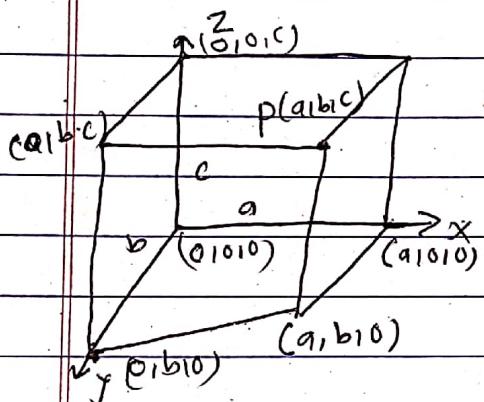
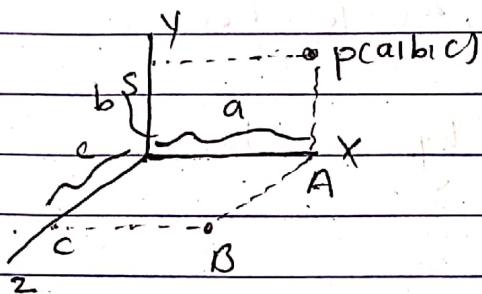


## Analytic geometry

- (I) plane geometry
- (II) Space geometry
- (III) Solid geometry

position of point in space :-



In space  $\mathbb{R}^3$

$$(x_1, y_1, z) = \{ (x_1, y_1, z) : \forall x_1, y_1, z \in \mathbb{R}^3 \}$$

Distance between two points

$$P_1(x_1, y_1, z_1) \& P_2(y_2, z_2, z_3)$$

$$|P_1 P_2| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

## Sphere

Equation of sphere with centre  $(h, k, l)$  and radius  $r$  is,

$$(x-h)^2 + (y-k)^2 + (z-l)^2 = r^2 \quad (1)$$

Also,

$$(x-h)^2 + (y-k)^2 + (z-l)^2 < r^2 \text{ (open disk)}$$

$$(x-h)^2 + (y-k)^2 + (z-l)^2 \leq r^2 \text{ (closed disk)}$$

The intersection of sphere (1) by  $x=0$  i.e.  $y_2$  plane is,

$$(0-h)^2 + (y-k)^2 + (z-l)^2 = r^2$$

$$\Rightarrow (y-k)^2 + (z-l)^2 = r^2 - h^2$$

$$\therefore (y-k)^2 + (z-l)^2 = (\sqrt{r^2 - h^2})^2 \quad (x)$$

$\therefore (x)$  is circle on  $y_2$  plane.

## Vectors:

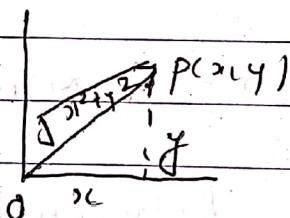
### Position vector

A vector which is defined with respect to some reference point is called position vectors.

$\overrightarrow{OP} = (x, y)$  plane vector

$\overrightarrow{OP} = (x, y, z)$  space vector.

$$|\overrightarrow{OP}| = \sqrt{x^2 + y^2}$$



$$\overrightarrow{OP} = (x, y)$$

Modulus of vector  $\overrightarrow{OP} = (x, y)$  is the distance from initial point to final point.

$$|\overrightarrow{OP}| = \sqrt{x^2 + y^2}$$

Similarly for Space vector

$$\overrightarrow{OP} = (x_1 y_1 z_1)$$

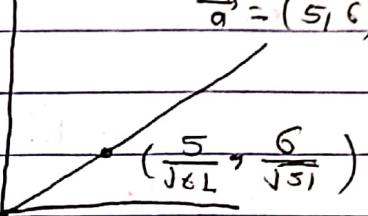
$$|\overrightarrow{OP}| = \sqrt{x_1^2 + y_1^2 + z_1^2}$$

Unit vector: - Vector having modulus 1 is unit vector.

Thus for a vector  $\vec{a} = (a_1 a_2)$  the unit vector is,

$$\hat{a} = \frac{\vec{a}}{|\vec{a}|}$$

$$\vec{a} = (5, 6)$$



- (8) Given the point P(100, 200) in the plane find a point on  $\overrightarrow{OP}$  whose length is 5.

Hint: Required =  $5 \times \left[ \frac{\overrightarrow{OP}}{|\overrightarrow{OP}|} \right]$

Every plane vectors  $(x_1 y_1)$  can be written as,

$$\begin{aligned} (x_1 y_1) &= x_1 \vec{i} + y_1 \vec{j} && \text{where } \vec{i} = (1, 0) \\ &\in x_1(1, 0) + y_1(0, 1) && \& \vec{j} = (0, 1) \\ &= (x_1 0) + (0 y_1) \\ &= (x_1 0, 0 + y_1) = (x_1 y_1) \end{aligned}$$

Thus every plane vector  $(x_1 y_1)$  can be written as linear combination of  $\vec{i}$  and  $\vec{j}$ .

Similarly every space vector  $(x_1 y_1 z_1)$  can be written as linear combination of  $\vec{i}, \vec{j}, \vec{k}$ ,

$$\text{i.e. } (x_1 y_1 z_1) = x_1 \vec{i} + y_1 \vec{j} + z_1 \vec{k}$$

$$\text{where } \vec{i} = (1, 0, 0) \text{ and } \vec{k} = (0, 0, 1)$$

Like vector:

Two vectors  $\vec{a}$  and  $\vec{b}$  are like if  
 $\vec{a} = k\vec{b}$  for  $k > 0$

Unlike vector:

$\vec{a} = -k\vec{b}$  where  $k > 0$

Example

$$\text{Let } \vec{a} = \vec{OA} \\ \therefore \vec{b} = \vec{AB}$$

$$\text{Then, } \vec{OB} = \vec{OA} + \vec{AB}$$

$$\begin{aligned} \vec{BA} &= \vec{BO} + \vec{OA} \\ &= -\vec{OB} + \vec{OA} \\ &= \vec{OA} - \vec{OB} \end{aligned}$$

Find  $\vec{AB}$ 

$$\vec{AB} = \vec{OB} - \vec{OA}$$

$$\text{Let } \vec{OA} = (1, 2)$$

$$\vec{OB} = (4, 6)$$

$$\text{Then, } \vec{AB} = \vec{OB} - \vec{OA}$$

$$= (4, 6) - (1, 2)$$

$$= (3, 4)$$

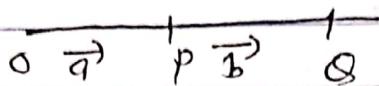
Triangle Inequality:

If three points are lie in same point line  
 They are called collinear point.

For any vectors  $\vec{a}$  and  $\vec{b}$

$$|\vec{a} + \vec{b}| \leq |\vec{a}| + |\vec{b}|$$

Case I :-



If  $O, P, Q$  lie on same line.

$$\vec{OQ} = \vec{OP} + \vec{PQ}$$

$$|\vec{OQ}| = |\vec{OP}| + |\vec{PQ}|$$

$$|\vec{OP} + \vec{PQ}| = |\vec{PQ}| + |\vec{OQ}|$$

$$\text{or } |\vec{a} + \vec{b}| = |\vec{a}| + |\vec{b}|$$

Case II :- If  $O, P, Q$  do not lie on same plane.

$$|\vec{a} + \vec{b}| < |\vec{a}| + |\vec{b}|$$

Let  $p, q$  be two vectors in  $\mathbb{R}^n$ .

Also, let  $c$  be a number  $\vec{p} = c\vec{q}$

$$\text{Then, } \vec{p}\vec{q} = c\vec{q}\cdot\vec{q} = c\|\vec{q}\|^2$$

where  $c$  is real number

Let  $c$  be a complex number

$$\vec{p} = c\vec{q}$$

$$|\vec{p} - c\vec{q}| = 0$$

$$\|\vec{p} - c\vec{q}\|^2 = 0$$

$$(\vec{p} - c\vec{q}) \cdot (\vec{p} - c\vec{q}) = 0$$

$$\Rightarrow \vec{p}\cdot\vec{p} - \vec{p}\cdot c\vec{q} - c\vec{q}\cdot\vec{p} + c\vec{q}\cdot c\vec{q} = 0$$

$$\Rightarrow \|\vec{p}\|^2 - c(\vec{p}\cdot\vec{q}) - c(\vec{p}\cdot\vec{q}) + c^2\|\vec{q}\|^2 = 0$$

$$\Rightarrow \|\vec{p}\|^2 - 2c(\vec{p}\cdot\vec{q}) + c^2\|\vec{q}\|^2$$

which is quadratic in  $c$  and value of  $c$  is

Imaginary

$$\begin{aligned} & 4(p \cdot q)^2 - 4\|q\|^2\|p\|^2 < 0 \\ \Rightarrow & \|p \cdot q\|^2 < \|\|p\|^2\|q\|^2\| \\ \Rightarrow & |p \cdot q| < \|\|p\|\|q\| \end{aligned}$$

### Angle between two vectors

Let  $\vec{a}$  and  $\vec{b}$  be two vectors

Then the cosine of the angle between  $\vec{a}$  and  $\vec{b}$  is,

$$\cos \theta = \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\| \|\vec{b}\|} \text{ where } \|\vec{a}\| \neq 0 \text{ and } \|\vec{b}\| \neq 0.$$

Thus, this can be written as,

$$\cos \theta = \vec{a} \cdot \vec{b}$$

Two vectors are orthogonal if and only if

$$\theta = 90^\circ$$

$$\cos \theta = \cos 90^\circ = 0$$

$$\vec{a} \cdot \vec{b} = 0$$

### Geometrical meaning of dot product :-

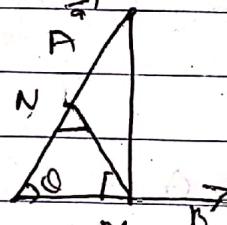
Let  $\theta$  be the angle between  $\vec{a}$  and  $\vec{b}$ .

$$\vec{a} = \vec{OA}$$

$$\vec{b} = \vec{OB}$$

Draw  $AM \perp OB$

$OM$  is projection of  $\vec{b}$  on  $\vec{a}$



$$\cos \theta = \frac{OM}{OA} = \frac{OM}{\|\vec{a}\|}$$

$$OM = \cos \theta \|\vec{a}\|$$

$$= \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\| \cdot \|\vec{b}\|}$$

$$= \frac{\vec{a} \cdot \vec{b}}{|\vec{b}|}$$

$$\vec{a} \cdot \vec{b} = |\vec{b}| \cdot OM$$

= magnitude of  $\vec{b}$  x projection of  $\vec{a}$  on  $\vec{b}$ .

$$\text{Case} = \frac{ON}{|\vec{b}|}$$

$$ON = \cos \theta |\vec{b}|$$

$$= \frac{\vec{a} \cdot \vec{b} \cdot |\vec{b}|}{|\vec{a}| |\vec{b}|}$$

$$= \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|}$$

$$= \frac{1}{|\vec{a}|}$$

$$\vec{a} \cdot \vec{b} = |ON| \cdot |\vec{a}|$$

= magnitude of  $\vec{a}$  x projection of  $\vec{b}$  on  $\vec{a}$ .

vector projection of  $\vec{a}$  on  $\vec{b}$

$$= \frac{\vec{a} \cdot \vec{b}}{|\vec{b}|} \frac{\vec{b}}{|\vec{b}|}$$

Similarly vector projection of  $\vec{b}$  on  $\vec{a}$

$$= \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|} \frac{\vec{a}}{|\vec{a}|}$$

Two projections are equal if two vectors have equal length.

$$\text{Let } \vec{a} = (5, 0)$$

$$\vec{b} = (7, 1)$$

$$\begin{aligned} \vec{a} \cdot \vec{b} &= (5, 0) \cdot (7, 1) \\ &= 35. \end{aligned}$$

$$\vec{a} = \sqrt{5^2 + 0^2} = 5$$

Vector projection of  $\vec{a}$  on  $\vec{b}$

$$= \frac{35}{5} \cdot \left( \frac{5}{5} \right)$$

$$= (7, 0)$$

Scalar product of unit vector

$$\vec{i} \cdot \vec{j} = 0$$

$$\vec{j} \cdot \vec{k} = 0$$

$$\vec{k} \cdot \vec{i} = 0$$

fact: Dot product is commutative

Vector products

Let  $\vec{a} = (a_1, a_2, a_3) \& \vec{b} = (b_1, b_2, b_3)$  be two vectors,

Then their vector product

$\vec{a} \times \vec{b}$  is defined by,

$$\vec{a} \times \vec{b} = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ 1 & 1 & 1 \end{vmatrix}$$

$$= (a_2 b_3 - b_2 a_3, a_3 b_1 - b_3 a_1, a_1 b_2 - b_1 a_2)$$

which is again vector.

Fact:  $\vec{a} \times \vec{b}$  &  $\vec{b} \times \vec{a}$  are not equal

$$\text{But } \vec{a} \times \vec{b} = -(\vec{b} \times \vec{a})$$

Note:  $\vec{a} \times \vec{b}$  is always perpendicular to  $\vec{a} \& \vec{b}$ .

example

$$\begin{aligned}\vec{a} &= (7, 0, 1) \\ \vec{b} &= (0, 1, 2) \\ \vec{a} \times \vec{b} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 7 & 0 & 1 \\ 0 & 1 & 2 \end{vmatrix} \\ &= (0, 0, 14)\end{aligned}$$

$$\vec{a} \cdot (\vec{a} \times \vec{b}) = (7, 0, 1) \cdot (0, 0, 14) \\ = 0$$

Example

$$\text{let } \vec{a} = (1, 5, 2) \\ \vec{b} = (2, 4, 1)$$

find r

$$\text{where } \vec{a} \cdot \vec{r} = 0 \\ \vec{b} \cdot \vec{r} = 0$$

Soln Here  $\vec{r}$  is perpendicular to both  $\vec{a}$  and  $\vec{b}$ . Hence r  
cross product of  $\vec{a}$  and  $\vec{b}$ .

Cross Product of

$$\vec{i} \times \vec{i} = 0$$

$$\vec{i} \times \vec{j} = \vec{k}$$

$$\vec{j} \times \vec{k} = \vec{i}$$

$$\vec{j} \times \vec{i} = \vec{0}$$

$$\vec{k} \times \vec{i} = \vec{0}$$

$$\vec{k} \times \vec{j} = \vec{0}$$

## Angle between two vectors using cross product

Let  $\vec{a}$  and  $\vec{b}$  be two non-zero vectors

Then the sine of angle between  $\vec{a}$  and  $\vec{b}$  is,

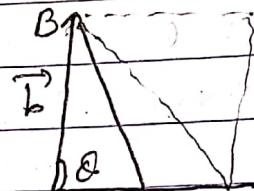
$$\sin \theta = \frac{|\vec{a} \times \vec{b}|}{|\vec{a}| |\vec{b}|} \leftarrow \text{To get Scalar}$$

### Geometrical meaning of $\vec{a} \times \vec{b}$

Let

$$\vec{a} = \vec{OA}$$

$$\vec{b} = \vec{OB}$$



Draw  $\perp r$  BM from  $\vec{OB}$  on  $\vec{OA}$

$$\text{Then } \sin \theta = \frac{BM}{|\vec{b}|}$$

$$BM = |\vec{b}| \sin \theta.$$

$$\text{Area of } \triangle OBA = \frac{1}{2} \times OA \times BM$$

$$= \frac{1}{2} \times |\vec{a}| \times |\vec{b}| \sin \theta$$

$$= \frac{1}{2} |\vec{a}| |\vec{b}| \cdot \frac{|\vec{a} \times \vec{b}|}{|\vec{a}| |\vec{b}|}$$

$$= \frac{1}{2} |\vec{a} \times \vec{b}|$$

$$\text{Area of parallelogram} = 2 \times \frac{1}{2} |\vec{a} \times \vec{b}|$$

$$= |\vec{a} \times \vec{b}|$$

$\therefore \vec{a} \times \vec{b}$  always represent the area of parallelogram with sides  $\vec{a}$  and  $\vec{b}$ .

### example

$$\text{If } \vec{a} = (1, 2, 0)$$

$$\vec{b} = (2, 1, 3)$$

$$\vec{a} \times \vec{b} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 2 & 0 \\ 2 & 1 & 3 \end{vmatrix}$$

$$= (6, -3, -3)$$

Hence

$$\text{Area} = |\vec{a} \times \vec{b}|$$

$$= \sqrt{6^2 + 3^2 + 3^2}$$

$$= \sqrt{54}$$

### Direction Angles :-

If  $\alpha, \beta, \gamma$  be the angles made by line with positive x, y and z axis then

$\cos \alpha, \cos \beta, \cos \gamma$  are called direction cosines of line and  $\alpha, \beta, \gamma$  are called direction angles.

If  $\vec{a} = (a_1, a_2, a_3)$  then unit

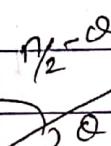
vector along  $\vec{a}$  is,

$$\hat{a} = \left( \frac{\vec{a}_1}{|\vec{a}|}, \frac{\vec{a}_2}{|\vec{a}|}, \frac{\vec{a}_3}{|\vec{a}|} \right)$$

$$= \left( \frac{a_1}{|\vec{a}|} \vec{i} + \frac{a_2}{|\vec{a}|} \vec{j} + \frac{a_3}{|\vec{a}|} \vec{k} \right)$$

$$= \cos \alpha \vec{i} + \cos \beta \vec{j} + \cos \gamma \vec{k}$$

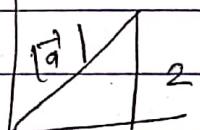
$$y - y_1 = \frac{\sin \theta}{\cos \theta} (x - x_1)$$



$$\frac{y - y_1}{r} = \tan \theta$$

$$\cos \theta = \frac{x - x_1}{r}$$

$$\vec{a} = (1, 2, 2)$$



$$\cos \alpha = \frac{1}{|\vec{a}|}$$

$$\cos \beta = \frac{2}{|\vec{a}|}$$

Here example

Let  $\vec{OP} = 2\vec{i} + 3\vec{j} + \vec{k}$

Find unit vector along  $\vec{OP}$  & direction cosine & direction angles:

$$\hat{a} = \frac{\vec{a}}{|\vec{a}|}$$

$$= \frac{2}{\sqrt{14}} \vec{i} + \frac{3}{\sqrt{14}} \vec{j} + \frac{1}{\sqrt{14}} \vec{k}$$

$$D.C.R \quad l = \cos \alpha = \frac{2}{\sqrt{14}}, m = \cos \beta = \frac{3}{\sqrt{14}}, n = \cos \gamma = \frac{1}{\sqrt{14}}$$

$$\Rightarrow \alpha = \cos^{-1}\left(\frac{2}{\sqrt{14}}\right), \beta = \cos^{-1}\left(\frac{3}{\sqrt{14}}\right) \quad \gamma = \cos^{-1}\left(\frac{1}{\sqrt{14}}\right)$$

Note:-

D.C Satisfies the relation,

$$l^2 + m^2 + n^2 = 1$$

Facts:  $|\vec{a}| = a$ ,  $\vec{a}^2 = \vec{a} \cdot \vec{a}$ ,  $\vec{a}^3$  is meaningless.

Theorem 1:

For any two vectors  $\vec{a}$  and  $\vec{b}$

$$|\vec{a} + \vec{b}|^2 = |\vec{a}|^2 + 2\vec{a} \cdot \vec{b} + |\vec{b}|^2$$

Proof:-

$$|\vec{a} + \vec{b}|^2 = (\vec{a} + \vec{b}) \cdot (\vec{a} + \vec{b}) = (\vec{a} + \vec{b})^2$$

$$[\because \vec{a}^2 = |\vec{a}|^2]$$

$$= \vec{a} \cdot \vec{a} + \vec{a} \cdot \vec{b} + \vec{b} \cdot \vec{a} + \vec{b} \cdot \vec{b} \quad [\because \vec{a}^2 = \vec{a} \cdot \vec{a}]$$

$$= |\vec{a}|^2 + 2\vec{a} \cdot \vec{b} + |\vec{b}|^2$$

$$= |\vec{a}|^2 + 2\vec{a} \cdot \vec{b} + |\vec{b}|^2 - (*)$$

Fact:- If  $\vec{a} \cdot \vec{b} = 0$  then by (xx)

$$|\vec{a} + \vec{b}|^2 = |\vec{a}|^2 + |\vec{b}|^2$$

$$\text{In } \triangle OAB, (OA)^2 + (AB)^2 = (OB)^2 \quad (\text{xxx})$$

This is Famous pythagorean theorem. 0.

### Parallelogram Law

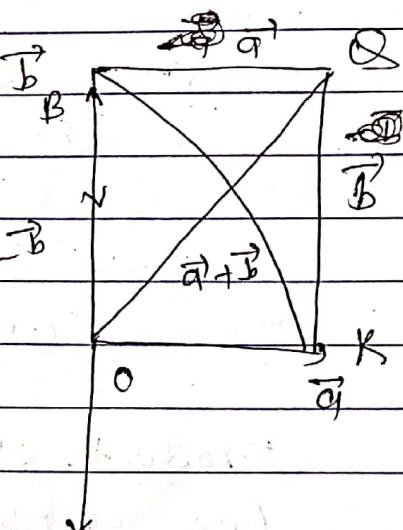
If  $\vec{a}$  and  $\vec{b}$  be two vectors

$$\begin{aligned} & |\vec{a} + \vec{b}|^2 + |\vec{a} - \vec{b}|^2 \\ &= (\vec{a} + \vec{b}) \cdot (\vec{a} + \vec{b}) + (\vec{a} - \vec{b}) \cdot (\vec{a} - \vec{b}) \\ &= |\vec{a}|^2 + 2\vec{a} \cdot \vec{b} + |\vec{b}|^2 + |\vec{a}|^2 - 2\vec{a} \cdot \vec{b} + |\vec{b}|^2 \\ &= 2|\vec{a}|^2 + 2|\vec{b}|^2 \\ &= 2(|\vec{a}|^2 + |\vec{b}|^2) \end{aligned}$$

$$\begin{aligned} \vec{RB} &= \vec{BQ} + \vec{QR} \\ &= -\vec{b} + \vec{a} \\ &= \vec{a} - \vec{b} \end{aligned}$$

$$\text{Here } |\vec{a} + \vec{b}| = \vec{OQ}$$

$$|\vec{a} - \vec{b}| = BR$$



2 times sum of the square of the side is equals to sum of the diagonal of parallelogram.

Fact:- If  $\vec{a}$  and  $\vec{b}$  be two vectors then the difference of  $\vec{b}$  and its vector projection onto  $\vec{a}$  is orthogonal to  $\vec{a}$ .

Soln The vector  $\vec{b} - \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|} \vec{a}$  is orthogonal to  $\vec{a}$ .

Now,

$$\text{Let } \vec{v} = \left[ \vec{b} - \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|} \cdot \vec{a} \right]$$

$$\Rightarrow \vec{v} \cdot \vec{b} = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|^2} (\vec{a} \cdot \vec{v})$$

$$\Rightarrow \vec{a} \cdot \vec{b} = \frac{a^2}{|\vec{a}|^2} [\vec{a} \cdot \vec{b}]$$

$$\Rightarrow \vec{a} \cdot \vec{b} - \vec{a} \cdot \vec{b} = 0$$

Example Let  $\vec{a} = (1, 0, 1, 0)$ ,  $\vec{b} = (0, 1, 1, 0)$ .

Find the vector orthogonal to  $\vec{b}$ .

$$\text{Here } \vec{a} = (1, 0, 1, 0), \vec{b} = (0, 1, 1, 0)$$

$$\vec{a} \cdot \vec{b} = (1, 0, 1, 0) \cdot (0, 1, 1, 0) = (0, 1, 0, 0)$$

$$\text{Hence } |\vec{a}| = \sqrt{1^2 + 0 + 0} = 1$$

$$|\vec{b}| = \sqrt{0^2 + 1^2 + 1^2} = 1$$

Vector orthogonal to  $\vec{b}$  is,

$$\vec{a} - \frac{\vec{a} \cdot \vec{b}}{|\vec{b}|} \cdot \vec{b}$$

$$= (1, 0, 1, 0) - \frac{(0, 1, 0, 0) \cdot (0, 1, 1, 0)}{1}$$

$$= (1, 0, 1, 0)$$

Product of three vectors

Let  $\vec{a}, \vec{b}, \vec{c}$  be three vectors, then,

(i)  $\vec{a} \cdot (\vec{b} \times \vec{c}) \rightarrow \text{Scalars}$

(ii)  $\vec{a} \times (\vec{b} \times \vec{c}) \rightarrow \text{Vectors}$ .

But  $\vec{a}(\vec{a} \times \vec{c})$ ,  $\vec{a} \times (\vec{b} - \vec{c})$  are undefined.

Let  $\vec{a}, \vec{b}, \vec{c}$  be three vectors. Then their scalar triple product is denoted by,  $[\vec{a} \vec{b} \vec{c}]$  or  $(\vec{a}, \vec{b}, \vec{c})$  and is defined as

$$[\vec{a} \cdot \vec{b} \cdot \vec{c}] = \vec{a} \cdot (\vec{b} \cdot \vec{c})$$

Fact:- Unit vectors  $\hat{i}, \hat{j}, \hat{k}$

$$= \hat{i} \cdot (\hat{j} \times \hat{k})$$

$$= \hat{i} \cdot \hat{i} = 1$$

Evaluate  $\vec{a} = (a_1, a_2, a_3) \mid \vec{b} = (b_1, b_2, b_3) \quad \&$

$$\vec{c} = (c_1, c_2, c_3)$$

Then  $[\vec{a} \cdot \vec{b} \cdot \vec{c}] = \vec{a} \cdot (\vec{b} \times \vec{c})$

$$\vec{b} \times \vec{c} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

$$= (b_2 c_3 - c_2 b_3) \hat{i} + (c_1 b_3 - b_1 c_3) \hat{j} + (b_1 c_2 - b_2 c_1) \hat{k}$$

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = a_1(b_2 c_3 - c_2 b_3) + a_2(c_1 b_3 - b_1 c_3) + a_3(b_1 c_2 - b_2 c_1)$$

$$= \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

This shows that scalar triple product can be expressed in terms of determinant.

Properties:-

- (1) The value of STP changes its sign if the position of two vectors are interchanged.

Geometrical Meaning of Scalar Triple product

Geometrically, the value of scalar triple product  $[\vec{a}, \vec{b}, \vec{c}]$  always represent the volume of parallelopiped with edge  $\vec{a}, \vec{b}, \vec{c}$ .

Fact: Find the volume of the parallelopiped with edge having 3 vectors.

$$(2, -3, 4) \times (1, 2, -1) \times (3, 1, 2)$$

$$\text{Let } \vec{a} = (2, -3, 4), \vec{b} = (1, 2, -1) \text{ and } \vec{c} = (3, 1, 2)$$

Then,

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = \begin{vmatrix} 2 & -3 & 4 \\ 1 & 2 & -1 \\ 3 & 1 & 2 \end{vmatrix} = (-7) = 7$$

We take positive value so value is 7.

Note:- If three vectors are coplanar then

Volume of ppd 0.

$$\text{i.e. } [\vec{a} \vec{b} \vec{c}] = 0.$$

Example Find the value of  $d$  such that three vectors

$$2\vec{i} - \vec{j} + \vec{k}, \quad \vec{i} + 2\vec{j} - 3\vec{k} \quad \text{&} \quad 3\vec{i} + d\vec{j} + 5\vec{k}$$

are coplanar.

Soln

$$\text{Here, } \vec{a} = 2\vec{i} - \vec{j} + \vec{k}$$

$$\vec{b} = \vec{i} + 2\vec{j} - 3\vec{k}$$

$$\vec{c} = 3\vec{i} + d\vec{j} + 5\vec{k}$$

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = \begin{vmatrix} 2 & -1 & 1 \\ 1 & 2 & -3 \\ 3 & d & 5 \end{vmatrix} = 0$$

$$\Rightarrow 2 \begin{vmatrix} 2 & -3 \\ 1 & 5 \end{vmatrix} + 1 \begin{vmatrix} 1 & -3 \\ 3 & 5 \end{vmatrix} + 1 \begin{vmatrix} 1 & 2 \\ 3 & 1 \end{vmatrix} = 0$$

$$\Rightarrow 2(10+3d) + (5+9) + (5-d) = 0$$

$$\Rightarrow 20 + 6d + 14 + d - 6 = 0$$

$$\Rightarrow 7d = -28$$

$$d = -4$$

### Vector triple product

Let  $\vec{a}, \vec{b}, \vec{c}$  be three vectors, then their vector triple product is

$$\vec{a} \times (\vec{b} \times \vec{c})$$

$$\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{a} \cdot \vec{b})\vec{c}$$

This shows that vector triple product can be expressed as linear combination of  $\vec{b}$  and  $\vec{c}$ .

example: Let  $\vec{a} = (1, 2, 0)$

$$\vec{b} = (0, 1, 2)$$

$$\vec{c} = (1, 1, 1)$$

Find  $\vec{a} \times \vec{b} \times \vec{c}$  & verify the formula.

Soln: Here  $\vec{a} = (1, 2, 0)$

$$\vec{b} = (0, 1, 2)$$

$$\vec{c} = (1, 1, 1)$$

$$\vec{b} \times \vec{c} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{vmatrix} = (7-2)\vec{i} + (2-0)\vec{j} + (-7)\vec{k} \\ \Rightarrow 5\vec{i} + 2\vec{j} - 7\vec{k}$$

again,

$$\vec{a} \times (\vec{b} \times \vec{c}) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 2 & 0 \\ 5 & 2 & -7 \end{vmatrix} = (-14)\vec{i} + 7\vec{j} + (2-10)\vec{k} \\ \Rightarrow -14\vec{i} + 7\vec{j} - 8\vec{k} \quad -①$$

A/Sec

$$(\vec{a} \cdot \vec{c}) = (1, 2, 0) \cdot (1, 1, 1)$$

$$= 1+2+0 = 3$$

$$(\vec{a} \cdot \vec{c}) \vec{b} = 3(0, 1, 2)$$

$$= (0, 2, 1, 6)$$

$$(\vec{a} \cdot \vec{b}) = (1, 2, 0) \cdot (0, 1, 2) = 14$$

$$(\vec{a} \cdot \vec{b}) \vec{c} = 14(1, 1, 1)$$

$$= (14, 14, 14)$$

$$\text{Now, } (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c}$$

$$= (0, 2, 1, 6) - (14, 14, 14)$$

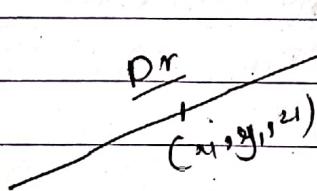
$$= (-14, 7, -8)$$

$$= -14\vec{i} + 7\vec{j} - 8\vec{k}$$

$$\text{Hence, } \vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c} \quad \underline{\text{proved}}$$

$$\text{we had: } \vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c}$$

Eqn of straight line in space



$$y - y_1 = \frac{y_2 - y_1}{x_2 - x_1} (x - x_1)$$

$$\frac{x - x_1}{x_2 - x_1} = \frac{y - y_1}{y_2 - y_1}$$

$$\text{Cosec}^2 = \frac{1}{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

Any three numbers that are proportional to the direction cosine  $\alpha, \beta, \gamma$  are called direction ratios.

Thus, if  $a, b, c$  be three numbers satisfied,

$$\frac{a}{l} = \frac{b}{m} = \frac{c}{n} = \frac{\sqrt{l^2 + m^2 + n^2}}{\sqrt{a^2 + b^2 + c^2}} = \frac{1}{\sqrt{a^2 + b^2 + c^2}}$$

Then,

$$\rho = \frac{a}{\sqrt{a^2+b^2+c^2}}, m = \frac{b}{\sqrt{a^2+b^2+c^2}}, n = \frac{c}{\sqrt{a^2+b^2+c^2}}$$

~~Topics~~

### Formulae

(i) The equation of straight line passing through  $(x_1, y_1, z_1)$  with direction cosine ratios is,

$$\frac{x - x_1}{l} = \frac{y - y_1}{m} = \frac{z - z_1}{n}$$

(ii) Two point form.

$$\frac{x - x_1}{x_2 - x_1} = \frac{y - y_1}{y_2 - y_1} = \frac{z - z_1}{z_2 - z_1}$$

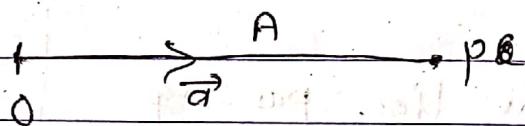
where  $x_2 - x_1, y_2 - y_1, z_2 - z_1$  are

Called direction ratio of PQ.

### Vector equation of a line

Vector equation of a line passing

through origin and with direction of  $\vec{a}$ .

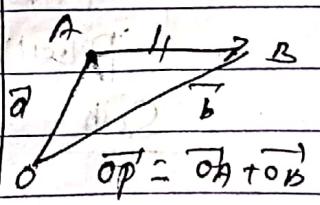


Let  $\overrightarrow{OA} = \vec{a}$  passing through origin.

Let, OP be any point on the line such that  $\overrightarrow{OP} = \vec{r}$ .

$$y - y_1 = mx - x_1$$

point  $(x_1, y_1)$  is  
moving point



Then  $\overrightarrow{OA}$  &  $\overrightarrow{OP}$  are Collinear.

$$\text{Eqn } \overrightarrow{OP} = t \overrightarrow{OA}$$

$\therefore \vec{r} = t\vec{a}$ , which is vector equation of straight line passing through origin.

### Verification

changing it into Cartesian form,

$\vec{r} = (x_1 \vec{i}, y_1 \vec{j}, z_1 \vec{k})$ ,  $\vec{a} = (a_1 \vec{i}, a_2 \vec{j}, a_3 \vec{k})$ , Then eqn (8) gives,

$$(x_1 \vec{i}, y_1 \vec{j}, z_1 \vec{k}) = t(a_1 \vec{i}, a_2 \vec{j}, a_3 \vec{k})$$

$$\left( \frac{x}{a_1}, \frac{y}{a_2}, \frac{z}{a_3} \right) = t \vec{a}_1, t \vec{a}_2, t \vec{a}_3$$

2) Equating the Corresponding Components,

$$x = t a_1, y = t a_2, z = t a_3$$

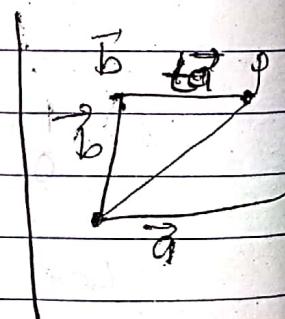
$$\left[ \frac{x}{a_1} = \frac{y}{a_2} = \frac{z}{a_3} = t \right] - \text{Eqn } ①$$

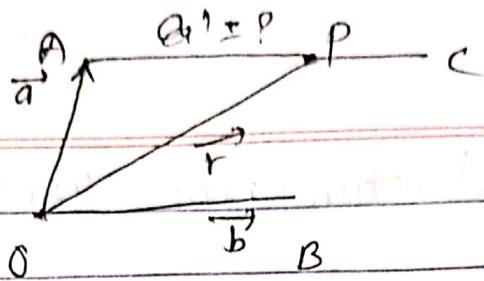
Eqn ① is in Cartesian form. This is the eqn of straight line with direction ratio  $a_1, a_2, a_3$ .

Example

→ vector eqn of straight line passing through a point A (where  $\overrightarrow{OA} = \vec{a}$ ) & parallel to vector  $\vec{b}$ .

Soln





Let  $\vec{OA} = \vec{a}$ , and  $\vec{OB} = \vec{b}$  be the given vectors.

Let  $P$  be any point on the required line  $AC$ ,  
so that  $\vec{OP} = \vec{r}$ .

From triangle law of vector addition.

$$\vec{OP} = \vec{OA} + \vec{AP}$$

$$\text{or } \vec{r} = \vec{a} + \vec{AP} \quad \text{since } \vec{AP} \text{ is parallel to } \vec{OB} = \vec{b} \quad \therefore \vec{AP} = t\vec{b}$$

$$\text{or } \vec{r} = \vec{a} + t\vec{b}. \quad \text{--- (ii)}$$

which is equation of straight line passing from  $\vec{a}$   
and parallel to  $\vec{b}$ .

Verification from Cartesian coordinates,

$$\vec{r} = (x_1, y_1, z_1), \vec{a} = (x_1, y_1, z_1) \text{ and } \vec{b} = (x_2, y_2, z_2)$$

$$\Rightarrow (x_1, y_1, z_1) = (x_1, y_1, z_1) + t(x_2, y_2, z_2)$$

$$\Rightarrow (x_1, y_1, z_1) = (x_1, y_1, z_1) + (tx_2, ty_2, tz_2)$$

$$\Rightarrow (x - x_1, y - y_1, z - z_1) = t(x_2, y_2, z_2) \quad \text{--- (iii)}$$

$$\Rightarrow \boxed{\frac{x - x_1}{x_2} = \frac{y - y_1}{y_2} = \frac{z - z_1}{z_2}} \quad \text{--- (iv)}$$

Eq (iii) is called parametric equation

∴ Eq (iv) is eqn of straight line passing through

$(x_1, y_1, z_1)$  with direction ratio  $x_2, y_2, z_2$

~~Vector~~

### Example 2

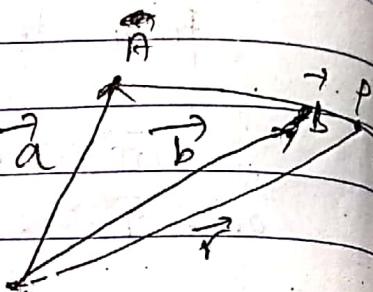
Vector eqn of straight lines passing through two vectors  $\vec{a}$  &  $\vec{b}$  with points  $\vec{A}$  and  $\vec{B}$ .

Soln:- Let  $\vec{OA} = \vec{a}$ ,  $\vec{OB} = \vec{b}$

be given vectors, let  $P$  be any point on the required line  $AC$ ,

So that  $\vec{OP} = \vec{r}$

From triangle



$$\vec{OP} = \vec{OA} + \vec{AP} \quad \text{--- (1)}$$

$$\vec{AB} = \vec{B} - \vec{a}$$

From triangle law vector addition,

From (1)

$$\vec{OP} = \vec{OA} + (\vec{OB} - \vec{OA})$$

$$\vec{OP} = \vec{OA} + \vec{AP}$$

$$\vec{r} = \vec{OA} + t(\vec{AB})$$

Where  $\vec{AP}$  is collinear to  $\vec{AB}$

$$\vec{r} = \vec{OA} + t(\vec{B} - \vec{a})$$

$$\vec{r} = \vec{a} + t(\vec{b} - \vec{a})$$

which is equation of straight line passing through two points  $A$  &  $B$  with position vectors  $\vec{a}$  and  $\vec{b}$ .

## Verification

Let  $\vec{r} = (x_1, y_1, z_1)$ ,  $\vec{a} = (x_1, y_1, z_1)$ ,  $\vec{b} = (x_2, y_2, z_2)$

$$(x_1, y_1, z_1) = (x_1, y_1, z_1) + t(x_2 - x_1, y_2 - y_1, z_2 - z_1)$$

$$\Rightarrow \frac{x - x_1}{x_2 - x_1} = \frac{y - y_1}{y_2 - y_1} = \frac{z - z_1}{z_2 - z_1} = t \quad (*)$$

Question :-

Find the eqn of line which is parallel to  $2\vec{i} - \vec{j} + 3\vec{k}$  and passes through  $(5, -2, 4)$ .

Soln Here, direction ratios are ~~cos~~,  $x_1 = 5$ ,  $x_2 = -2$ ,  $x_3 = 4$

also, it can be written as,

$$\vec{a} = (5, -2, 4) = 5\vec{i} - 2\vec{j} + 4\vec{k}$$

$$\vec{b} = 2\vec{i} - \vec{j} + 3\vec{k}$$

∴ vector equation of straight line parallel to  $\vec{b}$  and passes through  $(5, -2, 4)$

$$\vec{r} = \vec{a} + t\vec{b} \quad (1)$$

$$(x_1, y_1, z_1) = (5, -2, 4) + t(2, -1, 3)$$

$$\Rightarrow (x - 5, y + 2, z - 4) = (2t, -t, 3t)$$

$$\Rightarrow \frac{x - 5}{2} = \frac{y + 2}{-1} = \frac{z - 4}{3} = t$$

This is true for all  $t$  ∴

$$\frac{x - 5}{2} = \frac{y + 2}{-1} = \frac{z - 4}{3}$$

Example 5 - Find the vector equation of straight line whose Cartesian eqn is

$$\frac{x-1}{2} = \frac{y+1}{-3} = \frac{z+2}{4}$$

Let  $\frac{x-1}{2} = \frac{y+1}{-3} = \frac{z+2}{4} = t$  (say)

$$x-1 = 2t \quad y+1 = -3t \quad z+2 = 4t$$

$$x = 2t+1 \quad y = -3t-1 \quad z = 4t-2$$

Let  $\vec{r} = \vec{a} + t\vec{b}$  be the vector eqn

$$\text{or } \vec{r} = (2t+1)\vec{i} + (-3t-1)\vec{j} + (4t-2)\vec{k}$$

$$\text{or } \vec{r} = (2\vec{i} - 3\vec{j} + 4\vec{k}) + t(\vec{i} - \vec{j} - 2\vec{k})$$

$$\vec{r} = \vec{a} + t\vec{b}$$

where,

$$\vec{a} = (\vec{i} - \vec{j} - 2\vec{k})$$

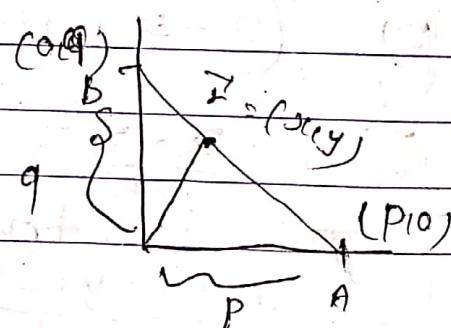
$$\vec{b} = (2\vec{i} - 3\vec{j} + 4\vec{k})$$

Example Find the vector or use vector method to find the equation of straight line in the form  $\frac{x}{p} + \frac{y}{q} = 1$  (i.e. Double Intercept Form.)

So, we have equation

of straight line in two point methods.

$$\vec{r} = \vec{a} + t(\vec{b} - \vec{a})$$



$$\Rightarrow \vec{x}\vec{i} + \vec{y}\vec{j} + \vec{z}\vec{k} = \vec{p}\vec{i} + \vec{q}\vec{j} + \vec{r}\vec{k} + t(\vec{o}\vec{i} - \vec{q}\vec{j} + \vec{z}\vec{k} - \vec{p}\vec{i} + \vec{q}\vec{j} + \vec{z}\vec{k})$$

$$\Rightarrow \vec{x}\vec{i} + \vec{y}\vec{j} + \vec{z}\vec{k} = \vec{p}\vec{i} + \vec{q}\vec{j} + \vec{r}\vec{k} + t(-\vec{p}\vec{i} - \vec{q}\vec{j})$$

$$\therefore (\vec{x}, \vec{y}, \vec{z}) = (\vec{p} + t\vec{q}, \vec{q}).$$

$$\therefore \vec{p} + t\vec{q} = \vec{x}$$

$$\vec{y} = t\vec{q}$$

$$\therefore -t\vec{q} = \vec{x} - \vec{p}$$

$$\therefore t = \frac{\vec{x} - \vec{p}}{-\vec{q}}, \quad t = \frac{\vec{y}}{\vec{q}} - \frac{\vec{y}}{\vec{q}}$$

$$\therefore \frac{\vec{y}}{\vec{q}} - \frac{\vec{y}}{\vec{q}} = \frac{\vec{x} - \vec{p}}{-\vec{q}}$$

$$\therefore \frac{\vec{x} - \vec{p}}{-\vec{q}} = \frac{\vec{y}}{\vec{q}} - \frac{\vec{y}}{\vec{q}}$$

$$\therefore \boxed{\frac{\vec{x}}{\vec{p}} + \frac{\vec{y}}{\vec{q}} = 1}$$

Another

$$\vec{BA} = \vec{OA} - \vec{OB}$$

$$AP = \vec{OP} - \vec{OA}$$

$$= (\vec{x} - \vec{p}, \vec{y})$$

$$PB = \vec{OB} - \vec{OP}$$

$$= (\vec{x}, \vec{y} - \vec{q})$$

$$AP = t(PB)$$

$$\Rightarrow (x-p, y) = t(x, y-q)$$

$$\Rightarrow (x-p, y) = (tx, t(y-q))$$

Equating,

$$x-p = tx \Rightarrow t = \frac{x-p}{x}$$

$$t(y-q) = y$$

$$t = \frac{y}{y-q}$$

$$\textcircled{1} \quad \frac{x-p}{x} = \frac{y}{y-q} \quad xy = (x-p)(y-q)$$

$$\Rightarrow xy = xy - xq - yq + pq$$

$$\text{Or, } 1 - \frac{p}{x} = \frac{y}{y-q} \quad \Rightarrow xq + yq = pq$$

$$\Rightarrow \frac{p}{x} = \frac{-y}{y-q} - 1 \quad \Rightarrow \frac{x}{p} + \frac{y}{q} = 1$$

$$\Rightarrow \frac{p}{x} = \frac{-y - y + q}{y-q}$$

$$\Rightarrow \frac{p}{x} = \frac{-2y + q}{y-q}$$

$$\Rightarrow p(y-q) = x(-2y + q)$$

$$\Rightarrow yp - pq = -2xy + xq$$

$$\Rightarrow \frac{y}{q} - 1 = -\frac{2xy}{pq} + \frac{x}{p}$$

## Equation of plane

A plane is the locus of the points such that any two points  $P$  &  $Q$  on the locus, the straight line joining  $P$  &  $Q$  lie wholly on the locus.

\* note the general equation of a plane passes through origin is,

$$ax + by + cz = 0$$

This can be written as,

$$(a, b, c) \cdot (x_1, y_1, z_1) = 0 \quad \text{--- (1)}$$

This shows that vector  $(a, b, c) = \vec{n}$  is perpendicular to  $\vec{r} = (x_1, y_1, z_1)$ .

This shows that from (1)

$$\vec{n} \cdot \vec{r} = 0$$

Thus, a plane is completely determined by a point  $\vec{r} = (x_1, y_1, z_1)$  on plane normal vector or  $\vec{n} = (a, b, c)$  which is normal to the plane.

## Determination of equation of plane

Find the eqn of plane which passes through  $A(x_0, y_0, z_0)$  and having normal vector  $\vec{n} = (a, b, c)$ .

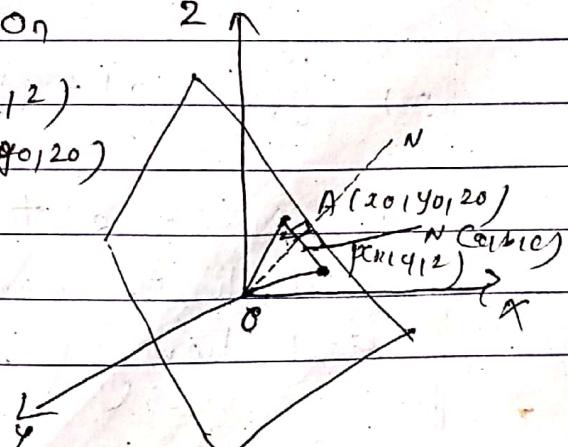
Let  $P(x_1, y_1, z_1)$  be any points on the plane where  $\vec{r} = \vec{OP} = (x_1, y_1, z_1)$

Given point on the plane  $A(x_0, y_0, z_0)$

$$\text{i.e. } \vec{r} = \vec{OA} = (x_0, y_0, z_0).$$

Then, the line

$\vec{AP}$  lies on the plane.



$$\therefore \vec{AP} = \vec{OP} - \vec{OA} = \vec{r} - \vec{a}$$

(x-x)

But  $\vec{PN}$  is orthogonal to  $\vec{AP}$

where  $\vec{n} = (a_1 b_1 c)$  i.e.  $\vec{AP} \cdot \vec{PN} = 0$

where  $\vec{ON} = \vec{n} = (a_1 b_1 c)$

$$\text{or } (\vec{r} - \vec{a}) \cdot \vec{n} = 0 - (x-x)$$

Note

If we shift  $\vec{PN}$  to  $\vec{ZN}$  then direction ratios of both lines are same

Eqn. (x-x) is the equation of plane

which passes through  $\vec{a} = \vec{OA} = (x_0, y_0, z_0)$ .

If the plane passes through origin, then,

$$A(x_0, y_0, z_0) \rightarrow O(0, 0, 0)$$

$$\text{i.e. } \vec{a} = 0$$

Hence eqn (x-x) becomes,

$$\vec{r} \cdot \vec{n} = 0 \Rightarrow \vec{n} \cdot \vec{r} = 0$$

When,  $\vec{n} = (a_1 b_1 c)$ ,  $\vec{r} = (x_1 y_1 z_1)$  and  $\vec{a} = (x_0 y_0 z_0)$

Then from (x-x)

$$\Rightarrow [(x_1 y_1 z_1) - (x_0 y_0 z_0)] \cdot (a_1 b_1 c) = 0$$

$$\Rightarrow [(x - x_0) + (y - y_0) + (z - z_0)] (a_1 b_1 c) = 0$$

$$\Rightarrow a_1(x - x_0) + b_1(y - y_0) + c_1(z - z_0) = 0 - (x-x)$$

which is equation of plane passes through  $(x_0, y_0, z_0)$  and having normal vector  $(a_1 b_1 c)$ .

$$\vec{r} \cdot \vec{n} = \vec{a} \cdot \vec{n}$$

$$ax + by + cz = a_0 + b_0 z + c_0 z - (xxx)$$

The eqn (xxx) if  $a_0 + b_0 z + c_0 z = d$

Then eqn (xxx) becomes

$$ax + by + cz = d$$

If the plane passes through origin

$$\text{i.e. } (x_0, y_0, z_0) = (0, 0, 0)$$

Then eqn becomes

$$ax + by + cz = 0$$

Example Find the equation of plane which passes through  $A(-1, 2, 3)$  with normal vector  $\vec{n} = (4, 1, 1, 2)$

Soln we have,

$$(\vec{r} - \vec{a}) \cdot \vec{n} = 0$$

where  $\vec{r} = (x, y, z)$ ,  $\vec{a} = (-1, 2, 3)$ ,  $\vec{n} = (4, 1, 1, 2)$

$$\Rightarrow [(x, y, z) - (-1, 2, 3)] \cdot (4, 1, 1, 2) = 0$$

$$\Rightarrow (x+1) + (y-2) + (z-3) \cdot (4, 1, 1, 2) = 0$$

$$\Rightarrow -4(x+1) + 2(y-2) + 2(z-3) = 0$$

$$\Rightarrow -x + 2y + 3z - 1 - 4 - 9 = 0$$

$$\Rightarrow -x + 2y + 3z = 14 - \textcircled{1}$$

Eq \textcircled{1} is required equation of plane.

Let  $\vec{a} = \vec{q} = (-1, 2, 3)$

Normal vector  $\vec{n} = (4, 1, 2)$

Then the vector equation of plane is,

$$(\vec{r} - \vec{q}) \cdot \vec{n} = 0$$

$$\Rightarrow \vec{r} \cdot \vec{n} = \vec{q} \cdot \vec{n}$$

$$\Rightarrow (x, y, z) \cdot (4, 1, 2) = (-1, 2, 3) \cdot (4, 1, 2)$$

Example Find the intercept of the plane.

$$4x + y + 2z = 0 \quad 4$$

Sketch the graph.

Soln

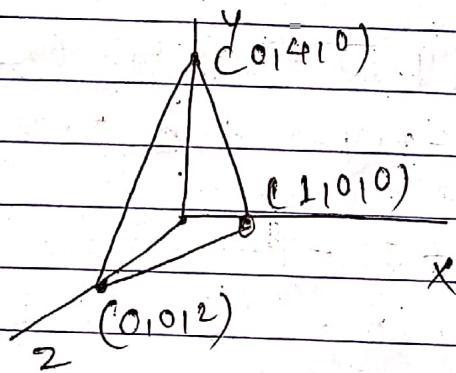
put  $y=0, z=0$ , then  $x=0$  1

put  $y=0, x=0$  then  $z=2$

put  $x=0, z=0$  then  $y=4$ .

The plane cut

$x, y$  and  $z$  intercept are 1, 2 & 4.



## Plane through three points

Find the equation of plane through three points,  $P(x_0, y_0, z_0)$ ,  $Q(x_1, y_1, z_1)$  &  $R(x_2, y_2, z_2)$ .  
Hint: Find  $\vec{PQ}$  also find  $\vec{PR}$ .

Step I find  $\vec{PQ}$  &  $\vec{PR}$

Step II Find normal vector to the plane.

$$\vec{n} = \vec{PQ} \times \vec{PR}$$

$\vec{PQ}$  is perpendicular to  $\vec{n}$

$$\text{So, } \vec{PQ} \cdot \vec{n} = 0$$

$$(\vec{r} - \vec{a}) \cdot [(\vec{b} - \vec{a}) \times (\vec{c} - \vec{a})] = 0$$

Here  $P = (x_0, y_0, z_0)$ ,  $Q = (x_1, y_1, z_1)$  &  $R = (x_2, y_2, z_2)$   
 Let  $(x, y, z)$  be the coordinate of point  $P$  on the plane whose position vector  $\vec{r}$ .

Then,

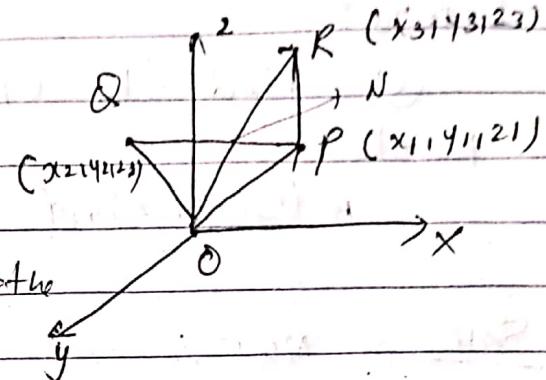
$$\vec{PA} = (x - x_0) \vec{i} + (y - y_0) \vec{j} + (z - z_0) \vec{k}$$

$$\vec{PQ} = (x_1 - x_0) \vec{i} + (y_1 - y_0) \vec{j} + (z_1 - z_0) \vec{k}$$

$$\vec{PR} = (x_2 - x_0) \vec{i} + (y_2 - y_0) \vec{j} + (z_2 - z_0) \vec{k}$$

Now required eqn of plane is obtained through

$$\begin{vmatrix} (x - x_0) & (y - y_0) & (z - z_0) \\ (x_1 - x_0) & (y_1 - y_0) & (z_1 - z_0) \\ (x_2 - x_0) & (y_2 - y_0) & (z_2 - z_0) \end{vmatrix} = 0 \quad \text{--- (1)}$$



Plane (1) passes through the point  $(x_0, y_0, z_0)$ ,  $(x_1, y_1, z_1)$ , and  $(x_2, y_2, z_2)$

Example :-

(v) Find the equation of plane through three points

$$A(3, -1, 2), B(-8, 2, 4) \text{ & } C(-1, 2, -3)$$

Soln

Now,

$$\begin{aligned}\vec{AB} &= \vec{OB} - \vec{OA} \\ &= (-8, 2, 4) - (3, -1, 2) \\ &= (-5, 3, 2)\end{aligned}$$

$$\begin{aligned}\vec{AC} &= \vec{OC} - \vec{OA} \\ &= (-1, 2, -3) - (3, -1, 2) \\ &= (-4, 1, -5)\end{aligned}$$

Now  $\vec{AB} \times \vec{AC} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -5 & 3 & 2 \\ -4 & 1 & -5 \end{vmatrix}$

$$\begin{aligned}&= \vec{i}(-15 + 2) + \cancel{\vec{j}(-20 + 15)} (-8 + 25) \\ &\quad + (-5 + 12) \vec{k}\end{aligned}$$

$$= -13\vec{i} + 17\vec{j} + 7\vec{k}$$

∴ Equation of plane passes through  $(3, -1, 2)$  with normal vector  $\vec{n} = (-13, 17, 7)$  is,

$$a(x - x_1) + b(y - y_1) + c(z - z_1) = 0$$

$$\Rightarrow -13(x - 3) + 17(y + 1) + 7(z - 2) = 0$$

$$\Rightarrow -13x + 13x_1 + 17y + 17 + 7z - 14 = 0$$

$$\Rightarrow -13x + 17y + 7z = -13x_1 - 17 + 14 \quad (*)$$

Point of Intersection of a Line & Plane

Example: Find the point of intersection of a line

$$\frac{x-2}{3} = \frac{y-0}{-4} = \frac{z-5}{1}$$

with a plane  $4x + 5y - 2z = 18$

Soln:-

$$\text{Let } \frac{x-2}{3} = \frac{y-0}{-4} = \frac{z-5}{1} = t \text{ say}$$

$$x = 3t + 2, y = -4t, z = t + 5 \quad (*)$$

The plane  $4x + 5y - 2z = 18 \quad (**)$

If the line (\*) intersects a plane (\*\*) then, (\*\*) must be satisfied by the value of  $x, y, z$ . (i.e.)

$$\therefore 4(3t + 2) + 5(-4t) - 2(t + 5) = 18 \quad 18$$

$$\Rightarrow 12t + 8 - 20t - 2t - 10 = 18$$

$$\Rightarrow -8t - 2t = 18 + 10 - 8$$

$$\Rightarrow t = -2$$

Substituting  $t = -2$  on  $(*)$

required point is  $x = -4, y = 8, z = 3$

$$\therefore (x_1 y_1 z_1) = (-4, 8, 3)$$

Angle between two plane :-

Angle between two planes is defined as the angle between their normal vector.

Formula :- The angle between two planes

$$P_1: a_1x + b_1y + c_1z = d_1 \quad -(1)$$

$$P_2: a_2x + b_2y + c_2z = d_2 \quad -(2)$$

The normal vector to the plane  $P_1$

$$\vec{n}_1 = (a_1, b_1, c_1)$$

Normal vector to the plane  $P_2$ ,

$$\vec{n}_2 = (a_2, b_2, c_2)$$

$\therefore$  Angle between them

$$\cos \theta = \frac{\vec{n}_1 \cdot \vec{n}_2}{|\vec{n}_1| |\vec{n}_2|}$$

$$|\vec{n}_1| |\vec{n}_2|$$

Example

Find the angle between two planes

$$x + y + 2z = 1, \quad x - 2y + 3z = 1$$

$- (*)$

$- (**)$

The normal vector of plane  $(*)$  and  $(**)$  are respectively,  $\vec{n}_1 = (1, 1, 1)$ ,  $\vec{n}_2 = (1, -2, 3)$

: Angle between them is

$$\cos \theta = \frac{\mathbf{h}_1 \cdot \mathbf{h}_2}{\|\mathbf{h}_1\| \|\mathbf{h}_2\|}$$

$$\|\mathbf{h}_1\| = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{3}$$

$$\|\mathbf{h}_2\| = \sqrt{1^2 + 4^2 + 9^2} = \sqrt{142}$$

$$\cos \theta = \frac{(-1, 1, 1) \cdot (1, -2, 3)}{\sqrt{3} \cdot \sqrt{142}}$$

$$= \frac{1 + (-2) + 3}{\sqrt{42}} = \frac{2}{\sqrt{42}}$$

$$\therefore \theta = \cos^{-1} \left( \frac{2}{\sqrt{42}} \right)$$

Equation of straight line through the intersection of two planes

$$\text{Let } P_1: a_1x + b_1y + c_1z = d_1 \quad (i)$$

$$P_2: a_2x + b_2y + c_2z = d_2 \quad (ii)$$

be two planes,

Step I. Find point on (i) put  $x=0$ , and ~~y=0~~  
then we get  $\frac{z = d_1}{c_1}$  on (i) and (ii).  $b_1y + c_1z = d_1$   
 $b_2y + c_2z = d_2$

$$\therefore \text{Required point } (x_1, y_1, z_1) = (0, 0, \frac{d_1}{c_1})$$

The required line L lies on both planes,

so the line L is  $\perp$  to both the planes

having normal vector  $\mathbf{n}_1 = (a_1, b_1, c_1)$ ,  $\mathbf{n}_2 = (a_2, b_2, c_2)$

$$\therefore \text{Required D.R.} = \vec{n}_1 \times \vec{n}_2$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}$$

$$= (a\vec{i} + b\vec{j} + c\vec{k}) \quad \text{say}$$

$$= (a_1 b_1 c)$$

$$\frac{(x-x_1)}{a} = \frac{y-y_1}{b} = \frac{z-z_1}{c}$$

Example find the Symmetrical eqn of line through the intersection of two planes

$$2x + y + z = 3$$

$$x + y + 3z = 6$$

Soln

Here, given two planes are,

$$2x + y + z = 3 \quad \text{--- (i)}$$

$$x + y + 3z = 6 \quad \text{--- (ii)}$$

Let  $(0, 0, 3)$  be the point in plane (i)

Also, normal vectors of two planes are,

$$\vec{n}_1 = (2, 1, 1), \vec{n}_2 = (1, 1, 3)$$

required direction ratios is,

$$= \vec{n}_1 \times \vec{n}_2 = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 2 & 1 & 1 \\ 1 & 1 & 3 \end{vmatrix}$$

$$= 2 \cdot (3-1)\vec{i} + (1-6)\vec{j} + (2-1)\vec{k}$$

$$= 2\vec{i} - 5\vec{j} + 2\vec{k} = (2, -5, 2)$$

Hence required line  $P_5$ ,

$$\frac{x-0}{2} = \frac{y}{-5} = \frac{z-3}{1}$$

$$\Rightarrow \frac{x}{2} = \frac{y}{-5} = \frac{z-3}{1} = t$$

$$x = 2t, y = -5t, z = t$$

Alternatively, put  $x=0$ ,

$$y+2z=3$$

$$y+3z=6$$

$$\underline{-2z=-3}$$

$$z=3$$

$$y=0$$

$$(0, 0, 3)$$

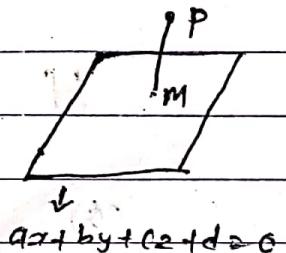
$$\Rightarrow \frac{x-0}{2} = \frac{y}{-5} = \frac{z-3}{1}$$

Formula

Length of  $L^1$  from  $P(x_1, y_1, z_1)$  to a plane

$$ax+by+cz+d=0$$

$$PM = \sqrt{a^2x_1^2 + b^2y_1^2 + c^2z_1^2 + d^2}$$



Example

Find the distance between two parallel planes,

$$x + y + z = 9 \quad \text{--- (1)}$$

$$2x + 2y + 2z = 10 \quad \text{--- (1')}$$

$$y + z = 9$$

$$2y + 2z = 10$$

Soln

Put,  $x = 0, y = 0$  then  $z = 9$ .  $(x_1, y_1, z_1) = (0, 0, 9)$

also, normal vector to the plane (1) is,  
 $(2, 2, 2)$

Hence distance between plane (1) and (1') is,

$$d = \frac{|ax_1 + by_1 + cz_1 + d|}{\sqrt{a^2 + b^2 + c^2}}$$

$$= \frac{9 - 10}{\sqrt{4+4+4}} = \frac{-1}{\sqrt{12}}$$

$$= \frac{1}{\sqrt{2}} \cdot \frac{2}{\sqrt{2}} \cdot \frac{8}{2\sqrt{3}} = \frac{4}{\sqrt{3}}$$

Fact:- If two lines are neither parallel nor intersect, then they are called skewed lines.

Set 3v Determine whether two lines  $L_1$  &  $L_2$  are parallel, Skewed or Intersect.

If intersecting find common point.

$$(i) \frac{x-3}{2} = \frac{y-4}{-1} = \frac{z-1}{3} \quad \text{--- (1)}$$

$$(ii) \frac{x-1}{4} = \frac{y-3}{-2} = \frac{z-4}{5} \quad \text{--- (1')}$$

Soln :- Here given eqns are,

$$\frac{x-3}{2} = \frac{y-4}{-1} = \frac{z-1}{3} = t \quad (\text{say})$$

$$\frac{x-1}{4} = \frac{y-3}{-2} = \frac{z-4}{5} = s \quad (\text{say})$$

then any point on first,

$$x = 2t+3, \quad y = -t+4, \quad z = 3t+1$$

$$(x, y, z) = (2t+3, -t+4, 3t+1)$$

Also, Any point on second,

$$x = 4s+1, \quad y = -2s+3, \quad z = 5s+4$$

$$(x, y, z) = (4s+1, -2s+3, 5s+4)$$

If ~~each~~ they meet each other then for certain ~~plus~~ S they are equal.

$$\therefore 2t+3 = 4s+1 \Rightarrow 2t - 4s = -2 \quad (III)$$

$$-t+4 = -2s+3 \Rightarrow -t + 2s = -1 \quad (IV)$$

$$3t+1 = 5s+4 \Rightarrow 3t - 5s = 3 \quad (V)$$

From (III) and (IV)

$$3t - 4s = -2$$

$$-t + 2s = -1$$

$$2t - 4s = 0$$

$$s = 0$$

$$t = 1$$

$s_1 = 0, t_1 = 1$  satisfies eqn (V) then it satisfies

We can not solve (III) and (IV). Also, solve (III) & (V).

If they are parallel or not,

$$\frac{2}{4} = \frac{-1}{-2} = \frac{3}{5}$$

ratio are not proportional. Hence they are Skew.

### Vector Function

Note: This is extension of vector function with Constant coordinates.

Let  $t$  Scalar variable defined on a interval  $(a, b)$  and Let  $\vec{r}$  be a vector function depends on scalar variable  $t$ . Then we say that  $\vec{r}$  is called vector function of scalar variable  $t$  and write

$$\vec{r} = \vec{r}(t)$$

Example let  $x = a \cos t, y = a \sin t, z = 0$

Then,

$$\vec{r} = \vec{x} + \vec{y} + \vec{z}$$

$$= a \cos t \vec{i} + a \sin t \vec{j} + 0 \cdot \vec{k}$$

$$\vec{r} = a \cos t \vec{i} + a \sin t \vec{j} \quad \text{--- (x)}$$

On squaring and adding,

$$r^2 = a^2 x^2 + y^2 = a^2, z = 0$$

This shows that  $\textcircled{*}$  represents a circle on  $xy$ -plane.

Example 2. Let  $x = a \cos t$ ,  $y = b \sin t$ ,  $t \in \mathbb{R}$

Then,  $\frac{x}{a} = \cos t$ ,  $\frac{y}{b} = \sin t$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, z = 0$$

$\therefore \vec{r} = a \cos t \hat{i} + b \sin t \hat{j} + 0 \hat{k}$  is a vector equation of ellipse on  $xy$ -plane.

It is also called vector function of ellipse on  $xy$ -plane.

Similarly, The equation  $x = at^2$ ,  $y = 2at$  represents a parabola.

i.e.,  $\vec{r} = at^2 \hat{i} + 2at \hat{j} + 0 \hat{k}$  is a parabola

Example Find the domain of vector function,

$$\vec{r} = \sqrt{4-t^2} \hat{i} + e^{-3t} \hat{j} + \ln(t+1) \hat{k}, t \in \mathbb{R}$$

Soln. Here,

$$\vec{r} = f(t) \hat{i} + g(t) \hat{j} + h(t) \hat{k}$$

Where,  $f(t) = \sqrt{4-t^2}$  is defined on  $[-2 \leq t \leq 2]$

$g(t) = e^{-3t}$  is defined for all

finite values of  $t$ .

&  $h(t) = \ln(1+t)$  is defined for all  $t > -1$

$\therefore$  The common domain  $(-1, 2]$

$$\text{or } -1 < t \leq 2$$

$\frac{0}{0}$  - Indeterminate form.  
 $\infty + \infty$  - Diverge  
 $\infty - \infty$  - Diverge

$\frac{0}{0}, \frac{\infty}{\infty}, \frac{\infty}{0}, \frac{0}{\infty}$

## Limit of a Vector Function

A function vector function

$\vec{r} = \vec{r}(t)$  is said to have limit  $\vec{L}$  as  $t \rightarrow t_0$  if

$$\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{L}$$

example :- Evaluate ~~limit~~

$$\lim_{t \rightarrow 0} \left( e^{-3t} \vec{i} + \frac{t^2}{\sin^2 t} \vec{j} + \cos 2t \vec{k} \right)$$

$$\text{Soln} \quad \lim_{t \rightarrow 0} (e^{-3t} \vec{i}) + \lim_{t \rightarrow 0} \frac{t^2}{\sin^2 t} \vec{j} + \lim_{t \rightarrow 0} \cos 2t \vec{k}$$

$$= 1 \vec{i} + 1 \vec{j} + 1 \vec{k}$$

$$= \vec{i} + \vec{j} + \vec{k}$$

Note:- If  $\vec{r}(t) = f(t) \vec{i} + g(t) \vec{j} + h(t) \vec{k}$

Then  $\lim_{t \rightarrow t_0} \vec{r}(t) = \lim_{t \rightarrow t_0} f(t) \vec{i} + \lim_{t \rightarrow t_0} g(t) \vec{j} + \lim_{t \rightarrow t_0} h(t) \vec{k}$

$\lim_{t \rightarrow t_0} h(t) \vec{k}$

This shows that limit of a vector function  $r(t)$  exist if each of its component ~~less~~  $f(t), g(t), h(t)$  exists.

## Continuity of Vector Function :-

A Vector Function  $\vec{r}(t)$  of scalar variable  $t$  is said to be continuous at point  $t = t_0$  if

$$\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{r}(t_0)$$

i.e., limiting value = functional value (of vector function)

Discuss the Continuity:-

$$\vec{r}(t) = 2t\vec{i} + 3t\vec{j} + 4t\vec{k}$$

Soln.  $\lim_{t \rightarrow 1} \vec{r}(t) = \lim_{t \rightarrow 1} 2t\vec{i} + \lim_{t \rightarrow 1} 3t\vec{j} + \lim_{t \rightarrow 1} 4t\vec{k}$

$$= 2\vec{i} + 3\vec{j} + 4\vec{k} \quad (\text{X})$$

Also, Functional Value,

$$\vec{r}(1) = 2\vec{i} + 3\vec{j} + 4\vec{k} \quad (\text{XX})$$

From (X) and (XX)

$$\lim_{t \rightarrow 1} \vec{r}(t) = \vec{r}(1)$$

∴  $\vec{r}(t)$  is continuous at  $t = 1$ .

## Differentiation of Vector Function

Let  $\vec{r} = \vec{r}(t)$  be a vector function of scalar variable  $t$ . Let  $\Delta t$  be small change in  $t$ . Then the derivative of  $\vec{r} = \vec{r}(t)$  is denoted by,  $\frac{d\vec{r}(t)}{dt}$  & is defined by

$$\frac{d\vec{r}(t)}{dt} = \lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t},$$

provided the limit on right hand side exists.

Fact If  $\vec{r} = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$  then

$$\frac{d\vec{r}}{dt} = \frac{df(t)}{dt}\vec{i} + \frac{dg(t)}{dt}\vec{j} + \frac{dh(t)}{dt}\vec{k}$$

$$\frac{d\vec{r}}{dt} = \left( \frac{df(t)}{dt}, \frac{dg(t)}{dt}, \frac{dh(t)}{dt} \right)$$

### Basic Rules on Differentiation

If  $\vec{r}_1, \vec{r}_2$  and  $\vec{r}_3$  be three vectors of scalar variable  $t$  then,

i) If  $\vec{r} = \vec{r}_1 \pm \vec{r}_2$  then,

$$\frac{d\vec{r}}{dt} = \frac{d\vec{r}_1}{dt} \pm \frac{d\vec{r}_2}{dt}$$

ii) If  $\vec{r}$  is constant vector,

$$\frac{d\vec{r}}{dt} = 0$$

iii)  $\frac{d}{dt}(\phi \vec{r}) = \phi \frac{d\vec{r}}{dt} + \text{where } \phi \text{ function of } t.$

$$\frac{d}{dt}(\vec{r}_1 \cdot \vec{r}_2) = \vec{r}_1 \frac{d\vec{r}_2}{dt} + \vec{r}_2 \frac{d\vec{r}_1}{dt}$$

$$(5) \frac{d}{dt} (\vec{r}_1 \times \vec{r}_2) = \vec{r}_1 \times \frac{d\vec{r}_2}{dt} + \frac{d\vec{r}_1}{dt} \times \vec{r}_2$$

$$(6) \frac{d}{dt} [\vec{r}_1 \cdot \vec{r}_2 \cdot \vec{r}_3] = \left[ \frac{d\vec{r}_1}{dt} \cdot \vec{r}_2 \cdot \vec{r}_3 \right] + \left[ \vec{r}_1 \cdot \frac{d\vec{r}_2}{dt} \cdot \vec{r}_3 \right] + \left[ \vec{r}_1 \cdot \vec{r}_2 \cdot \frac{d\vec{r}_3}{dt} \right]$$

Proof

We know that,

$$[\vec{r}_1 \cdot \vec{r}_2 \cdot \vec{r}_3] = \vec{r}_1 \cdot \vec{r}_2 \times \vec{r}_3$$

$$\begin{aligned} d(\vec{r}_1 \cdot \vec{r}_2 \times \vec{r}_3) &= \frac{d\vec{r}_1}{dt} (\vec{r}_2 \times \vec{r}_3) + \\ &\quad \vec{r}_1 \cdot \frac{d(\vec{r}_2 \times \vec{r}_3)}{dt} \\ &= \frac{d\vec{r}_1}{dt} (\vec{r}_2 \times \vec{r}_3) + \vec{r}_1 \cdot \left[ \vec{r}_2 \times \frac{d\vec{r}_3}{dt} + \right. \\ &\quad \left. \frac{d\vec{r}_2}{dt} \times \vec{r}_3 \right] \\ &= \left[ \frac{d\vec{r}_1}{dt} \cdot \vec{r}_2 \times \vec{r}_3 + \vec{r}_1 \cdot \vec{r}_2 \times \frac{d\vec{r}_3}{dt} + \right. \\ &\quad \left. \vec{r}_1 \cdot \frac{d\vec{r}_2}{dt} \times \vec{r}_3 \right] \\ &= \left[ \frac{d\vec{r}_1}{dt}, \vec{r}_1 \cdot \vec{r}_2 \right] + \left[ \vec{r}_1 \cdot \frac{d\vec{r}_2}{dt}, \vec{r}_3 \right] \\ &\quad + \left[ \vec{r}_1 \cdot \vec{r}_2, \frac{d\vec{r}_3}{dt} \right] \end{aligned}$$

(F) Derivative for vector triple product.

$$\frac{d}{dt} (\vec{r}_1 \times \vec{r}_2 \times \vec{r}_3) = \frac{d\vec{r}_1}{dt} \times (\vec{r}_2 \times \vec{r}_3) + \vec{r}_1 \times \frac{d(\vec{r}_2 \times \vec{r}_3)}{dt} \\ + \vec{r}_1 \times \vec{r}_2 \times \frac{d\vec{r}_3}{dt}$$

Example

(G) If  $\vec{r} = t^2 \vec{i} - t \vec{j} + (2t+1) \vec{k}$  find

$$(i) \frac{d\vec{r}}{dt} \cdot \frac{d^2\vec{r}}{dt^2} \quad (ii) \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2}$$

Soln

$$\vec{r} = t^2 \vec{i} - t \vec{j} + (2t+1) \vec{k}$$

$$\frac{d\vec{r}}{dt} = 2t \vec{i} - \vec{j} + 2 \vec{k}$$

$$\frac{d^2\vec{r}}{dt^2} = 2 \vec{i}$$

$$(i) \frac{d\vec{r}}{dt} \cdot \frac{d^2\vec{r}}{dt^2} = (2t, -1, 2) \cdot (2, 0, 0) \\ = 4t = 0$$

$$(ii) \frac{d\vec{r}}{dt} \times \frac{d^2\vec{r}}{dt^2} = (2t \vec{i} - \vec{j}, 2 \vec{k}) \times (2 \vec{i}, 0, 0) \\ = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 2t & -1 & 2 \\ 2 & 0 & 0 \end{vmatrix} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0 & -1 & 2 \\ 2 & 0 & 0 \end{vmatrix} \\ = 0\vec{i} + 4\vec{j} + 2\vec{k}.$$

Example 2 If  $\vec{r}_1 = +3\vec{i} + t^2\vec{j} + t\vec{k}$   
 $\vec{r}_2 = (t+1)\vec{i} + (1+t^2)\vec{j} - 3t\vec{k}$

Find

$$\frac{d}{dt} (\vec{r}_1 \times \vec{r}_2) \text{ at } t=2$$

$$\begin{aligned} \text{Soln.} \quad \frac{d}{dt} (\vec{r}_1 \times \vec{r}_2) &= \vec{r}_1 \times \frac{d\vec{r}_2}{dt} + \frac{d\vec{r}_1}{dt} \times \vec{r}_2 \\ &= (+3\vec{i} + t^2\vec{j} + t\vec{k}) \times (\vec{i} + \vec{j} - 3\vec{k}) \end{aligned}$$

$$+ (3+2\vec{i} + 2\vec{j} + \vec{k}) \times (t+1)\vec{i} + (t+2)\vec{j} - 3t\vec{k}$$

$$\frac{d}{dt} (\vec{r}_1 \times \vec{r}_2) \text{ at } t=2$$

$$\begin{aligned} &= (8\vec{i} + 4\vec{j} + 2\vec{k}) \times (\vec{i} + \vec{j} - 3\vec{k}) \\ &\quad + (12\vec{i} + 4\vec{j} + \vec{k}) \times (3\vec{i} + 4\vec{j} - 6\vec{k}) \\ &\quad \begin{array}{ccc|ccc} \vec{i} & \vec{j} & \vec{k} & \vec{i} & \vec{j} & \vec{k} \\ 8 & 4 & 2 & 12 & 4 & 1 \\ 1 & 1 & -3 & 3 & 4 & 6 \end{array} \end{aligned}$$

$$\begin{aligned} &= (-12-2)\vec{i} + (2+24)\vec{j} + (8-4)\vec{k} \\ &\quad + (24-4)\vec{i} + (3-12 \times 6)\vec{k} + (12 \times 4 - 12)\vec{k} \\ &= (12\vec{i} + 26\vec{j} + 4\vec{k}) + 20\vec{i} - 69\vec{j} \\ &\quad + 24\vec{k} \\ &= 8\vec{i} + 28\vec{k} \end{aligned}$$

(Q) If  $\frac{d\vec{a}}{dt} = \vec{c}' \times \vec{a}'$

8  $\frac{d\vec{b}}{dt} = \vec{c}' \times \vec{b}'$

then show that  $\frac{d}{dt}(\vec{a}' \times \vec{b}') = \vec{c}' \times (\vec{a}' \times \vec{b}')$

Soln

$$\frac{d\vec{a}'}{dt} \times \frac{d\vec{b}'}{dt} = \frac{d}{dt}(\vec{a}' \times \vec{b}')$$

$$= \vec{a}' \times \frac{d\vec{b}'}{dt} + \frac{d\vec{a}'}{dt} \times \vec{b}'$$

$$= \vec{a}' \times (\vec{c}' \times \vec{b}') + (\vec{c}' \times \vec{a}') \times \vec{b}'$$

$$= (\vec{a}' \times (\vec{c}' \times \vec{b})) + \vec{c}' \times (\vec{a}' \times \vec{b}')$$

$$= -[\vec{b}' \times (\vec{c}' \times \vec{a}')] + \vec{a}' \times (\vec{c}' \times \vec{b}')$$

$$= -[(b \cdot a)\vec{c} - (b \cdot c)\vec{a}]$$

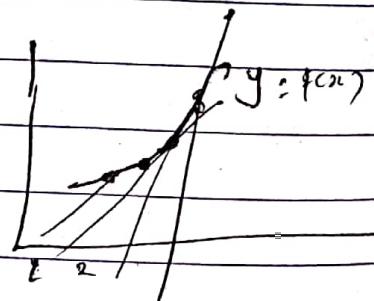
$$+ (a \cdot b)\vec{c} - (a \cdot c)\vec{b}$$

$$= (b \cdot c)\vec{a}' - (a \cdot c)\vec{b}'$$

$$= (\vec{c} \cdot \vec{b}')\vec{a}' - (\vec{c} \cdot \vec{a}')\vec{b}'$$

$$= \vec{c}' \times (\vec{a}' \times \vec{b}')$$

Note: derivative represent Slope of tangent to the curve



$$t = 2\pi + \theta + 2\pi n$$



$\frac{d\mathbf{r}}{dt}$  → vector along the tangent

Date \_\_\_\_\_  
Page \_\_\_\_\_

### Geometrical meaning

If  $\vec{r} = \vec{r}(t)$  be a vector function of scalar variable  $t$  then  $\frac{d\mathbf{r}}{dt}$  always represent the vector along the tangent in the sense of  $t$  increasing.

Example Let  $\vec{r} = 2t^2 \vec{i} + 3t^2 \vec{j}$  find the unit vector along the tangent at point  $t=2$

$$\text{Soln} \quad \vec{r} = 2t^2 \vec{i} + 3t^2 \vec{j}$$

$$\frac{d\vec{r}}{dt} = 4t \vec{i} + 6t \vec{j} \\ \text{at } t=2 \quad = 8\vec{i} + 12\vec{j}$$

$$|\frac{d\vec{r}}{dt}| = \sqrt{64+144} \\ = \sqrt{208}$$

$t=2$

$$\vec{r} = \frac{8}{\sqrt{208}} \vec{i} + \frac{12}{\sqrt{208}} \vec{j}$$

vector along the tangent having length 5

$$= 5 \times \left[ \frac{8}{\sqrt{208}} \vec{i} + \frac{12}{\sqrt{208}} \vec{j} \right]$$

## Vector Integration

Integration of a vector function is the reverse process of differentiation.

Consider a vector  $\vec{r} = \vec{r}(t)$  then its integral is denoted by

$$\int \vec{r}(t) dt$$

Note:- If  $\vec{r} = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$  then its Vector Integration is,

$$\int \vec{r}(t) dt = (\int f(t) dt) \vec{i} + (\int g(t) dt) \vec{j} + (\int h(t) dt) \vec{k}$$

## Definite Integral

As in the real valued function we can evaluate the definite integral for vector valued function.

If  $\vec{r} = \vec{r}(t)$  be a vector function and

$\int \vec{r}(t) dt = \vec{R}(t) + \vec{c}$ . Then definite integral of  $\vec{r}(t)$  w.r.t.  $t$  from  $t=t_1$  to  $t=t_2$  is,

$$\text{Definite } \int_{t_1}^{t_2} \vec{r}(t) dt = [\vec{R}(t)]_{t_1}^{t_2}$$

↓      ↓  
Integrand    Integral

$$= \vec{R}(t_2) - \vec{R}(t_1)$$

(Q) If  $\vec{r} = t^2 \vec{i} + t \vec{j} + t^2 \vec{k}$  find  $\int_0^2 \left( \frac{d^2 \vec{r}}{dt^2} \right) dt$

Soln Here  $\vec{r}(t) = t^2 \vec{i} + t \vec{j} + t^2 \vec{k}$

$$\frac{d\vec{r}}{dt} = 2t \vec{i} + 1 \vec{j} + 2t \vec{k}$$

$$\frac{d^2 \vec{r}}{dt^2} = 2 \vec{i} + 0 \vec{j} + 2 \vec{k}$$

$$\vec{r} \times \frac{d^2\vec{r}}{dt^2} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1^2 & 1 & 1^2 \\ 2 & 0 & 2 \end{vmatrix}$$

$$= 2\mathbf{i} + (2\mathbf{i}^2 - 2\mathbf{i}^2)\mathbf{j} + -2\mathbf{k}$$

$$= 2\mathbf{i} + 0\mathbf{j} - 2\mathbf{k}$$

$$\int_0^2 \vec{r} \times \frac{d^2\vec{r}}{dt^2} = \int_0^2 2\mathbf{i} - \int_0^2 2\mathbf{k}$$

$$= [t^2]_0^2 \mathbf{i} - [t^2]_0^2 \mathbf{k}$$

$$= 4\mathbf{i} - 4\mathbf{k}$$

### Arc length of a curve

Recall that the arc length of a Cartesian curve

$$y = f(x) \text{ from } x=a \text{ to } x=b$$

$$S = \int_a^b \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

Also from differential calculus,

$$x = f(t) \text{ & } y = g(t)$$

$$\frac{ds}{dx} = \sqrt{1 + \left(\frac{dy}{dx}\right)^2}$$

Then,

$$\begin{aligned} \frac{ds}{dt} &= \frac{ds}{dx} \cdot \frac{dx}{dt} = \sqrt{1 + \left(\frac{dy}{dx}\right)^2} \cdot \left(\frac{dx}{dt}\right) \\ &= \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} \end{aligned}$$

If we extending this concept to vector function  
 $\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$ , where  $x, y, z$  are functions of  $t$ , then,

$$\frac{ds}{dt} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2}$$

Integrating w.r.t  $t$  from  $t = t_1$  to  $t = t_2$

$$s = \int_{t_1}^{t_2} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt \quad \text{--- (1)}$$

Is arc length of vector valued function from  $t_1$  to  $t_2$ .

example Find the arc length of the vector function

$$\vec{r}(t) = \cos t \vec{i} + \sin t \vec{j} + t \vec{k} \quad \text{from } t = 0 \text{ to } t = 2\pi$$

Soln:

$$\vec{r}(t) = (\cos t \vec{i} + \sin t \vec{j} + t \vec{k})$$

$$x = \cos t \quad y = \sin t \quad z = t$$

$$\frac{dx}{dt} = -\sin t \quad \frac{dy}{dt} = \cos t \quad \frac{dz}{dt} = 1$$

$$\frac{ds}{dt} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2}$$

$$[s]_0^{2\pi} = \int_0^{2\pi} \sqrt{(-\sin t)^2 + (\cos t)^2 + 1^2} dt$$

$$= \int_0^{2\pi} \sqrt{2} dt$$

$$= \sqrt{2} [t]_0^{2\pi}$$

$$= 2\sqrt{2}\pi.$$

Facts: If  $\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$

$$\frac{d\vec{r}}{dt} = \frac{dx}{dt}\vec{i} + \frac{dy}{dt}\vec{j} + \frac{dz}{dt}\vec{k}$$

$$\left| \frac{d\vec{r}}{dt} \right| = \sqrt{\left( \frac{dx}{dt} \right)^2 + \left( \frac{dy}{dt} \right)^2 + \left( \frac{dz}{dt} \right)^2}$$

\* Can be written as

$$[s]_{t_1}^{t_2} = \int_{t_1}^{t_2} \left| \frac{d\vec{r}}{dt} \right| dt$$

$$= \int_{t_1}^{t_2} |r'(t)| dt$$

Curvature:

We had the derivatives of  $\vec{r}$  w.r.t  $t$  i.e  $\frac{d\vec{r}}{dt}$  represent the vector along the tangent.

Also, unit vector,

$$T(t) = \frac{\vec{r}}{\left| \frac{d\vec{r}}{dt} \right|} = \frac{\vec{r}(t)}{|r'(t)|}$$

The Curvature of a curve  $\vec{r} = \vec{r}(t)$  is the rate of change of  $T(t)$  w.r.t arc length s. i.e. It is denoted by  $K$ .

$$\text{Thus, } K = \left| \frac{dT}{ds} \right|$$

This can be evaluated as,

$$K = \left| \frac{\frac{dT}{dt}}{\frac{ds}{dt}} \right|$$

(Q) Find the curvature of a circle of radius  $a$ .

Sol) we know circle with radius  $x = a \cos t$   
 $y = a \sin t$ .

$$\therefore \vec{r} = a \cos t \vec{i} + a \sin t \vec{j}$$

$$\frac{d\vec{r}}{dt} = -a \sin t \vec{i} + a \cos t \vec{j}$$

$$T(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \frac{-a \sin t \vec{i} + a \cos t \vec{j}}{|a|}$$

$$= -\sin t \vec{i} + \cos t \vec{j}$$

$$T(t) = \cos t \vec{i} - \sin t \vec{j}$$

$$\frac{ds}{dt} = |\vec{r}'(t)| = a$$

$$K = \frac{|\frac{dT}{dt}|}{\frac{ds}{dt}} = \frac{|-\cos t \vec{i} - \sin t \vec{j}|}{a} = \frac{a}{a} = 1$$

We had.

$T(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$ , unit vector in the direction

of tangent.

$$K = \frac{dT}{ds} = \frac{\frac{dT}{dt}}{\frac{ds}{dt}}, \text{ where } \frac{ds}{dt} = |\vec{r}'(t)|$$

Alternative formula to find curvature

The Curvature of a vector function  $\vec{r} = \vec{r}(t)$   
is,

$$k(t) = \frac{|r'(t) \times r''(t)|}{|r'(t)|^3}$$

Example Find the curvature of a curve

$$\vec{r}(t) = (t^2, \ln t, t \ln t) \text{ at } (1, 0, 0)$$

$$r'(t) = 2t + \frac{1}{t} + \ln t + t \cdot \frac{1}{t}$$

$$= 2\vec{i} + \left(\frac{1}{t}\right)\vec{j} + [1 + \ln t]\vec{k}$$

$$r''(t) = 2 - \frac{1}{t^2} + \frac{1}{t}$$

$$r'(t) \times r''(t) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 2t & \frac{1}{t} & 1 + \ln t \\ 2 & -\frac{1}{t^2} & \frac{1}{t} \end{vmatrix}$$

$$= \left[ \frac{1}{t^2} + \frac{1}{t^2} (1 + \ln t) \right] \vec{i} +$$

$$[2 + 2\cancel{\ln t} - 2] \vec{j} + \left(-\frac{2}{t} - \frac{2}{t}\right) \vec{k}$$

$$= (-2) \vec{i} + 2 \vec{j} + -4 \vec{k}$$

$$= 2\vec{i} + 2\vec{j} - 4\vec{k}$$

$$|\vec{r}'(t) \times \vec{r}''(t)| = \sqrt{a^2 + b^2 + c^2} = \sqrt{20}$$

$$|\vec{r}'(t)| = |\alpha \vec{i} + \beta \vec{j} + \gamma \vec{k}|$$

$$= \sqrt{\alpha^2 + \beta^2 + \gamma^2}$$

$$= \sqrt{6}$$

$$k(t) = \frac{\sqrt{20}}{\sqrt{6}}$$

$$(\sqrt{6})^3$$

Curvature with Cartesian eqn  $y = f(x)$

If vector function  $\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$   
is expressed in plane curve  $y = f(x)$ . Then  
 $\vec{r} = x\vec{i} + f(x)\vec{j}$

$$\vec{r}' = \vec{i} + f'(x)\vec{j}$$

$$\vec{r}'' = f''(x)\vec{j}$$

Hence, above formula becomes,

$$k(x) = \frac{|\vec{r}'(x) \times \vec{r}''(x)|}{|\vec{r}(x)|^3} =$$

$$\vec{r}'(x) \times \vec{r}''(x) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & f'(x) & 0 \\ 0 & f''(x) & 0 \end{vmatrix}$$

$$= \vec{0} + \vec{0} + F''(x) \vec{F}$$

$$|r'(x)|^2 = \sqrt{1 + [F'(x)]^2}$$

$$k(x) = \frac{\sqrt{[F''(x)]^2}}{\sqrt{1 + [F'(x)]^2}}^{3/2}$$

$$= \frac{|F''(x)|}{\sqrt{1 + [F'(x)]^2}}^{3/2}$$

Example find the curvature of the curve

$$y = x^4 \text{ at } x=2$$

Soln Here,

$$y = x^4$$

$$y' = 4x^3 \quad y'|_{x=2} = 32$$

$$y'' = 12x^2 \quad y''|_{x=2} = 12 \times 4 = 48$$

$$= \frac{|48|}{\sqrt{1 + (32)^2}}^{3/2}$$

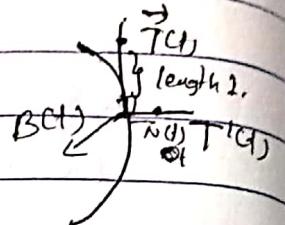
$$= \frac{|48|}{\sqrt{1 + 1024}}^{3/2}$$

$$= \frac{48}{(1025)^{3/2}}$$

## Normal & Binormal Vector

~~Fact~~ For a vector function  $\vec{r}(t)$  we have  
unit tangent vector

$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$$



There are infinitely many vectors in the direction of  $\vec{T}(t)$  but we have only one single vector along the direction of  $t$  with  $\|\vec{T}(t)\| = 1$ .

Fact: For every constant unit vector  $\vec{r}$ ,

$$\vec{r} \cdot \frac{d\vec{r}}{dt} = 0$$

This means that

$$\vec{T}(t) \cdot \frac{d\vec{T}}{dt} = 0$$

$$\text{i.e. } \vec{T}(t) \cdot \vec{T}'(t) = 0$$

The principal normal vector  $N(t)$  is defined ~~for~~ by

$$N(t) = \frac{\vec{T}'(t)}{\|\vec{T}'(t)\|}$$

The vector perpendicular to both  $\vec{T}(t) \otimes N(t)$  is called Binormal vector and is denoted by Thus,

$$\vec{B}(t) = \vec{T}(t) \otimes \vec{N}(t)$$

If it is  $\perp r$  to both vector  $\vec{T}(t)$  &  $\vec{N}(t)$ .

C.W Find the tangent vector, normal vector and binormal vector of the vector function.

$$\vec{r}(t) = (t^2, \frac{2}{3}t^3, t) \text{ at } t = (1, \frac{2}{3}, 1)$$

Soln

$$\text{Here } \vec{r}(t) = (t^2, \frac{2}{3}t^3, t) \text{ at } t = (1, \frac{2}{3}, 1)$$

$$\begin{aligned} \vec{r}'(t) &= 2\vec{i} + \frac{2}{3} \cdot 3t^2 \vec{j} + \vec{k} \\ &= 2\vec{i} + 2t^2 \vec{j} + \vec{k} \end{aligned}$$

$$\vec{r}''(t) = 2\vec{j} + 4t\vec{k}$$

$$\begin{aligned} \vec{T}(t) &= \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \frac{2\vec{i} + 2t^2\vec{j} + \vec{k}}{\sqrt{2^2 + 2^2 + 1}} \\ &= \frac{2\vec{i} + 2\vec{j} + \vec{k}}{\sqrt{9}} \\ &= \frac{2}{3}\vec{i} + \frac{2}{3}\vec{j} + \frac{1}{3}\vec{k} = \frac{2t\vec{i} + 2t^2\vec{j} + \vec{k}}{3} \end{aligned}$$

$$\begin{aligned} \vec{T}'(t) &= d \left( \frac{2}{3}, \frac{2t^2}{3}, \frac{1}{3} \right) \\ \frac{d}{dt} & \end{aligned}$$

$$\left( \frac{2}{3}, \frac{4t}{3}, 0 \right)$$

$$= \left( \frac{2}{3}, \frac{4}{3}, 0 \right)$$

$$\text{Normal vector } N(t) = \frac{T(t)}{\|T'(t)\|} = \frac{\frac{2}{3}\vec{i} + \frac{2}{3}\vec{j} + \frac{1}{3}\vec{k}}{\sqrt{\left(\frac{2}{3}\right)^2 + \left(\frac{1}{3}\right)^2 + 0^2}}$$

$$= \frac{\frac{2}{3}\vec{i} + \frac{2}{3}\vec{j} + \frac{1}{3}\vec{k}}{\sqrt{(2)^2 + (1)^2}} = \frac{\frac{2}{3}\vec{i} + \frac{2}{3}\vec{j} + \frac{1}{3}\vec{k}}{\sqrt{3^2}} = \frac{\frac{2}{3}\vec{i} + \frac{2}{3}\vec{j} + \frac{1}{3}\vec{k}}{\sqrt{20}}$$

$$= \frac{2\vec{i}}{\sqrt{20}} + \frac{2\vec{j}}{\sqrt{20}} + \frac{1\vec{k}}{\sqrt{20}}$$

Now, Binormal vector is,

$$B(t) = T(t) \times N(t)$$

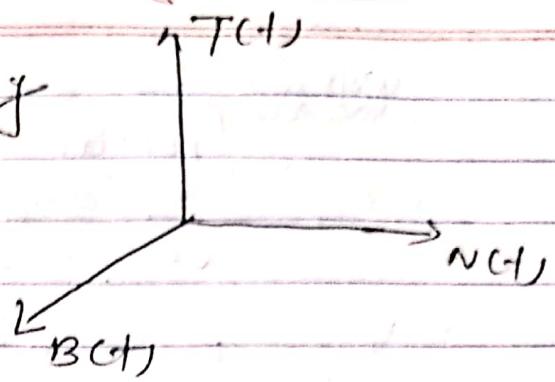
$$= \left( \frac{2}{3}\vec{i} + \frac{2}{3}\vec{j} + \frac{1}{3}\vec{k} \right) \times$$

$$\left( \frac{2}{\sqrt{20}}\vec{i} + \frac{2}{\sqrt{20}}\vec{j} + \frac{1}{\sqrt{20}}\vec{k} \right)$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 1 & 1 \\ \frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{2}{\sqrt{20}} & \frac{2}{\sqrt{20}} & \frac{1}{\sqrt{20}} \end{vmatrix}$$

$$= ( )\vec{i} + ( )\vec{j} + ( )\vec{k}$$

Defn, The plane determined by the vectors  $N(t)$  &  $T(t)$  is called Osculating plane.



If  $\vec{r} = \vec{r}(t)$  be a position of a moving particle at time  $t$ . Then, the velocity ( $v$ ) is  $\frac{d\vec{r}}{dt}$  and acceleration  $\vec{a}$  is  $\frac{d^2\vec{r}}{dt^2}$

example The acceleration of a particle at time  $t$  is  $\vec{a}(t) = e^{2t}\vec{i} + e^t\vec{j} + 2\vec{k}$ . Find the velocity  $\vec{v}$  and displacement  $\vec{r}$  at time  $t$ . Given  $\vec{v} = \vec{i} + \vec{j}$  if  $\vec{r} = 0$  at

$$\text{Here, } \vec{a}(t) = e^{2t}\vec{i} + e^t\vec{j} + 2\vec{k}$$

$$\int a(t) dt = \int (e^{2t}\vec{i} + e^t\vec{j} + 2\vec{k}) dt$$

$$= \int e^{2t}\vec{i} dt + \int e^t\vec{j} dt + \int 2\vec{k} dt$$

$$= \frac{e^{2t}}{2}\vec{i} + e^t\vec{j} + 2\vec{k} + C \quad \text{--- (x)}$$

given, At  $t = 0$ ,  $\vec{v} = \vec{i} + \vec{j}$

$$\vec{i} + \vec{j} = \frac{1}{2}\vec{i} + \vec{j} + C$$

$$\Rightarrow C = \frac{1}{2}\vec{i}$$

put  $C = \frac{1}{2}\vec{i}$  in eq (x)

$$\int a(t) dt = \frac{e^{2t}}{2}\vec{i} + e^t\vec{j} + 2\vec{k} + \frac{1}{2}\vec{i}$$

against

$$\begin{aligned}\int r(t) dt &= \int a(t) dt \\ &= \int \left[ \frac{e^{2t}}{2} \vec{i} + e^t \vec{j} + t^2 \vec{k} + \frac{1}{2} t \vec{i} + c \right] dt \\ &= \left[ \frac{e^{2t}}{4} \vec{i} + e^t \vec{j} + \frac{t^3}{3} \vec{k} + \frac{1}{2} t^2 \vec{i} + c \right] - \text{(x)(y)}\end{aligned}$$

When  $c(t) = 0$ ,  $r(t) = 0$

$$\therefore 0 = \frac{1}{4} \vec{i} + \vec{j} + c$$

$$\therefore c = -\frac{1}{4} \vec{i} - \vec{j}$$

put  $\varphi_0$  ( $x \times$ )

$$= \frac{e^{2t}}{4} \vec{i} + e^t \vec{j} + t^2 \vec{k} + \frac{1}{2} t^2 \vec{i} - \frac{1}{4} \vec{i} - \vec{j} - (\times \times \times)$$

( $\times \times \times$ ) is required displacement.

### Vector Calculus

#### Smooth Curve

If a curve  $\vec{r} = \vec{r}(t)$  is determined in space depending on the parameter  $t$ , such that

$$\vec{r} = x(t) \vec{i} + y(t) \vec{j} + z(t) \vec{k}$$

Then,  $\vec{r}$  is called curve in space. If it is continuous and differentiable on the integrable then  $\vec{r}$  is called smooth curve.

Ex The curve  $\vec{r} = \vec{r}(t) = 2t\vec{i} + \frac{2}{t}\vec{j} + \frac{3}{t^2}\vec{k}$  is not smooth  $t \in [2, 3]$ .

### Line Integral :-

$$F(t) = 2t\vec{i} + 3t\vec{j} + 4t\vec{k}$$

Any integral which is evaluated along a curve is called line integral. Line integral  $\int_C F \cdot d\vec{r}$ .

### Line Integral $\int_C F \cdot d\vec{r}$ :-

Let us consider vector point function.

$$\vec{F} = F_1(x_1, y_1, z_1)\vec{i} + F_2(x_1, y_1, z_1)\vec{j} + F_3(x_1, y_1, z_1)\vec{k}$$

defined on a smooth curve  $C$  which is represented by  $\vec{r}$ . on the interval  $[a, b]$ .

Then line integral of  $F$  along the curve  $C$  is given by,

$$\int_C \vec{F} \cdot d\vec{r} \quad \text{where } \vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$$

Example Evaluate the line integral.  $\int_C \vec{F} \cdot d\vec{r}$  where  $x^2\vec{i} + y^3\vec{j}$  and  $C$  is arc of the parabola  $y = x^2$

from  $(0, 0)$  to  $(1, 1)$ .

Soln Here  $\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$

$$d\vec{r} = dx\vec{i} + dy\vec{j} + dz\vec{k}$$

$$\vec{F} \cdot d\vec{r} = (x^2\vec{i} + y^3\vec{j}) \cdot (dx\vec{i} + dy\vec{j} + dz\vec{k})$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_C (x^2 dx + y^3 dy) dx$$

$$= \int_0^1 x^2 dx + \int_0^1 2x^7 dx$$

$$= \left[ \frac{x^3}{3} \right]_0^1 + \left[ \frac{2x^8}{8} \right]_0^1$$

$$= \frac{1}{3} + \frac{2}{8} = \frac{4+3}{12} = \frac{7}{12}$$

(Q) Evaluate  $\int_C \vec{F} \cdot d\vec{r}$ , where  $\vec{F} = y^2 \vec{i} + x^2 \vec{j}$   
 C is the straight line joining  $(0,0)$  to  $(1,0)$  and  
 then from  $(1,0)$  to  $(1,1)$

Soln St. line joining  $(0,0)$  to  $(1,0)$

$$y-0 = \frac{0-0}{1-0} (x-0) \Rightarrow y=0$$

St. line Joining  $(1,0)$  to  $(1,1)$

$$y-1 = \frac{1-0}{1-1} (x-1) \Rightarrow x=1$$

$$r = x\vec{i} + y\vec{j} + z\vec{k}$$

$$dr = dx\vec{i} + dy\vec{j} + dz\vec{k}$$

$$\begin{aligned} \vec{F} \cdot dr &= (y^2 \vec{i} + x^2 \vec{j}) \cdot (dx\vec{i} + dy\vec{j}) \\ &= y^2 dx \vec{i} + x^2 dy \vec{j} \end{aligned}$$

$$\int_C \vec{F} \cdot d\vec{r} =$$

$$\therefore \text{required integral} = \int_C \vec{F} \cdot d\vec{r}$$

## Line Integration Independent of path.

Theorem: The line integral  $\int_C \vec{F} \cdot d\vec{r}$  of a continuous function  $\vec{F}$  is independent of path ( $C$ ) if  $\vec{F}$  can be expressed as  $\vec{F} = \nabla\phi$  where  $\phi$  is some scalar valued function.

Proof :- We proved that if  $\vec{F} = \nabla\phi$ , then  $\int_C \vec{F} \cdot d\vec{r}$  is independent of path ( $C$ ).

Let  $C$  be a path joining  $A$  to  $B$ .

$$\begin{aligned}
 \text{Now, } \int_C \vec{F} \cdot d\vec{r} &= \int_C \nabla\phi \cdot (\vec{i}dx + \vec{j}dy + \vec{k}dz) \\
 &= \int_C \left( \vec{i} \frac{\partial \phi}{\partial x} + \vec{j} \frac{\partial \phi}{\partial y} + \vec{k} \frac{\partial \phi}{\partial z} \right) \cdot (\vec{i}dx + \vec{j}dy + \vec{k}dz) \\
 &= \int_C \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \\
 &= \int_C d\phi \\
 &= [\phi]_A^B \\
 &= \phi(B) - \phi(A).
 \end{aligned}$$

This shows that  $\int_C \vec{F} \cdot d\vec{r}$  is independent of path.

Definition:- (Irrotational vector)

We know that if  $\vec{F} = \nabla\phi$  for some scalar valued function  $\phi$ , then  $\int_C \vec{F} \cdot d\vec{r}$  is independent of path. In such case  $\vec{F}$  is called irrotational vector function.

For such function  $\vec{F}$

$$\nabla \times \vec{F} = 0$$

i.e  $\vec{F}$  is irrotational if  $\nabla \times \vec{F} = 0$

$$\nabla \times \vec{F} = \nabla \times (\nabla \phi) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{vmatrix}$$

$$= \left( \frac{\partial^2 \phi}{\partial y \partial z} - \frac{\partial^2 \phi}{\partial z \partial y} \right) \vec{i} +$$

$$\left( \frac{\partial^2 \phi}{\partial z \partial x} - \frac{\partial^2 \phi}{\partial x \partial z} \right) \vec{j} +$$

$$\left( \frac{\partial^2 \phi}{\partial x \partial y} - \frac{\partial^2 \phi}{\partial y \partial x} \right) \vec{k} = 0$$

Example.

Show that the vector function

$\vec{F} = (x^2 - y^2) \vec{i} + (y^2 - zx) \vec{j} + (z^2 - xy) \vec{k}$  is irrotational. Also find a scalar function  $\phi$  such that  $\vec{F} = \nabla \phi$ .

Soln

Curl  $\vec{F} = \nabla \times \vec{F} = \nabla \times \vec{F}$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{vmatrix}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (x^2 - y^2) & (y^2 - zx) & (z^2 - xy) \end{vmatrix}$$

$$= \left[ \frac{\partial (z^2 - xy)}{\partial y} - \frac{\partial (y^2 - zx)}{\partial z} \right] \vec{i} +$$

$$\left[ \frac{\partial (x^2 - y^2)}{\partial z} - \frac{\partial (z^2 - xy)}{\partial x} \right] \vec{j} +$$

$$\left[ \frac{\partial (y^2 - zx)}{\partial x} - \frac{\partial (x^2 - y^2)}{\partial y} \right] \vec{k}$$

$$\begin{aligned}
 & [ -x + x ] \vec{i} + [ -y + y ] \vec{j} + [ -z + z ] \vec{k} \\
 & = (0 \vec{i} + 0 \vec{j} + 0 \vec{k}) \\
 & = \vec{0} \text{ vector} \\
 & \Rightarrow \text{Curl } \vec{F} \text{ is zero, Hence } \vec{F} \text{ is irrotational.}
 \end{aligned}$$

For second part,

$$\text{we have } \vec{F} = \nabla \phi$$

$$\Rightarrow (x^2 - y^2) \vec{i} + (y^2 - zx) \vec{j} + (z^2 - xy) \vec{k} = \\
 \frac{\partial \phi}{\partial x} \vec{i} + \frac{\partial \phi}{\partial y} \vec{j} + \frac{\partial \phi}{\partial z} \vec{k}.$$

$$\begin{aligned}
 \Rightarrow x^2 - y^2 = \frac{\partial \phi}{\partial x} & \Rightarrow | 2x = \frac{\partial \phi}{\partial x} | \\
 y^2 - zx = \frac{\partial \phi}{\partial y} & \Rightarrow | 2y = \frac{\partial \phi}{\partial y} | \\
 z^2 - xy = \frac{\partial \phi}{\partial z} & \Rightarrow | 2z = \frac{\partial \phi}{\partial z} |
 \end{aligned}$$

Integrating w.r.t  $x$ .

$$\phi = \frac{x^3}{3} - xy^2 + C_1, \quad \rho = \frac{y^3}{3} - xyz^2 + C_2,$$

$$\rho = \frac{y^3}{3} - xyz^2 + C_3$$

$\therefore$  Hence,  $\phi$  is,

$$\phi = \frac{x^3}{3} + \frac{y^3}{3} + \frac{z^3}{3} - 3xyz^2 + C$$

## Surface Integral :-

Facts: If  $\phi = ax + by + cz$  be a plane or surface. Then,  
 $\nabla \phi$  always represent vector normal to the surface  
 eg  $\phi = x + 2y + 3z = 0$  be a plane.  
 Then,

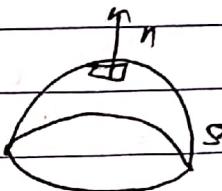
$$\nabla \phi = \vec{i} \cdot \vec{1} + 2\vec{j} + 3\vec{k} = (1, 2, 3)$$

(1, 2, 3)  
Normal vector

Defn Any integral which is evaluated over a surface is called  $x + 2y + 3z = 0$  Surface integral.

Let  $S$  be the surface  $\vec{n}$  be the vector normal to the surface of small rectangle  $ds$  in the surface. Then the integral of over the surface  $S$  of a vector function  $\vec{F}$

$$= \iint_S \vec{F} \cdot \vec{n} ds$$



where  $\vec{n}$  is the unit vector normal to the given surface  $S$ . If  $S = \phi(x_1 y_1 z)$

$$\vec{n} = \frac{\nabla \phi}{|\nabla \phi|} \times \underline{ds} = \frac{dx dy}{|\nabla \phi|}$$

$$\text{where } \vec{k} = (0, 0, 1)$$

Evaluate The Surface integral

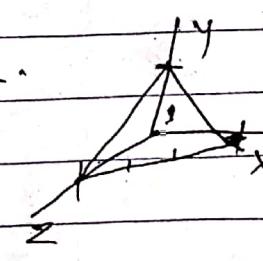
$$\iint_S \vec{F} \cdot \vec{n} ds \text{ where } \vec{F} = x^2 \vec{i} + y^2 \vec{j} + z^2 \vec{k},$$

and  $S$  be the finite plane  $x + y + z = L$ .

Soln

$$\vec{F} = x^2 \vec{i} + y^2 \vec{j} + z^2 \vec{k}$$

$$S \text{ is, } x + y + z = L$$



$$\phi = (x+y+z-1) \neq 0$$

Now,  $\nabla \phi = \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z}$   
 $= (\vec{i} + \vec{j} + \vec{k})$

$\Rightarrow \vec{n} = \nabla \phi = \frac{\vec{i} + \vec{j} + \vec{k}}{\|\nabla \phi\|} = \frac{\vec{i} + \vec{j} + \vec{k}}{\sqrt{3}}$

Now,

$$S = \iint_S \vec{F} \cdot \vec{n} dS$$

$$= \iint_S \vec{F} \cdot \vec{n} dS$$

where

$$dS = \frac{dx dy}{\|\vec{n}\|} = \frac{dx dy}{\sqrt{1+\frac{1}{3}}} = \sqrt{3} dx dy$$

Also,

$$z = 1-x-y$$

$\therefore$  Surface Integral.

$$(S) = \iint_S \vec{F} \cdot \vec{n} dS$$

$$= \iint_S (x^2 \vec{i} + y^2 \vec{j} + z^2 \vec{k}) \cdot (\vec{i} + \vec{j} + \vec{k}) \cdot \frac{\sqrt{3} dx dy}{\sqrt{3}}$$

$$= \iint_{\substack{x=0 \\ y=0}}^{1-x} [x^2 \vec{i} + y^2 \vec{j} + (1-x-y)^2 \vec{k}] \cdot [\vec{i} + \vec{j} + \vec{k}] dx dy$$

$$= \int_{x=0}^1 \int_{y=0}^{1-x} \left\{ [x^2 + y^2 + (1-x-y)^2] dy \right\} dx$$

$$= \int_{x=0}^1 \left[ x^2 y + \frac{y^3}{3} + \frac{(1-x-y)^3}{3 \cdot (-1)} \right]_0^{1-x} dx$$

$$= \int_{x=0}^1 x^2(1-x) + \frac{(1-x)^3}{3} + \left[ \frac{2(1-x)(1-x)^3}{-3} - \frac{8(1-x)^3}{3} \right] dx$$

$$= \int_{x=0}^1 \left[ x^2 - x^3 + \frac{(1-x)^3}{-3} + \frac{(1-x)^3}{3} \right] dx$$

$$= \left[ \frac{x^3}{3} - \frac{x^4}{4} + \frac{2(1-x)^4}{3 \cdot 4 \cdot (-1)} \right]_0^1$$

$$= \left[ \frac{1}{3} - \frac{1}{4} + \frac{2}{3} \right] = \frac{1}{3} - \frac{1}{4} = \frac{2}{3} - \frac{1}{4} = \frac{1}{12}$$

$$= \left[ \frac{1}{3} - \frac{1}{4} + \frac{2}{12} \right]$$

$$= \frac{4-3+2}{12}$$

$$= \frac{3}{12}$$

$$= \frac{1}{4}$$

Example: Find the Surface Integral of the Vector Function  $\vec{F} = yz\vec{i} + zx\vec{j} + xy\vec{k}$  through that of sphere  $x^2 + y^2 + z^2 = 1$  in the first octant.

Soln: Given the surface is  $x^2 + y^2 + z^2 = 1$ , we know that  $\nabla \phi$  is a vector normal to the surface.  $\nabla \phi(x, y, z) = ($

taking  $\psi(x, y, z) = x^2 + y^2 + z^2$

$$\nabla \phi = \frac{\partial \phi}{\partial x} \vec{i} + \frac{\partial \phi}{\partial y} \vec{j} + \frac{\partial \phi}{\partial z} \vec{k}$$

$$= 2x\vec{i} + 2y\vec{j} + 2z\vec{k}$$

$\therefore$  unit vector normal

$$\hat{n} = \frac{\nabla \phi}{|\nabla \phi|}$$

$$\hat{n} = \frac{2(x\vec{i} + y\vec{j} + z\vec{k})}{\sqrt{2^2(x^2 + y^2 + z^2)}}$$

$$= \frac{x\vec{i} + y\vec{j} + z\vec{k}}{\sqrt{x^2 + y^2 + z^2}}$$

$$= \frac{x\vec{i} + y\vec{j} + z\vec{k}}{a} \quad (\because x^2 + y^2 + z^2 = 1)$$

Also if  $\vec{F} = y_2 \vec{i} + zx \vec{j} + xy \vec{k}$

$$\vec{F} \cdot \hat{n} = \frac{1}{a} (xy_2 + y_2 z + zx_2)$$

$$= \frac{3xy_2}{a} \quad \text{---(1)}$$

$$ds = \frac{dx dy}{\sqrt{1 + z^2}} = \frac{dx dy}{\sqrt{1 + \frac{y_2^2}{x^2}}} = \frac{a dx dy}{x}$$

from (1) and (2)

$$\iint_S \vec{F} \cdot \hat{n} \cdot ds = \iint_R \frac{3xy_2}{a} a dx dy = \iint_R 3xy dy dx$$

The region of integration is the quadrant of the circle  $x^2 + y^2 = 1$

$$\begin{aligned}
 \iint_S \vec{F} \cdot \hat{n} \, ds &= 3 \int_{x=0}^1 \int_{y=0}^{\sqrt{1-x^2}} xy \, dy \, dx \\
 &= 3 \int_{x=0}^1 x \left[ \frac{y^2}{2} \right]_{y=0}^{\sqrt{1-x^2}} \, dx \\
 &= \frac{3}{2} \int_0^1 x(1-x^2) \, dx \\
 &= \frac{3}{2} \left[ \frac{x^2}{2} - \frac{x^4}{4} \right]_0^1 \\
 &= \frac{3}{2} \left[ \frac{1}{2} - \frac{1}{4} \right] \\
 &= \frac{3}{8}
 \end{aligned}$$

Thus  $\iint_S (y\vec{i} + z\vec{j} + xy\vec{k}) \cdot \hat{n} \, ds$

$$= \frac{3q^4}{8}$$

Gradient field.

If  $\phi(x_1, y_1, z)$  be surface function of three variables  $x, y, z$  then its gradient function or gradient field

$$\nabla \phi \text{ is. i.e } \nabla \phi = \vec{i} \frac{\partial \phi}{\partial x} + \vec{j} \frac{\partial \phi}{\partial y} + \vec{k} \frac{\partial \phi}{\partial z}$$

(Q) Find the gradient field of  $f(x, y) = x^2y^2 - x^2 - y^2$

$$\text{Soln: Here } f(x, y) = x^2y^2 - x^2 - y^2$$

$$\text{Gradient } \vec{F} = \vec{i} \frac{\partial F}{\partial x} + \vec{j} \frac{\partial F}{\partial y} + \vec{k} \frac{\partial F}{\partial z}$$

$$= \vec{i}(2xy^2 - 2x) + \vec{j}(2x^2y - 2y)$$

Note:  $\text{Grad } f = \text{vector normal to the surface}$   
 If we have to find line integral of scalar function  $f(x, y)$   
 Then the line integral of the scalar function  $f(x, y)$   
 over the curve  $C$  is given by the formula,  
 $\int_C f(x, y) ds$  where  $ds = \text{arc length.}$

$$= \int_C f(x, y) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

where  $t \in [a, b]$

$$= \int_a^b f(x, y) \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

(Q) Evaluate the line integral  $\int_C f(x, y) ds$   
 Where,  $f(x, y) = 2 + x^2y$ .

$C$  is upper half of unit circle.

Soln:- Clearly, unit circle is  $x = \cos t, y = \sin t$   
 $[x^2 + y^2 = \cos^2 t + \sin^2 t = 1]$

clearly  $t$  lies in between  $0 \leq t \leq \pi$ .

i.e  $0 \leq t \leq \pi$ .

$t = \pi$        $t = 0$

$$\therefore \text{required line integral} = \int_C f(x, y) ds$$

$$= \int_0^\pi (2 + x^2y) \sqrt{(-\sin t)^2 + (\cos t)^2} dt$$

$$= \int_0^\pi (2 + x^2y) dt$$

$$= \int_0^\pi (2 + \cos^2 t \cdot \sin t) dt$$

$$= \int_0^\pi 2 dt + \int_0^\pi \cos^2 t \cdot \sin t dt$$

$$\text{put } \cos t = y$$

$$-\sin t dt = dy$$

If  $t=0, y=1, t=2\pi, y=-1,$

$$= [2t]_0^{\pi} + \left[ -\frac{y^3}{3} \right]_1^{-1}$$

$$= 2\pi + \frac{1}{3} + \frac{1}{3} = 2\pi + \frac{2}{3}$$

Workdone by force [Application of line integral]

Soln) If a force  $\vec{F}$  act on a particle which is moved along a curve  $C$ . Then the workdone  $W_D$  of the force  $F$  along the tangent to the curve  $C$  is,

$$W_D = \vec{F} \cdot \frac{d\vec{r}}{dt}$$

$$\therefore \text{Total Workdone} = \int_C \vec{F} \cdot \frac{d\vec{r}}{dt}$$

(a) Find the workdone in moving a particle once along the circle  $x^2+y^2=4, z=0$  if the force field  $\vec{F}$  is defined by  $\vec{F} = (2x-y+2z)\vec{i} + (x+y-z)\vec{j} + (3x-2y+5z)\vec{k}$

Soln) Here circle  $C$  is  $x^2+y^2=4, z=0$  which is given by  $x=2\cos t, y=2\sin t,$

$$\vec{F} = (2x-y)\vec{i} + (x+y)\vec{j} + (3x-2y)\vec{k}$$

$$\vec{F} = (2 \cdot 2\cos t - 2\sin t)\vec{i} + (2\cos t + 2\sin t)\vec{j} + (3 \cdot 2\cos t - 2 \cdot 2\sin t)\vec{k}$$

$$= (4\cos t - 2\sin t)\vec{i} + (2\cos t + 2\sin t)\vec{j} + (6\cos t - 4\sin t)\vec{k}$$

Also,  $d\vec{r} = \vec{i}dx + \vec{j}dy$  where  $dx = -2\sin t dt$   
 $dy = 2\cos t dt.$

$\therefore$  Work done by force ( $F$ ) is  $\int_C \vec{F} \cdot d\vec{r}$ .

$$= \int_0^{2\pi} (4\cos t - 2\sin t) \vec{i} + (2\cos t + 2\sin t) \vec{j} + (6\cos t - 4\sin t) \vec{k} \cdot (-2\sin t) \vec{i} + 2\cos t \vec{j} \cdot dt$$

$$= \int_0^{2\pi} (-8\cos t \sin t + 4\sin^2 t) dt + (4\cos^2 t + 4\cos t) dt$$

$$= \int_0^{2\pi} -8\cos t \sin t dt + \int_0^{2\pi} 4\sin^2 t dt + \int_0^{2\pi} 4\cos^2 t dt \\ + \int_0^{2\pi} 4\cos t \sin t dt$$

$$= \int_0^{2\pi} [-4\cos t \sin t dt + 4] dt$$

$$= \int_0^{2\pi} [-2\sin 2t + 4] dt$$

$$= [-2(-1) \frac{\cos 2t}{2}]_0^{2\pi} + [4t]_0^{2\pi}$$

$$= [\cos 2t]_0^{2\pi} + [4t]_0^{2\pi}$$

Green's Theorem

Relation Between Line Integral and Surface Integral

C Double Integral

If  $D$  be a closed region in the  $(x, y)$  plane, bounded by a simple closed curve  $C$ . If  $P(x, y)$  and  $Q(x, y)$  are two continuous functions in  $D$ .

Then,

$$\int_C [P dx + Q dy] = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy.$$

example Verify Green's theorem for the function

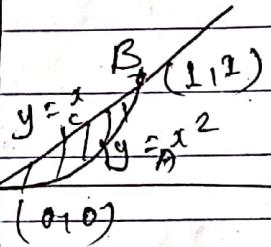
$P = xy + y^2$  &  $Q = x^2$  where  $C$  is the closed curve of the region bounded by the line  $y = x$  & parabola  $y = x^2$

Soln  $\frac{\partial Q}{\partial x} = 2x, \quad \frac{\partial P}{\partial y} = x + 2y$

the line  $y = x$  and  $y = x^2$  meets at  $O(0,0)$  &  $A(1,1)$

$\therefore$  L.H.S

The parabola & line intersect at  
 $O(0,0)$  &  $A(1,1)$



Now,  $\int_C (xy + y^2) dx + x^2 dy$

Along  $y = x^2$

$$I_1 = \int_{x=0}^{x=1} x \cdot x^2 dx + \int_0^1 x^2 \cdot 2x dx$$

$$= \frac{x^4}{4} \Big|_0^1 + \frac{x^5}{5} \Big|_0^1 + 2 \int_0^1 \frac{x^4}{4} dx$$

$$= \frac{1}{4} + \frac{1}{5} + \frac{1}{2} = \frac{19}{20}$$

Again, along the curve  $y = x$  i.e BCO

$$= \int_C (xy + y^2) dx + x^2 dy$$

$$= \int_1^0 (x^2 + x^2) dx + \int_0^1 x^2 dx$$

$$= -\frac{x^3}{3} \Big|_1^0 + \frac{x^3}{3} \Big|_0^1 + \frac{x^3}{3} \Big|_1^0$$

$$= -\frac{1}{3} + \frac{1}{3} - \frac{1}{3}$$

$$= \frac{-1 - 1 - 1}{3}$$

$$I_2 = -1$$

$$\therefore \text{line Integral} \Sigma I_L + I_2$$

$$= \frac{19 - 1}{20}$$

$$= -\frac{1}{20} \quad \text{(A)}$$

Again, Surface integral

$$= \iint_D \left[ \frac{\partial \phi}{\partial x} - \frac{\partial \phi}{\partial y} \right] dx dy$$

$$= \iint_D \left[ \frac{\partial x^2}{\partial x} - \frac{\partial (xy + y^2)}{\partial y} \right] dx dy$$

$$= \int_0^1 \int_{x^2}^x \left[ \frac{\partial x^2}{\partial x} - \frac{\partial (xy + y^2)}{\partial y} \right] dx dy$$

$$= \int_0^1 \int_{x^2}^x [2x - (x + 2y)] dx dy$$

$$= \int_0^1 \int_{x^2}^x (x - 2y) dx dy$$

$$= \int_0^1 \left[ xy \Big|_{x=0}^x - \frac{y^2}{2} \Big|_{x=0}^x \right] dx$$

$$= \int_0^1 (x^2 - x^3 - x^2 + x^4) dx$$

$$= \int_0^1 (x^4 - x^3) dx$$

$$= \int_0^1 (x^4 - x^3) dx$$

$$= \left[ \frac{x^5}{5} - \frac{x^4}{4} \right]_0^1 \quad \text{Total area} = \frac{1}{2} \int_C (x dy - y dx)$$

$$= \frac{1}{5} - \frac{1}{4} = -\frac{1}{20} \quad \text{--- (B)}$$

i. from (A) & (B)

$$\int_C p dx + q dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

Application :-

Statement :- The area enclosed by the curve  $C$  is given by  $\frac{1}{2} \int_C x dy - y dx$

Proof :- By Green theorem in the plane,

$$\int_C p dx + q dy = \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy \quad (\text{--- (X)})$$

In particular, Let us choose

$$P = -y \quad \& \quad Q = x \quad \text{in (X)}$$

$$\int_C x dy - y dx = \iint_D \left[ \frac{\partial x}{\partial x} - \frac{\partial y}{\partial y} \right] dx dy$$

$$\text{or } \int_C x dy - y dx = \iint_D (1+1) dx dy$$

$$\text{or } \frac{1}{2} \int_C x dy - y dx = \iint_D dx dy$$

= Total area of region D.

## Divergence & Curl of a Vector Function

Divergence: If  $\vec{V} = P\vec{i} + Q\vec{j} + R\vec{k}$  where  $P, Q, R$  are function of  $x, y, z$ , then divergence of  $\vec{V}$  is denoted by  $\nabla \cdot \vec{V}$  and is defined by

$$\nabla \cdot \vec{V} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}, \text{ provided all the partial derivatives exist.}$$

In Symbolic notation

$$\nabla \cdot \vec{V} = \left( \vec{i} \cdot \frac{\partial}{\partial x} + \vec{j} \cdot \frac{\partial}{\partial y} + \vec{k} \cdot \frac{\partial}{\partial z} \right) \cdot (P\vec{i} + Q\vec{j} + R\vec{k})$$

$$= \vec{i} \left( \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial v}{\partial z} \right)$$

$$= \vec{i} \cdot \frac{\partial v}{\partial x}$$

Curl or If  $\vec{V} = P\vec{i} + Q\vec{j} + R\vec{k}$ , where  $P, Q, R$  are function of  $x, y, z$ , then curl of  $\vec{V}$  is denoted by  $\nabla \times \vec{V}$  and is defined by

$$\nabla \times \vec{V} = \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \text{ and is given by}$$

$$= \left( \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \right) \times (P\vec{i} + Q\vec{j} + R\vec{k})$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

$$= \left( \frac{\partial R - \partial Q}{\partial y} \right) \vec{i} + \left( \frac{\partial P - \partial R}{\partial z} \right) \vec{j} + \left( \frac{\partial Q - \frac{\partial P}{\partial y}}{\partial x} \right) \vec{k}$$

provided that all partial derivatives exist.

### In Symbolic Notation

$$\begin{aligned}\nabla \times \vec{V} &= \left( \overset{\circ}{i} \frac{\partial}{\partial x} + \overset{\circ}{j} \frac{\partial}{\partial y} + \overset{\circ}{k} \frac{\partial}{\partial z} \right) \times \vec{V} \\ &= \overset{\circ}{i} X \frac{\partial \vec{V}}{\partial x} + \overset{\circ}{j} X \frac{\partial \vec{V}}{\partial y} + \overset{\circ}{k} X \frac{\partial \vec{V}}{\partial z} \\ &= \overset{\circ}{i} X \frac{\partial \vec{V}}{\partial x}\end{aligned}$$

Example :-

$$\text{If } \vec{F} = \vec{x} + y\vec{j} + z\vec{k}$$

Find divergence & curl  $\vec{F}$ .

Sol Here,  $\vec{F} = \vec{x} + y\vec{j} + z\vec{k}$

Divergence of  $\vec{F}$  is given by,

$$\nabla \cdot \vec{F} = \frac{\partial}{\partial x} x + \frac{\partial}{\partial y} y + \frac{\partial}{\partial z} z$$

$$= 1 + 1 + 1$$

$$= 3$$

Also

$$\nabla \times \vec{F} = \left( \frac{\partial}{\partial x} \overset{\circ}{i} + \frac{\partial}{\partial y} \overset{\circ}{j} + \frac{\partial}{\partial z} \overset{\circ}{k} \right) \times (\vec{x} + y\vec{j} + z\vec{k})$$

	$\overset{\circ}{i}$	$\overset{\circ}{j}$	$\overset{\circ}{k}$
$\frac{\partial}{\partial x}$	$x$	$y$	$z$
$x$	$y$	$z$	

$$= \left( \frac{\partial x}{\partial x} - \frac{\partial x}{\partial z} \right) \overset{\circ}{i} + \left( \frac{\partial y}{\partial x} - \frac{\partial z}{\partial x} \right) \overset{\circ}{j} + \left( \frac{\partial z}{\partial x} - \frac{\partial y}{\partial z} \right) \overset{\circ}{k}$$

$$\Sigma 0 + 0 + 0 = 0$$

Example If  $\vec{r} = \vec{x}\hat{i} + \vec{y}\hat{j} + \vec{z}\hat{k}$  &  $r = |\vec{r}|$   
 prove that (i)  $\nabla \cdot (r^3 \vec{r}) = 6r^3$  (ii)  $\operatorname{Div}(\frac{\vec{r}}{r}) = \frac{2}{r}$

Soln  $\vec{r} = \vec{x}\hat{i} + \vec{y}\hat{j} + \vec{z}\hat{k}$

$$\begin{aligned}\frac{\partial r}{\partial x} &= \frac{\partial}{\partial x} (\sqrt{x^2 + y^2 + z^2}) \stackrel{x}{=} \frac{x}{r} \\ &= \frac{x}{\sqrt{x^2 + y^2 + z^2}}\end{aligned}$$

similarly,

$$\frac{\partial r}{\partial y} = \frac{y}{r}$$

$$\frac{\partial r}{\partial z} = \frac{z}{r}$$

$$\begin{aligned}\text{Now, } (i) \quad &\nabla \cdot (r^3 \vec{r}) \\ &= \sum_i \frac{\partial}{\partial x_i} (r^3 \vec{r}) \\ &= \vec{i} \cdot \frac{\partial}{\partial x} (r^3 \vec{r}) \quad [ \because \text{By definition of divergence} ] \\ &= \vec{i} \cdot \left\{ r^3 \frac{\partial \vec{r}}{\partial x} + 3r^2 \frac{\partial r}{\partial x} \vec{i} \right\} \\ &= \boxed{\vec{i} \cdot \left\{ r^3 \frac{x}{r} \hat{i} + 3r^2 \frac{\partial r}{\partial x} \hat{i} \right\}} \\ &= \vec{i} \cdot \left\{ r^3 \hat{i} + 3r^2 \frac{\partial r}{\partial x} \hat{i} \right\} \\ &= \vec{i} \cdot \left\{ r^3 \hat{i} + 3r^2 \hat{i} \right\} \\ &= \boxed{r^3 (i \cdot i) + 3r^2 (i \cdot \vec{r})} \\ &= \boxed{6r^3 + 3r^2}\end{aligned}$$

$$= \Sigma r^3 (1) + \Sigma 3rx \cdot x$$

$$r^3 = (1) + 3r = x^2$$

$$= 3r^3 + 3r^2$$

$$= 3r^3 + 3r^2$$

$$= 6r^3$$

$$(P.P) \quad \text{Div } (\frac{\vec{r}}{r})$$

$$(P.P) \quad \nabla^2 \left( \frac{1}{r} \right) = 0$$

Note:- A vector function  $v$  is said to be

(i) Solenoidal if  $\nabla \cdot \vec{v} = 0$  i.e.  $\text{div } \vec{v} = 0$

(ii) Irrotational  $\nabla \times \vec{v} = 0$  i.e.  $\text{curl } \vec{v} = 0$

$$\text{Div } (\frac{\vec{r}}{r}) = \nabla \cdot (\frac{\vec{r}}{r}) = \nabla \cdot \left( \frac{x \hat{i} + y \hat{j} + z \hat{k}}{r} \right)$$

$$= \Sigma i \frac{\partial}{\partial x} \cdot \frac{x}{\sqrt{x^2+y^2+z^2}}$$

$$= \Sigma i \cdot \frac{\partial}{\partial x} \left\{ \frac{x}{\sqrt{x^2+y^2+z^2}} \right\}$$

$$= \Sigma i \cdot \frac{1}{\sqrt{x^2+y^2+z^2}} \cdot \frac{1}{\sqrt{x^2+y^2+z^2}} \cdot \frac{x}{(\sqrt{x^2+y^2+z^2})^2}$$

$$= \Sigma i \cdot \frac{x^2+y^2+z^2 - x^2}{(x^2+y^2+z^2) \cdot \sqrt{x^2+y^2+z^2}}$$

$$= \Sigma i \cdot \frac{y^2+z^2}{r^3}$$

$$= \frac{2(x^2+y^2+z^2)}{r^3}$$

$$= \frac{2r^2}{r^3}$$

$$= \frac{2}{r}$$

Example find the value of constant  $P$  so that  
the vector

Soln  $\vec{V} = (x+3y, y-2z, x+pz)$  is solenoidal,

$$\nabla \cdot \vec{V} = 0$$

$$\Rightarrow \frac{\partial}{\partial x}(x+3y) + \frac{\partial}{\partial y}(y-2z) + \frac{\partial}{\partial z}(x+pz) = (0+0+0)$$

$$\Rightarrow \cancel{i} + \cancel{j} + p\cancel{k} = (0^i + 0^j + 0^k)$$

$$L + L + p = 0$$

$$\Rightarrow p = -2$$

H.W find the value of the constant  $p_1$  and  $\vec{r}$  so that the vector,

$\vec{V} = (x+2y+pz) \vec{i} + (qx-3y-z) \vec{j} + (4x+ry+2z) \vec{k}$  is irrotational

Soln  $\nabla \times \vec{V} = \left( \frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \times \begin{cases} (x+2y+pz) \vec{i} + \\ (qx-3y-z) \vec{j} + \\ (4x+ry+2z) \vec{k} \end{cases}$

$i$	$j$	$k$	Ans
$\frac{\partial}{\partial x}$	$\frac{\partial}{\partial y}$	$\frac{\partial}{\partial z}$	$p=4$
$(x+2y+pz)$	$(qx-3y-z)$	$(4x+ry+2z)$	$q=2$
			$r=-2$

$$= \left\{ \frac{\partial}{\partial y} (4x+ry+2z) - \frac{\partial}{\partial z} (qx+3y-z) \right\} \vec{i} +$$

$$+ \left\{ \frac{\partial}{\partial z} (x+2y+pz) - \frac{\partial}{\partial x} (4x+ry+2z) \right\} \vec{j} +$$

$$+ \left\{ \frac{\partial}{\partial x} (qx-3y-z) - \frac{\partial}{\partial y} (x+2y+pz) \right\} \vec{k}$$

## Conservative & Non-Conservative field :-

A vector field  $\vec{F} = p\vec{i} + q\vec{j}$  is called conservative if

$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$$

Non-conservative,

$$\text{If, } \frac{\partial P}{\partial y} \neq \frac{\partial Q}{\partial x}$$

eg Does the vector field

$$\vec{F} = (x-y)\vec{i} + (x-2)\vec{j} \text{ is Conservative?}$$

Soln

$$\boxed{\begin{aligned}\frac{\partial F}{\partial x} &= \vec{i} + \vec{j} \\ \frac{\partial F}{\partial y} &= -\vec{i} + \vec{0}\end{aligned}}$$

$$P = (x-y) \quad Q = (x-2)$$

$$\frac{\partial P}{\partial y} = -1$$

$$\frac{\partial Q}{\partial x} = 1$$

$$\frac{\partial P}{\partial y} \neq \frac{\partial Q}{\partial x}$$

Example Check whether the vector function or field  $\vec{F}(x,y) = (3+2xy)\vec{i} + (x^2 - 3y^2)\vec{j}$  is conservative

Soln

Given function

$$\vec{F}(x,y) = p\vec{i} + q\vec{j} \text{ where } p = (3+2xy) \\ q = (x^2 - 3y^2)$$

$$\frac{\partial P}{\partial y} = 2x$$

$$\frac{\partial Q}{\partial x} = 2x$$

$\therefore \frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$  Hence is conservative.

Note:- If  $\vec{F} = p\vec{i} + q\vec{j}$  Find curl  $\vec{F}$

Soln

$$\text{curl } \vec{F} = \nabla \times \vec{F}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ p & q & r \end{vmatrix}$$

$$= \cancel{q} \cdot \frac{\partial r}{\partial x} - \cancel{o} \cdot \frac{\partial p}{\partial y} - \cancel{r} \cdot \frac{\partial q}{\partial z}$$

$$= \vec{k} \left\{ \frac{\partial r}{\partial x} - \frac{\partial p}{\partial y} \right\} = 0$$

Note:- from (\*) we can say that

(i)  $\vec{F}$  is Conservative if  $\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y}$

i.e.  $\text{curl } \vec{F} = 0$

(ii)  $\vec{F}$  is non conservative if  $\frac{\partial Q}{\partial x} \neq \frac{\partial P}{\partial y}$

i.e.  $\text{curl } \vec{F} \neq 0$  i.e.  $\vec{F}$  is not irrotational

Question: Show that the vector field

$\vec{F} = x^2 \vec{i} + xy^2 \vec{j} - y^2 \vec{k}$  can not be written as the curl of another function  $G$ , such that

$$\vec{F} \neq \text{curl } G.$$

Soln:-  $\text{div } \vec{F}$

$$= \frac{\partial (xz)}{\partial x} + \frac{\partial (xy^2)}{\partial y} + \frac{\partial (-y^2)}{\partial z}$$

$$= 2z + x^2 + 0$$

$$= z(1+x) - \cancel{x}$$

$$\text{div } \vec{F} \neq 0$$

If  $\vec{F} = \text{curl } \vec{G}$  for some vector  $\vec{G}$ .

$$\text{div } \vec{F} = 0$$

But By  $\cancel{(1)}$ .  $\text{div}(\text{curl } G) \neq 0$

So our supposition is false.

Evaluate  $\operatorname{div} \operatorname{curl} \vec{V} = p_1$ , where  $\vec{V}$  is any vector.  
 Soln Let  $\vec{V} = V_1 \vec{i} + V_2 \vec{j} + V_3 \vec{k}$

$$\operatorname{div} \operatorname{curl} \vec{V} = \nabla \cdot (\nabla \times \vec{V})$$

$$\begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_1 & V_2 & V_3 \end{vmatrix} = 0$$

$$= \frac{\partial}{\partial x} \left[ \frac{\partial V_3}{\partial y} - \frac{\partial V_2}{\partial z} \right] - \frac{\partial}{\partial y} \left[ \frac{\partial V_3}{\partial x} - \frac{\partial V_1}{\partial z} \right] +$$

$$\frac{\partial}{\partial z} \left[ \frac{\partial V_2}{\partial x} - \frac{\partial V_1}{\partial y} \right]$$

$$= \cancel{\frac{\partial^2 V_3}{\partial x \partial y}} - \cancel{\frac{\partial^2 V_2}{\partial x \partial z}} + - \cancel{\frac{\partial^2 V_3}{\partial y \partial x}} + \cancel{\frac{\partial^2 V_1}{\partial y \partial z}}$$

$$+ \cancel{\frac{\partial^2 V_2}{\partial z \partial x}} - \cancel{\frac{\partial^2 V_1}{\partial z \partial y}}$$

$$= 0$$

Green theorem used Green theorem to find the area of the ellipse.  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ .

Soln for the ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$

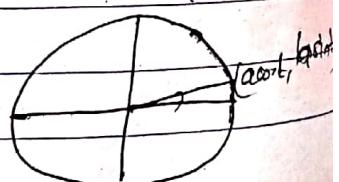
parametric representation,

$$x = a \cos \theta, y = b \sin \theta$$

where  $\theta$  varies,  $0 \leq \theta \leq 2\pi$

$$dx = -a \sin \theta d\theta$$

$$dy = b \cos \theta d\theta$$



i. By green theorem

$$= \frac{1}{2} \int_C (x dy - y dx)$$

$$= \frac{1}{2} \int_0^{2\pi} (a \cos t b \cos t dt + b \sin t a \sin t dt)$$

$$= ab \int_0^{2\pi} dt$$

$$= \frac{ab}{2} [t]_0^{2\pi}$$

$$= \frac{ab}{2} \times 2\pi$$

$$= ab\pi$$

How used Green theorem to find the area of the circle  $x^2 + y^2 = a^2$ .

Soln. For circle  $x^2 + y^2 = a^2$  parametric representation is  $x = a \cos t, y = a \sin t$ .

where  $0 \leq t \leq 2\pi$

$$dx = -a \sin t dt$$

$$dy = a \cos t dt$$

By green theorem

$$= \frac{1}{2} \int_0^{2\pi} (x dy - y dx)$$

$$= \frac{1}{2} \int_0^{2\pi} (a \cos t a \cos t dt + a \sin t a \sin t dt)$$

$$= \frac{1}{2} \int_0^{2\pi} a^2 (\cos^2 t + \sin^2 t) dt$$

$$= \frac{a^2}{2} \int_0^{2\pi} dt = \frac{a^2}{2} + \int_0^{2\pi} dt = \frac{a^2}{2} \times 2\pi = \pi a^2$$

Stokes Theorem / Relation between line integral & Surface Integral in Vector Function

If  $f$  is continuous & differential vector function defined over the surface  $S_1$ . Then,

$$\int_C \vec{F} \cdot d\vec{r} = \iint_S (\operatorname{curl} \vec{F}) \cdot \vec{n} ds$$

where  $ds = \frac{\sqrt{dx^2 + dy^2}}{h \cdot T_0}$

$$\int_C \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot \vec{n} ds$$

## Example

Special Case of Stokes Theorem

In plane Surface, prove that Green theorem is the particular Case of Stock's theorem.

**PROOF:-** If  $S$  is the plane surface lying in  $xy$  plane so that  $z$  axis is the direction of unit normal vector  $\vec{n}$  so that,  $\vec{n} = \vec{k}$ .

Also in  $xy$  plane.  $z=0$

$$\text{Let } \vec{F} = \vec{p} + \vec{q} + \vec{r}$$

$$8 \quad \vec{r} = a\vec{i} + b\vec{j} + c\vec{k}$$

$$\therefore \vec{dr} = dx\hat{i} + dy\hat{j} + dz\hat{k}$$

$$\text{L.H.S} \int_C \vec{F} \cdot d\vec{r}$$

$$= \int_C (P\vec{i} + Q\vec{j} + R\vec{k}) \cdot (dx\vec{i} + dy\vec{j} + dz\vec{k})$$

$$= \int_C P dx + Q dy - \text{(X)} \quad \text{But } z=0 \quad dz=0$$

From R.H.S

$$\iint_S (\nabla \times \vec{F}) \cdot \vec{n} ds = (x \alpha)$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

$$= \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \vec{i} + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \vec{j} + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \vec{k}$$

From (x-x)

$$\iint_S \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \vec{i} + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \vec{j} + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \vec{k} \cdot \vec{k}$$

$$dz dy$$

$$2 \iint_S \left( \frac{\partial Q}{\partial z} - \frac{\partial P}{\partial y} \right) dz dy \rightarrow (xxx)$$

From (x) and (xxx)

$$\int_C P dx + Q dy = \iint_S \left( \frac{\partial Q}{\partial z} - \frac{\partial P}{\partial y} \right) dz dy$$

which is green theorem.

Consequence of Stoke Law :-

prove that  $\int_C \vec{F} \cdot d\vec{r} = \iint_S (\vec{n} \times \vec{F}) \cdot \vec{F} ds$

Proof :- from Stokes theorem,

$$\int_C \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot \vec{n} ds \quad (x)$$

$$\begin{aligned} \text{Now, } (\nabla \times \vec{F}) \cdot \vec{n} &= \vec{n} \cdot (\nabla \times \vec{F}) \\ &= (\vec{n} \times \vec{\nabla}) \cdot \vec{F} \\ &= (\vec{n} \times \nabla) \cdot \vec{F} \end{aligned}$$

Problem :- Verify Stokes theorem for the vector function  $\vec{F} = x^2 \vec{i} + xy \vec{j}$  for the square region in the  $xy$  plane bounded by line  $x=0, y=0, x=a, y=a$ .

Proof Here,  $\vec{F} = x^2 \vec{i} + xy \vec{j}$

We verify  $\int_C \vec{F} \cdot d\vec{r} = \iint_S (\text{curl } \vec{F}) \cdot \vec{k} dy$

$$\text{curl } \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{F} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 & xy & 0 \end{vmatrix}$$

$$\begin{aligned} &\approx ((0-0) \vec{i} + (0-0) \vec{j} + T_k (y-0)) \\ &= T_k y \end{aligned}$$

$$\text{L.H.S. } \iint_S (\operatorname{curl} \vec{F}) \cdot \vec{k} \, dA = \iint_S k_y \cdot \vec{k} \, dA \, dy$$

$$= \iint_S y \, dA \, dy$$

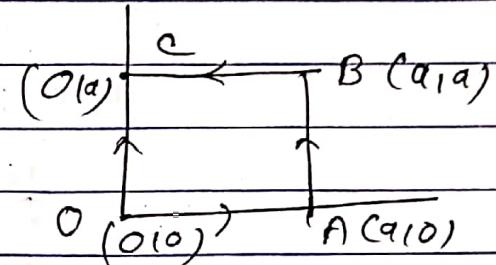
$$= \int_0^a \left[ \int_0^a y \, dy \right] dx$$

$$= \int_0^a \frac{a^2}{2} dx$$

$$\frac{a^3}{2}$$

Also,

$$\int_C \vec{F} \cdot d\vec{r} =$$



We denote the closed curve C by  $\partial ABC$

$$\int_C \vec{F} \cdot d\vec{r} = \int_{OA} \vec{F} \cdot d\vec{r} + \int_{AB} \vec{F} \cdot d\vec{r} + \int_{BC} \vec{F} \cdot d\vec{r} +$$

$$\int_{CO} \vec{F} \cdot d\vec{r} \quad \text{--- (1)}$$

Now,  $\int_{OA} \vec{F} \cdot d\vec{r} = \int_{OA} (x^2 \vec{i} + xy \vec{j}) \cdot (\vec{i} dx + \vec{j} dy)$

But eqn on  
 $y = 0$

$$= \int_0^a x^2 dx$$

$$= \frac{x^3}{3} \Big|_0^a$$

$$= \frac{a^3}{3}$$

$$\int_{AB} \vec{F} \cdot d\vec{r} = \int_{OA} (x^2 \vec{i} + xy \vec{j}) \cdot (\vec{i} dx + \vec{j} dy)$$

But eqn AB  
 $x = a$

$$= \int (a^2 \vec{i} + ay \vec{j}) \cdot (\vec{j} dy) = \int_0^a ay dy$$

$$= a \cdot \frac{y^2}{2} \Big|_0^a$$

$$= a \cdot \frac{a^2}{2} = \frac{a^3}{2}$$

$$\int_{BC} \vec{F} \cdot d\vec{r} = \int_{BC} (\alpha^2 \vec{i} + \alpha y \vec{j}) \cdot (\vec{i} dx + \vec{j} dy)$$

But at BC  $y = a$   
 $dy = 0$

$$= \int_B (\alpha^2 \vec{i} + \alpha y \vec{j}) \cdot (\vec{i} dx + \vec{j} dy)$$

$$= \int_a^0 \alpha^2 dx$$

$$= -\frac{\alpha^3}{3}$$

$$\int_{C_0} \vec{F} \cdot d\vec{r} = \int_{C_0} (\alpha^2 \vec{i} + \alpha y \vec{j}) \cdot (\vec{i} dx + \vec{j} dy)$$

But at  $C_0$   $y = 0$   
 $dy = 0$

$$\int (\alpha^2 \vec{i} + \alpha \vec{j}) \cdot (\vec{i} dx + \vec{j} dy)$$

$$= \int_0^0 \alpha^2 dx$$

$$= \frac{\alpha^3}{3} \Big|_0^0$$

$$= 0$$

put all value in ①

$$= \frac{a^3}{3} + \frac{a^3}{2} - \frac{a^3}{3} + 0$$

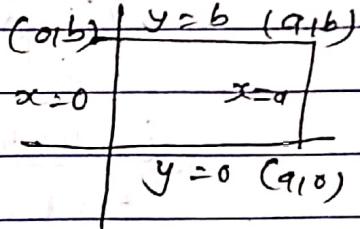
$$= \frac{a^3}{2}$$

② Verify Stokes theorem for

$$\textcircled{i} \quad \vec{F} = (x^2y + y^2)\vec{i} - xy\vec{j}$$

$$\textcircled{ii} \quad \vec{F} = (x^2 - y^2)\vec{i} + 2xy\vec{j}$$

taken around the rectangle  $R$  in the  $xy$  plane bounded by  $x=0$  &  $x=a$ ,  $y=0$ ,  $y=b$



Example Use Stokes theorem to prove

$$\int_C \vec{r} \cdot d\vec{r} = 0$$

~~for Soln~~  $\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$

$$d\vec{r} = dx\vec{i} + dy\vec{j} + dz\vec{k}$$

we have,

$$\int_C \vec{r} \cdot d\vec{r} = \iint_S (\operatorname{curl} \vec{r}) \cdot \vec{n} ds \quad \text{--- } \textcircled{*}$$

Replace  $\vec{r} = \vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$

Now,  $\operatorname{curl} \vec{r} =$

$$\begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix}$$

$$= \left( \frac{\partial z}{\partial y} - \frac{\partial y}{\partial z} \right) \vec{i} + \left( \frac{\partial x}{\partial z} - \frac{\partial z}{\partial x} \right) \vec{j} +$$

$$\left( \frac{\partial y}{\partial x} - \frac{\partial x}{\partial y} \right) \vec{k}$$

From (\*)

$$\int_C \vec{r} \cdot d\vec{l} = 0 \quad \text{Hence proved}$$

Divergence Theorem (Gauss's Theorem)

If  $\vec{F}$  be vector differentiable function then normal surface integral of  $\vec{F}$  over the closed surface  $S$  enclosing the volume  $V$  is equal to volume integral of divergence of  $\vec{F}$  over  $V$ .

$$\iint_S \vec{F} \cdot \vec{n} ds = \iiint_V \nabla \cdot \vec{F} dv$$

Evaluate  $\iint_S \vec{F} \cdot \vec{n} ds$  where  $S$  is the closed surface enclosing the volume  $V$ .

Soln :- Here we use Gauss's Theorem,

$$\iint_S \vec{F} \cdot \vec{n} ds = \iiint_V \nabla \cdot \vec{F} dv$$

replacing  $\vec{F}$  by  $\vec{r}$  where  $\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$

$$\begin{aligned} \text{Then, } \iint_S \vec{r} \cdot \vec{n} ds &= \iiint_V \nabla \cdot \vec{r} dv \\ &= \iiint_V \left( i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \cdot (x\vec{i} + y\vec{j} + z\vec{k}) dv \\ &= \iiint_V \left( \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} \right) dv \\ &= \iiint_V 3 dv \end{aligned}$$

$$= 3V$$

(\*) Prove that  $\iint_S \vec{r} \cdot \vec{n} ds = 6V$

Soln where  $V$  is the volume enclosed by the surface  $S$ .

$$\nabla r^2 = \vec{i} \frac{\partial r^2}{\partial x} + \vec{j} \frac{\partial r^2}{\partial y} + \vec{k} \frac{\partial r^2}{\partial z}$$

$$= 2r \vec{i} \frac{\partial r}{\partial x} + 2r \vec{j} \frac{\partial r}{\partial y} + 2r \vec{k} \frac{\partial r}{\partial z}$$

$$= 2r \vec{r}$$

Replacing  $\vec{F}$  by  $2\vec{r}$

$$\iint_S 2\vec{r} \cdot \vec{n} dS = \iiint_V \nabla r dV$$

$$= \iiint_V \left( \vec{i} \frac{\partial r}{\partial x} + \vec{j} \frac{\partial r}{\partial y} + \vec{k} \frac{\partial r}{\partial z} \right) (\vec{i} \frac{\partial r}{\partial x} + \vec{j} \frac{\partial r}{\partial y} + \vec{k} \frac{\partial r}{\partial z}) dV$$

$$= 2 \iiint_V \left( \frac{\partial^2 r}{\partial x^2} + \frac{\partial^2 r}{\partial y^2} + \frac{\partial^2 r}{\partial z^2} \right) dV$$

$$= 6V$$

- (Q) Evaluate the Surface Integral  $\iint_S \vec{F} \cdot \vec{n} dS$  where  
 $\vec{F} = (2x+3z)\vec{i} - (x_2+y)\vec{j} + (y^2+2z)\vec{k}$  and  $S$  be  
 the Surface of Sphere of  $(x-3)^2 + (y+1)^2 + (z-2)^2 = 9$   
Soln: Here  $\vec{F} = (2x+3z)\vec{i} - (x_2+y)\vec{j} + (y^2+2z)\vec{k}$   
 and given surface is  $(x-3)^2 + (y+1)^2 + (z-2)^2 = 9$ .  
 we have,

$$\iint_S \vec{F} \cdot \vec{n} dS = \iiint_V \nabla \cdot \vec{F} dV$$

$$= \iiint_V \left( \frac{\partial \vec{i}}{\partial x} + \frac{\partial \vec{j}}{\partial y} + \frac{\partial \vec{k}}{\partial z} \right) \cdot (2x+3z)\vec{i} - (x^2+y)\vec{j} + (y^2+2z)\vec{k} dV$$

$$= \iiint_V (2-1+2) dV$$

$$= 3 \iiint_V dV$$

$$= 3V = 3 \times \frac{4}{3}\pi r^3 = 3 \times \frac{4}{3}\pi (3)^3 = 108\pi$$

Q) If  $\vec{F} = 2x\vec{i} + 3y\vec{j} + 4z\vec{k}$  prove that Normal Surface of unit sphere.

Soln, Here  $\vec{F} = 2x\vec{i} + 3y\vec{j} + 4z\vec{k}$

$$\iiint_V \left( \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \right) \cdot (2x\vec{i} + 3y\vec{j} + 4z\vec{k}) dV$$

$$= \iiint_V \frac{\partial (2x)}{\partial x} + \frac{\partial (3y)}{\partial y} + \frac{\partial (4z)}{\partial z} dV$$

$$= \iiint_V (2 + 3 + 4) dV$$

$$= 9V = 9 \times \frac{4}{3} \pi r^3 = 9 \times \frac{4}{3} \pi (1)^3$$

(Q) with the help of Gauss divergence theorem show that

$$\iint_S (ax\vec{i} + by\vec{j} + cz\vec{k}) \cdot \vec{n} ds = \frac{4}{3} \pi (a+b+c)$$

where S is the surface of sphere  $x^2 + y^2 + z^2 = 1$

Soln Here  $\vec{F} = (ax\vec{i} + by\vec{j} + cz\vec{k})$

$$\iiint_V \left( \frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \cdot (ax\vec{i} + by\vec{j} + cz\vec{k}) dV$$

$$= \iiint_V \left( \frac{\partial ax}{\partial x} + \frac{\partial by}{\partial y} + \frac{\partial cz}{\partial z} \right) dV$$

$$= \iiint_V (a+b+c) dV$$

$$= (a+b+c)V$$

$$= (a+b+c) \frac{4}{3} \pi$$

Some extra problem

(1) For any closed surface S prove that,

$$(i) \iint_S \operatorname{curl} \vec{F} \cdot \vec{n} dS = 0$$

$$(ii) \iint_S \vec{n} \cdot d\vec{s} = 0$$

(iii) From ~~div~~ divergence theorem,

$$\iint_S \vec{F} \cdot \vec{n} dS = \iiint_V \nabla \cdot \vec{f} dv \rightarrow (iv)$$

$$\text{Here } \vec{F} = \operatorname{curl} \vec{f}$$

put in (iv)

$$\begin{aligned} \iint_S \vec{F} \cdot \vec{n} dS &= \iiint_V \nabla \cdot \operatorname{curl} \vec{f} dv \\ &= 0 \quad [\because \nabla \cdot \operatorname{curl} \vec{f} = 0] \end{aligned}$$

$$(v) \text{ Here } \vec{F} = \vec{L}$$

$$\iint_S \vec{n} \cdot d\vec{s} = \iiint_V \nabla \cdot \vec{L} dv$$

$$= \iiint_V 0 dv$$

$$= 0$$

(vi) If  $S$  be the closed surface of volume  $V$

$$\vec{F} = x\vec{i} + y\vec{j} + z\vec{k}$$

Show that  $\iint_S \vec{F} \cdot \vec{n} dS = 6V$ .

Parametric Surface

The eqn of sphere is written in parametric form,

$$\vec{r} = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k} \text{ where } a \leq t \leq b$$

e.g.  $\vec{r} = at^2\vec{i} + 2at\vec{j}$  is the parametric eqn of parabola as  $t \leq b$ .

Also, if  $\vec{r}$  is expressed as function of  $u, v$ . Then,

$$\vec{r} = f(u, v)\vec{i} + g(u, v)\vec{j} + h(u, v)\vec{k}$$

example find the Cartesian eqn of surface Jirey by the parametric representation.

$$\vec{r}(u, v) = u\vec{i} + u\cos v\vec{j} + u\sin v\vec{k}$$

Soln:- Here  $x = u, y = u\cos v, z = u\sin v$

Squaring and adding

$$y^2 + z^2 = u^2 \cos^2 v + u^2 \sin^2 v = u^2 = x^2$$

$\therefore x^2 = y^2 + z^2$  as required surface.

example find the parametric representation of

$$x = 5y^2 + 2z^2 - 10$$

Soln Here,  $x = 5y^2 + 2z^2 - 10, y = y, z = z$

$\therefore$  parametric representation,

$$\vec{r} = (5y^2 + 2z^2 - 10)\vec{i} + y\vec{j} + z\vec{k}$$

Some Application :-

We can find the equation of tangent plane to the surface  $\vec{r}(u, v) = f(u, v)\vec{i} + g(u, v)\vec{j} + h(u, v)\vec{k}$ .

At point  $(u_0, v_0)$

Step I find partial derivatives  $\vec{r}_u$  and  $\vec{r}_v$ , which gives tangent vector to the surface

Step II. Find normal vector to the surface  $\vec{h}$

$$\vec{h} = \vec{r}_u \times \vec{r}_v$$

Step III eqn of tangent plane at point  $(u_0, v_0, w_0)$   
 $(\vec{r} - \vec{q}) \cdot \vec{h} = 0$  where,  $\vec{q} = (u_0, v_0, w_0)$   
 $\vec{r} = (x_1, y_1, z_1)$ .

Example: Find the equation of tangent plane to the surface given by ~~given~~

(1)  $f(u, v) = u\vec{i} + 2v^2\vec{j} + (u^2 + v)\vec{k}$  at point  $(2, 1, 3)$ .

Now Differentiating partially w.r.t  $u$  and  $v$ .

$$f_u = \vec{i} + 0\vec{j} + 2\vec{k}$$

$$f_v = \vec{0} + 2u\vec{k}$$

$$f_v = 0\vec{i} + 4v\vec{j} + \vec{k}$$

$$= 4v\vec{j} + \vec{k}$$

These

Now the normal vector ~~is~~ represent the direction of tangent,

$$\vec{h} = \vec{f}_u + \vec{f}_v$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 2u \\ 0 & 4v & 1 \end{vmatrix}$$

$$= -8v^2\vec{i} + -\vec{j} + 4v\vec{k}$$

$$= -8v^2\vec{i} - \vec{j} + 4v\vec{k}$$

$$= -8uv\vec{i} - \vec{j} + 4v\vec{k}$$

But for point  $(2, 2, 3)$

$$2\vec{i} + 2\vec{j} + (4^2 + v)\vec{k} = 2\vec{i} + 2\vec{j} + 8\vec{k}$$

$$\Rightarrow u = 2$$

$$2v^2 = 2 \Rightarrow v = 0 \pm 1$$

$$u^2 + v = 3$$

Here  $v = 1$  does not satisfy remaining eqn  
So we take  $v = -1$ .

From (1)

$$-8 \cdot 2 \cdot -1 \vec{i} - \vec{j} + 4 \cdot -1 \vec{k}$$

$$16\vec{i} - \vec{j} - 4\vec{k}$$

$$\vec{n} = (\cancel{16}, 16, -1, -4)$$

$\therefore$  eqn of plane tangent plane through  $(2, 2, 3) = (x_1, y_1, z_1)$  with normal  $(16, -1, -4)$   
is,

$$a(x - x_1) + b(y - y_1) + c(z - z_1) = 0$$

$$\Rightarrow 16(x - 2) - 1(y - 2) - 4(z - 3) = 0$$

$$\Rightarrow 16x - 16 - y + 2 - 4z + 12 = 0$$

$$\Rightarrow 16x - y - 4z - 12 = 0$$

$$\Rightarrow 16x - y - 4z - 18 = 0$$

Ques find the equation of tangent plane to the surface with parametric eqn.

$$x = u^2, y = v^2, z = u + 2v$$

Soln) Here parametric curve is,

$$\begin{aligned} f(u, v) &= x\vec{i} + y\vec{j} + z\vec{k} \\ &= u^2\vec{i} + v^2\vec{j} + (u+2v)\vec{k} \end{aligned}$$

$$\vec{f}(u) = 2u\vec{i} + 0\vec{j} + \vec{k}$$

$$\vec{f}'_v = 0\vec{i} + 2v\vec{j} + 2\vec{k}$$

Now,

$$\vec{n} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 2u & 0 & 1 \\ 0 & 2v & 2 \end{vmatrix} = -2v\vec{i} - 4u\vec{j} + 4uv\vec{k}$$

$$u^2\vec{i} + v^2\vec{j} + (u+2v)\vec{k} = \vec{i} + \vec{j} + 3\vec{k}$$

$$u^2 = \pm 1$$

$$v^2 = \pm 1$$

$$u+2v = 3$$

$$u=1, v=1$$

$$\vec{n} = -2\vec{i} - 4\vec{j} + 4\vec{k}$$

Now eqn of plane

$$a(x-x_1) + b(y-y_1) + c(z-z_1) = 0$$

$$P) -2(x-1) - 4(y-1) + 4(z-3) = 0$$

$$\Leftrightarrow -2x + 2 - 4y + 4 + 4z - 12 = 0$$

$$\Rightarrow -2x - 4y + 4z - 6 = 0$$

$$\Rightarrow x + 2y + 2z + 3 = 0$$

## problem related to line integral

Evaluate the line integral  $\int_C \vec{F} \cdot d\vec{r}$  where

$$\vec{F} = (2x+y)\vec{i} + (3y-x)\vec{j}$$

&  $C$  is the curve in  $xy$  plane consisting the straight line from  $(0,0)$  to  $(2,0)$  and then to  $(3,2)$

Soln Here -

$$\vec{F} = (2x+y)\vec{i} + (3y-x)\vec{j}$$

$$\vec{r} = x\vec{i} + y\vec{j}$$

$$dr = \vec{i} dx + \vec{j} dy$$

$$\vec{F} \cdot dr = (2x+y)dx + (3y-x)dy$$

$$\text{line integral} = \int \vec{F} \cdot dr$$

$$= \int_{OA} \vec{F} \cdot dr + \int_{AB} \vec{F} \cdot dr \quad (2,0) \quad (3,2)$$

- (8)

for OA

$$x = 2$$

$$y = 0$$

for AB

$$y = 0 = \frac{2-0}{3-2}(x-2)$$

$$\therefore y = 2x-4$$

$$dy = 2dx$$

$$= \int_0^2 (2x+y)dx + (3y-x)dy + \int_2^3 (2x+y)dx + (3y-x)dy$$

$$\begin{aligned}
 &= \int_0^2 2x \, dx + \int_2^3 (2x + 2x - 4) \, dx + \left( \frac{8(2x-4)}{2} \right) \Big|_2^3 \\
 &= \int_0^2 2x \, dx + \int_2^3 (4x - 4) \, dx + (6x - 8) \Big|_2^3 \\
 &= \int_0^2 2x \, dx + \int_2^3 (4x - 4) \, dx + (12x - 24 - 2x) \Big|_2^3 \\
 &= \frac{2x^2}{2} \Big|_0^2 + \frac{4x^2 - 4x}{2} \Big|_2^3 + \frac{12x^2 - 24x - 2x^2}{2} \Big|_2^3 \\
 &= 12
 \end{aligned}$$

Evaluate  $\int_C \vec{F} \cdot d\vec{r}$

where  $\vec{F} = xy \vec{i} + (x^2 + y^2) \vec{j}$

$C$  is the  $x$ -axis from  $x=2$  to  $x=4$  and straight line  $x=4$  from  $y=0$  to  $y=12$

$C(4, 12)$

Soln Here,

$$\vec{F} = xy \vec{i} + (x^2 + y^2) \vec{j}$$

$$d\vec{r} = \vec{i} \, dx + \vec{j} \, dy$$

$$\vec{F} \cdot d\vec{r} = (xy \vec{i} + (x^2 + y^2) \vec{j}) \cdot (\vec{i} \, dx + \vec{j} \, dy)$$

$$= xy \, dx + (x^2 + y^2) \, dy$$

$$\text{One line integral} = \int_C \vec{F} \cdot d\vec{r}$$

$$= \int_{AB} \vec{F} \cdot d\vec{r} + \int_{BC} \vec{F} \cdot d\vec{r}$$

$$= \int_2^4 x \cdot 0 \, dx + (x^2 + y^2) \, dy + \int_{BC} \vec{F} \cdot d\vec{r}$$

$$\int_0^{1/2} xy \, dx + (x^2 + y^2) \, dy$$

where the equation of BC  $x=4$   
 $dx=0$

$$\int_0^{1/2} (16+y^2) \, dy$$

$$16y + \frac{y^3}{3} \Big|_0^{1/2}$$

$$16 \times \frac{1}{2} + \frac{12^3}{3}$$

A.10 Evaluate the line integral  $\int_C \vec{F} \cdot d\vec{r}$  where

- (a)  $\vec{F} = x^2 \vec{i} + -xy \vec{j}$  & C is the curve from  $(0,0)$  to  $(1,1)$  along parabola  $y^2 = x$ .

Hint:  $\int_C \vec{F} \cdot d\vec{r} = \int_{\text{on } C} \vec{F} \cdot d\vec{r}$

$$= \int_{y=0}^{y=1} \int_{x=0}^{x=y^2} x^2 \, dx - xy \, dy$$

$$= \int_{y=0}^{y=1} y^4 - y^4 \cancel{2y} \, dy = y^3 \cdot y \, dy$$

$$= \int_{y=0}^{y=1} 2y^5 \, dy - y^3 \, dy.$$

$$= \frac{2 \cdot y^6}{6} \Big|_0^1 - \frac{y^4}{4} \Big|_0^1$$

$$= \frac{2 \cdot 1}{6} - \frac{1}{4}$$

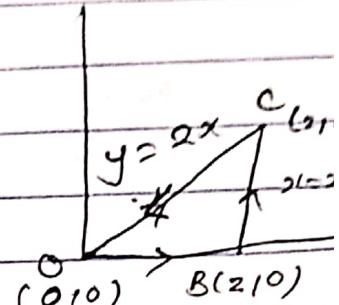
$$(b) \vec{F} = (2x^2 + y^2)\vec{i} + (3y - 4x)\vec{j}$$

\$ around the triangle ABC whose vertices are A(0|0|0) | B(2|0) & C(2|2)

Soh Here,

$$\vec{F} = (2x^2 + y^2)\vec{i} + (3y - 4x)\vec{j}$$

$$d\vec{r} = \vec{i} dx + \vec{j} dy$$



$$\begin{aligned}\vec{F} \cdot d\vec{r} &= (2x^2 + y^2)\vec{i} + (3y - 4x)\vec{j} \cdot (\vec{i} dx + \vec{j} dy) \\ &= (2x^2 + y^2)dx + (3y - 4x)dy\end{aligned}$$

Now, Line integral

$$= \int_C \vec{F} \cdot d\vec{r}$$

$$y = 2x$$

$$dy = 2dx$$

$$\begin{aligned}&= \int_{OB} (2x^2 + y^2)dx + \int_{BC} (2x^2 + y^2)dx + (3y - 4x) \\ &\quad + \int_{CO} (2x^2 + y^2)dx + (3y - 4x) dy\end{aligned}$$

$$= \int_0^2 2x^2 dx + \int_0^1 (3y - 8) dy +$$

$$\int_2^0 (2x^2 + 4x^2) dx + (3 \cdot 2x - 8) 2 dx$$

$$\begin{aligned}&= \frac{2x^3}{3} \Big|_0^2 + \frac{3y^2}{2} \Big|_0^1 + \frac{2x^3}{3} \Big|_0^2 + \frac{4x^3}{3} \Big|_0^0 \\ &\quad + \frac{6x^2}{2} \Big|_0^2 - 16x \Big|_0^2\end{aligned}$$