

COMP9417 - Week 7 Tutorial notes

Kernel Methods

Primal and Dual Algorithms

- The dual view of a problem is simply just another way to view a problem mathematically
- Instead of pure parameter based learning (i.e. minimising a loss function, etc), dual algorithms introduce instance-based learning

In the primal problem, we typically learn parameters:

$$w \in \mathbb{R}^n$$

meaning we learn parameters for each of the p features in our dataset

In the dual problem, we typically learn parameters:

$$\alpha \quad \text{for } i \in [1, n]$$

meaning we learn parameters for each of the n data-points

α_i represents the importance of a data point (x_i, y_i)

The Dual/Kernel Perceptron

Recall the primal perceptron:

converged $\leftarrow 0$

while not converged do

 converged $\leftarrow 1$

 for $x_i \in X, y_i \in Y$ do

If we define the number of iterations the perceptron makes as $k \in \mathbb{N}^+$ and assume $n=1$, we can derive an expression for the final weight vector $w^{(k)}$:

```

if  $y_i w \cdot x_i \leq 0$  then
     $w \leftarrow w + \eta y_i x_i$ 
    converged  $\leftarrow 0$ 
endif
endfor
end while

```

$$w^{(k)} = \sum_{i=1}^N \sum_{j=1}^k 1_{\{y_i w^{(j)} \cdot x_i \leq 0\}} x_i$$

we can simplify our expression and take out the indicator variable:

$$\begin{aligned} w^{(k)} &= \sum_{i=1}^N \sum_{j=1}^k 1_{\{y_i w^{(j)} \cdot x_i \leq 0\}} y_i x_i \\ &= \sum_{i=1}^N \alpha_i y_i x_i \end{aligned}$$

where α_i is the number of times the perceptron makes a mistake on a data point (x_i, y_i) .

If we sub in $w^{(k)} = \sum_{i=1}^N \alpha_i y_i x_i$. we get the algorithm for the dual perceptron.

```

converged  $\leftarrow 0$ 
while not converged do
    converged  $\leftarrow 1$ 
    for  $x_i \in X, y_i \in Y$  do
        if  $y_i \sum_{j=1}^N \alpha_j y_j x_j \cdot x_i \leq 0$  then
             $\alpha_i \leftarrow \alpha_i + 1$ 
            converged  $\leftarrow 0$ 
        endif
    endfor
end while

```

Gram Matrix

 $- G = X^T X$

$$G = \begin{bmatrix} \langle x_1, x_1 \rangle & \langle x_1, x_2 \rangle & \dots & \langle x_1, x_n \rangle \\ \langle x_2, x_1 \rangle & \langle x_2, x_2 \rangle & \dots & \langle x_2, x_n \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle x_n, x_1 \rangle & \langle x_n, x_2 \rangle & \dots & \langle x_n, x_n \rangle \end{bmatrix}$$

$$G_{i,j} = \langle x_i, x_j \rangle$$

Transformations

How do we go about solving non-linearly separable datasets with linear classifiers?

Project them to higher dimensional spaces through a transformation $\phi: \mathbb{R}^p \rightarrow \mathbb{R}^k$