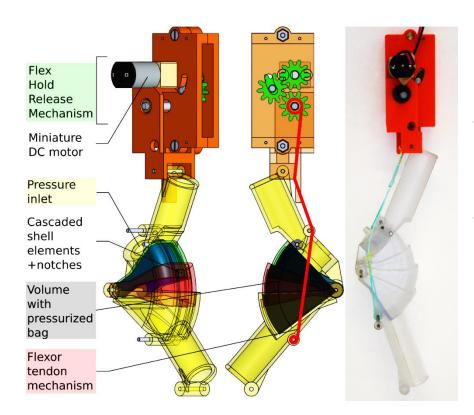


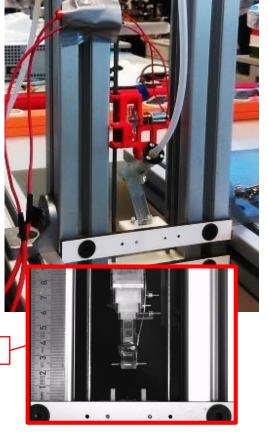
## **Spider Inspired Robotic Joint**

**ICRA 2017 Published Conference Paper** 



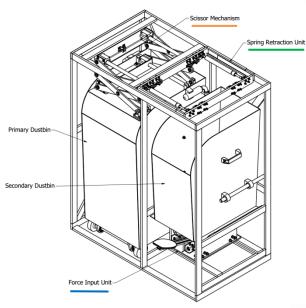
Designed spider
inspired pneumatic and
cable driven robotic
joint actuator
Fabricated it using 3D
printing, laser cutting
and rubber molding
Built two experiments
for its characterization
under static and
dynamic conditions

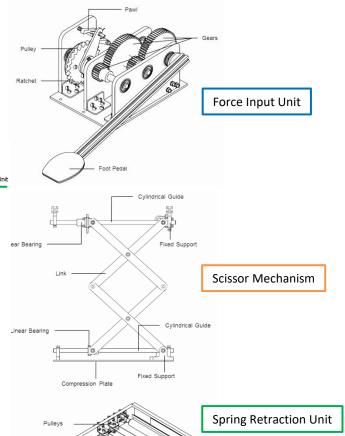
**Testing Apparatus** 



mid-jump snapshot







Cables







A trash-can capable of reducing regular municipal, residential and commercial garbage to less than one-third of its volume. Designed to be inexpensive and robust for use in Indian public spots

Awarded best Senior-year project

## Robocon 2015: Robominton

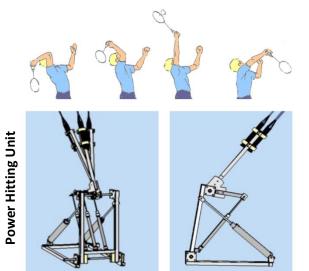
BADMINTON PLAYING ROBOTS

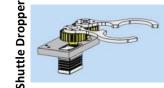


Built two robots to play badminton doubles game on an actual-size court against robots from other universities in a knock-out tournament

## Role: Senior Member/ Mechanical Lead (Racket actuation and Chassis Drive)

Designed and fabricated racket actuation mechanisms mimicking real badminton strokes used by human players during a match **D**evised holonomic drive mechanism for enhanced mobility of robots

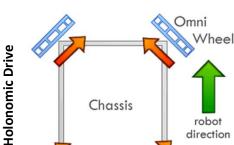


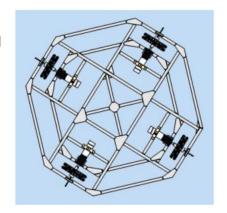












Service Mechanism

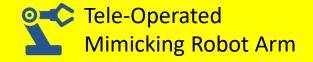
## **Assembled Robot**

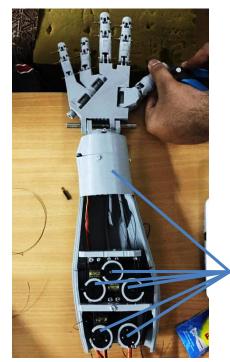


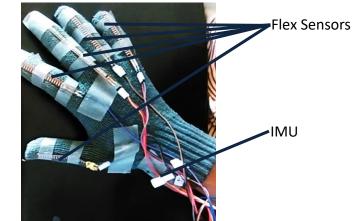














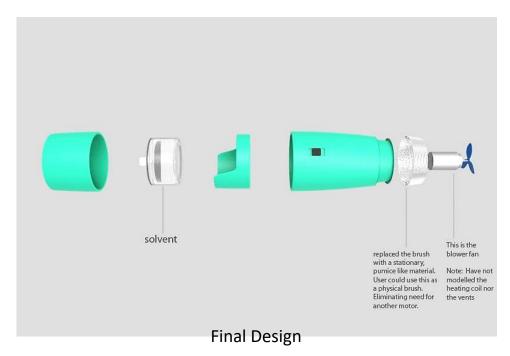
Controller Glove (Master)

Servo Motors

Recorded user arm movement using a glove equipped with IMU and flex sensors and converted sensor readings to appropriate motion commands for the bionic arm actuated using servo motors

Robot Arm (Slave)







Miniaturized dry cleaning
equipment and built hand-held
device capable of removing small
stains from clothing
Prototyped using 3D printing and
using commercial off-the-shelf
components
Finalist in 'Pitch your Product' at
Entrepreneurship Summit IITK 2016

