

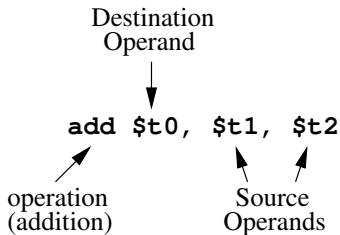
# MIPS Assembly Language

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(draft)

# MIPS Operands and Operations

- A MIPS instruction consists of an **operation** and zero or more **operand**
- **Operation** specifies the function of the instruction
- **Operand** specifies data to use with the instruction
- Example:



# MIPS Operations

- **Arithmetic Operations:** addition, subtraction, ...
- **Logical Operations:** AND, OR, ...
- **Shift:** Moves bits left or right
- **Compare:** equal, less than, etc
- **Load/Store:** load data from memory or store data to memory
- **Branch/Jump:** make decisions or go to a certain instruction
- **System control**

# MIPS Operands

- Registers (32-bit general-purpose register): ( $\$t0$ ,  $\$v0$ , ...)
- Fixed registers: Hi and Lo registers
- Memory location (Base Address + Offset)
  - Base Address: from a register
  - Offset: a constant value
- Immediate Value (constant)

# MIPS Registers

- In MIPS, there are 32 general-purpose registers (32-bit word each)

Name	Number	Use	Name	Number	Use
\$zero	0	The Constant Value 0	\$s0	16	Saved Temporary
\$at	1	Assembler Temporary	\$s1	17	Saved Temporary
\$v0	2	Return Value	\$s2	18	Saved Temporary
\$v1	3	Return Value	\$s3	19	Saved Temporary
\$a0	4	Argument	\$s4	20	Saved Temporary
\$a1	5	Argument	\$s5	21	Saved Temporary
\$a2	6	Argument	\$s6	22	Saved Temporary
\$a3	7	Argument	\$s7	23	Saved Temporary
\$t0	8	Temporary	\$t8	24	Temporary
\$t1	9	Temporary	\$t9	25	Temporary
\$t2	10	Temporary	\$k0	26	Reserved for OS Kernel
\$t3	11	Temporary	\$k1	27	Reserved for OS Kernel
\$t4	12	Temporary	\$gp	28	Global Pointer
\$t5	13	Temporary	\$sp	29	Stack Pointer
\$t6	14	Temporary	\$fp	30	Frame Pointer
\$t7	15	Temporary	\$ra	31	Return Address

- Hi and Lo are used to store result from multiplication operation
  - Multiply two 32-bit number results in a 64-bit number
- \$pc or program counter
  - Store the memory address of the current or next instruction
  - Cannot directly manipulate by programmer

# General-Purpose Registers

- Can be use to store values or as operands in instructions
- Need to follow conventions:
  - \$zero or \$0: always 0 and cannot be used to store any other value
  - \$v0 and \$v1: are used for storing return values
  - \$a0 to \$a3: are used for storing arguments/parameters for functions
  - \$t0 to \$t9: can be used freely without any restrictions
  - \$s0 to \$s7: values in these registers should be stored somewhere (generally stack) before we can use them and restore them back after we finish using them
  - \$at, \$k0 and \$k1 are reserved for assembler and OS kernel.  
**Do not use them.**
  - \$gp, \$sp, and \$fp will be explained later. **Do not use them yet.**
  - \$ra is used for storing return address before calling a function

# Instruction Encoding

- Computers only understand binary numbers
- Instructions are encoded in binary number
- Assembler translates an assembly program into a series of binary numbers
- All MIPS instructions are 32-bit wide
- Processor fetch an instruction (32-bit binary number) and decode it to see what it needs to do
- Encoding from assembly program to machine code is simple (done by software)
- Decoding from machine code in hardware is hard
- We need formats of 32-bit instructions which will help processors decode them

# R-Type

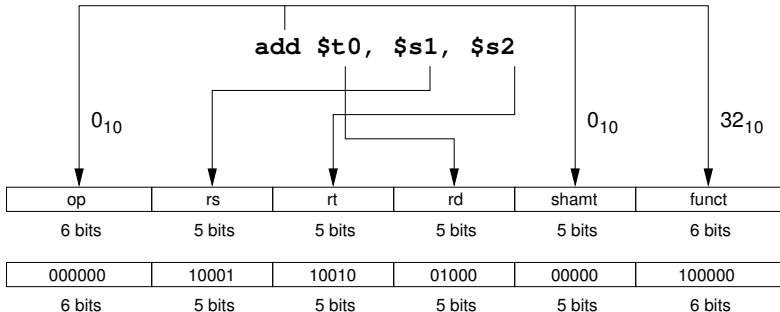
op	rs	rt	rd	shamt	funct
6 bits	5 bits	5 bits	5 bits	5 bits	6 bits

- **op**: Operation (opcode)
- **rs**: First register source operand
- **rt**: Second register source operand
- **rd**: Destination register operand
- **shamt**: Shift amount
- **funct**: Function code
- For R-type, all operands must be registers



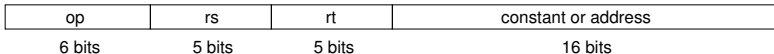
# Example (add)

- For the instruction add:
  - op**: must be 0 ( $000000_2$ )
  - shamt**: must be 0 ( $00000_2$ )
  - funct**: must be  $32_{10}$  ( $100000_2$ )

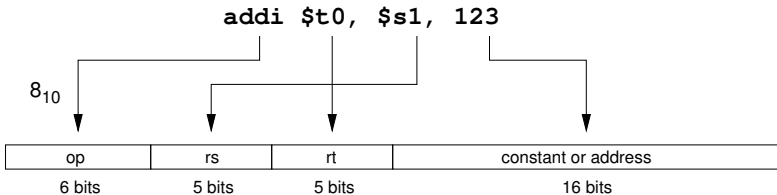


- Note:** \$t0 is 8 ( $01000_2$ ), \$s1 is 17 ( $10001_2$ ), and \$s2 is 18 ( $10010_2$ ).

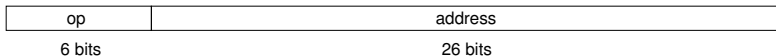
# I-type (Immediate)



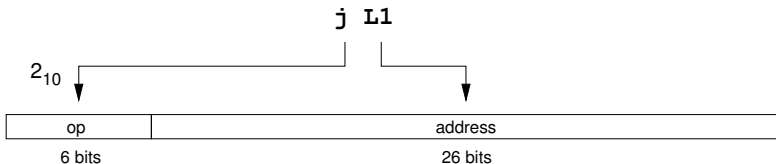
- **op**: Operation (opcode)
- **rs**: First register source operand
- **rt**: Second register source operand **OR** destination register operand
- **Constant or Address**: (Immediate field) constant operand
- For example: `addi`, **op** field must be  $8_{10}$  ( $01000_2$ )



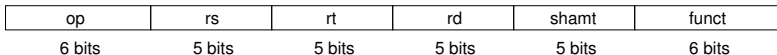
# J-type (Jump)



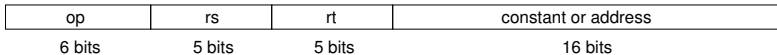
- **op**: Operation (opcode)
- **address**: the 26-bit **word** address to jump to
- For example, jump instruction (j), the **op** must be  $2_{10}$  ( $000010_2$ )



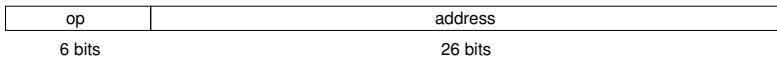
- R-type:



- I-type:



- J-type:



# Arithmetic Instructions

- Format:

`<op> <Destination>, <First Source>, <Second Source>`

- All operands must be registers
- MIPS field: R-type
- Examples:

```
add $t0, $t1, $t2    # $t0 = $t1 + $t2
sub $a0, $v0, $s3    # $a0 = $v0 - $s3
```

# Logical Instructions

- Big-wise logic operations
- Format:

```
<op> <Destination>, <First Source>, <Second Source>
```

- MIPS Field: R-type
- Examples:

```
and $t0, $t1, $t2    # $t0 = $t1 & $t2
or  $s3, $s4, $t1    # $s3 = $s4 | $t1
nor $s4, $t3, $t4    # $s4 = ~($t3 | $t4)
nor $s6, $v0, $0     # $s6 = ~($v0 | 0) = ~$v0
xor $a2, $t3, $s4    # $a2 = $t3 xor $s4
```

# Arithmetic and Logical Instructions with Immediate

- Some operations require a constant
  - $x = y + 2$ ;
  - $y = y - 1$ ;
  - $z = x \& 0x1a2b$
- **Note:** 0x1a2b represents 4-digit hexadecimal number (16-bit binary)
- Format:

`<op> <Destination>, <First Source>, <Constant>`

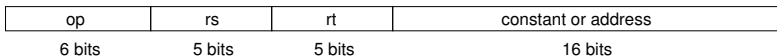
- MIPS Field: I-type
- Examples:

<code>addi \$t1, \$s1, 35</code>	<code># \$t1 = \$s1 + 35</code>
<code>andi \$t5, \$t6, 0x34ab</code>	<code># \$t5 =</code>
	<code># \$t6 &amp; 0011010010101011b</code>
<code>ori \$t2, \$v0, 0x0f0f</code>	<code># \$t2 =</code>
	<code># \$v0   0000111100001111b</code>

- **Note:** 0000111100001111b represents 16-bit binary number

# Long Immediate Values

- Note that the arithmetic and logical instruction with immediate field have I-type
- The size of constant field is only 16 bit



- If an instruction requires 32-bit constant:
  - load upper half of the constant into a register
  - or the lower half with that register



# Long Immediate Values

- For example, suppose we need to use the following 32-bit constant:

0000 1111 0000 1111 0101 0101 0101 0101

we need to perform the following:

```
lui $t0, 0000111100001111b
```

Now the content of the register \$t0 is

0000 1111 0000 1111 0000 0000 0000 0000

then

```
ori $t0, $t0, 0101010101010101b
```

Now the content of the register \$t0 is

0000 1111 0000 1111 0101 0101 0101 0101

# Pseudo-Ops

- Pseudo-ops are instructions that are not implemented in hardware (processor do not understand)
- The purpose of pseudo-ops is to help programmer just like high-level language
- A pseudo-op will be translated to a series of instruction that processor understand
- For example: `li` (load immediate 16/32 bit)

```
li $t0, 0x00012345
```

may be translated to

```
lui $at, 0x0001  
ori $t0, $at, 0x2345
```

# Pseudo-Ops

- For example: move move the value in one register to another

```
move $t1, $t2    # $t1 = $t2
```

may be translated to

```
addu $t1, $t2, $0
```

- For example: la (load address)

```
la  $a0, L1
```

may be translated to

```
lui $at, <upper half of L1>  
ori $a0, $at, <lower half of L1>
```

# Interacting with the OS

- Often times, we need help from the OS
  - display numbers on screen
  - read keyboard input
  - terminate the program
  - open/close/read/write files
- These are called operating system services
- It is a special instruction called `syscall`
  - It is a software interrupt to notify OS to perform actions
  - Need to indicate the service type
  - May need to pass argument value for a certain service

# Some Useful syscall

- To use syscall, we need to perform the following:
  - ① Provide arguments (in specific registers) if required
  - ② Set the service type ID in the register \$v0
  - ③ Call syscall
- Useful syscall:
  - **Print integer:** Store integer to print in \$a0 and set \$v0 to 1
  - **Read integer:** Set \$v0 to 5, after syscall, \$v0 holds the integer read from keyboard
  - **Print string:** Store the memory address of the string print (terminated by null) and set \$v0 to 4
  - **Exit (halt):** Set \$v0 to 10
- See MARS documents for more information about syscall

# Example: Print an Integer

- Consider the following Java code

```
int x = 5;  
int y = 9;  
  
y = x + y;  
  
System.out.println(y);
```

- When we want to show an integer number on the console screen, we need help from the OS

# Example: Print an Integer

- The code from previous slide can be translated to assembly code as shown below:

```
.text
    add  $t0, $zero, 5      # $t0 = 5
    addi $t0, $t0, 9       # $t0 = $t0 + 9
    add  $v0, $zero, 1     # Syscall 1: print integer
    add  $a0, $t0, $zero   # $a0 = $t0: integer to be printed
    syscall                # Print integer
    add  $v0, $zero, 10    # Syscall 10: terminate program
    syscall                # Terminate program
```

- Note that `.text` defines the text segment of a program (the segment where instructions are stored in the main memory)

# Example: Print a String

- Consider the following Java code:

```
System.out.println("Hello World!");
```

- The above code can be translated to assembly code as shown below:

```
.data
    msg: .asciiz "Hello World!"
.text
    addi $v0, $zero, 4    # Syscall 4: print string
    la    $a0, msg        # Set $a0 to memory address of msg
    syscall               # Print the string msg
    addi $v0, $zero, 10   # Syscall 10: terminate program
    syscall               # Terminate program
```

- Note that `.data` defines the data segment of a program (the segment where data are stored in the main memory)
- Note that `.asciiz` create an array of characters that is terminated by the null character



# Example: Keyboard Input

- Consider the following Java code:

```
Scanner s = new Scanner(System.in);  
  
System.out.print("Please enter an integer number: ");  
int x = s.nextInt();  
System.out.println("Thanks for entering " + x + ".");
```

- We need help from OS to display messages
- We need help from OS to get an input from the keyboard

# Example: Keyboard Input

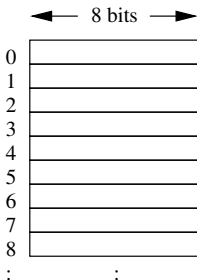
```
.data
    prompt1: .asciiz "Please enter an integer number: "
    msg:      .asciiz "Thanks for entering "
    period:   .asciiz "."
.text
    addi $v0, $zero, 4    # Syscall 4: print string
    la    $a0, prompt1    # Set $a0 to memory address of prompt1
    syscall               # Print the string prompt1
    addi $v0, $zero, 5    # Syscall 5: read integer
    syscall               # Read integer and store it in $v0
    add   $t0, $zero, $v0 # Store the input integer in $t0
    la    $a0, msg         # Set $a0 to memory address of msg
    addi $v0, $zero, 4    # Syscall 4: print string
    syscall               # Print the string msg
    addi $v0, $zero, 1    # Syscall 1: print integer
    add   $a0, $zero, $t0 # Set integer to be printed
    syscall               # Print integer
    addi $v0, $zero, 4    # Syscall 4: print string
    la    $a0, period      # Set $a0 to memory address of period
    syscall               # Print the string period
    addi $v0, $zero, 10   # Syscall 10: terminate program
    syscall               # Terminate program
```

# Memory Transfer Instructions

- **Load** Read data from memory
- **Store** data into memory
- The following are memory transfer instructions in MIPS (32-bit architecture):
  - **Word** (32 bits) or `int` in Java
    - `lw`: load word
    - `sw`: store word
  - **Half-word** (16 bits) or `short` in Java
    - `lh`: load half word
    - `sh`: store half word
    - `lhu`: load half word unsigned
  - **Byte** (8 bits) or `byte` in Java
    - `lb`: load byte
    - `sb`: store byte
    - `lbu`: load byte unsigned

# Memory View

- Memory is a large one-dimensional 8-bit array



- A memory location can be accessed using index the same as in array
- Notation: `Memory[4]` means the memory location referred by index 4 (the fifth byte)

# Effective Address Calculation

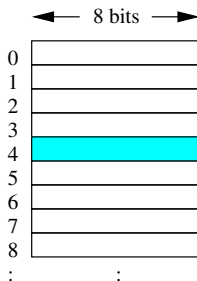
- In MIPS, the effective memory address specified as

`< immediate value > (< $register >)`

- `$register` stores a base address
  - `immediate value` is use to determine the offset from the base address
  - The `immediate value` is a 16-bit value that can be either positive or negative value
  - The actual location is `immediate value` plus the value stored in the `$register`
- Example:

```
addi $t0, $zero, 32    # Set $t0 to 32
lw    $s0, 12($t0)      # the address is 32 + 12 = 44
sw    $s1, -24($t0)     # the address is 32 - 24 = 8
```

# Accessing a Byte



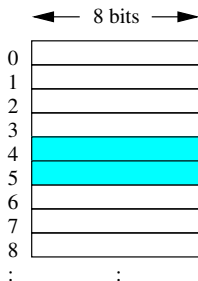
- The highlighted byte (location 4) can be loaded or stored using the following instructions:

```
addi $t0, $zero, 4  
lw    $s0, 0($t0)  
sw    $s1, 0($t0)
```

or

```
add  $t0, $zero, $zero  
lw   $s0, 4($t0)  
sw   $s1, 4($t0)
```

# Accessing a Half-word



- The highlighted half-word (starting at location 4) can be loaded or stored using the following instructions:

```
addi $t0, $zero, 4
lh    $s0, 0($t0)
sh    $s1, 0($t0)
```

or

```
add  $t0, $zero, $zero
lh   $s0, 4($t0)
sh   $s1, 4($t0)
```

# Accessing a Word



- The highlighted word (starting at location 4) can be loaded or stored using the following instructions:

```
addi $t0, $zero, 4
lw    $s0, 0($t0)
sw    $s1, 0($t0)
```

or

```
add  $t0, $zero, $zero
lw   $s0, 4($t0)
sw   $s1, 4($t0)
```



# Load Address

- Recall that values stored in variables are actually stored in memory locations
- For example:

```
int x = 5;
```

- a memory location is assigned to the variable named `x`
  - the value 5 is stored in that memory location
- For example:

```
char[] str = "Hello World!";
```

- a memory location is assigned to the variable named `str`
- The character `H` is stored in that memory location
- The character `e` is stored in the next memory location

# Load Address in Assembler

- To create variables in assembler

```
.data
num:  .word  973
str:  .asciiz "Hello"
```

Names                  Types                  Values

- To access variables, we need to load their address (la) into registers first

```
la $t0, num
la $t1, str
```

- Then use load or store instruction to access them

```
lw $s0, 0($t0)
lb $s1, 0($t1)
```

- Note that la is a pseudo-op which is translated into the following sequence of instructions:

```
lui $at, <upper half of the address>
ori $t0, $at, <lower half of the address>
```

# Exercise

- Create a word (integer) variables named x with initial value 0, and y with initial value 5

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- Create a word (integer) variables named x with initial value 0, and y with initial value 5

```
.data
    x: .word
    y: .word 5
```

- Print the value of y on the console

# Exercise

- Create a word (integer) variables named x with initial value 0, and y with initial value 5

```
.data
    x: .word
    y: .word 5
```

- Print the value of y on the console

```
.text
    la    $s0, y           # Load address of y
    lw    $a0, 0($s0)      # Load data stored in y
    addi  $v0, $zero, 1    # Service 1: print integer
    syscall                # Print integer
```

- Terminate the program

# Exercise

- Create a word (integer) variables named x with initial value 0, and y with initial value 5

```
.data
    x: .word
    y: .word 5
```

- Print the value of y on the console

```
.text
    la    $s0, y           # Load address of y
    lw    $a0, 0($s0)      # Load data stored in y
    addi  $v0, $zero, 1    # Service 1: print integer
    syscall                # Print integer
```

- Terminate the program

```
    addi  $v0, $zero, 10   # Service 10: exit
    syscall                # Exit
```

- Note: The directive .space (with a number of bytes) should be used when creating a variable without initial value

```
.data
    z: .space 4            # 4 bytes
```

# Exercise

- Add 9 to `y` and store it into `x` and print the value of `x` on the console

- Add 9 to y and store it into x and print the value of x on the console

```
.data
    x: .word 0          # Variable x
    y: .word 5          # Variable y initialized to 5

.text
    la    $s0, x         # Load the address of x to $s0
    la    $s1, y         # Load the address of y to $s1
    lw    $t0, 0($s1)     # Load value stored in y to $t0
    addi   $t0, $t0, 9    # $t0 = $t0 + 9
    sw     $t0, 0($s0)    # Store $t0 into x
    addi   $a0, $zero, $t0 # $a0 = $t0
    addi   $v0, $zero, 1  # Service 1: print integer
    syscall                               # Print integer
    addi   $v0, $zero, 10 # Service 10: exit
    syscall                               # Exit
```



# Example

- Consider the following code:

```
int a[4] = {1,3,2,5};  
int temp;  
  
temp = a[1];  
a[1] = a[2];  
a[2] = temp;
```

- What is the MIPS code corresponds to the above code?

# Example

```
.data
    a: .word 1,3,2,4
.text
    la    $s0, a           # $s0 is the address of a[0]
    addi  $t0, $zero, 1    # Use $t0 as the index
    sll   $t1, $t0, 2      # Use $t1 as the offset (index * 4)
    add   $t2, $s0, $t1    # $t2 is the address of a[index]
    lw    $t3, 0($t2)      # $t3 = a[1]
    lw    $t4, 4($t2)      # $t4 = a[2]
    sw    $t4, 0($t2)      # a[1] = $t4
    sw    $t3, 4($t2)      # a[2] = $t3
    addi  $v0, $zero, 10   # Service 10: exit
    syscall                # Exit
```

Note that we can use effective addresses `0($t2)` and `4($t2)` in this case because they are next to each other.

# Memory Organization

- MIPS use byte addressing
  - Each memory location is 8-bit wide (1 byte)
  - Each byte can be accessed directly
  - For example, memory locations 0, 1, 2, ...
- A word in MIPS is 32-bit wide
  - Each word requires 4 bytes
  - Words are aligned in memory
  - Two Least Significant Bits (LSBs) of every word memory addresses are always 0s
  - For example, memory location 0, 4, 8, 12, ...
- Half-word in MIPS is 16-bit wide
  - Each half-word requires 2 bytes
  - Half-words are aligned in memory
  - The LSB of every half-word memory addresses is always 0.
  - For example, 0, 2, 4, 6, ...

# Big-Endian vs Little-Endian

- Suppose we have a 32-bit number 0x12345678 (hexadecimal)
- How do we store this number as a word at memory location 0?

# Big-Endian vs Little-Endian

- Suppose we have a 32-bit number  $0x12345678$  (hexadecimal)
- How do we store this number as a word at memory location 0?
- Divide the number into 4 bytes ( $12\ 34\ 56\ 78_{16}$ )
- **Big-Endian:** most significant byte in the smallest address
  - Location 0:  $12_{16}$
  - Location 1:  $34_{16}$
  - Location 2:  $56_{16}$
  - Location 3:  $78_{16}$
- **Little-Endian:** least significant byte in the smallest address
  - Location 0:  $78_{16}$
  - Location 1:  $56_{16}$
  - Location 2:  $34_{16}$
  - Location 3:  $12_{16}$
- What is MIPS in MARS (Big-Endian or Little-Endian)?

# Big-Endian vs Little-Endian

```
.data
    x: .word 0x12345678
.text
    la    $t0, x           # Set $t0 to the address of x
    lbu   $t0, 0($t0)       # Load a byte at location x
    addi  $v0, $zero, 10    # Service 10: exit
    syscall                 # Exit
```

- After lbu, check the value of the register \$t0
  - If \$t0 is 12, it is a Big Endian
  - If \$t0 is 78, it is a Little Endian
- Why lbu instead of lb?

# Shift Instructions

- Change bits position inside a word
- Format:

`<op> <Destination>, <Source>, <Shift Amount>`

- MIPS Field: R-type
- Example:

```
sll  $t0, $t1, 6      # $t0 = $t1 << 6
sllv $t1, $t2, $t3     # $t1 = $t2 << $t3 (lower 5 bits)
srl  $s0, $s1, 3       # $s0 = $s1 >> 3
srlv $t1, $t2, $t3     # $t1 = $t2 >> $t3 (lower 5 bits)
```

- Shift Right Arithmetic (sra) reserves the sign of the number
  - If MSB is 0, shift in with 0
  - If MSB is 1, shift in with 1

# Exercise: Shift Instruction

- Suppose we have four 8-bit numbers 0xaa, 0xbb, 0xcc, and 0xdd stored in registers \$t0, \$t1, \$t2, and \$t3 respectively.
- Write a code that generates a 32-bit number 0xaabbccdd from registers \$t0 to \$t3.

```
.text
    addiu $t0, $zero, 0xaa    # Set $t0 to 0xaa
    addiu $t1, $zero, 0xbb    # Set $t1 to 0xbb
    addiu $t2, $zero, 0xcc    # Set $t2 to 0xcc
    addiu $t3, $zero, 0xdd    # Set $t3 to 0xdd
    or     $t4, $zero, $t0     # Now $t4 is 0xaa
    sll    $t4, $t4, 8         # Now $t4 is 0xaa00
    or     $t4, $t4, $t1       # Now $t4 is 0xaabb
    sll    $t4, $t4, 8         # Now $t4 is 0xaabb00
    or     $t4, $t4, $t2       # Now $t4 is 0xaabbcc
    sll    $t4, $t4, 8         # Now $t4 is 0xaabbcc00
    or     $t4, $t4, $t3       # Now $t4 is 0xaabbccdd
```



- In high-level language, we can choose to execute a set of statements or not using the `if` statement.

Line	High-Level Language	Assembly Language
1.	<code>if(condition)</code>	Go to line 5 if the condition is false
2.	<code>{</code>	
3.	<code>    :</code>	Instruction(s) in if body
4.	<code>}</code>	
5.	<code>:</code>	Instructions after if statement

- In high-level language, we can choose to execute a set of statements or another set of statements using the if-else statement

Line	High-Level Language	Assembly Language
1.	if(condition)	Go to line 7 if the condition is false
2.	{	
3.	:	Instruction(s) in if body
4.	}	Go to line 9
5.	else	
6.	{	
7.	:	Instruction(s) in else body
8.	}	
9.	:	Instruction after if-else statement

- In high-level language, we can choose to execute among sets of statements using the else-if construct

Line	High-Level Language	Assembly Language
1.	if(condition1)	Go to line 5 if the condition1 is false
2.	{	
3.	:	Instruction(s) in if body
4.	}	Go to line 13
5.	else if(condition2)	Go to line 11 if the condition2 if false
6.	{	
7.	:	Instruction(s) in second if body
8.	}	Go to line 13
9.	else	
10.	{	
11.	:	Instruction(s) in else body
12.	}	
13.	:	Instruction after if-else statement

# Branches

- In MIPS, you can jump to a certain instruction (referred by its location) based on either equal or not equal condition
- These are called **conditional branches**

beq	\$t0, \$t1, L1	# If \$t0 == \$t1 go to L1
bne	\$t0, \$t1, L2	# If \$t0 != \$t1 go to L2

- MIPS also support **unconditional branches** (jump)

j	L3	# Go to L3
---	----	------------

- In assembly, we use a label to reference to an address in memory
  - The actual location of an instruction in memory can be changed during programming
  - By using labels, we do not have to keep track of the actual locations

# Set Less Than

- Conditional branches in MIPS only support equal to or not equal to
- Note that the conditions in higher-level languages include less than, less than or equal to, greater than, and greater than or equal to.
- MIPS has basic instructions called **Set Less Than**
  - `slt $t0, $t1, $t2`:
    - **Set Less Than**: Set \$t0 to 1 if \$t1 is less than \$t2. Otherwise, \$t0 will be 0.
  - `slti $t0, $t1, 100`
    - **Set Less Than Immediate**: Set \$t0 to 1 if \$t1 is less than 100. Otherwise, \$t0 will be 0.
  - `sltiu $t0, $t1, 100`
    - **Set Less Than Immediate Unsigned**: Treat the value in \$t1 as an unsigned number. Set \$t0 to 1 if \$t1 is less than 100. Otherwise, \$t0 will be 0.
  - `sltu $t0, $t1, $t2`
    - **Set Less Than Unsigned**: Treat values in \$t1 and \$t2 as unsigned numbers. Set \$t0 to 1 if \$t1 is less than \$t2. Otherwise, \$t0 will be 0.

# Using Branches for if Statement

- Equal to:

Line	High-Level Language	Assembly Language
1.	if(\$t0 == \$t1)	bne \$t0, \$t1, label
2.	{	
3.	:	...
4.	}	
5.	:	label: ...

- Not Equal to:

Line	High-Level Language	Assembly Language
1.	if(\$t0 != \$t1)	beq \$t0, \$t1, label
2.	{	
3.	:	...
4.	}	
5.	:	label: ...

# Using Branches for if Statement

- Less Than:

Line	High-Level Language	Assembly Language
0.		<code>slt \$t2, \$t0, \$t1</code>
1.	<code>if(\$t0 &lt; \$t1)</code>	<code>beq \$t2, \$zero, label</code>
2.	<code>{</code>	
3.	<code>    :</code>	<code>...</code>
4.	<code>}</code>	
5.	<code>:</code>	<code>label: ...</code>

- Less Than or Equal to:

Line	High-Level Language	Assembly Language
0.		<code>slt \$t2, \$t1, \$t0</code>
1.	<code>if(\$t0 &lt;= \$t1)</code>	<code>bne \$t2, \$zero, label</code>
2.	<code>{</code>	
3.	<code>    :</code>	<code>...</code>
4.	<code>}</code>	
5.	<code>:</code>	<code>label: ...</code>

- Note that the condition `$t0 <= $t1` is the same as `!($t1 < $t0)`

# Using Branches for if-else Statement

Line	High-Level Language	Assembly Language
1.	if(\$t0 != \$t1)	beq \$t0, \$t1, else
2.	{	
3.	:	...
4.	}	j    label
5.	else	
6.	{	
7.	:	else:  ...
8.	}	
9.	:	label:  ...



# Exercise

- Convert the following program into MIPS assembly code:

```
Scanner in = new Scanner(System.in);

System.out.print("Please enter an integer number: ")

int x = in.nextInt();

if(x % 2 == 0)
{
    System.out.println(x + " is an even number.");
}
else
{
    System.out.println(x + " is an odd number.");
}
```

# Solution

```
.data
prompt: .asciiz "Please enter an integer number: "
evenmsg: .asciiz " is an even number."
oddmsg: .asciiz " is an odd number."

.text
la    $a0, prompt           # Set $a0 to prompt
addi  $v0, $zero, 4         # Service 4: print string
syscall                               # Print string
addi  $v0, $zero, 5         # Service 5: read integer
syscall                               # Read integer
add   $s0, $zero, $v0       # Store read integer in $s0
add   $a0, $zero, $v0       # Set integer to print
addi  $v0, $zero, 1         # Service 1: print integer
syscall                               # Print integer
andi  $s0, $s0, 1           # Retrieve the LSB
bne   $s0, $zero, odd       # If LSB != 0 go to odd
la    $a0, evenmsg          # Set $a0 to evenmsg
j     print                 # Go to print
odd:   la    $a0, oddmsg      # Set $a0 to oddmsg
print: addi  $v0, $zero, 4    # Service 4: print string
syscall                               # Print string
addi  $v0, $zero, 10        # Service 10: exit
syscall                               # Exit
```

# Loops

- We can use conditional/unconditional branches and set less than instructions to construct loop
- Note that the following code

```
for(initial expression; loop condition; loop expression)
{
    loop body;
}
```

is the same as

```
initial expression;

while(loop condition)
{
    loop body;
    loop expression;
}
```

- Note that converting a while loop to assembly code is simpler than converting from a for loop.

# The while Loop

High-Level Language	Assembly Language
<pre>i = 0;  while(i &lt; 10) {     :     i = i + 1; } :</pre>	<pre>        add  \$t0, \$zero, \$zero loop:   slti  \$t1, \$t0, 10         beq  \$t1, \$zero, exit          ...         addi \$t0, \$t0, 1         j    loop exit:   ...</pre>

- Can we branch when \$t1 is equal to 10?

```
        add  $t0, $zero, $zero
        addi $t5, $zero, 10
loop:   beq  $t1, $t5, exit
        :
exit:   ...
```

# The do Loop

High-Level Language	Assembly Language
<pre>do {     :     : } while(\$t0 &lt; \$t1) :</pre>	<pre>loop:  ...       ...       slt \$t2, \$t0, \$t1       bne \$t2, \$zero, loop       ...</pre>

- Consider the following program:

```
char[] str = {'H','e','l','l','o',' ','  
              'W','o','r','l','d','!','\0'};  
  
int length = 0;  
  
while(str[length] != '\0')  
{  
    length = length + 1;  
}  
  
System.out.println("The length is " + length);
```

# Solution

```
.data
    str: .asciiz "Hello World!"
    msg: .asciiz "The length is "

.text
    la    $s0, str           # Set $s0 to point to str
    add   $t0, $zero, $zero  # Set length to 0
loop:   add   $t1, $t0, $s0    # Add length to the address of str
        lbu   $s1, 0($t1)     # Load a character into $s1
        beq   $s1, $zero, exit # If $s1 == 0, go to exit
        addi  $t0, $t0, 1      # Increase length by 1
        j     loop           # Go to loop
exit:   la    $a0, msg        # Set $a0 to point to msg
        addi  $v0, $zero, 4    # Service 4: print string
        syscall              # Print string
        add   $a0, $zero, $t0  # Set $a0 to length
        addi  $v0, $zero, 1    # Service 1: print integer
        syscall              # Print integer
        addi  $v0, $zero, 10   # Service 10: exit
        syscall              # Exit
```

# Address in I-type

- Conditional branches instructions use I-type
- The address field of the I-type instruction is 16-bit wide
  - This is a **signed** two's complement number
  - The address field is used to specify the number of instructions to be skipped (forward and backward)
- This value is used to adjust the program counter (\$pc)
- Note that the program counter is 32-bit wide but the address field is only 16-bit wide
  - 16-bit address field is needed to be sign-extended to a 32-bit number
- Note that MIPS uses byte addressing (each byte can be accessed directly)
  - The number of instructions to be skipped must be changed to the number of bytes to be skipped
  - Since all MIPS instructions are 32-bit wide, each instruction takes 4 bytes
  - This can be done by multiplying the number of instructions to be skipped by 4



# Address in I-type

- The new address can be calculated by

$$PC + 4 + (\text{sign-extend}(16\text{-bit address field}) \ll 2)$$

- This is called **relative addressing** (address related to program counter in this case)
- Example: Suppose the instruction `beq $t0, $t1, exit` is located at the address 16, and the instruction at the `exit:` label is located at the address 32
  - From the above formula, we need to solve

$$32 = 16 + 4 + (\text{sign-extend}(16\text{-bit address field}) \ll 2)$$

which gives us

$$\text{sign-extend}(16\text{-bit address field}) \ll 2 = 12$$

or

$$\text{sign-extend}(16\text{-bit address field}) = 3$$

Thus the actual code for the instruction `beq $t0, $t1, exit` will be `beq $t0, $t1, 3`

# Sign Extension

- The purpose of sign extension is to extend a number with lower number of bits to higher number of bits where its value is preserved.
- For example
  - The value 5 in 4-bit representation is  $0101_2$
  - $0101_2$  can be extended to 8-bit representation as  $00000101_2$
  - Note that the value is still 5
- Another example
  - The value -4 in 4-bit representation is  $1100_2$
  - $1100_2$  can be extended to 8-bit representation as  $11111100_2$
  - Note that the value is still -4
- Simply extend the most significant bit (signed bit)
- For a positive number, it is easy to see that the value is preserved
- What about negative number?

# Sign Extension

Recall that the value of a 4-bit representation  $x_3x_2x_1x_0$  in two's complement is

$$-(x_3 \times 2^3) + (x_2 \times 2^2) + (x_1 \times 2^1) + (x_0 \times 2^0)$$

Consider the first term, if  $x_3$  is 0, the first term is 0. If  $x_3$  is 1, the first time is -8. Suppose we extend this number to 5-bit representation by copying the value of the most significant bit ( $x_3$ ), we get  $x_3x_3x_2x_1x_0$  and its value is

$$-(x_3 \times 2^4) + (x_3 \times 2^3) + (x_2 \times 2^2) + (x_1 \times 2^1) + (x_0 \times 2^0)$$

Now consider the first two terms. If  $x_3$  is 0, the first two term is 0. If  $x_3$  is 1, the first two terms is  $-16 + 8 = -8$ . Notice that it is the same value as the first term before sign extension. Suppose we extend this number to 6-bit representation by copying the value of the most significant bit ( $x_3$ ), we get  $x_3x_3x_3x_2x_1x_0$  and its value is

$$-(x_3 \times 2^5) + (x_3 \times 2^4) + (x_3 \times 2^3) + (x_2 \times 2^2) + (x_1 \times 2^1) + (x_0 \times 2^0)$$

Now consider the first three terms. If  $x_3$  is 0, the first three terms is 0. If  $x_3$  is 1, the first three terms is  $-32 + 16 + 8 = -8$ . Again, it is the same. Therefore, by extending the most significant bit, the value is preserved.

# Jump Addressing

- Instruction jump (j) uses J-type (26-bit address field)
- Jump does not use relative addressing
- Since each instruction is a word (32-bit) wide, jump uses word addressing instead of byte addressing
  - Note that for byte addressing to access a word, the last two least significant bit are always 0 any way.
  - This also increase the range of jump
- After multiply by 4 (shift left by 2), we get the byte address
- But it is only  $26 + 2 = 28$  bits (we need 32-bit for program counter)
- MIPS takes the most significant four bits from the original program counter to fill it to 32 bits.

# Procedures/Functions

- We use procedures/functions (methods) often in high-level programming language
  - The main function calls function insert
  - The function insert may call function isEmpty

```
public static void main(String[] args)
{
    :
    insert(...);
    :
}

private static void insert(...)
{
    :
    if(isEmpty())
    :
}

private static boolean isEmpty()
{
    :
}
```

# Procedures/Functions

- From previous code:
  - Function `main` calls function `insert`
  - Function `insert` calls function `isEmpty`
  - When function `isEmpty` is done, it goes back to the `if` statement of the function `insert`
  - When function `insert` is done, it goes back to the next statement after the statement `insert(...)`;
- To simulate function calls in assembly, we need a way to:
  - call a function
  - return back to caller
  - pass arguments
  - return values

# Procedure Call

- Simply jump to the first instruction of the procedure using label
- When the procedure is done, it needs to jump back to the instruction immediately after the call
- Need to tell the procedure where to jump back using the register `$ra` (return address)
- Example: To call a procedure at the label `myFunction`, use

```
jal myFunction    # Jump and Link to myFunction
```

- The instruction `jal myFunction` performs two things:
  - Set `$ra` to `PC + 4` (next instruction after `jal`)
  - Set `PC` to `PC[31:28] | (myFunction << 2)`

# Procedure Return

- When a function is finished, it needs to return back to the instruction immediately after the call
- The address of that instruction is stored in \$ra
- Simply use

```
jr $ra    # Jump back to the address stored in $ra
```

- The instruction `jr $ra` simply sets PC to the value stored in \$ra



- Write a procedure named `_greeting`
  - This procedure prints the string "Hello "
- Write the main program that calls the procedure `_greeting` and then prints the string "How are you?"

# Solution

```
.data
    asking: .asciiz "How are you?"

.text
    jal  _greeting      # Call the procedure _greeting
    la   $a0, asking     # Set $a0 to the string asking
    addi $v0, $zero, 4    # Service 4: print string
    syscall              # Print string
    addi $v0, $zero, 10   # Service 10: exit
    syscall              # Exit

_greeting:
.data
    str: .asciiz "Hello. "

.text
    la   $a0, str        # Set $a0 to the string str
    addi $v0, $zero, 4    # Service 4: print string
    syscall              # Print string
    jr   $ra             # Go back to caller
```

# Arguments and Return Values

- Register conventions:
  - \$a0 – \$a3: Four arguments for passing values to called procedure
  - \$v0 and \$v1: Two values returned from called procedure
  - \$ra: return address register (set by caller and used by return)
- Sending Arguments:
  - Caller stores argument values in registers \$a0 to \$a3
  - Called procedure will know that argument values are stored in those register
- Returning Values:
  - Called procedure stores return values in register \$v0 and \$v1
  - Caller will know that return values are stored in those registers

# Exercise

- Suppose we do not have the multiplication operator ( $*$ )
- Create a function named `_multi(int a, int b)` that returns the result of `a` multiplied by `b`
- For simplicity, both `a` and `b` are greater than or equal to 0

# Exercise

- Suppose we do not have the multiplication operator (\*)
- Create a function named `_multi(int a, int b)` that returns the result of a multiplied by b
- For simplicity, both a and b are greater than or equal to 0
- You may come up with the following Java code:

```
int _multi(int a, int b)
{
    int result = 0;
    int i = 0;

    while(i < b)
    {
        result = result + a;
        i = i + 1;
    }

    return result;
}
```

# Solution

```
.text
    addi $a0, $zero, 5      # Set value of the first argument
    addi $a1, $zero, 9      # Set value of the second argument
    jal  _multi             # Call the procedure _multi
    add  $a0, $zero, $v0     # Set $a0 to returned value (from _multi)
    addi $v0, $zero, 1      # Service 1: print integer
    syscall                 # Print integer
    addi $v0, $zero, 10     # Service 10: exit
    syscall                 # Exit

_multi:
    add  $v0, $zero, $zero  # Set result to 0
    add  $t0, $zero, $zero  # Set counter to 0
loop:  slt  $t1, $t0, $a1    # $t1 is 1 if counter < $a1
       beq  $t1, $zero, done # If $t1 == 0 go to done
       add  $v0, $v0, $a0    # result = result + $a0
       addi $t0, $t0, 1      # Increase counter by 1
       j    loop            # Go back to loop
done:  jr   $ra              # Go back to caller
```

- It is a good idea to put comment in detail about the procedure
- For example, the procedure `_multi`

```
# _multi - Perform multiplication
#
# Arguments:
#   $a0 - multiplicand
#   $a1 - multiplier
# Return values:
#   $v0 - result of $a0 * $a1
#
# Note: Trash values stored in register $t0 and $t1

_multi:
    :
```

# Call Chains

- Imagine the main program calls procedure X and procedure X calls procedure Y
- According to the conventions, we use `$ra` for return address
  - The main program sets `$ra` and calls procedure X
  - The procedure X sets `$ra` and calls procedure Y
  - The previous value stored in `$ra` is destroyed
- If a procedure needs to call another procedure, it must backup `$ra` first
  - Simple solution (for now): Store `$ra` in an unused register
- Leaf procedure (does not make any calls): does not need to save `$ra`



# Exercise

- Write a procedure named `_power(int x, int y)` that calculates  $x$  to the power of  $y$  ( $x^y$ ) by using procedure `_multi`

# Exercise

- Write a procedure named `_power(int x, int y)` that calculates  $x$  to the power of  $y$  ( $x^y$ ) by using procedure `_multi`
- You may come up with the following Java code:

```
int _power(int x, int y)
{
    int result = 1;
    int i = 0;

    while(i < y)
    {
        result = _multi(result, x);
        i = i + 1;
    }

    return result;
}
```

# Solution

```
_power:
    add    $s0, $zero, $a0    # Save $a0 in $s0 (x)
    add    $s1, $zero, $a1    # Save $a1 in $s1 (y)
    add    $s7, $zero, $ra    # Save $ra in $s7
    addi   $s2, $zero, 1      # Set result to 1
    add    $s3, $zero, $zero   # Set counter to 0
ploop:   slt    $s4, $s3, $s1   # $s4 is 1 if counter < $s1
        beq    $s4, $zero, pdone # If $s4 == 1 go to pdone
        add    $a0, $zero, $s2  # Set $a0 to result
        add    $a1, $zero, $s0  # Set $a1 to x
        jal    _multi           # Call procedure _multi
        add    $s2, $zero, $v0   # Save return value in $s2
        addi   $s3, $s3, 1       # Increase counter by 1
        j      ploop           # Go back to ploop
pdone:   add    $ra, $zero, $s7  # Restore $ra back from $s7
        jr     $ra             # Go back to caller
```

# Sharing Registers

- **Caller:** The procedure that calls other procedure(s)
- **Callee:** The procedure that is called by other procedure(s)
- In MIPS, there are limited number of registers
- Callee may want to use same registers as caller
  - Values stored in those registers were destroyed after the callee use them
  - Usually temporary saved registers (\$s0 to \$s7)
  - Same situation as in \$ra
- Caller may want to use same registers as callee
  - Similarly, values are destroyed
  - Usually temporary registers (\$t0 to \$t9)

# Register Usage Conventions

- \$t0 – \$t9:
  - These registers are temporary registers
  - Caller **should not** expect that values stored in these register will not be destroyed by callee
  - If caller wants to use them, caller must save their values before the call and restore their values back after the call
- \$s0 – \$s7:
  - These registers are temporary saved registers
  - Callee **must** maintain their values
  - If callee wants to use them, callee must save their values before using them and restore their values before return to caller

# Where to Save Values of Registers?

- Simply save in other registers may not be a good idea
  - We have limited number of registers
  - We may run out of registers
- Need memory space to hold saved ("spilled") registers
  - Caller spills  $\$t0 - \$t9$  that must be saved to memory
  - Callee spills  $\$s0 - \$s7$  that are used to memory
  - Other registers ( $\$a0 - \$a3$ ,  $\$v0$ , and  $\$v1$ ) may also need to be saved
  - Non-leaf caller saves  $\$ra$  to memory before they make another call
- Each procedure needs memory locations to save registers
- We cannot simply allocate a fixed size and fixed memory location of each procedure
  - Hard to keep track
  - Required memory size for recursive procedure cannot be determined in advance
  - Call-chain depth (the number of called procedures) is generally unknown. Need to support undetermined length

# Program Stack

- **Program Stack:** Memory locations used by running program
- Generally used for:
  - saving values of spilled registers
  - storing local variables, if we do not have enough registers
  - arguments, if we have more than four arguments
  - return values, if we have more than two return values
  - storing return address (\$ra)
- Each procedure allocates space called **activation frame**
  - The size of activation frame is fixed for each procedure being called
  - The size can be determined by its purpose
  - The location of the activation frame is unknown until procedure call made

# Calling Convention

- Caller saves needed registers, sets up arguments, makes call
  - Saves temporary registers (\$t0 to \$t9) as needed
  - Sets up arguments (\$a0 to \$a3) as needed
  - If more arguments are required, put arguments onto the stack
- Callee procedure when entering the procedure
  - Adjust the stack pointer according to activation frame size to hold temporary saved registers, locals, return address (non-left)
  - Save return address to the stack
  - Save any temporary saved registers to the stack
- Callee procedure body
  - Access stack items as needed (additional arguments, locals, etc)
- Callee procedure before leaving the procedure
  - Restore any temporary saved registers
  - Restore return address
  - Restore the stack (deactivate activation frame)
  - Return to caller



# Example: Leaf Procedure

- Consider a leaf procedure that needs to use all temporary registers \$t0 to \$t9 and three temporary saved registers \$s0 to \$s2
- According to the convention, this procedure only needs to save values stored in registers \$s0, \$s1, and \$s2 (3 words or 12 bytes)
- When entering the procedure, it must perform the following:

```
addi $sp, $sp, -12    # Allocate activation frame
sw    $s0, 0($sp)     # Store $s0 in memory
sw    $s1, 4($sp)     # Store $s1 in memory
sw    $s2, 8($sp)     # Store $s2 in memory
```

- Before return back to the caller, it must perform the following:

```
lw    $s2, 8($sp)     # Restore $s2 from memory
lw    $s1, 4($sp)     # Restore $s1 from memory
lw    $s0, 0($sp)     # Restore $s0 from memory
addi $sp, $sp, 12     # Deallocate activation frame
```

# Example: Non-Leaf Procedure

- Consider a non-leaf procedure that uses registers \$s0, \$s1, \$s2, \$t0 and \$t1
- This procedure needs to call another procedure located at the label `_aFunction`
- The size of the activation frame is 6 words including \$ra (24 bytes)
- When entering the procedure, it must perform the following:

```
addi $sp, $sp, -24    # Allocate activation frame
sw   $ra, 0($sp)      # Store return address in memory
sw   $s0, 4($sp)      # Store $s0 in memory
sw   $s1, 8($sp)      # Store $s1 in memory
sw   $s2, 12($sp)     # Store $s2 in memory
```

# Example: Non-Leaf Procedure

- Before and after calling `_aFunction`, it must perform the following:

```
sw    $t0, 16($sp)    # Store $t0 in memory
sw    $t1, 20($sp)    # Store $t1 in memory
jal   _aFunction       # Call function _aFunction
lw    $t1, 20($sp)    # Restore $t1 from memory
lw    $t0, 16($sp)    # Restore $t0 from memory
```

- Before return back to the caller, it must perform the following

```
lw    $s2, 12($sp)    # Restore $s2 from memory
lw    $s1, 8($sp)     # Restore $s1 from memory
lw    $s0, 4($sp)     # Restore $s0 from memory
lw    $ra, 0($sp)     # Restore $ra from memory
addi  $sp, $sp, 24    # Deallocate activation frame
jr    $ra             # Return to caller
```

# Example: Recursive Multiplication

- Note that the result of  $a * b$  is the same as  $a + (a * (b - 1))$  which is the same as  $a + a + (a * (b - 2))$  and so on.
- A recursive version of a multiplication function can be as follows:

```
int multi(int a, int b)
{
    if(b == 1)
    {
        return a;
    }
    else
    {
        return a + multi(a, b - 1);
    }
}
```

# Solution

```
_multi: addi $sp, $sp, -8      # Adjust the stack
        sw   $ra, 0($sp)     # Store $ra in memory
        sw   $s0, 4($sp)     # Store $s0 in memory
        addi $s0, $zero, 1    # Set $s0 to 1
        bne  $a1, $s0, else    # If $a1 != 1 to to else
        add  $v0, $zero, $a0  # Set return value to $a0 (multiplicand)
        j    exit            # Go to exit
else:    addi $a1, $a1, -1     # Reduce multiplier by 1
        jal  _multi          # Call the procedure _multi
        add  $v0, $v0, $a0    # Add return value to mutiplicand
exit:    lw   $s0, 4($sp)     # Restore $s0 from memory
        lw   $ra, 0($sp)     # Restore $ra from memory
        addi $sp, $sp, 8     # Adjust the stack
        jr   $ra             # Go back to caller
```