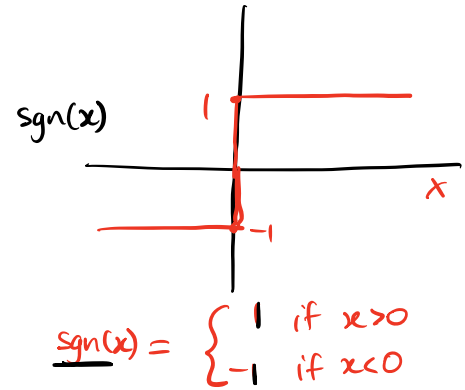
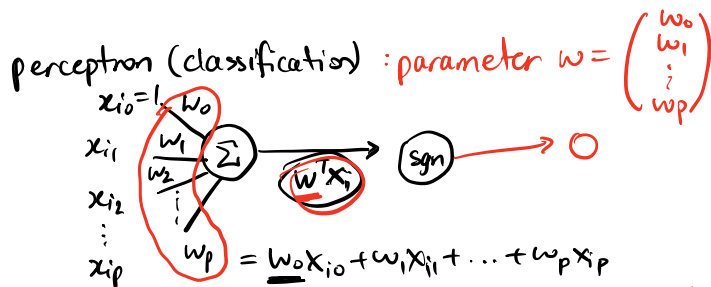
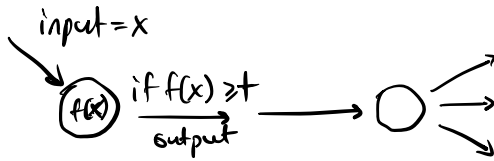
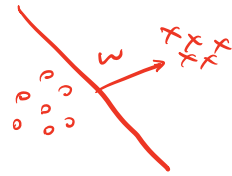


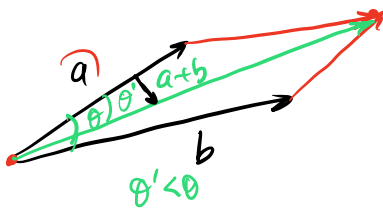
# Neural Learning

- Neural Networks  $\rightarrow$  Deep Learning (Multi-Layer Perceptron)
- Perceptron (Building block of NNs) (linear classifier)

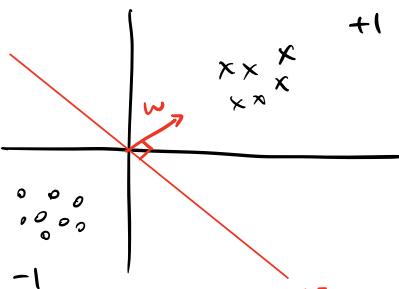


$$D = \{(x_i, y_i)\} \quad y_i \in \{-1, 1\}$$

## vector addition

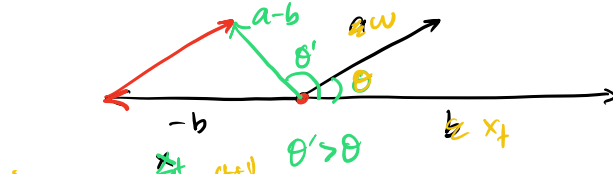


$$a + b$$



$$\tilde{w} = \begin{pmatrix} w_0 \\ w_1 \\ \vdots \\ w_p \end{pmatrix} \quad \tilde{x} = \begin{pmatrix} 1 \\ x_1 \\ x_2 \\ \vdots \\ x_p \end{pmatrix} \quad \tilde{w}^T \tilde{x} = 0$$

## vector subtraction



$$a - b = a + (-b)$$

$$w^T x = w \cdot x = \langle w, x \rangle$$

## Perceptron:

- Init  $w$  randomly ( $w^{(0)} = (0, 0, \dots, 0)$ )

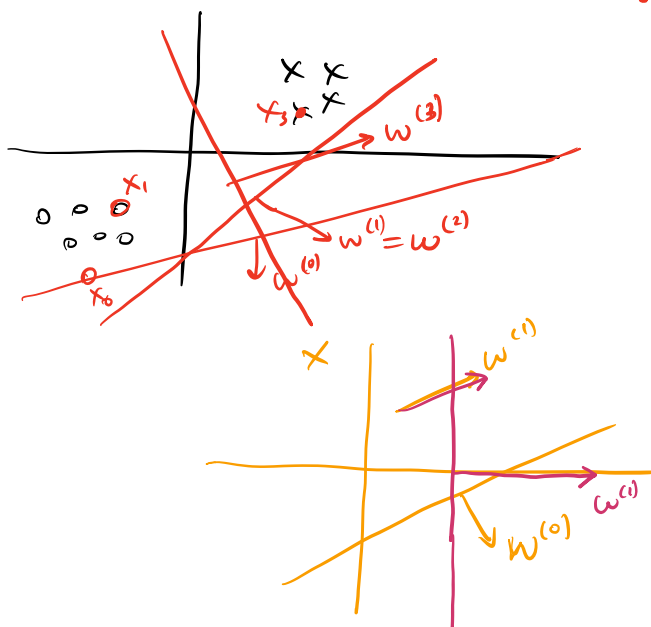
- For  $i = 1, \dots, T$ :

$w^{(t)} x_t y_t \geq 0$  pick data point  $(x_t, y_t)$

- if  $w^{(t)} \cdot x_t \geq 0$  and  $y_t = 1$ : do nothing
- if  $w^{(t)} \cdot x_t < 0$  and  $y_t = -1$ : do nothing
- if  $w^{(t)} \cdot x_t \geq 0$  and  $y_t = -1$ :  $w^{(t+1)} = w^{(t)} - x_t y_t$
- if  $w^{(t)} \cdot x_t < 0$  and  $y_t = 1$ :  $w^{(t+1)} = w^{(t)} + x_t y_t$

## Mistakes:

- if  $w^T x_i > 0$  and  $y_i = -1$  For  $t = 1, \dots, T$ : receive  $(x_t, y_t)$



• if  $w^T x_i < 0$  and  $y_i = +1$

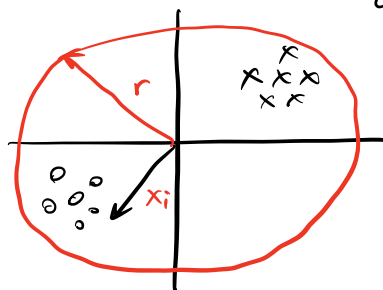
if  $y_i w^{(t)} \cdot x_i < 0$ :  
 $w^{(t+1)} = w^{(t)} + y_i x_i$   
 $y_i \in \{-1, 1\}$

if  $y_i + w^{(t)} \cdot x_i < 0$ : update "eta"  
 $w^{(t+1)} = w^{(t)} + y_i x_i \eta$  ← learning rate

## Perceptron Mistake Band

Theorem: Assume:  $\|x_i\|_2 \leq R$  (inputs are finite)

Assume: there exists  $w^*$  with  $\|w^*\|_2 = 1$  and  $y_i w^* \cdot x_i \geq r$  for all  $i$  data points. margin

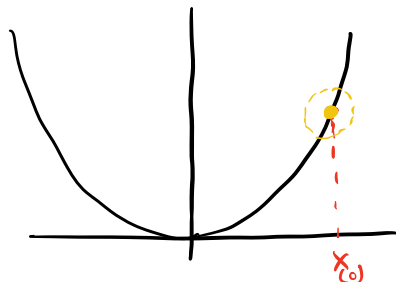


## Gradient Descent (numerical technique)

•  $\min_x f(x)$

Least squares Reg:  $\min_w L(w)$

Ex:  $f(x) = x^2 \rightarrow f'(x) = 0$



$2x = 0$   
 $x = 0$

minimiser has a closed form solution

- Start with init value  $x_{(0)}$
- direction of steepest descent  $-f'(x_{(0)}) \approx 1.8 - 0.7 = 1.1$
- $x_{(t)} = \underbrace{x_{(t-1)}}_{\text{current pos}} - \underbrace{\alpha f'(x_{(t-1)})}_{\text{step}}$

$f(x) = x^2$   
 $f'(x) = 2x$

$\alpha = 0.2$

$x_{(0)} = 3$   
 $x_{(1)} = x_{(0)} - 0.2 \cdot 2 \cdot x_{(0)}$   
 $= 3 - 0.4 \cdot 3 = 1.8$   
 $x_{(2)} = 1.8 - 0.2 \cdot 2 \cdot 1.8$   
 $= 1.1$

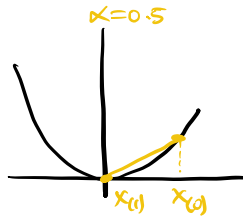
$f(x)$   
 $f(1.8) = (1.8)^2 = 3.24$   
 $f(1.1) = (1.1)^2 = 1.21$

$x_{(3)} = \dots$

step-size

$$x_{(0)} = 3 \quad \alpha = 0.5$$

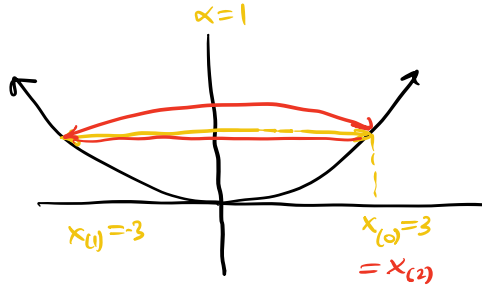
$$x_{(1)} = 3 - 0.5 \times 2 \times 3 = 0$$



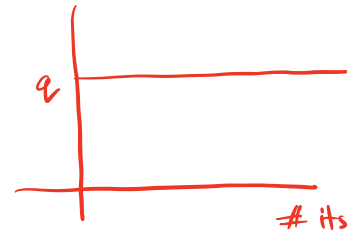
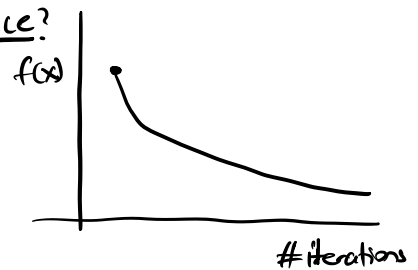
$$\alpha = 1$$

$$x_{(1)} = 3 - 1 \times 2 \times 3 = -3$$

$$x_{(2)} = -3 - (1 \times 2 \times (-3)) = -3 + 6 = 3$$



Convergence?



Least Squares (simple):

$$\mathcal{L}(w_0, w_1) = \frac{1}{n} \sum_{i=1}^n (y_i - (w_0 + w_1 x_i))^2$$

$$\frac{\partial \mathcal{L}}{\partial w_0} = -\frac{2}{n} \sum_{i=1}^n (y_i - w_0 - w_1 x_i)$$

$$\frac{\partial \mathcal{L}}{\partial w_1} = -\frac{2}{n} \sum_{i=1}^n x_i (y_i - w_0 - w_1 x_i)$$

closed form sol:

$$\begin{aligned} w_0 &= \bar{y} - w_1 \bar{x} \\ w_1 &= \frac{\bar{xy} - \bar{x}\bar{y}}{\bar{x}^2 - \bar{x}^2} \end{aligned}$$

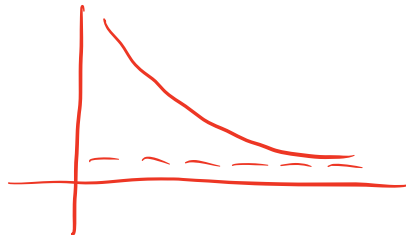
Gradient Descent

$$\text{init } w_0^{(0)}, w_1^{(0)}$$

$$w_0^{(t)} = w_0^{(t-1)} + \frac{2\alpha}{n} \sum_{i=1}^n (y_i - w_0^{(t-1)} - w_1^{(t-1)} x_i)$$

$$w_1^{(t)} = w_1^{(t-1)} + \frac{2\alpha}{n} \sum_{i=1}^n x_i (y_i - w_0^{(t-1)} - w_1^{(t-1)} x_i)$$

$$\text{print}(\mathcal{L}(w_0^{(t)}, w_1^{(t)}))$$



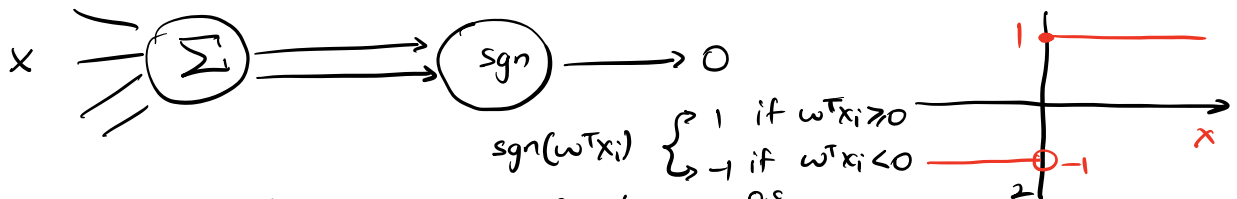
Least Squares

$$\mathcal{L}(\beta) = \|y - X\beta\|_2^2 \quad \beta \in \mathbb{R}^{p+1}$$

$$\nabla_{\beta} \mathcal{L}(\beta) = -2X^T(y - X\beta) \rightarrow \beta_{LS}^T = (X^T X)^{-1} X^T y$$

$$\beta^{(0)} = \text{init}$$

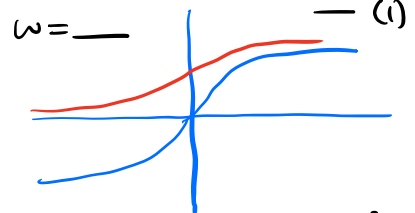
$$\beta^{(t)} = \beta^{(t-1)} + \alpha 2X^T(y - X\beta^{(t-1)})$$



$$\mathcal{L}(w) = \frac{1}{n} \sum_{i=1}^n (y_i - \underline{g}_i)^2 = \frac{1}{n} \sum_{i=1}^n (y_i - \text{sgn}(\underline{w^T x_i}))^2$$

use different "sigmoidal" - function

logistic sigmoid:  $\sigma(x) = \frac{1}{1 + e^{-ax}}$



$$\frac{d\sigma(x)}{dx} = \sigma(x)(1 - \sigma(x))$$

$$\mathcal{L}(w) = \frac{1}{n} \sum_{i=1}^n (y_i - \sigma(w^T x_i))^2$$

$y_i \in \{0, 1\}$

Grad- Desc

- init  $w^{(0)}$
- repeat:  $w^{(t)} = w^{(t-1)} - \alpha \nabla \mathcal{L}(w^{(t-1)})$
- stop when change in  $\nabla(w^{(t)})$  is negligible

$$\mathcal{L}(w) = \frac{1}{2} \sum_{i=1}^n (y_i - \sigma(w^T x_i))^2$$

$$\nabla_w \mathcal{L}(w) = \frac{1}{2} \sum_{i=1}^n \nabla_w (y_i - \sigma(w^T x_i))^2$$

$$= \sum_{i=1}^n \nabla_w (y_i - \sigma(w^T x_i)) [y_i - \sigma(w^T x_i)]$$

$$= - \sum_{i=1}^n x_i \sigma(w^T x_i) (1 - \sigma(w^T x_i)) (y_i - \sigma(w^T x_i))$$

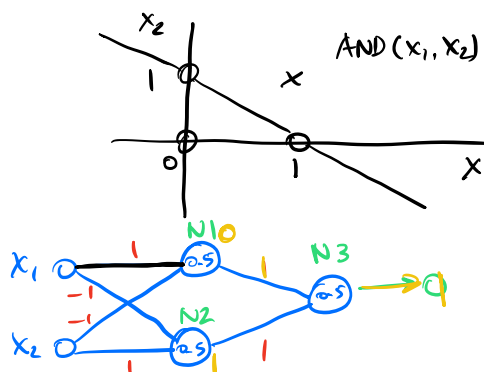
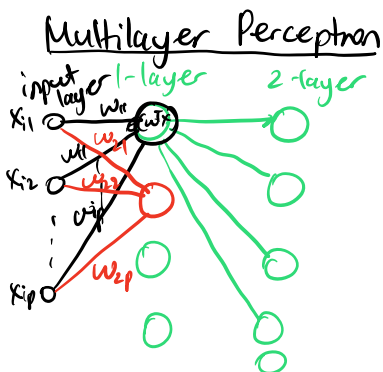
$$\nabla_w (y_i - \sigma(w^T x_i))$$

$$= - \nabla_w \sigma(w^T x_i)$$

$$= - \nabla_w (w^T x_i) \cdot \sigma(w^T x_i)$$

$$= - x_i \sigma(w^T x_i) (1 - \sigma(w^T x_i))$$

$$\text{update: } w^{(t)} = w^{(t-1)} + \alpha \sum_{i=1}^n x_i \sigma(w^{(t-1)} \cdot x_i) (1 - \sigma(w^{(t-1)} \cdot x_i)) (y_i - \sigma(w^{(t-1)} \cdot x_i))$$



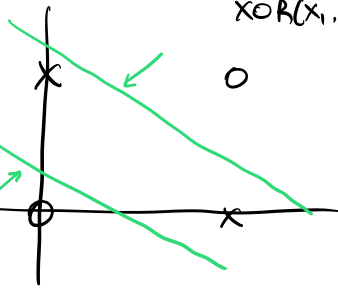
$x_1$	$x_2$	$\text{AND}(x_1, x_2)$
0	0	0
0	1	0
1	0	0
1	1	1

$$x_1=0, x_2=0 \mid x_1=1, x_2=1$$

$$N1: 0 \times 1 + 0 \times (-1) = 0 < 0.5$$

$$N2: 0 \times (-1) + 0 \times 1 = 0 < 0.5$$

$$N3: 0 \times 1 + 0 \times 1 = 0 < 0.5$$



XOR( $x_1, x_2$ )

0

$x_1$	$x_2$	XOR( $x_1, x_2$ )
0	0	0
0	1	1
1	0	1
1	1	0

$$x_1=0, x_2=1$$

$$N1: 0 \times 1 + 1 \times (-1) = -1 < 0.5$$

$$N2: 0 \times (-1) + 1 \times 1 = 1 > 0.5$$

$$N3: 0 \times 1 + 1 \times 1 = 1 > 0.5$$