

MA101 : Linear Algebra and Matrices

Tutorial 6

1. Let $B = \{b_1, b_2\}$ and $C = \{c_1, c_2\}$ be basis of \mathbb{R}^2 given below. Find the change of coordinate matrix from B to C . Find coordinates of $e_1 = [1 \ 0]^T$ with respect to both bases.

$$b_1 = \begin{bmatrix} -1 \\ 8 \end{bmatrix}, \quad b_2 = \begin{bmatrix} 1 \\ -5 \end{bmatrix}, \quad c_1 = \begin{bmatrix} 1 \\ 4 \end{bmatrix}, \quad c_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Let x be a vector in \mathbb{R}^2 .

then, $[x]_B$ are co-ordinates of vector with respect to bases B and $[x]_C$ are co-ordinates of vector with respect to C .

The change of coordinate matrix from B to C , that is $P_{B \rightarrow C}$ is a matrix such that

$$(P_{B \rightarrow C}) [x]_B = [x]_C$$

$$\text{Now, } P_{B \rightarrow C} = \begin{bmatrix} [b_1]_C & [b_2]_C \end{bmatrix} \quad \text{---(1)}$$

$[b_1]_C$ is $[p \ q]^T$ such that $p c_1 + q c_2 = b_1$

$$\therefore p \begin{bmatrix} 1 \\ 4 \end{bmatrix} + q \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 8 \end{bmatrix}$$

$$p + q = -1$$

$$4p + q = 8$$

Solving the equations, we get,

$$p = 3 \text{ and } q = -4$$

$$\therefore [b_1]_C = \begin{bmatrix} 3 \\ -4 \end{bmatrix}$$

$[b_2]_c$ is $[r \ s]^T$ such that $rc_1 + sc_2 = b_2$

$$r \begin{bmatrix} 1 \\ 4 \end{bmatrix} + s \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -5 \end{bmatrix}$$

$$r + s = 1$$

$$4r + s = -5$$

Solving the equations, we get,

$$r = -2 \text{ and } s = 3$$

$$\therefore [b_2]_c = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$$

∴ change of co-ordinate matrix from B to C is

$$P_{B \rightarrow C} = \begin{bmatrix} 3 & -2 \\ -4 & 3 \end{bmatrix}$$

coordinates of $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ w.r.t to bases B are m and n such that

$$m b_1 + n b_2 = e_1$$

$$m \begin{bmatrix} -1 \\ 8 \end{bmatrix} + n \begin{bmatrix} 1 \\ -5 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$-m + n = 1$$

$$8m - 5n = 0$$

Solving the equations we get

$$m = \frac{5}{3} \text{ and } n = \frac{8}{3}$$

$$\therefore [e_1]_b = \begin{bmatrix} 5/3 \\ 8/3 \end{bmatrix}$$

$$\text{Now, } [e_1]_c = P_{B \rightarrow C} [e_1]_B$$

$$[e_1]_c = \begin{bmatrix} 3 & -2 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} 5/3 \\ 8/3 \end{bmatrix}$$

$$[e_1]_c = \begin{bmatrix} -1/3 \\ 4/3 \end{bmatrix}$$

Hence, coordinates of e_1 w.r.t bases B are $\begin{bmatrix} 5/3 \\ 8/3 \end{bmatrix}$

and w.r.t basis C are $\begin{bmatrix} -1/3 \\ 4/3 \end{bmatrix}$.

2. Let V be the set of all 3×3 anti-symmetric matrices with entries from R. Is V a vector space? If yes then find its basis and dimension. What can you say if 3 is replaced by n?

V is the set of all 3×3 anti-symmetric matrices.

$$\text{Let } A = \begin{bmatrix} 0 & p & q \\ -p & 0 & r \\ -q & -r & 0 \end{bmatrix} \text{ and } B = \begin{bmatrix} 0 & m & l \\ -l & 0 & n \\ -m & -n & 0 \end{bmatrix}$$

be

$$\text{and } C = \begin{bmatrix} 0 & x & y \\ -x & 0 & z \\ -y & -z & 0 \end{bmatrix} \text{ belong to } V.$$

For V to be a vector space, it must satisfy following axioms

i) $A + B \in V$

$$A + B = \begin{bmatrix} 0 & p+l & q+m \\ -(p+l) & 0 & r+n \\ -(q+m) & -(r+n) & 0 \end{bmatrix}$$

$A + B$ is also skew-symmetric and belongs to V .

(ii) $A + B = B + A$

$$A + B = \begin{bmatrix} 0 & p+l & q+m \\ -(p+l) & 0 & r+n \\ -(q+m) & -(r+n) & 0 \end{bmatrix} = \begin{bmatrix} 0 & l+p & m+q \\ -(l+p) & 0 & n+r \\ -(m+q) & -(n+r) & 0 \end{bmatrix} = B + A$$

Hence, $A + B = B + A$.

(iii) $(A + B) + C = A + (B + C)$

$$(A + B) + C = \begin{bmatrix} 0 & p+l & q+m \\ -(p+l) & 0 & r+n \\ -(q+m) & -(r+n) & 0 \end{bmatrix} + \begin{bmatrix} 0 & x & y \\ -x & 0 & z \\ -y & -z & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & p+l+x & q+m+y \\ -(p+l+x) & 0 & r+n+z \\ -(q+m+y) & -(r+n+z) & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & p & qr \\ -p & 0 & r \\ -qr & -r & 0 \end{bmatrix} + \begin{bmatrix} 0 & l+x & m+y \\ -(l+x) & 0 & n+z \\ -(m+y) & -(n+z) & 0 \end{bmatrix}$$

$$= A + (B + C)$$

(iv) $\vec{0}$ should be in V .

If $p = q = r = 0$ in A ,

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

which is a skew-symmetric matrix.

(v) $A + (-A) = 0$

$$-A = \begin{bmatrix} 0 & -p & -q \\ p & 0 & -r \\ q & r & 0 \end{bmatrix}$$

$$\therefore A + (-A) = \begin{bmatrix} 0 & p & q \\ -p & 0 & r \\ -q & -r & 0 \end{bmatrix} + \begin{bmatrix} 0 & -p & -q \\ p & 0 & -r \\ q & r & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

(vi) For each matrix P in V , cP should also be in V where c is scalar

$$\therefore A = \begin{bmatrix} 0 & p & q \\ -p & 0 & r \\ -q & -r & 0 \end{bmatrix} \Rightarrow cA = \begin{bmatrix} 0 & cp & cq \\ -cp & 0 & cr \\ -cq & -cr & 0 \end{bmatrix}$$

cA is a skew-symmetric matrix.
 Hence, $cA \in V$.

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$$(vii) \quad c(A+B) = cA + cB$$

$$c(A+B) = c \begin{bmatrix} 0 & p+l & q+m \\ -(p+l) & 0 & r+n \\ -(q+m) & -(r+n) & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & cp+cl & cq+cm \\ -cp-cl & 0 & cr+cn \\ -cq-cm & -cr-cn & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & cp & cq \\ -cp & 0 & cr \\ -cq & -cr & 0 \end{bmatrix} + \begin{bmatrix} 0 & cl & cm \\ -cl & 0 & cn \\ -cm & -cn & 0 \end{bmatrix}$$

$$= cA + cB$$

$$(viii) \quad (c+d)A = cA + dA$$

$$(c+d)A = \begin{bmatrix} 0 & p & q \\ -p & 0 & r \\ -q & -r & 0 \end{bmatrix} (c+d)$$

$$= \begin{bmatrix} 0 & cp+dp & cq+dr \\ -cp-dp & 0 & cr+dr \\ -cq-dr & -cr-dr & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & cp & cq \\ -cp & 0 & cr \\ -cq & -cr & 0 \end{bmatrix} + \begin{bmatrix} 0 & dp & dr \\ -dp & 0 & dr \\ -dr & -dr & 0 \end{bmatrix}$$

$$= cA + dA$$

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$$(ix) c(dA) = (cd)(A)$$

$$c(dA) = c \begin{bmatrix} 0 & dp & dv \\ -dp & 0 & dr \\ -dv & -dr & 0 \end{bmatrix} = \begin{bmatrix} 0 & (cd)p & (cd)v \\ -(cd)p & 0 & (cd)r \\ -(cd)v & -(cd)r & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & (cd)p & (cd)v \\ -p(cd) & 0 & (cd)r \\ -q(cd) & -r(cd) & 0 \end{bmatrix}$$

$$= (cd)(A)$$

$$(x) 1 A = A$$

it is clearly satisfied.

Hence, V is a vector space

Since, any matrix in V can be represented as

$$\begin{bmatrix} 0 & p & qr \\ -p & 0 & r \\ -qr & -r & 0 \end{bmatrix} = p \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + qr \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix} + r \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$

$$\therefore \text{basis of } V = \left\{ \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} \right\}$$

\therefore dimension of V = number of vectors in basis

$$\therefore \dim V = 3$$

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Similarly a $n \times n$ skew-symmetric set will be a vector space.

For a $n \times n$ skew-symmetric matrix

dimension = no. of elements - no. of zeroes - similar elements

$$= n^2 - n - \frac{(n^2 - n)}{2}$$

$$= \frac{n(n-1)}{2}$$

3. Let V be the set of all vectors of the form

$$C = \begin{bmatrix} a - 2b + 5c \\ 2a + 5b - 8c \\ -a - 4b + 7c \\ a + b + 4c \end{bmatrix} . \text{ Is } V \text{ a vector space? If yes}$$

find its basis.

Let A and $B \in V$.

$$\therefore A = \begin{bmatrix} p - 2q + 5r \\ 2p + 5q - 8r \\ -p - 4q + 7r \\ p + q + 4r \end{bmatrix} \text{ and } B = \begin{bmatrix} l - 2m + 5n \\ 2l + 5m - 8n \\ -l - 4m + 7n \\ l + m + 4n \end{bmatrix}$$

It can be easily verified that

- $A+B = B+A$
- $(A+B)+C = A+(B+C)$
- $A+(-A) = 0$
- $\delta(A+B) = \delta A + \delta B$

- $(\delta + \gamma) A = \delta A + \gamma A$
- $\delta(\gamma A) = (\delta\gamma) A$
- $cA \in V$
- If $p = q = r = 0$, zero vector is in V .
- $1A = A$

Apart from properties mentioned above only one property remains that is necessary for V to be vector space.

that property is $(A+B) \in V$.

$$\therefore A+B = \begin{bmatrix} p - 2q + 5r \\ 2p + 5q - 8r \\ -p - 4q + 7r \\ p + q + 4r \end{bmatrix} + \begin{bmatrix} l - 2m + 5n \\ 2l + 5m - 8n \\ -l - 4m + 7n \\ l + m + 4n \end{bmatrix}$$

$$= \begin{bmatrix} (p+l) - 2(q+m) + 5(r+n) \\ 2(p+l) + 5(q+m) - 8(r+n) \\ -(p+l) - 4(q+m) + 7(r+n) \\ (p+l) + (q+m) + 4(r+n) \end{bmatrix}$$

Hence, $A+B \in V$.

$\therefore V$ is a vector space.

Since any vector in V can be represented as

$$A = \begin{bmatrix} p - 2q + 5r \\ 2p + 5q - 8r \\ -p - 4q + 7r \\ p + q + 4r \end{bmatrix}$$

$$A = P \begin{bmatrix} 1 \\ 2 \\ -1 \\ 1 \end{bmatrix} + Q \begin{bmatrix} -2 \\ 5 \\ -4 \\ 1 \end{bmatrix} + R \begin{bmatrix} 5 \\ -8 \\ 7 \\ 4 \end{bmatrix}$$

v_1 v_2 v_3

Hence any vector in V can be formed using the vectors v_1, v_2 and v_3 .

$$\therefore \text{basis of } V = \{v_1, v_2, v_3\}$$

$$= \left\{ \begin{bmatrix} 1 \\ 2 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 5 \\ -4 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ -8 \\ 7 \\ 4 \end{bmatrix} \right\}$$

4. Which of the following sets are linearly independent set in $\mathbb{R}[x]$?

(a) $\{1, 2x+1, 3x^2, x\}$

(b) $\{2x+1, 3x+2\}$

(c) $\{1, x+1, x^2+x+1, x^3+x^2+x+1\}$

a) the Set will be linearly independent only if

$$c_1(1) + c_2(2x+1) + c_3(3x^2) + c_4(x) = 0 \quad \text{--- (1)}$$

has only trivial solutions.

It is clear that if $c_1 = -1, c_4 = -2, c_3 = 0$

and $c_2 = 1$, then,

$$c_1(1) + c_2(2x+1) + c_3(3x^2) + c_4(x) = 0$$

Hence, a non-trivial solution of equation 1 exists.

Hence, the given set is not linearly independent.

b) for the set to be linearly independent

$$c_1(2x+1) + c_2(3x+2) = 0 \text{ must have}$$

trivial solutions only.

The above equation can be represented as

$$\begin{bmatrix} x & 1 \\ 3x^2 & 1 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = 0$$

The equation will have trivial solutions only if there are 2 pivot columns in $\begin{bmatrix} 2 & 3 \\ 1 & 2 \end{bmatrix}$ (say A)

$$\therefore A = \begin{bmatrix} 2 & 3 \\ 1 & 2 \end{bmatrix}$$

$$\text{ref of } A = \begin{bmatrix} 2 & 3 \\ 0 & 1/2 \end{bmatrix}$$

Since, there are two ^{pivot} entries, only trivial solution exists and hence the vectors in the set are linearly independent.

(C) for the set to be linearly independent

$$c_1(1) + c_2(x+1) + c_3(x^2+x+1) + c_4(x^3+x^2+x+1) = 0 \quad (1)$$

must have only trivial solutions.

equation 1 can be represented as

$$\begin{bmatrix} 1 & x & x^2 & x^3 \end{bmatrix} \left[\begin{array}{cccc} 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right] \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix} = 0$$

$\underbrace{\qquad\qquad\qquad}_{A}$

equation will have only trivial solution iff A has 4 pivot entries. As A is already in its row echelon form and has four pivot entries, only trivial solution exists.

Hence, the vectors in the set are linearly independent.

5. Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear transformation defined by

$$T \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 + 3x_2 - 2x_3 \\ 2x_1 + 3x_2 \\ x_2 - x_3 \end{bmatrix}$$

Determine whether T is an isomorphism and if so find the formula for inverse of linear transformation T^{-1} .

The transformation T will be isomorphic if it is invertible. T will be invertible if the standard matrix representation of T, say A, is bijective.

$$\therefore A_{3 \times 3} = [T(e_1) \ T(e_2) \ T(e_3)]$$

$$= \begin{bmatrix} 1 & 3 & -2 \\ 2 & 3 & 0 \\ 0 & 1 & -1 \end{bmatrix}$$

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reducing A to its Row echelon form

$$R_2 \rightarrow R_2 - 2R_1$$

$$\sim \left[\begin{array}{ccc|c} 1 & 3 & -2 & 7 \\ 0 & -3 & 4 & \\ 0 & 1 & -1 & \end{array} \right]$$

$$R_3 \rightarrow R_3 + \frac{1}{3}R_2$$

$$\text{REF of } A = \left[\begin{array}{ccc|c} 1 & 3 & -2 & 7 \\ 0 & -3 & 4 & \\ 0 & 0 & \frac{1}{3} & \end{array} \right]$$

Since, REF of A has three pivot entries, hence T is both one-one and onto, and hence T is isomorphic.

$$\text{Let us suppose } T \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$$\therefore y_1 = x_1 + 3x_2 - 2x_3$$

$$y_2 = 2x_1 + 3x_2$$

$$y_3 = x_2 - x_3$$

To find T^{-1} , we have to convert x_1, x_2 and x_3 in terms of y_1, y_2 and y_3 and then replace x by y .

The augmented matrix system for the above equations

$$\left[\begin{array}{ccc|c} 1 & 3 & -2 & y_1 \\ 2 & 3 & 0 & y_2 \\ 0 & 1 & -1 & y_3 \end{array} \right]$$

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$$R_2 \rightarrow R_2 - 2R_1$$

$$\left[\begin{array}{ccc|c} 1 & 3 & -2 & y_1 \\ 0 & -3 & 4 & y_2 - 2y_1 \\ 0 & 1 & -1 & y_3 \end{array} \right]$$

$$R_3 \rightarrow R_3 + \frac{1}{3}R_2$$

$$\left[\begin{array}{ccc|c} 1 & 3 & -2 & y_1 \\ 0 & -3 & 4 & y_2 - 2y_1 \\ 0 & 0 & \frac{1}{3} & y_3 + \frac{y_2 - 2y_1}{3} \end{array} \right]$$

$$R_3 \rightarrow 3R_3$$

$$\left[\begin{array}{ccc|c} 1 & 3 & -2 & y_1 \\ 0 & -3 & 4 & y_2 - 2y_1 \\ 0 & 0 & 1 & 3y_3 + y_2 - 2y_1 \end{array} \right]$$

$$R_2 \rightarrow R_2 - 4R_3$$

$$\left[\begin{array}{ccc|c} 1 & 3 & -2 & y_1 \\ 0 & -3 & 0 & y_2 - 2y_1 - 12y_3 - 4y_2 + 8y_1 \\ 0 & 0 & 1 & 3y_3 + y_2 - 2y_1 \end{array} \right]$$

$$R_1 \rightarrow R_1 + 2R_3$$

$$\left[\begin{array}{ccc|c} 1 & 3 & 0 & y_1 + 6y_3 + 2y_2 - 4y_1 \\ 0 & -3 & 0 & 6y_1 - 3y_2 - 12y_3 \\ 0 & 0 & 1 & 3y_3 + y_2 - 2y_1 \end{array} \right]$$

$$R_1 \rightarrow R_1 + R_2$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 3y_1 - y_2 - 6y_3 \\ 0 & -3 & 0 & 6y_1 - 3y_2 - 12y_3 \\ 0 & 0 & 1 & 3y_3 + y_2 - 2y_1 \end{array} \right]$$

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$$R_2 \rightarrow -\frac{1}{3} R_2$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 3y_1 - y_2 - 6y_3 \\ 0 & 1 & 0 & -2y_1 + y_2 + 4y_3 \\ 0 & 0 & 1 & -2y_1 + y_2 + 3y_3 \end{array} \right]$$

$$\therefore \begin{aligned} x_1 &= 3y_1 - y_2 - 6y_3 \\ x_2 &= -2y_1 + y_2 + 4y_3 \\ x_3 &= -2y_1 + y_2 + 3y_3 \end{aligned}$$

Replace x_1, x_2, x_3 by y_1, y_2, y_3 .

$$\therefore \begin{aligned} y_1 &= 3x_1 - x_2 - 6x_3 \\ y_2 &= -2x_1 + x_2 + 4x_3 \\ y_3 &= -2x_1 + x_2 + 3x_3 \end{aligned}$$

$$\therefore T^{-1} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$$T^{-1} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3x_1 - x_2 - 6x_3 \\ -2x_1 + x_2 + 4x_3 \\ -2x_1 + x_2 + 3x_3 \end{bmatrix}$$

6. Let S be a finite minimal set spanning a vector space V . That is, S has the property that if a vector is removed from S , then the new set will no longer span V . Prove that S must be a basis of V .

Suppose the set S with the described property be linearly dependent. This means that there at least one vector $x \in S$ which is a

linear combination of other vectors in S . If we remove the vectors x , then also the remaining vectors $\underset{S - \{x\}}{\sim}$ will span same space as that of S .

This contradicts the property of S given in question, that says if you remove a vector from S it will no longer span V .

Hence, S must be a set of linearly independent vectors that spans V . Hence, S is a basis of ~~V~~ vector space V because a set of linearly independent vectors that span the vector space is the basis of vector space.

T. Show that if A is $n \times n$ and B is $n \times p$, then $\text{rank}(AB) \leq \text{rank}(A)$.

rank of a matrix is dimension of its column space.

$$\therefore \text{rank}(AB) = \dim(\text{Col } AB)$$

$$\text{and, } \text{rank}(A) = \dim(\text{Col } A)$$

If a vector v is ~~subset~~ subset of another vector space w , then

$$\dim(v) \leq \dim(w)$$

→ (1)

Now, consider any vector $y \in \text{Col } AB$. Then there exists a vector $x \in \mathbb{R}^p$ such that

$$y = (AB)x$$

by the definition of column space.

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Let $z = Bx \in \mathbb{R}^n$.

∴ we have

$$\begin{aligned}y &= (AB)x = A(Bx) \\&= Az\end{aligned}$$

hence, any vector $y \in \text{Col } AB$ also belongs to $\text{Col } A$.

∴ $\text{Col } AB$ is a subset of $\text{Col } A$.

∴ $\dim(\text{Col } AB) \leq \dim(\text{Col } A)$ {from ①}

$$\text{rank}(AB) \leq \text{rank } A.$$

Hence, proved.

Q. Show that if A is $n \times n$ matrix and B is $n \times p$ matrix; then $\text{rank}(AB) \leq \text{rank } B$.

$$\therefore \text{Rank}(D) = \text{Rank}(D^T) \quad \text{--- (1)}$$

$$\begin{aligned}\therefore \text{Rank}(AB) &= \text{Rank}(AB^T) \\&= \text{Rank}(B^T A^T)\end{aligned}$$

Also from previous question,
 $\text{Rank}(CD) \leq \text{Rank } C$

$$\therefore \text{Rank}(B^T A^T) \leq \text{Rank}(B^T)$$

$$\text{Rank} \{(B^T A^T)^T\} \leq \text{Rank}((B^T)^T) \quad \{\text{from ①}\}$$

$$\text{Rank}(AB) \leq \text{Rank}(B)$$

Hence, proved that $\text{rank}(AB) \leq \text{rank}(B)$.

9. Let V be a vector space over R of dimension n .

Let V' be the set of all linear transformation from V to V . Show that V' is also a vector space over R and find its basis.

Let $T, S \in V'$. Then, S and T are linear transformations from V to V ,

then $T+S: V \rightarrow V$

such that $(T+S)(u) = T(u) + S(u)$

Let us prove that $T+S$ is a linear map:

$$\begin{aligned} \therefore (T+S)(u+v) &= (\cancel{T} + \cancel{S})(u+v) + S(u+v) \\ &= T(u) + T(v) + S(u) + S(v) \\ &= (T+S)u + (T+S)v \end{aligned}$$

$$\begin{aligned} \text{and, } (T+S)(cu) &= T(cu) + S(cu) \\ &= cT(u) + cS(u) \quad (\because T \text{ and } S \text{ are LT}) \\ &= c(T+S)(u) \end{aligned}$$

Hence, $T+S$ is a linear transformation, hence it belongs to vector space V' .

Now, we have to prove V' is a vector space.

(i) for $T, S \in V'$, $T+S \in V'$ (proved above)

(ii) for $T \in V'$, cT also belongs to V'

(iii) $T=0$ is also a linear transformation.

$$(iv) (c+d)T = cT + dT \quad \forall T \in V'$$

$$(v) c(dT) = (cd)T \quad \forall T \in V'$$

(vi) for every T in V' , there exists $-T$ such that
 $T + (-T) = 0$

$$(vii) \text{ For every } T, U, V \in V' \\ T + (U + V) = (T + U) + V$$

Hence, the ~~vector~~ space V' satisfies all properties
of a ~~vector~~
^{vector}
space, hence it is a vector space.

Now, suppose $\{v_1, v_2, \dots, v_n\}$ is a basis for V .
for $i=1 \dots n$ define f_i belongs to V' by,

$$f_i(a_1v_1 + a_2v_2 + \dots + a_nv_n) = a_i$$

for constants a_i .

Note that f_i is uniquely valued for each v_j in V .
Also, $f_i(v_j) = 1$ for $i=j$ and 0 otherwise.

Consider the linear combination $a_1f_1 + \dots + a_nf_n = 0$.

Taking the value at every v_j , we get $a_j = 0$
showing that $\{f_1, f_2, \dots, f_n\}$ is linearly independent.

Let g be a vector in V' . Assume g cannot be written as $a_1f_1 + \dots + a_nf_n$. Then the value of g is zero. This shows that every member of V' is either 0 or linear combination of $\{f_1, f_2, \dots, f_n\}$. Hence, $\{f_1, f_2, \dots, f_n\}$ spans V' .

$\therefore \{f_1, f_2, \dots, f_n\}$ is a basis of V' .

10. Suppose that U and W are finite dimensional subspaces of a vector space V . Then show that $U+W$ is also finite dimensional subspace and $\dim(U+W) = \dim(U) + \dim(W) - \dim(U \cap W)$ where $U+W = \{x \mid x = y+z \text{ for some } y \in U, z \in W\}$

(Note: $U+W$ is smallest subspace containing $U \cup W$)

Let $v \in U+W$ and $v' \in U+W$. Suppose $v = u+w$ and $v' = u'+w'$ where $u, u' \in U$ and $w, w' \in W$.

Then $v+v' = (u+u') + (w+w')$. This is in $U+W$. Since U and W are closed under addition, thus $u+u' \in U$ and $w+w' \in W$.

Theorem: If U, W are two subspaces of a vector space V , then

$$\dim(U+W) = \dim U + \dim W - \dim(U \cap W)$$

Proof: Let $\dim(U \cap W) = k$

And the set $S = \{\gamma_1, \gamma_2, \dots, \gamma_k\}$ be a basis of $U \cap W$.

Then $S \subseteq U$ and $S \subseteq W$.

Since, S is linearly independent and $S \subseteq U$

Therefore, S can be extended to form a basis of U .

Let $\{\lambda_1, \lambda_2, \dots, \lambda_k, \alpha_1, \alpha_2, \dots, \alpha_m\}$ be a basis of U .

$$\therefore \dim U = k+m$$

Similarly let $\{\lambda_1, \lambda_2, \dots, \lambda_k, \beta_1, \beta_2, \dots, \beta_n\}$ be a basis of W .

$$\therefore \dim W = k+m+n$$

Now, to prove that $\dim(U+W) = k+m+n$, we claim set S_1 to be

$S_1 = \{\lambda_1, \lambda_2, \dots, \lambda_k, \alpha_1, \alpha_2, \dots, \alpha_m, \beta_1, \beta_2, \dots, \beta_n\}$
 in a basis of $U+W$.

First we have to show S_1 is linearly independent.

$$\text{Let } c_1\lambda_1 + c_2\lambda_2 + \dots + c_k\lambda_k + a_1\alpha_1 + \dots + a_m\alpha_m + b_1\beta_1 + \dots + b_n\beta_n = 0$$

$$\therefore (c_1\lambda_1 + \dots + c_k\lambda_k + a_1\alpha_1 + \dots + a_m\alpha_m) \in U$$

$$\text{and } b_1\beta_1 + b_2\beta_2 + \dots + b_n\beta_n \in W$$

$$\Rightarrow b_1\beta_1 + \dots + b_n\beta_n = -(c_1\lambda_1 + \dots + c_k\lambda_k + a_1\alpha_1 + \dots + a_m\alpha_m)$$

Hence, S_1 is linearly independent.

$$\Rightarrow b_1\beta_1 + b_2\beta_2 + \dots + b_n\beta_n \in U$$

and

$$b_1\beta_1 + b_2\beta_2 + \dots + b_n\beta_n \in W$$

$$\Rightarrow b_1\beta_1 + b_2\beta_2 + \dots + b_n\beta_n \notin U \cap W$$

\therefore It can be expressed as linear combination of basis of $U \cap W$.

Thus:-

$$b_1\beta_1 + \dots + b_n\beta_n = d_1\lambda_1 + d_2\lambda_2 + \dots + d_k\lambda_k$$

$$\Rightarrow b_1\beta_1 + \dots + b_n\beta_n - d_1\lambda_1 - d_2\lambda_2 - \dots - d_k\lambda_k = 0$$

But $\beta_1, \beta_2, \dots, \beta_k, \lambda_1, \lambda_2, \dots, \lambda_k$ are linearly independent

$$\Rightarrow b_1, b_2, b_3, \dots, b_n = 0$$

from ① we get

$$c_1\lambda_1 + c_2\lambda_2 + \dots + c_k\lambda_k + a_1\alpha_1 + \dots + a_m\alpha_m = 0$$

$$\Rightarrow c_1 = 0, c_2 = 0, \dots, c_k = 0 \quad [\because \lambda_1, \lambda_2, \dots, \lambda_k, a_1, a_2, \dots, a_m \text{ are linearly independent}]$$

$$a_1 = 0, a_2 = 0, \dots, a_m = 0$$

$\therefore S_1$ is a linearly independent set.

Now, prove $L(S_1) = U + W$

$\because U + W$ is subspace of V ,
 and each element of S_1 belongs to $U + W$.

$$\therefore L(S_1) \subseteq U + W \quad \text{--- } \textcircled{C}$$

Again, let α be any element of $U + W$.
 $\alpha \in U + W$.

i.e. $\alpha = \text{some element of } U + \text{some element of } W$

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$\alpha = \text{a linear combination of elements of basis } U$
 $+ \text{ a linear combination of elements of basis of } W$

$\alpha = \text{a linear combination of } S_1$

$$\therefore \alpha \in L(S_1) \Rightarrow U+W \subseteq L(S_1)$$

Hence, $L(S_1) = U+W$

∴ S_1 is a basis of $U+W$

$$\therefore \dim(U+W) = k+m+n$$