

# LI Yefeng (李烨锋)

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## RESEARCH INTERESTS

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My research interests lie in the broad area of Programming Languages and Software Systems. I am interested in formal verification for distributed programming and for compilation, type systems, proof assistants, functional programming, and so on. I hope to develop rigorously founded theories and tools at the service of reliable software.

## EDUCATION

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### Purdue University

*Doctor of Philosophy student in Computer Science*

West Lafayette, IN, USA

### Hong Kong University of Science and Technology (HKUST)

*Master of Philosophy in Computer Science and Engineering*

*Bachelor of Engineering in Computer Engineering | Minor in Robotics*

Hong Kong S.A.R.

*Sept. 2018 – June 2020*

*Sept. 2014 – June 2018*

## RESEARCH PROJECTS

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### Manifoldness Preserving Contraction

*M.Phil. thesis, advised by Prof. Quan Long*

VisGraph Lab, CSE, HKUST

*Aug. 2018 – May 2020*

- Designed a new contraction method that guarantees manifold output given a manifold input using augmentation and the separation of singularities. It can be applied to geometry processing as a replacement to the conventional contraction operation which may destroy topology and produce imperfect results.

### Triangle mesh simplification

*Advised by Prof. Quan Long*

VisGraph Lab, CSE, HKUST

*Aug. 2018 – May 2020*

- Used new contraction techniques to improve triangle mesh simplification wherein traditional methods fail to effectively restrict the destruction of input topology.
- Facilitated the parallelization in the construction of Levels-of-Detail of 3D models using 2D-projection of tile boundaries.

### Centralized Wireless Local Area Networks

*Undergraduate final-year thesis, advised by Prof. Brahim Bensaou*

HKUST

*Sept. 2017 – Mar. 2018*

- Specified a centralization protocol for Wireless LANs as an (software-defined networking) extension atop CSMA/CA to explore the improvement of resource utilization in dense indoor networks. It was partially implemented in C based on hostapd's source code and experimented on OpenWrt embedded Linux system.

### Photograph capturing with drones

*Undergraduate Research Opportunity Program, advised by Prof. Quan Long*

VisGraph Lab, CSE, HKUST

*Aug. – Nov. 2016*

- Investigated in the application of Computer Vision and Graphics for Android devices as remote controls for drones, with a focus on human-drone interaction. An Android application was built to retrieve data from a geography database and visualize useful information on the screen according to the vision of the drone.

## PROFESSIONAL EXPERIENCE

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### Everest Innovation Technology (merged into Apple Inc.)

*Researcher & Software Developer*

Shenzhen & Hong Kong, China

*June – Aug. 2019*

- Triangle mesh processing:** Transferred novel geometry processing techniques into *Altizure*, a world-class cloud-based 3D reconstruction platform; developed efficient mesh processing program in C++.
- ZRPC:** Participated in the development of ZRPC, an RPC distributed computing framework, in Go.
- Data management and visualization:** Developed a photographic data validation, management, and visualization desktop application in JavaScript.

**Dash Serviced Suites**  
*Part-time JavaScript Developer*

Hong Kong  
*Feb. – May 2018*

- **Web development:** Worked on the Web interface, API, and database management of *DASH2*, an online marketplace Web application by the startup company.

## TEACHING EXPERIENCE

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**Department of Computer Science and Engineering, HKUST**  
*Teaching Assistant*

Hong Kong  
*2018 – 2019*

- COMP1021: Introduction to Computer Science, Fall 2019
- COMP3311: Database Management Systems, Fall 2018

## EXTRACURRICULAR ACTIVITIES

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**ACM SIGPLAN Symposium on Principles of Programming Languages**  
*Student Volunteer*

New Orleans, LA, USA  
*Jan. 2020*

- Supported event organization.

**RoboMaster Robotics Competition**  
*Mechanical/Computer Engineer*

Shenzhen, China  
*Feb. – Aug. 2017*

- Co-designed the mechanical structure of *Hero*, the main-force in this multi-robot contest, for RoboMaster HKUST team. Our Hero robot was controlled remotely, capable of capturing, storing and shooting bullets, and climbing onto stairs with telescopic legs.

**Chinese Folk-Art Society, HKUST**  
*IT Secretary, Executive Committee*

Hong Kong  
*Feb. 2015 – Feb. 2016*

- Independently built the official website of our society and developed a Web application in JavaScript to assist the hosting of a knowledge competition named *Who is Still Standing*.
- Took charge of photographing and Internet platform promotions.
- Organized trips to the Yangzi, China and Dragon's Back, Hong Kong.