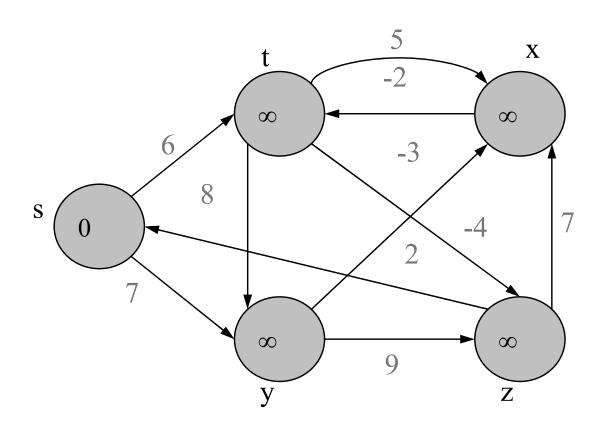
Bellman-Ford Single source shortest path algorithm



Bellman-Ford Algorithm for Single Source Shortest Paths

- More general than Dijkstra's algorithm:
- Edge-weights can be negative
- Detects the existence of negative-weight cycle(s) reachable from source S.
- Follows Dynamic programming strategy (Try out all possible solutions and pickup the best solution)







Procedure

- The Bellman ford algorithm starts with computing the path from source to each node i in v.
- Since there are n nodes in a graph, the path to any node can contain at most n-1 nodes.
- Then for each node u, remaining n-2 nodes are required to be examined.
- If <j, u>€E then the condition dist[u] is compared with dist[j] + cost[j][u].
- If dist[u] is greater than dist[j]+dist[j][u] then dist[u] is updated to dist[j]+cost[j][u].



• Idea:

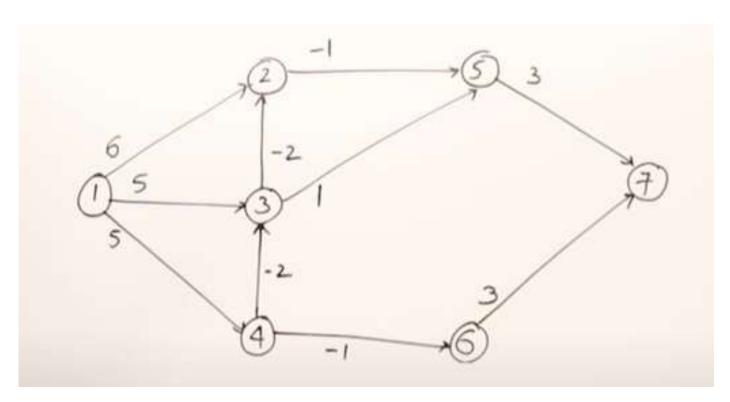
- Each edge is relaxed |V-1| times by making
 |V-1| passes over the whole edge set.
- To make sure that each edge is relaxed exactly
 |V 1| times, it puts the edges in an unordered list and goes over the list |V 1| times.

Relaxation:

for all edges
$$(u, v) \in E$$

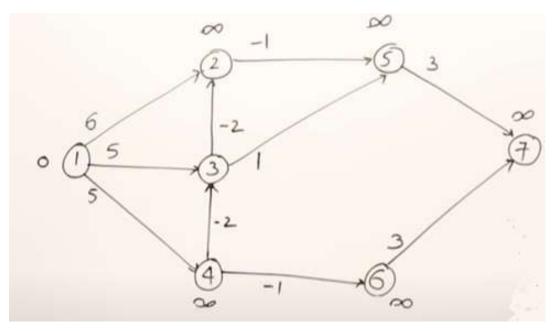
if $dist[v] > dist[u] + w(u, v)$
 $dist[v] \leftarrow dist[u] + w(u, v)$



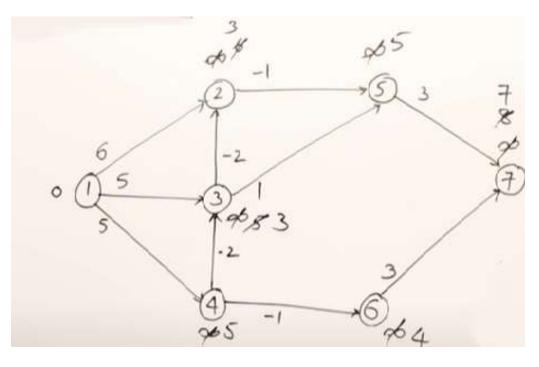


List of Edges: (1,2), (1,3), (1,4), (2,5), (3,2), (3,5), (4,3), (5,7), (6,7)





Initiation



Iteration - 1

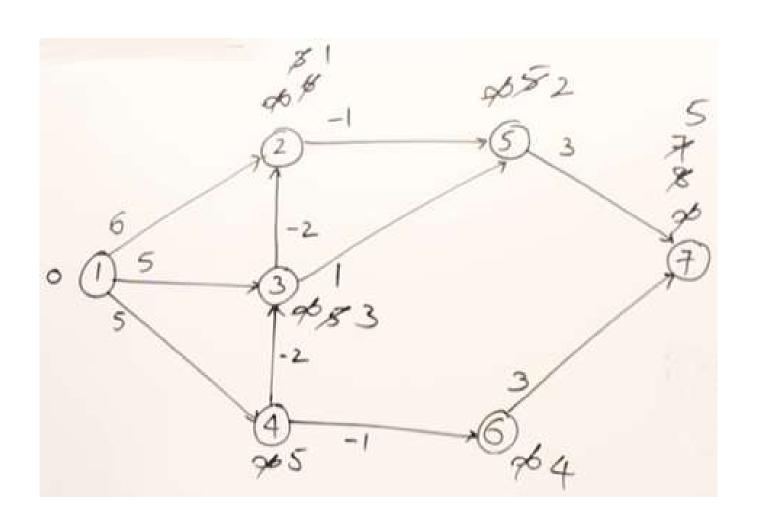
List of Edges: (1,2), (1,3), (1,4), (2,5), (3,2), (3,5), (4,3), (5,7), (6,7)

Relaxation:

If (d[u]+c(u,v) < d[v]d[v]=d[u]+c(u,v)

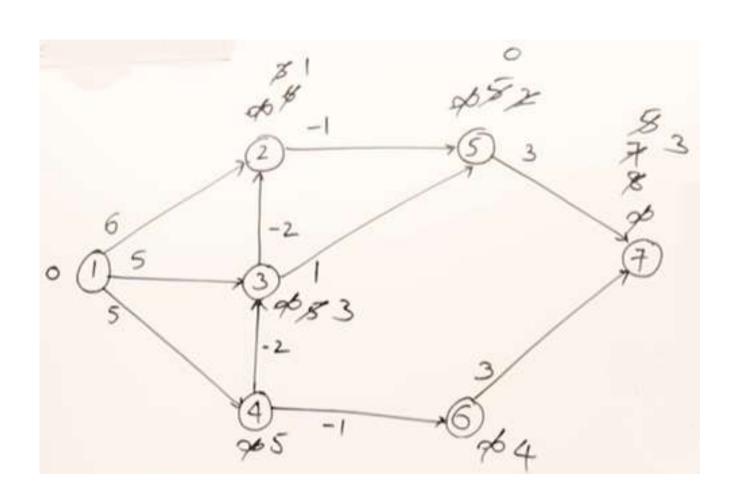


Iteration - 2 (1,2), (1,3), (1,4), (2,5), (3,2), (3,5), (4,3), (5,7), (6,7)

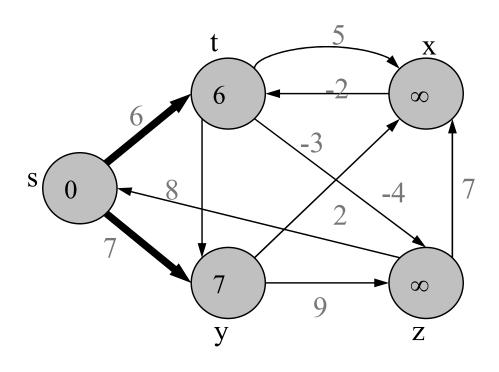




Iteration - 3 (1,2), (1,3), (1,4), (2,5), (3,2), (3,5), (4,3), (5,7), (6,7)

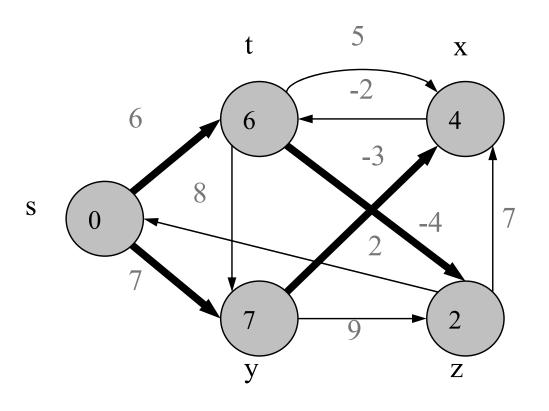






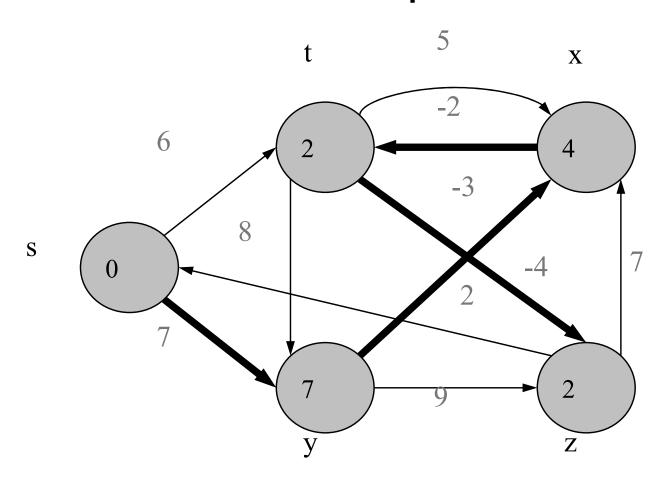
List of Edges: (s,t), (s,y), (t,x), (t,y), (t,z), (x,t), (y,x), (y,z), (z,x), (z,s)



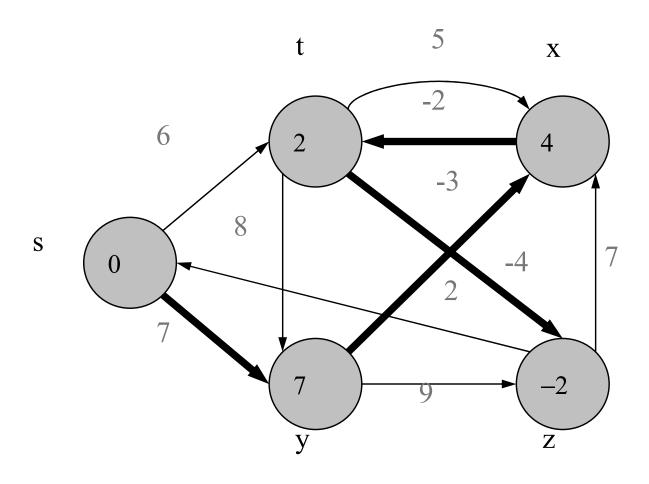


Iteration - 1











```
Bellman-Ford(G, s)
     for all v \in V
                 dist[v] \leftarrow \infty
 2
                 prev[v] \leftarrow null
 3
     dist[s] \leftarrow 0
 5
     for i \leftarrow 1 to |V|-1
 6
                 for all edges (u, v) \in E
                            if dist[v] > dist[u] + w(u,v)
 8
                                       dist[v] \leftarrow dist[u] + w(u,v)
 9
                                       prev[v] \leftarrow u
     for all edges (u, v) \in E
10
                 if dist[v] > dist[u] + w(u, v)
11
```

 $return\ false$

12



Application

Assembly Line Scheduling

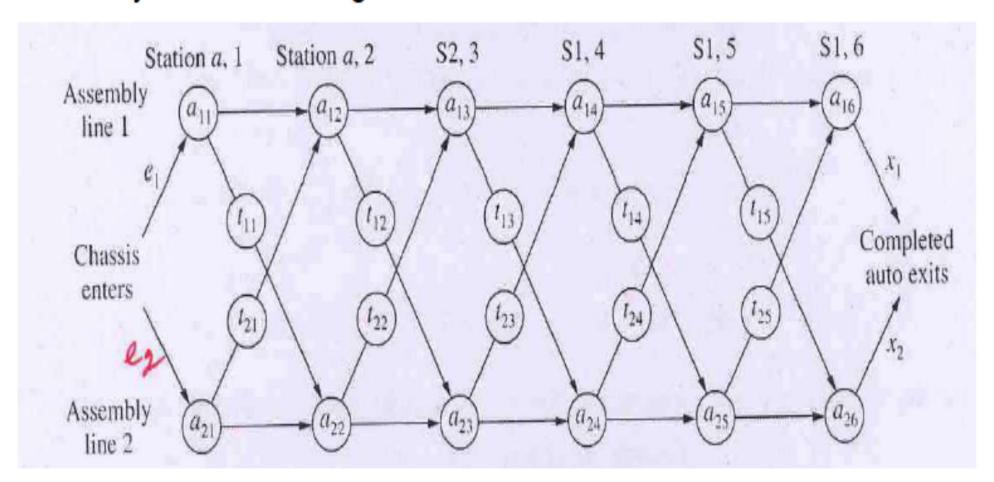




Illustration of Assembly line Scheduling

