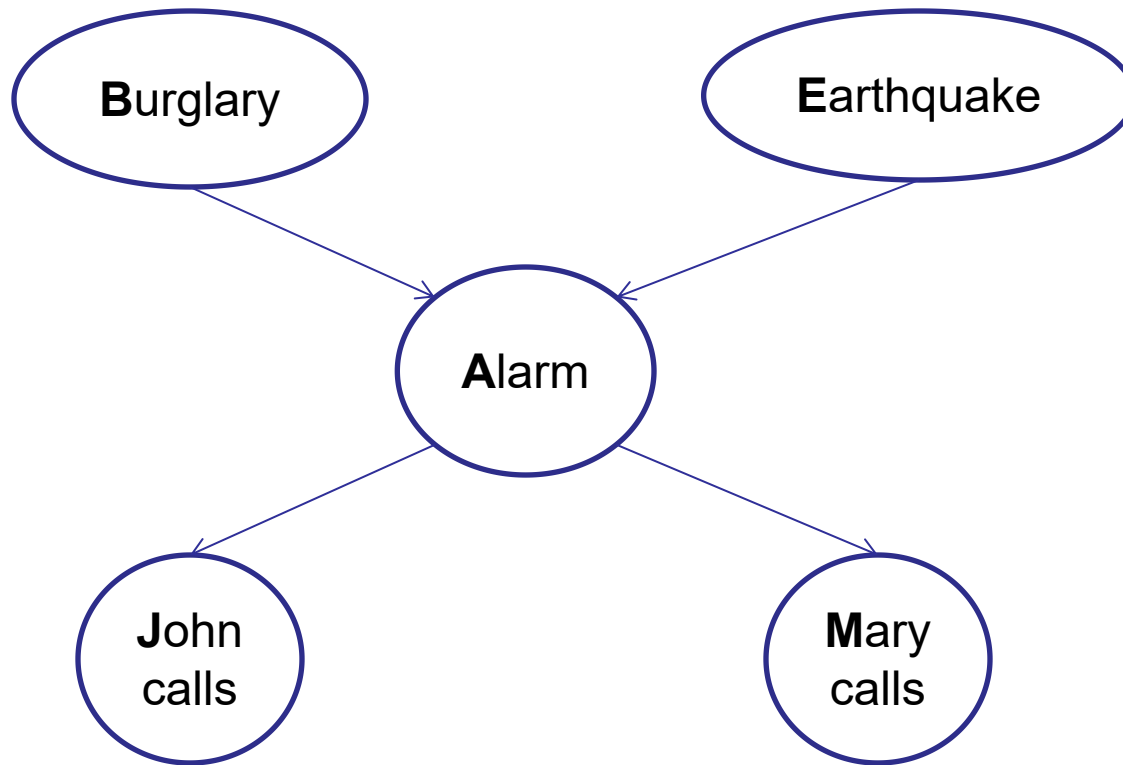
E	P(E)
+e	0.002
¬e	0.998

A	J	P(J A)
+a	+j	0.9
+a	¬j	0.1
¬a	+j	0.05
¬a	¬j	0.95

A	M	P(M A)
+a	+m	0.7
+a	¬m	0.3
¬a	+m	0.01
¬a	¬m	0.99

B	E	A	P(A B,E)
+b	+e	+a	0.95
+b	+e	¬a	0.05
+b	¬e	+a	0.94
+b	¬e	¬a	0.06
¬b	+e	+a	0.29
¬b	+e	¬a	0.71
¬b	¬e	+a	0.001
¬b	¬e	¬a	0.999

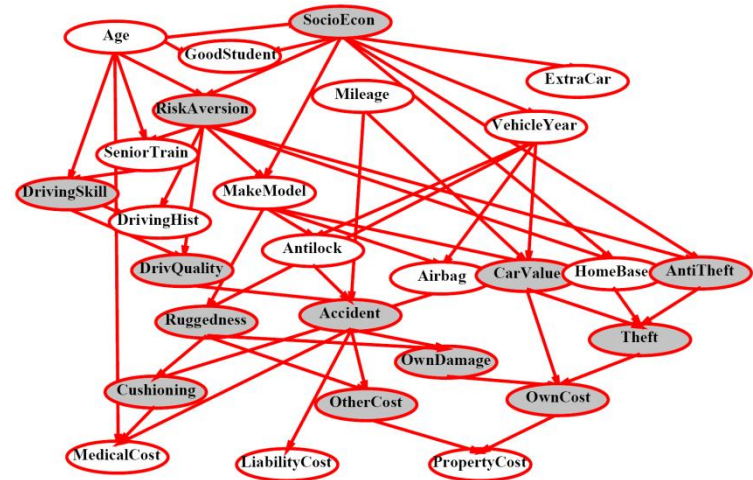
Example: Alarm Network



$$\prod_i P(X_i | \text{Parents}(X_i)) = P(B) \cdot P(E) \cdot P(A|B, E) \cdot P(J|A) \cdot P(M|A)$$

Bayes' Nets

- A Bayes' net is an efficient encoding of a probabilistic model of a domain

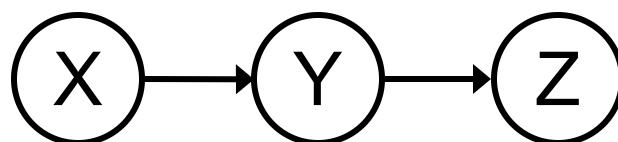


- Questions we can ask:
 - Inference: given a fixed BN, what is $P(X | e)$?
 - Representation: given a BN graph, what kinds of distributions can it encode?
 - Modeling: what BN is most appropriate for a given domain?

-
- Find Conditional (In)Dependencies
 - Concept of “d-separation”

Causal Chains

- This configuration is a “causal chain”



X: Low pressure

Y: Rain

Z: Traffic

$$P(x, y, z) = P(x)P(y|x)P(z|y)$$

- Is X independent of Z given Y?

$$\begin{aligned} P(z|x, y) &= \frac{P(x, y, z)}{P(x, y)} = \frac{P(x)P(y|x)P(z|y)}{P(x)P(y|x)} \\ &= P(z|y) \end{aligned} \quad \text{Yes!}$$

- Evidence along the chain “blocks” the influence

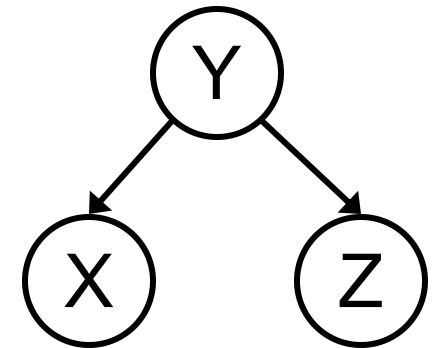
Common Cause

- Another basic configuration: two effects of the same cause

- Are X and Z independent?
- Are X and Z independent given Y?

$$\begin{aligned}P(z|x, y) &= \frac{P(x, y, z)}{P(x, y)} = \frac{P(y)P(x|y)P(z|y)}{P(y)P(x|y)} \\ &= P(z|y)\end{aligned}$$

Yes!



Y: Alarm

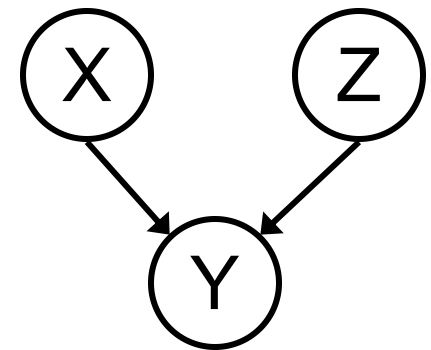
X: John calls

Z: Mary calls

- Observing the cause blocks influence between effects

Common Effect

- Last configuration: two causes of one effect (v-structures)
 - Are X and Z independent?
 - Yes: the ballgame and the rain cause traffic, but they are not correlated
 - Still need to prove they must be (try it!)
 - Are X and Z independent given Y?
 - No: seeing traffic puts the rain and the ballgame in competition as explanation?
 - **This is backwards from the other cases**
 - Observing an effect **activates** influence between possible causes



X: Raining

Z: Ballgame

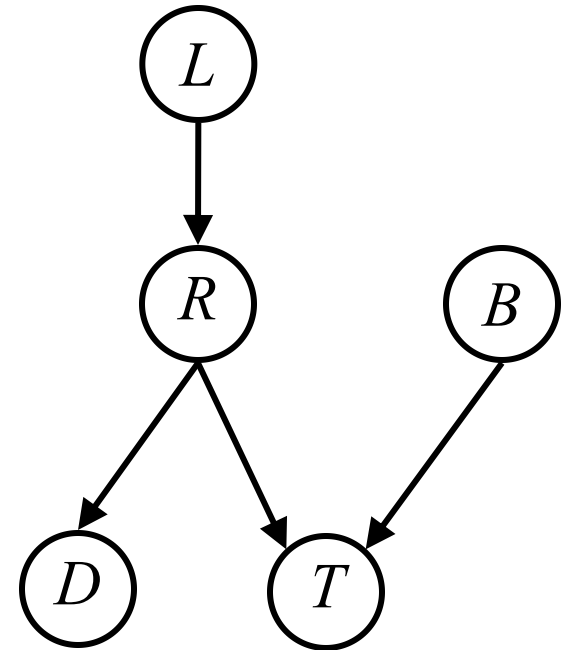
Y: Traffic

The General Case

- Any complex example can be analyzed using these three canonical cases
- General question: in a given BN, are two variables independent (given evidence)?
- Solution: analyze the graph

Reachability

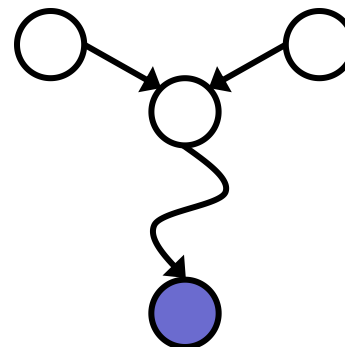
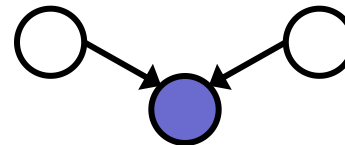
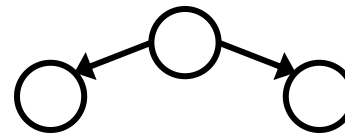
- Recipe: shade evidence nodes
- Attempt 1: Remove shaded nodes. If two nodes are still connected by an undirected path, they are not conditionally independent
- Almost works, but not quite
 - Where does it break?
 - Answer: the v-structure at T does n't count as a link in a path unless “active”



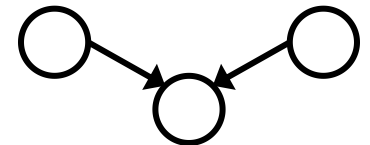
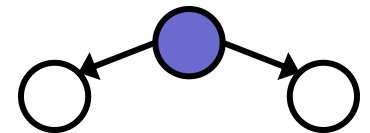
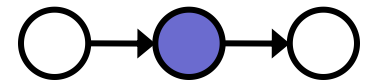
Reachability (D-Separation)

- Question: Are X and Y conditionally independent given evidence vars $\{Z\}$?
 - Yes, if X and Y “separated” by Z
 - Look for active paths from X to Y
 - No active paths = independence!
- A path is active if each triple is active:
 - Causal chain $A \rightarrow B \rightarrow C$ where B is unobserved (either direction)
 - Common cause $A \leftarrow B \rightarrow C$ where B is unobserved
 - Common effect (aka v-structure) $A \rightarrow B \leftarrow C$ where B or one of its descendants is observed
- All it takes to block a path is a single inactive segment

Active Triples



Inactive Triples



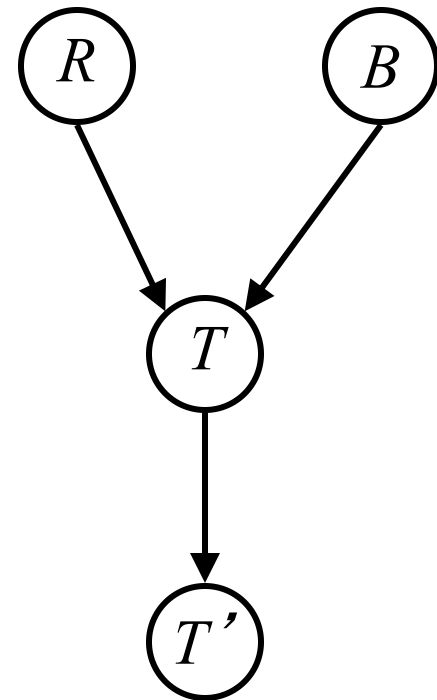
Example

$$R \perp\!\!\!\perp B$$

Yes

$$R \perp\!\!\!\perp B | T$$

$$R \perp\!\!\!\perp B | T'$$



Example

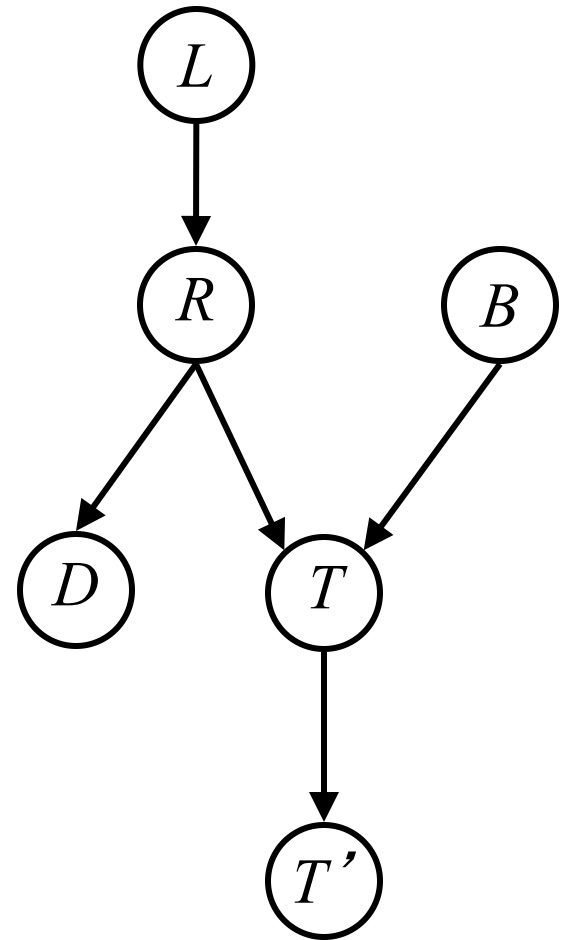
$L \perp\!\!\!\perp T' | T$ **Yes**

$L \perp\!\!\!\perp B$ **Yes**

$L \perp\!\!\!\perp B | T$

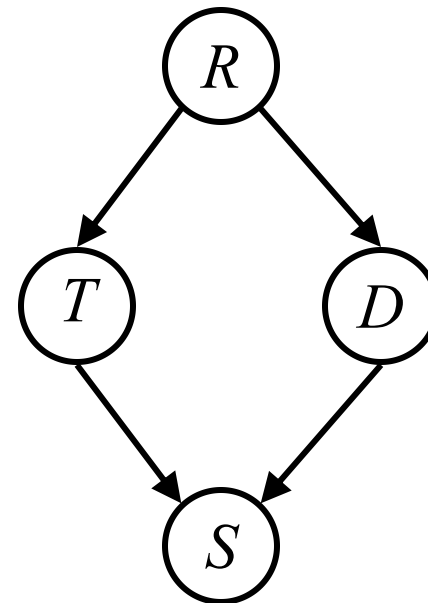
$L \perp\!\!\!\perp B | T'$

$L \perp\!\!\!\perp B | T, R$ **Yes**



Example

- Variables:
 - R: Raining
 - T: Traffic
 - D: Roof drips
 - S: I'm sad



- Questions:

$$T \perp\!\!\!\perp D$$

$$T \perp\!\!\!\perp D | R$$

Yes

$$T \perp\!\!\!\perp D | R, S$$

Causality?

- When Bayes' nets reflect the true causal patterns:
 - Often simpler (nodes have fewer parents)
 - Often easier to think about
 - Often easier to elicit from experts
- BNs need not actually be causal
 - Sometimes no causal net exists over the domain
 - End up with arrows that reflect correlation, not causation
- What do the arrows really mean?
 - Topology may happen to encode causal structure
 - **Topology only guaranteed to encode conditional independence**