

#### Graph Depth First Search

261217 Data Structures for Computer Engineers

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#### Motivation

You're playing a video game and want to make sure that you've found everything in a level before moving on.

How do you ensure that you accomplish this?

#### Examples

- This notion of exploring a graph has many applications:
  - Finding a routes
  - Ensuring connectivity
  - ■Solving puzzles and mazes

#### Paths

We want to know what is reachable from a given vertex.

#### Definition

A path in a graph G is a sequence of vertices  $v_0, v_1, \ldots, v_n$  so that for all i,  $(v_i, v_{i+1})$  is an edge of G.

#### Reachability

### Reachability

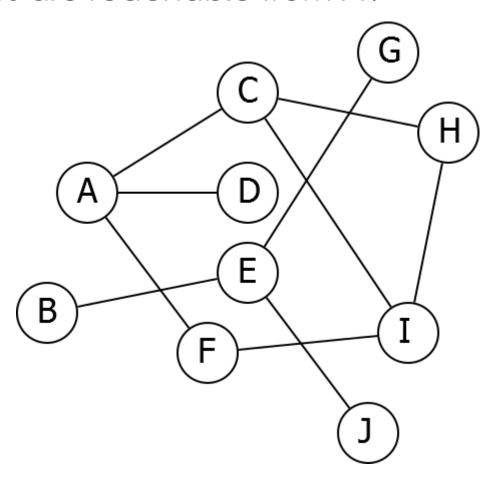
Input: Graph G and vertex s

Output: The collection of vertices v of G so

that there is a path from s to v.

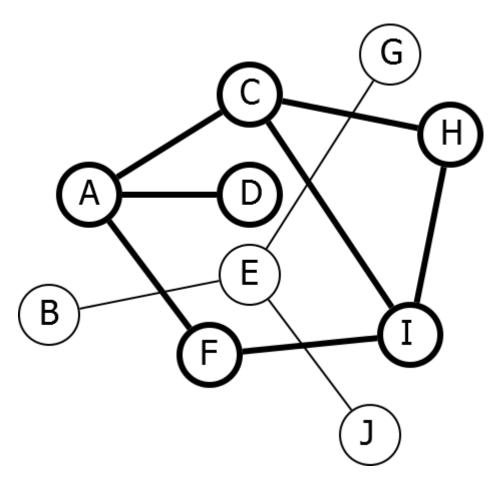
#### Problem

Which vertices are reachable from A?



#### Solution

A, C, D, F, H, I



#### Visit Marker

To keep track of vertices found:

Give each vertex boolean visited(v)

```
If (v.visited != true){
    // Do something
    v.visited = true;
}
```

#### Depth First Traversal

- To explore new edges in Depth First order
- To follow a long path forward, only backtracking when hitting a dead end

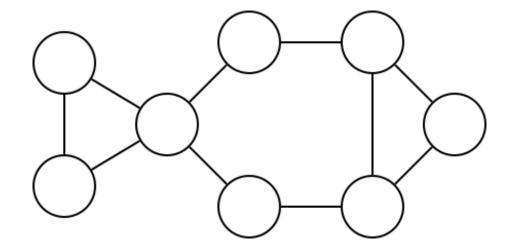
#### Depth First Exploration

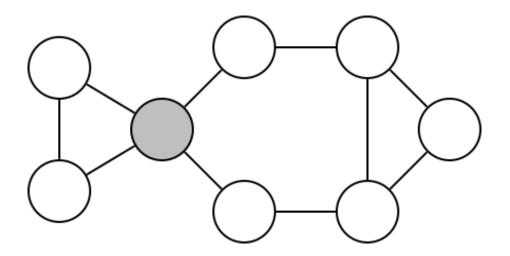
Explore will mark as visited all vertices reachable from v v, w are vertices; E is a set of all edges in the graph

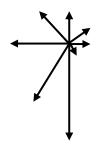
# Explore(v)

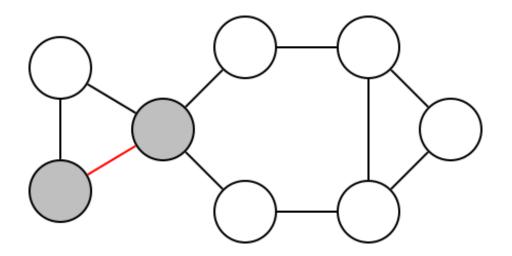
```
visited(v) ← true
for (v, w) \in E:
  if not visited(w):
    Explore(w)
```

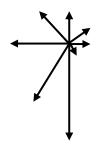
Need adjacency list representation!

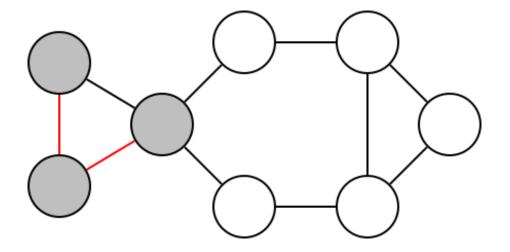


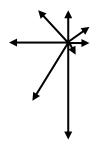


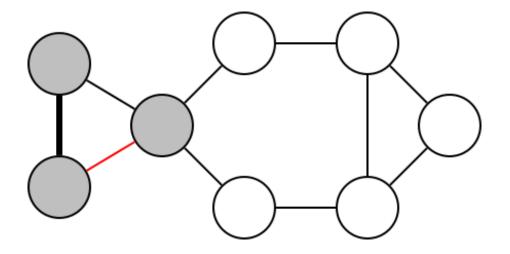


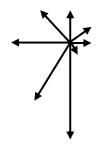


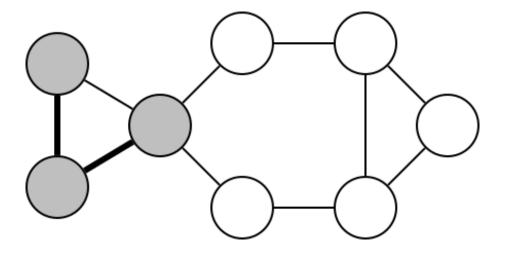


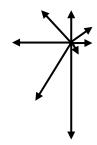


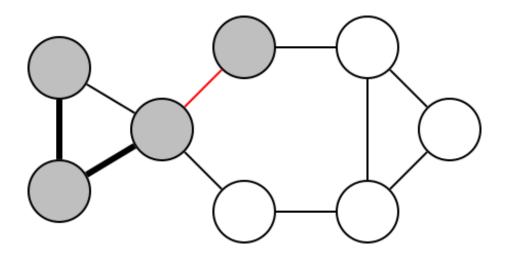


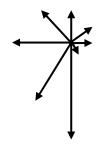


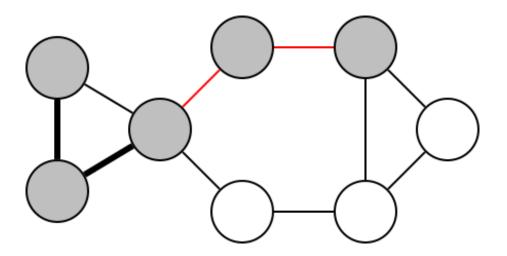


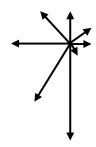


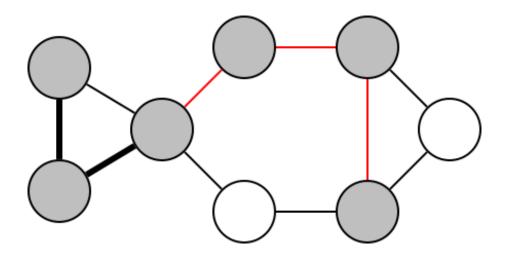


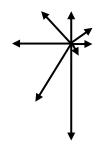


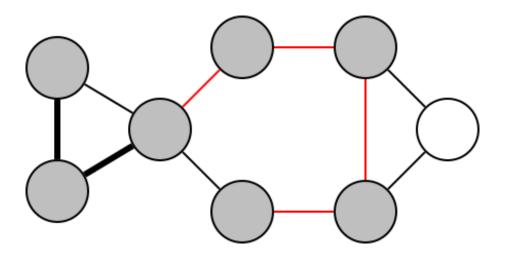


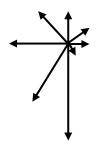


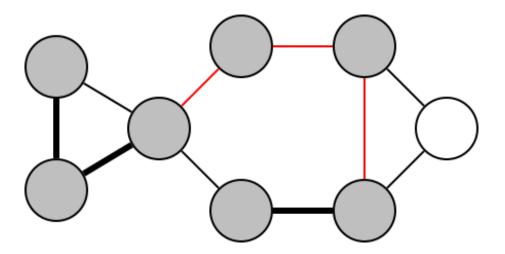


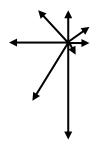


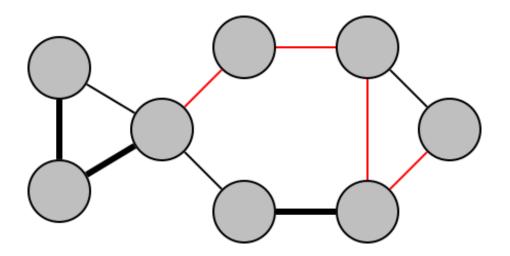


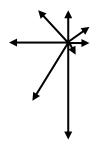


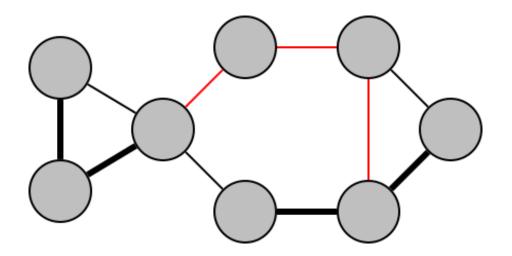


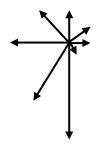


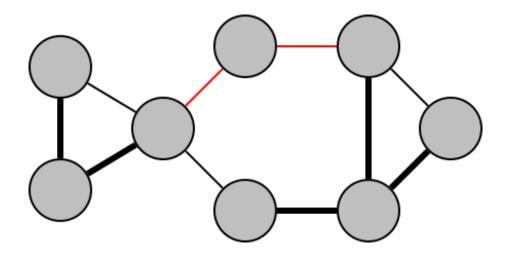


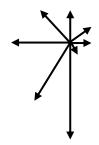


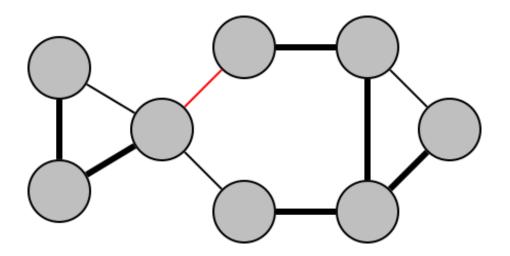


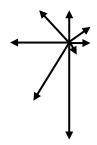


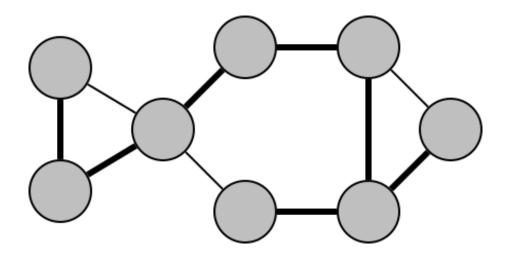


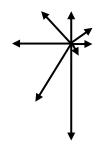












#### Result

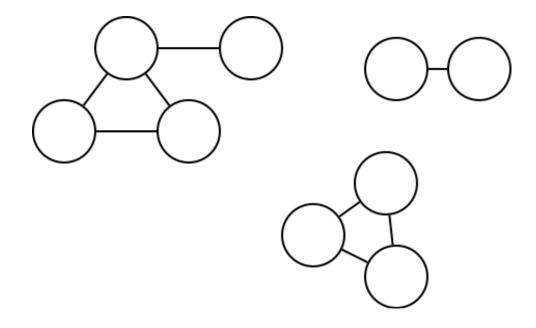
#### Theorem

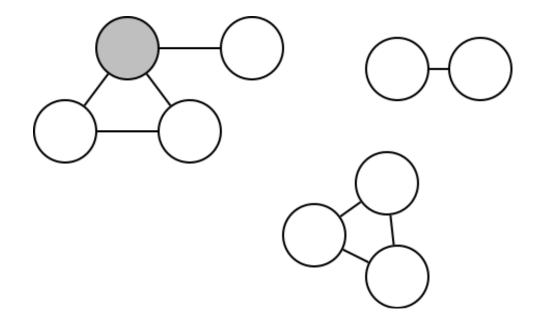
If all vertices start unvisited, Explore(v) marks as visited exactly the vertices reachable from v.

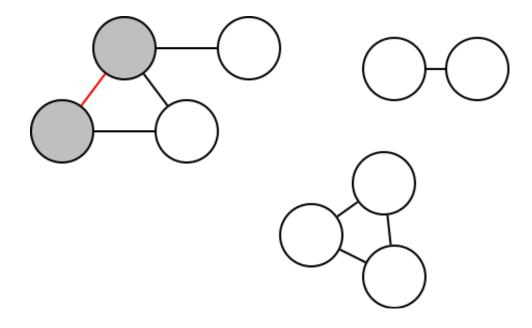
#### Depth First Search: DFS

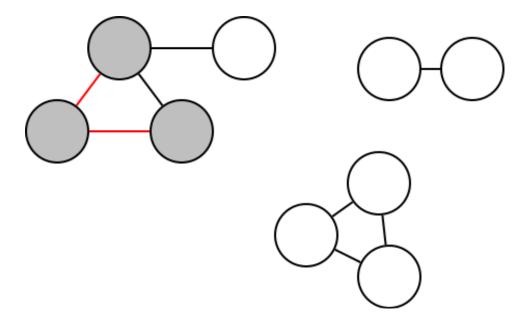
This algorithm will explore every node even though they are not connected

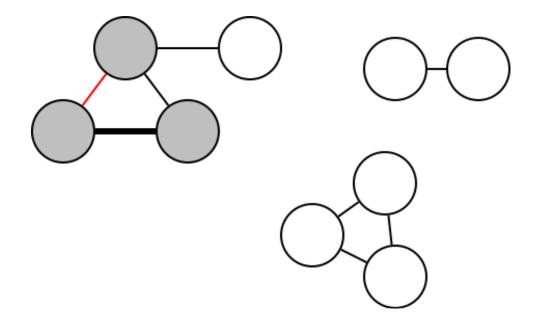
```
DFS(G)
for all v \in V:
                   mark v unvisited
for v \in V:
  if not visited(v):
    Explore(v)
```

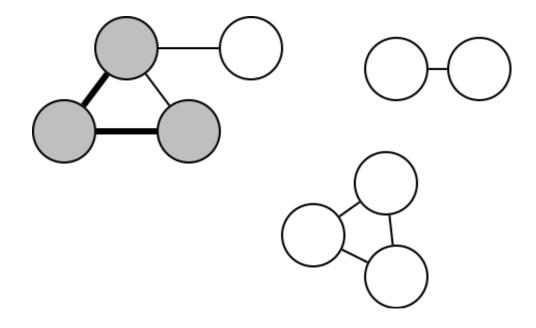


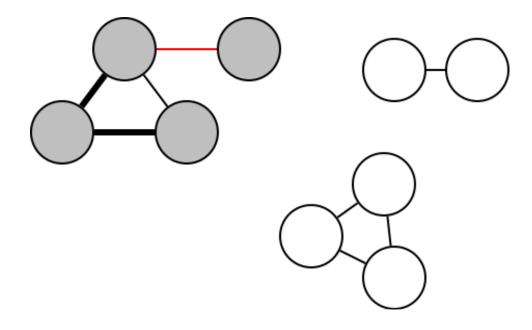


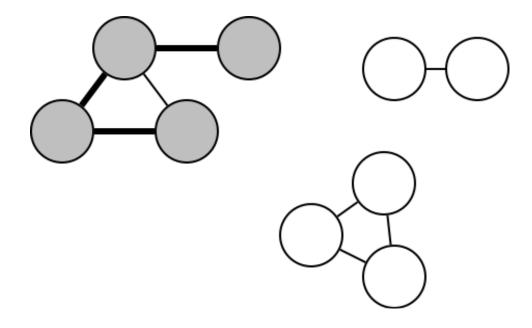


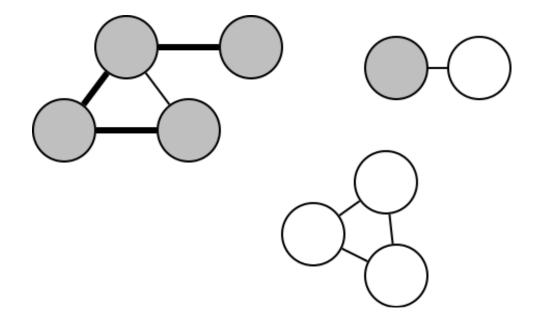


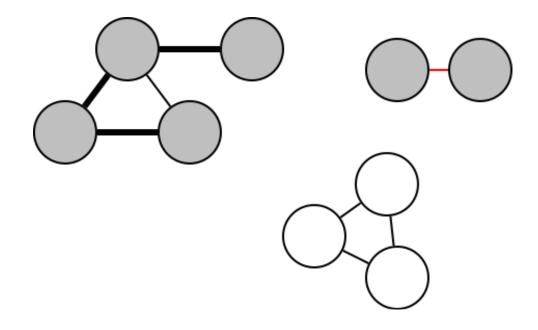


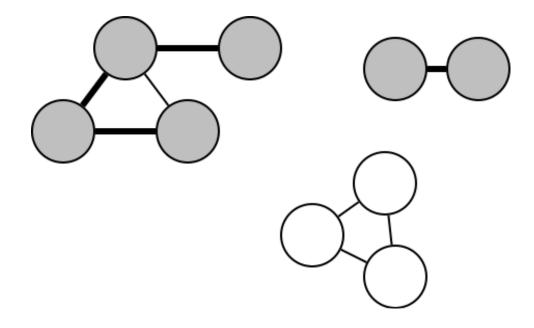


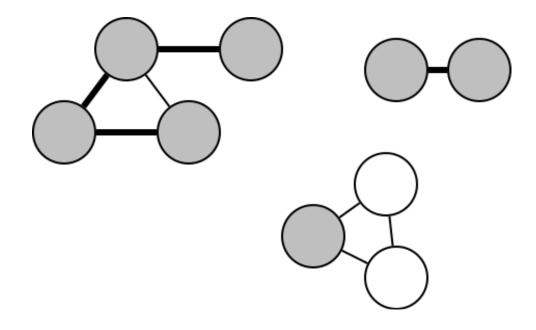


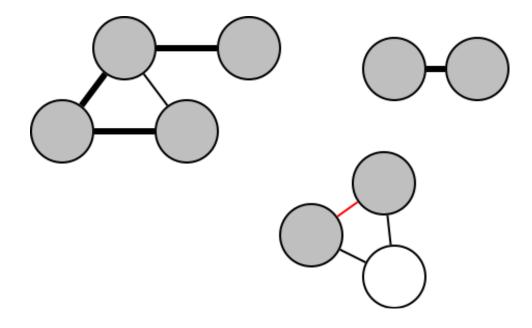


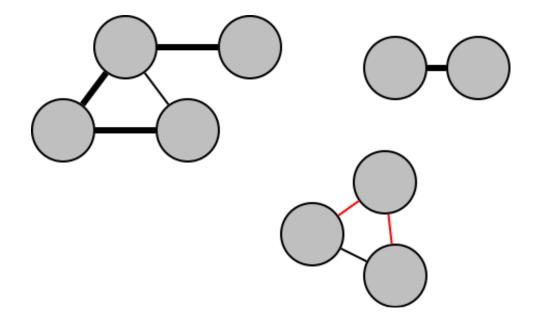


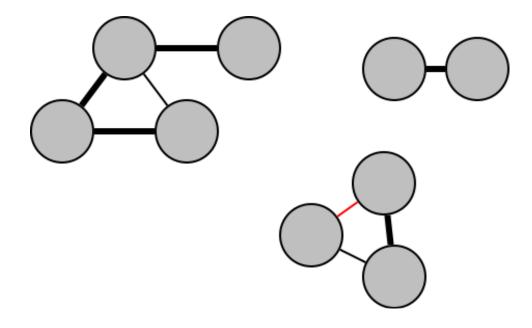


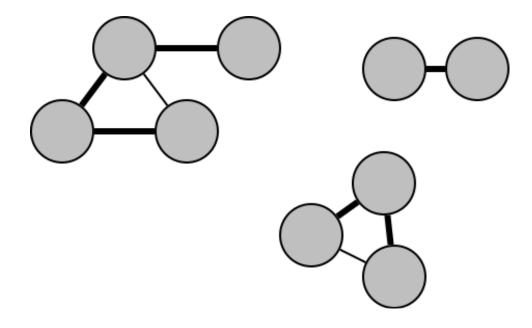












#### Runtime Analysis

- Number of calls to explore:
  - Each explored vertex is marked visited.
  - No vertex is explored after visited once.
  - Each vertex is explored exactly one.

#### Runtime Analysis

- Checking for neighbors:
  - Each vertex checks each neighbor.
  - Total number of neighbors over all vertices is O(|E|)

#### Runtime Analysis

- Total runtime:
  - O(1) work per vertex
  - O(1) work per edge
  - Total O(|V| + |E|)

#### Connected Components

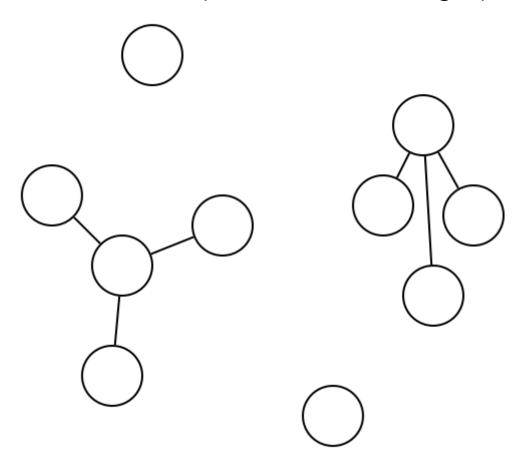
The vertices of a graph G can be partitioned into **Connected Components** so that v is reachable from w

if and only if

they are in the same connected component.

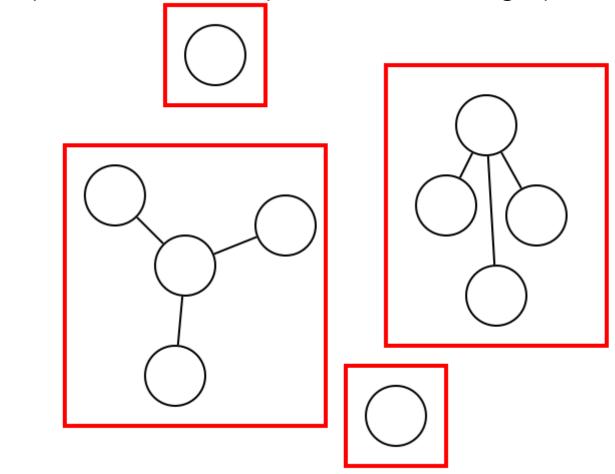
#### Problem

How many connected components does the graph below have?



#### Solution

How many connected components does the graph below have?



#### Connected Component Algorithm

- Explore(v) finds the connected component of v. Just need to repeat to find other components.
- Modify DFS to do this.
- Modify goal to label connected components.

#### Modification of Explore

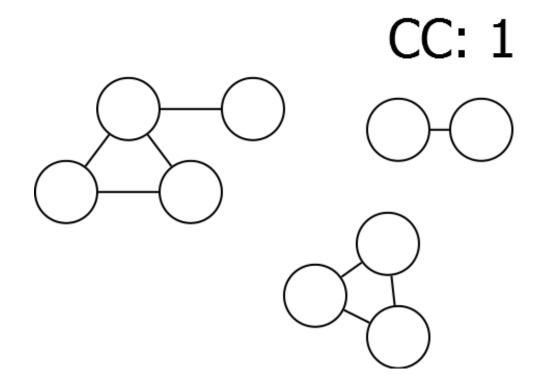
```
visited(v) \leftarrow true
CCnum(v) \leftarrow cc
for (v, w) \in E:
if not visited(w):
Explore(w)
```

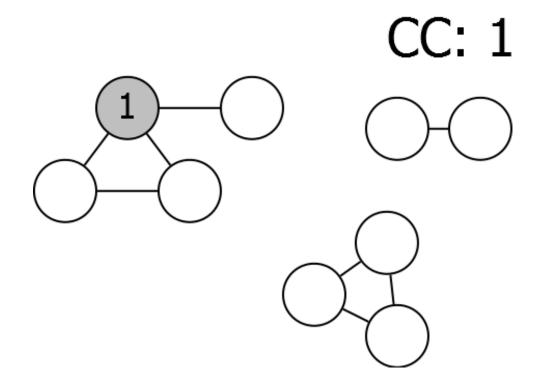
Explore(v)

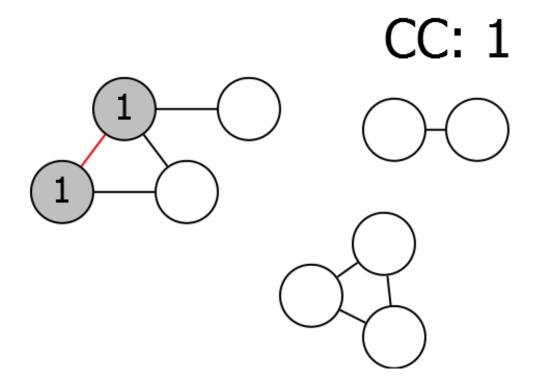
#### Modification of DFS

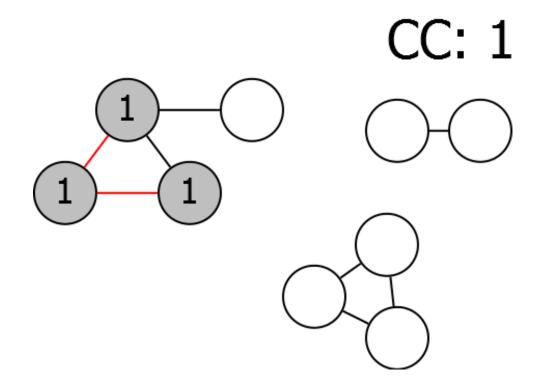
# DFS(G)

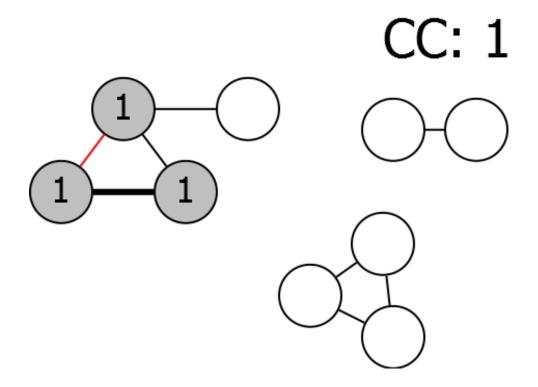
```
for all v \in V mark v unvisited
cc \leftarrow 1
for v \in V:
  if not visited(v):
     Explore(v)
     cc \leftarrow cc + 1
```

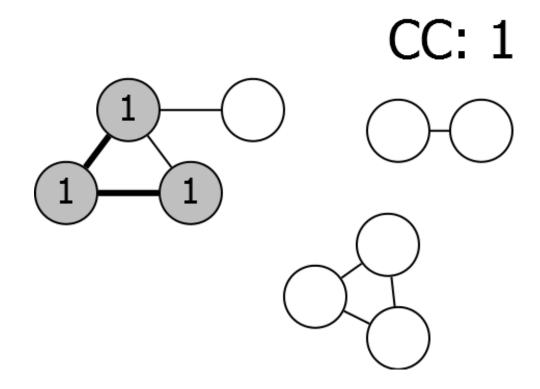


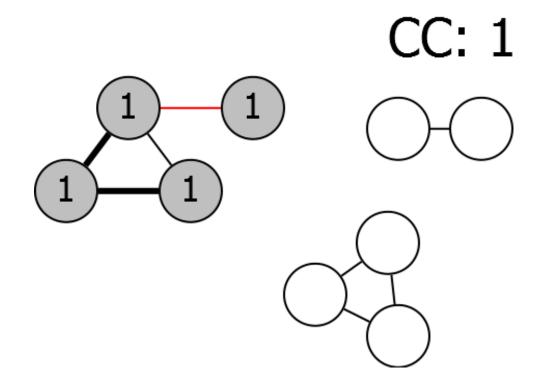


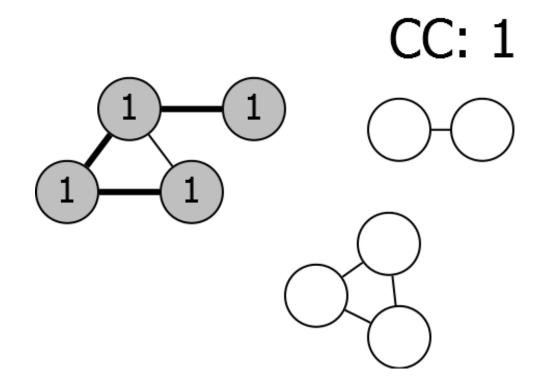


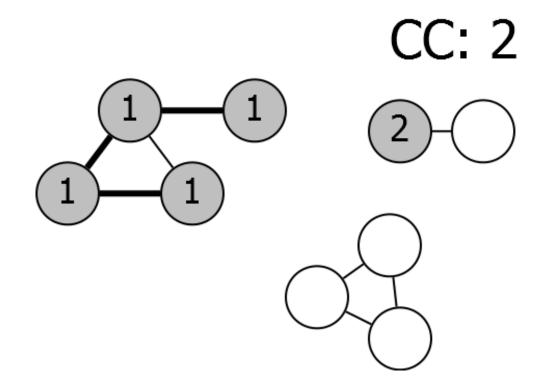


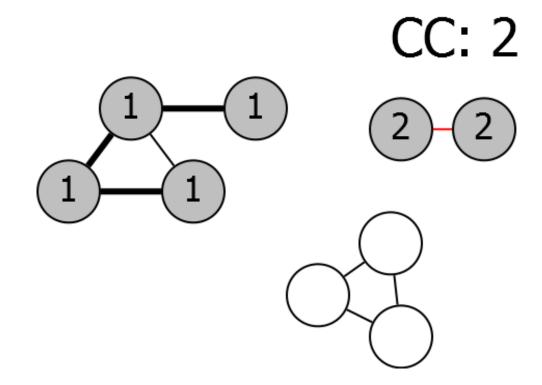


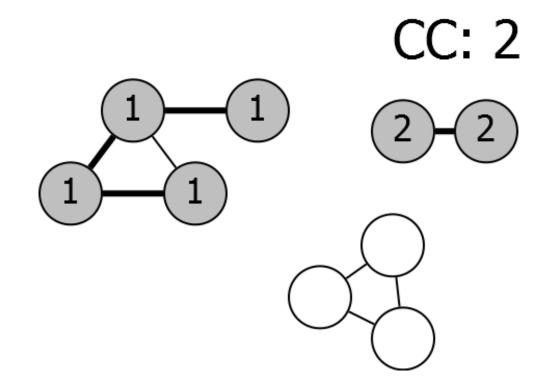


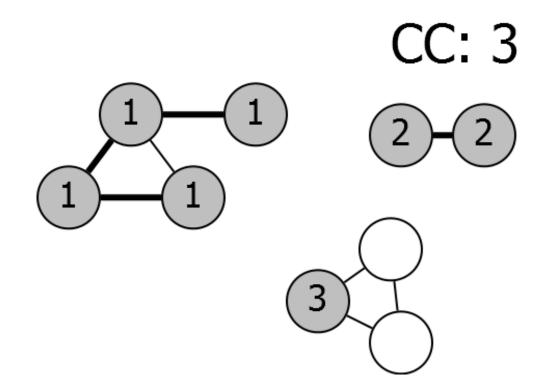


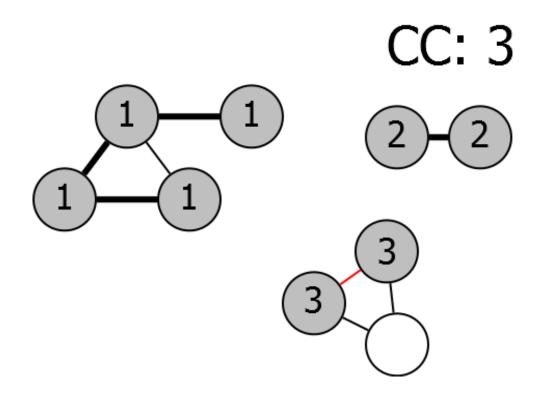


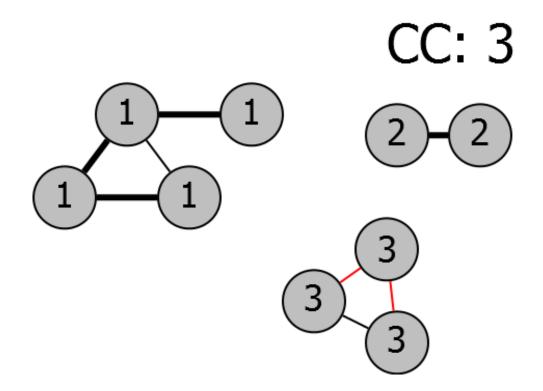


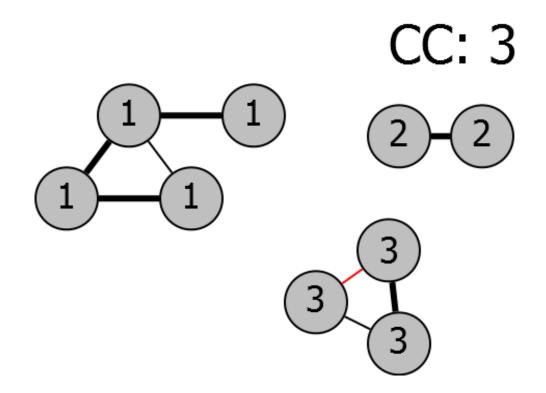


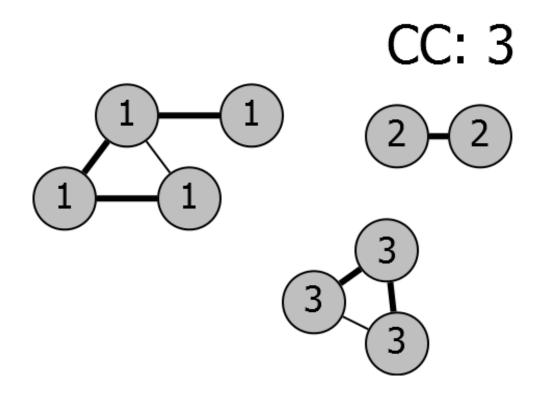












#### Correctness

- Each new explore finds new connected component.
- Eventually find every vertex
- $\square$  Runtime still O(|V| + |E|)