

include/enpm808x_final
_inspection_robot/CanCharacterizer.hpp

```
graph BT; A[src/CanCharacterizer.cpp] --> B[include/enpm808x_final_inspection_robot/CanCharacterizer.hpp]; C[src/CanCharacterizerNode.cpp] --> B;
```

The diagram illustrates the relationship between two source files and a header file. At the top, a gray box contains the header file path: `include/enpm808x_final_inspection_robot/CanCharacterizer.hpp`. Below this, two white boxes represent source files: `src/CanCharacterizer.cpp` on the left and `src/CanCharacterizerNode.cpp` on the right. Blue arrows point from each source file box up to the header file box, indicating that both source files include the header file.

src/CanCharacterizer.cpp

src/CanCharacterizerNode.cpp