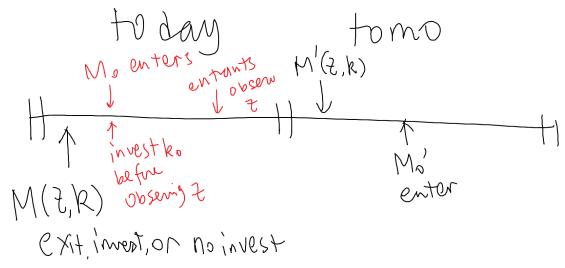
1 dFixed z over time

Timing:



Entrants:

- Firms can pay a fixed labor cost $c_E w$ to enter
- Before drawing z, they decide how much initial capital k_0 to invest
 - Cost of investing k_0 capital is $\frac{k_0}{A}$ units of final/investment/consumption goods today
- No operation or anything today
- End of today:
 - they draw z from initial distribution f(z), cannot change investment decision further.
- Tomorrow, they are effectively an existing firm with (z, k_0) (for example, they could exit right away)

The problem for the entry firm conditional on choosing to enter is:

$$V^{E} \equiv \max_{k_{0}} -c_{E}w - c_{0}w - \frac{k_{0}}{A} + \beta (1 - \psi) E_{z} [V(z, k_{0})]$$

Existing firms:

- To fix the idea:
 - -c, i: are potatoes (final goods)
 - Each potato turns into A units of capital k' (potato factories) tomorrow
- Existing firms have state variable (z, k)
- Each period, they could
 - Exit: sell capital k at a loss
 - Operate without investment: don't pay investment cost, next period end up with (z, (1-d)k)
 - Operate with investment: pay investment cost, decide how much to invest, operate with k today, get k' tomorrow

Investment technology:

• For firm (z, k) that operates without investing

$$V^{\text{no invest}}(z,k) = \max_{n} z \left(k^{\alpha} n^{1-\alpha} \right)^{\xi} - wn - c_f w + \beta \left(1 - \psi \right) V \left(z, \left(1 - \delta \right) k \right)$$

- $-c_f$: cost of operating
- For firm (z, k) that invests or de-invests, value is

$$V^{\text{invest}}(z,k) = \max_{n,i,k'} z \left(k^{\alpha} n^{1-\alpha} \right)^{\xi} - wn - c_f w - c_0 w - i + \beta (1 - \psi) V(z, (1 - \delta) k + Ai)$$

- $-c_0w$: fixed cost of investment or de-investment (capital adjustment)
- A: exogenously increasing over time, capturing cheaper investment cost over time (similar to Simone)
- Note: investment i has the same cost as consumption, but the return is Ai, which adds to capital tomorrow
- For firm (z, k) that exits,

 - They sell their capital k for a total price of $\frac{\omega k}{A}$
 - $-\omega < 1$ captures a loss of sale

– Whoever buys k can only use it to morrow on. This will save the buyer some investment i to day of $\frac{\omega k}{A}$ units

$$V^{\text{exit}}(z,k) = \frac{\omega k}{A}$$

• Firm value is

$$V\left(z,k\right) = \max \left\{ V^{\mathrm{exit}}\left(z,k\right), V^{\mathrm{no\ invest}}\left(z,k\right), V^{\mathrm{invest}}\left(z,k\right) \right\}$$

• Let's call policy function:

$$I_t(z,k) = \begin{cases} 0 & \text{firm chooses to exit at } t \\ 1 & \text{firm chooses not to invest at } t \\ 2 & \text{firm chooses to invest at } t \end{cases}$$

Optimal capital if invest:

$$k_{t+1}^*(z,k) = (1-\delta)k + A_t \times i_t(k,z)$$

Note: in our model, k_{t+1}^* doesn't depend on k.

• Next period capital if invest or no invest:

$$k'_{t+1}(z,k) = \begin{cases} -\inf \text{ (this is just arbitrary number)} & \text{firm chooses to exit at } t \\ (1-\delta)k & \text{firm chooses not to invest at } t \\ k^*_{t+1}(z,k) & \text{firm chooses to invest at } t \end{cases}$$

Market Clearing Condition:

• Goods market in terms of final goods

$$\int_{\text{no invest | invest}} y(z,k) dM + \int_{\text{exit}} \frac{\omega k}{A} dM = C + \int i(z,k) dM + M_0 \frac{k_0}{A}$$

• Labor market

$$\int_{\text{no invest | invest}} n(z, k) dM + c_f \int_{\text{no invest | invest}} dM + c_0 \int_{\text{invest}} dM + M_0 (c_E + c_0) = N$$

• HH FOC

$$w = \frac{v'(N)}{u'(C)}$$

Measures:

- Suppose in period t, measure of firms are given by $M_{t}\left(z,k\right)$ and M_{0t} new firms enter
- Then measure of firms in period t+1 is $M_{t+1}(z,k)$

$$M_{t+1}\left(z,k'\right) = M_{0t} \times 1 \left(k_{0t} = k'\right) + (1-\psi) \times 1 \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = k'} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = 1} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = 1} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = 1} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = 1} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = 1} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + \int_{I_t(z,k) = 2, k_{t+1}^*(z,k) = 1} \left(I_t\left(\frac{k'}{1-\delta},z\right) = 1\right) \times M_t\left(z,\frac{k'}{1-\delta}\right) + 1$$

Strategy

- What we have: $V_t(z,k); w_t$; We found this using the free entry condition.
- $M_{0,t=1}$; $M_{t=1}(z,k)$ (We assume the world is in some stationary state before the beginning of time to find these.) (This might be irrational since we're going to start along a trajectory of changes in A)
- What we need is $M_{0,t}$ and $M_t(z,k)$
- Idea: We can solve for measure variables sequentially in time. $M_t(z, k)$ can be derived easily from $M_{0,t}$ & $M_{t-1}(z, k)$ and the policy function.
 - Either use a solver or guess on $M_{0,t}$ and see if $w = \frac{v'(N)}{u'(C)}$ is satisfied.

2 Persistent z over time

Timing:

exog exit

V(2,k)

V(2,k)

V(2,k)

V(2,k)

V(2,k)

Mo enters

Chronis draw 2

Vivolent

Vivolent

Vivolent

M(2,k)

No invest

Entrants:

- Firms can pay a fixed labor cost $c_E w$ to enter
- Before drawing z, they decide how much initial capital k_0 to invest
 - Cost of investing k_0 capital is $\frac{k_0}{A}$ units of final/investment/consumption goods today
 - Maybe: include a a minimum amount of initial investment $k_0 \ge \underline{k}$ (not necessary)
- No operation or anything today
- End of today: they draw z from initial distribution f(z), cannot change investment decision further.
- Tomorrow, they are effectively an existing firm with (z, k_0) (for example, they could exit right away)

The problem for the entryfirm conditional on choosing to enter is:

$$V^{E} \equiv \max_{k_{0}} -c_{E}w - c_{0}w - \frac{k_{0}}{A} + \beta E_{z} [V(z, k_{0})]$$

Existing firms:

- To fix the idea:
 - -c, i: are potatoes (final goods)
 - Each potato turns into A units of capital k' (potato factories) tomorrow
- Existing firms have state variable (z, k):
 - -z is productivity today, k is capital they enter the period with
- Each period, existing firm (z, k)
 - 1. First they receive a shock of **exogenous exit with prob** ψ , if they get the exog exit shock, they cannot operate/invest, just smashing their capital back today to

$$\frac{\omega k}{\Delta}$$

- Alternatively, if we assume their capital is destroyed instead of smashed back, then this will encourage more volunatary exits (because operating has the risk of hitting ψ , which leads to loss of all capital)
- 2. If they don't receive the shock of exog exit, then they could

- Voluntary Exit: pay fixed investment adjustment cost to exit, sell capital k at no loss
- Operate without investment: don't pay investment cost, next period end up with (z', (1-d) k)
- Operate with investment or de-investment: pay investment fixed cost, decide how much to invest, operate with k today, get k' tomorrow

Investment technology:

- $V^{\text{operate}}, V^{\text{voluntary exit}}$: are values contigent on no exoge exit (which happens at beginning of period)
- For firm (z, k) that operates (invest, no invest, or de-invest), value is

$$V^{\text{operate}}(z,k) = \max_{n,i,k'} z \left(k^{\alpha} n^{1-\alpha} \right)^{\xi} - wn - c_f w - c_0 w \times 1 \left\{ i \neq 0 \right\} - i + \beta E_{z'|z} \left[V\left(z', (1-d) \, k + Ai \right) \right]$$

- Problem: if de-invest, should also have the option to smashing and not paying fixed investment cost
 - * Solution??? set $\omega = 0$ and no worry about it!!
- $-c_f w$: cost of operating
- $-c_0w$: fixed cost of <u>investment or de-investment</u>. If firm chooses inaction, then don't pay this cost
 - * This is in spirit of Bachmann, Caballero, Engel (2013)
- A: exogenously increasing over time, capturing cheaper investment cost over time (similar to Simone)
- Note: investment i has the same cost as consumption, but the return is Ai, which adds to capital tomorrow
- For firm (z, k) that voluntarily exits

$$V^{\text{voluntary exit}}\left(z,k\right) = \max\left\{\frac{\omega\left(1-\delta\right)k}{A}, -c_{0}w + \frac{\left(1-\delta\right)k}{A}\right\}$$

- Assume: even if firms voluntarily exit, their capital still depreciate. This way, there's no jump discontinuity between voluntary exits and de-invest.

- Let's call voluntary exit policy function

$$VolExit_t(z,k) = \begin{cases} 1 & \text{voluntary exit by smashing and get } \frac{\omega k}{A} \\ 2 & \text{voluntary exit by paying fixed cost and get } -c_0w + \frac{k}{A} \\ 0 & \text{operate (invest, de-invest, or inaction)} \end{cases}$$

- Could pay fixed cost c_0w to recycle all capital with no loss
- Or could take all capital to junk yard and suffer a loss
- Firm value is

$$V(z,k) = (1 - \psi) \max \left\{ V^{\text{exit}}(z,k), V^{\text{operate}}(z,k) \right\} + \psi \frac{\omega (1 - d) k}{A}$$

- Exogenous exit shock ψ : capital partially obselete (Nokia)
- Voluntary exit or de-invest: capital still usable, not subject to ω depreciation
- Optimal capital if invest:

$$k_{t+1}^*(z,k) = (1-d)k + A_t \times i_t(k,z)$$

Note: in our model, k_{t+1}^* doesn't depend on k.

• Next period capital if invest or no invest:

$$k'_{t+1}(z,k) = \begin{cases} \text{this firm no longer exits} & \text{firm chooses to exit at } t \\ (1-d)k & \text{firm chooses not to invest at } t \\ k^*_{t+1}(z,k) & \text{firm chooses to invest or de-invest at } t \end{cases}$$

- In the code, if firm exits, we set k' to - inf to avoid accidental errors

Market Clearing Condition:

• Goods market in terms of final goods

$$(1 - \psi) \int_{VolExit=0} y(z, k) M(z, k)$$

$$(1 - \psi) \int_{VolExit=1} \frac{\omega(1 - \delta) k}{A} M(z, k)$$

$$(1 - \psi) \int_{VolExit=2} \frac{(1 - \delta) k}{A} M(z, k)$$

$$+ \frac{\omega(1 - \delta) k}{A} \psi \int M(z, k)$$

$$=$$

$$(1 - \psi) \int_{VolExit=0} i(z, k) M(z, k)$$

$$+ C + M_0 \frac{k_0}{A}$$

• Labor market

$$(1 - \psi) \int_{VolExit=0} \left[n\left(z, k\right) + c_f \right] M\left(z, k\right)$$

$$+ (1 - \psi) c_0 \int_{VolExit=0 \text{ and } i(z, k) \neq 0} M\left(z, k\right)$$

$$+ (1 - \psi) c_0 \int_{VolExit=2} M\left(z, k\right)$$

$$+ M_0 \left(c_E + c_0\right)$$

$$= N$$

$$w = \frac{v'(N)}{u'(C)}$$

Measures:

- Define M(z, k) to be entering measure
- Define O(z, k) to be production measure
- Suppose in period t, measure of firms are given by $M_{t}\left(z,k\right)$ and M_{0t} new firms enter
- Then measure of firms in period t+1 is $M_{t+1}(z,k)$:
 - When z is fixed over time:

$$M_{t+1}(z, k') = M_{0t} \times 1 \left(k_{0t} = k'\right) \times f(z) + (1 - \psi) \times 1 \left(I_t\left(z, \frac{k'}{1 - \delta}\right) = 1\right) \times M_t\left(z, \frac{k'}{1 - \delta}\right) + \int_{I_t(z, k) = 1} f(z, k') dz dz$$

- When z is persistent over time:
 - * Measure at beginning of period

$$\begin{split} M_{t+1}\left(z',k'\right) &= M_{0t} \times 1\left(k_{0t} = k'\right) \times f\left(z'\right) \\ &+ \left(1 - \psi\right) \int_{z:E\left(z,k = \frac{k'}{1-d}\right) = 0, i\left(z,k = \frac{k'}{1-d}\right) = 0} M_t\left(z,\frac{k'}{1-d}\right) \times f\left(z'|z\right) dz \\ &+ \left(1 - \psi\right) \iint_{z,k:E\left(z,k\right) = 0, i\left(z,k\right) \neq 0} 1\left\{k_{t+1}^*\left(z\right) = k'\right\} \times M_t\left(z,k\right) \times f\left(z'|z\right) dk dz \end{split}$$

* Measure of firms at production stage

$$O_t(z,k) = (1 - \psi) M_t(z,k) 1 \{ E(z,k) = 0 \}$$

Numerical Strategy

- What we have: $V_t(z,k); w_t$; We found this using the free entry condition.
- $M_{0,t=1}$; $M_{t=1}(z,k)$ (We assume the world is in some stationary state before the beginning of time to find these.) (This might be irrational since we're going to start along a trajectory of changes in A)
- What we need is $M_{0,t}$ and $M_t(z,k)$
- Idea: We can solve for measure variables sequentially in time. $M_t(z, k)$ can be derived easily from $M_{0,t}$ & $M_{t-1}(z, k)$ and the policy function.
 - Either use a solver or guess on $M_{0,t}$ and see if $w = \frac{v'(N)}{u'(C)}$ is satisfied.