

K-Means Clustering Hardware for a Real-Time Image Processing on FPGA

The growing need for smart surveillance solutions requires that modern video capturing devices to be equipped with advance features, such as object detection, scene characterization, and event detection, etc. Image segmentation into various connected regions is a vital pre-processing step in these and other advanced computer vision algorithms. Thus, the inclusion of a hardware accelerator for this task in the conventional image processing pipeline inevitably reduces the workload for more advanced operations downstream. Moreover, design entry by using high-level synthesis tools is gaining popularity for the facilitation of system development under a rapid prototyping paradigm. To address these design requirements, we have developed a hardware accelerator for image segmentation, based on an online K-Means algorithm using a Simulink high-level synthesis tool. The developed hardware uses a standard pixel streaming protocol, and it can be readily inserted into any image processing pipeline as an Intellectual Property (IP) core on a Field Programmable Gate Array (FPGA). Furthermore, the proposed design reduces the hardware complexity of the conventional architectures by employing a weighted instead of a moving average to update the clusters

Keywords: image segmentation; K-Means; image processing pipeline; FPGA; high-level synthesis