

Senior Undergraduate Mechanical Engineering Indian Institute of Technology, Kanpur, INDIA

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## **EDUCATION**

Qualification	Institute	Year	Performance
BTech Mechanical Engineering	Indian Institute of Technology, Kanpur	2013-2017	9.3/10
Intermediate (12 <sup>th</sup> CBSE)	Delhi Public School, Indira Nagar, Lucknow	2013	92.4%
High School (10th CBSE)	Delhi Public School, Indira Nagar, Lucknow	2011	CGPA 10

### RESEARCH INTERESTS

Robotics, Mechanical Design, Biomimetics

#### **PUBLICATION**

A. Spröwitz, K. Petersen, C. Göttler, A. Sinha, C. Caer, M. U. Öztekin, and M. Sitti, "Scalable Pneumatic and Tendon Driven Robotic Joint Inspired by Jumping Spiders", manuscript submitted for publication

### **INTERNSHIPS**

# MAX PLANCK INSTITUTE FOR INTELLIGENT SYSTEMS, STUTTGART **GUEST SCIENTIST**

(May 2016 – July 2016)

Project Title: "Scalable Pneumatic and Tendon Driven Robotic Joint Inspired by Jumping Spiders"

**Project Supervisors:** Dr. Metin Sitti, Dr. Alexander Spröwitz, Dr. Kirstin Petersen

- Developed a novel leg-joint mechanism employing both pneumatics and electrically-actuated tendons with its implementation closely inspired by joints seen in real spiders
- Designed and fabricated mechanical analogues of spider-leg joints using inferences drawn from scanning-electron microscope images of real spiders developed by another collaborator
- · Built cam-based cable-driven quick release mechanism to mimic the flexor muscles in spiders
- Designed and molded soft rubbery joints for their comparison against proposed spider-inspired joints
- · Built two experimental setups for characterization of the system under static and dynamic conditions

# TATA MOTORS LIMITED LUCKNOW

(May 2015 - June 2015)

Project Title: "Problem resolution and Root Cause Analysis for specified part belonging to vehicle's chassis"

Project Supervisor: Mr. Naveen Agnihotri

- Operated in Supplier Quality department to resolve a recurring fitment issue for a particular cross-member
- Identified possible causes of defect in its complete manufacturing process which led to the fitment issue
- · Altered the riveting fixture and replaced the worn out punch of bending press to eliminate the defect

## **PROJECTS**

SUMMER INTERN

### ROBOCON 2015 - ROBOMINTON

**NATIONAL ROBOTICS CONTEST** (Centre for Mechatronics, IITK)

(September 2014 – March 2015)

- Designed and built two badminton playing robots for doubles match on an actual size court
- · Synthesized mechanisms for racket actuation to implement various badminton strokes
- Devised a pneumatically powered double actuation mechanism which replicates the combined motion of the elbow and wrist joints while playing a badminton stroke
- · Selected suitable pneumatic pistons and motors for driving the mechanisms with required speed and force
- · Implemented holonomic drive using omni wheels to provide three degrees of freedom to the chassis
- Finished Eleventh in eighty-five teams representing different universities from all over India

### MECHANICALLY ACTUATED GARBAGE COMPACTOR

**DEPARTMENTAL PROJECT** (Dr. Bishakh Bhattacharya, Mechanical Engineering, IITK)

(August 2016 – Ongoing)

- · Aim at developing inexpensive and robust garbage compressing solution for Indian circumstances
- Constructed mechanism for amplifying user input force without using electronics or hydraulics
- Current design generates 1635N output for an input of 300N and achieves compression factor of five

# ■ DEVELOPMENT OF PENNATE MUSCLE INSPIRED ACTUATOR USING SHAPE MEMORY ALLOY WIRES

**COURSE TERM PAPER** (Smart Materials and Structures)

(January 2016 - April 2016)

- · Conceptualised Shape Memory Alloy (SMA) based actuator inspired by the functioning of pennate muscles
- · Established kinematic and force formulations for the SMA based actuator
- Determined relations between actuator characteristics like resultant force, displacement and actuation time

# HAND HELD DRY CLEANER (CLEANEASY)

**DESIGN PROJECT** (New Product Design and Prototyping)

(January 2016 – April 2016)

- Identified substantial untapped market needs with subsequent ideation of profitable solutions
- · Developed design and prototype of a novel device capable of performing all stages in dry cleaning process
- Performed and analysed market survey to identify potential customer segments and tuned product accordingly
- · Pitched idea along with business plan to ME department and won monetary grant for first stage prototyping

# ■ THERMODYNAMIC ANALYSIS OF SOLAR POWERED CLOSED CIRCUIT VAPOUR TURBINE

**SUMMER PROJECT** (Dr. Santanu De, Mechanical Engineering, IITK)

(June 2015 – July 2015)

- · Analysis of solar powered vapour turbine for production of electric power for domestic or small-scale use
- · Development of Aspen HYSYS models and their efficiency comparison through simulations

#### MODEL OF AN SEMI AUTOMATIC CAR PARKING SYSTEM

**COURSE PROJECT** (Manufacturing Processes Laboratory)

(January 2015 – April 2015)

- · Prepared CAD design and fabricated a small-scale hand-driven model of an automatic car parking system
- · Gained hands-on experience with basic machine-shop operations and conventional machining methods

## **AWARDS AND ACHIEVEMENTS**

- · Awarded **DAAD WISE 2016 Scholarship** for pursuing summer internship in Germany at MPI for Intelligent Systems
- Received Academic Excellence Award for the year 2013-14 at Indian Institute of Technology Kanpur
- Ranked among **Top 0.2% of 1.3 million** applicants in Joint Entrance Examination for engineering in India in 2013
- · Ranked among the Top 0.1% of successful candidates in Physics in All India Senior Secondary Board Examinations
- · Secured City Rank 1 and State Rank 8 in Science Olympiad Foundation's 14th National Science Olympiad
- · Secured All India Rank 41 in National Level Science Talent Search Examination 2012

# **KEY COURSES AND SKILLS**

• **CORE** : Robot Motion Planning\*, Probabilistic Mobile Robotics\*, Robot Manipulators, Theory of Mechanisms and Machines, Design of Machine Elements, Finite Element Methods, Smart Materials and Structures,

Mechanics of Solids, Vibration and Control

• BREADTH : Basics of Modern Control Systems, Fundamentals of Computing, Introduction to Electronics, Complex

Variables, Ordinary Differential Equations, Partial Differential Equations, Matrix and Determinants

• SKILLS : SolidWorks, Autodesk Inventor, AutoCAD, MATLAB, C, Latex, Web Development, Android Development Starred (\*) courses would be completed by May 2017

## POSITION OF RESPONSIBILITY

### **SENIOR MEMBER** – TEAM ROBOCON IITK 2015

- · Represented IIT Kanpur in National Robocon 2015 organized by Asia-Pacific Broadcasting Union
- Led a team of fifteen freshers to create two robots for playing doubles badminton matches against other teams
- · Arranged exhibitions at IIT's technical festival Techkriti 2015 and annual Science and Technology Day of IIT Kanpur
- · Felicitated by Science and Technology Council, IITK for contributions towards science and technical activities of institute

## **EXTRA CURRICULAR ACTIVITIES**

- Designed Nitinol actuated self-assembling structures for participating in 'Lab2Moon' contest which challenges teams to construct a useful experiment which will be sent on the Moon by a participant of Google's Lunar XPrize contest
- · Participated in Entrepreneur Summit IITK's 'Pitch Your Product' and presented our product 'CleanEasy' in finale round
- Stood 1st in Wild Soccer in Takneek 2015 the intra-institute technical festival of IIT Kanpur. The contest required the teams to build two robots aimed at playing soccer and destroying the opponent's robots
- Won the Stop-Motion Film making contest in Spectrum 2014 the intra-institute film festival of IIT Kanpur