

Individual Project Report

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Group 13

In this lab, I tried my controller for the first half of the lab. It turns out to be working fine and we later decided to use Jianxiong's SE3 controller to ensure the best performance. For the second half of the lab, I tested my trajectory generator on all three of the test maps and proved them working before going to the lab the next day. During the second lab, we used my minimum jerk trajectory generator for the experiment. Jianxiong and Bozhou also tried their trajectory generator on scene and got that to work.