

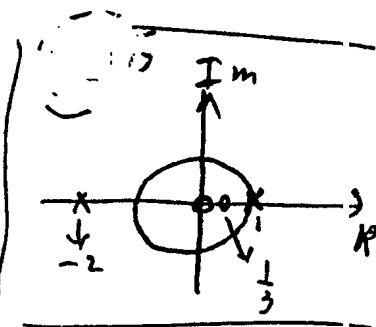
Q<sub>1</sub>

solution: Final 2010, ELEC442-6601

$$H(z) = \frac{1 - \frac{1}{3}z^{-1}}{1 + z^{-1} - 2z^{-2}} = \frac{1 - \frac{1}{3}z^{-1}}{(1 - z^{-1})(1 + 2z^{-1})}$$

zeros: 0 and  $\frac{1}{3}$ 

poles: 1 and -2



$$H(z) = \frac{Y(z)}{X(z)} = \frac{1 - \frac{1}{3}z^{-1}}{1 + z^{-1} - 2z^{-2}} \Rightarrow Y(z) + z^{-1}Y(z) - 2z^{-2}Y(z) = X(z) - \frac{1}{3}z^{-1}X(z)$$

$$\Rightarrow y[n] = -y[n-1] + 2y[n-2] + x[n] - \frac{1}{3}x[n-1]$$

Q<sub>2</sub> There are three cases where the system is unstablei)  $\text{Roc } |z| > 2$   
and causalii)  $\text{Roc } |z| < 2$   
not causaliii)  $\text{Roc } |z| < 1$   
not causalWe consider  $\text{Roc } |z| > 2$  ~~and~~ since due to being right sided the system is causal

$$H(z) = \frac{1 - \frac{1}{3}z^{-1}}{(1 - z^{-1})(1 + 2z^{-1})} = \frac{A}{1 - z^{-1}} + \frac{B}{1 + 2z^{-1}} = \frac{A + 2Az^{-1} + B - Bz^{-1}}{(1 - z^{-1})(1 + 2z^{-1})}$$

$$\begin{cases} A + B = 1 \\ 2A - B = -\frac{1}{3} \end{cases} \quad A = \frac{2}{9} \quad B = \frac{7}{9}$$

$$H(z) = \frac{\frac{2}{9}}{1 - z^{-1}} + \frac{\frac{7}{9}}{1 + 2z^{-1}} \quad |z| > 2$$

$$h[n] = \frac{2}{9}u[n] + \frac{7}{9}(-2)^n u[n]$$

Q3

$$h[n] = h_1[n] * h_2[n] = \{\delta[n-1] + 2\delta[n] + \delta[n+1]\} * h_2[n]$$

$$= \delta[n-1] * h_2[n] + 2\delta[n] * h_2[n] + \delta[n+1] * h_2[n]$$

$$h[n] = h_2[n-1] + 2h_2[n] + h_2[n+1]$$

$$h_2[n] = \delta[n-2] + \delta[n-1] + \delta[n] + \delta[n+1] + \delta[n+2]$$

$$h[n] = \{\delta[n-3] + \delta[n-2] + \delta[n-1] + \delta[n] + \delta[n+1]\} + \\ + 2\{\delta[n-2] + \delta[n-1] + \delta[n] + \delta[n+1] + \delta[n+2]\} + \\ + \{\delta[n-1] + \delta[n] + \delta[n+1] + \delta[n+2] + \delta[n+3]\}$$

$$h[n] = \delta[n-3] + 3\delta[n-2] + 4\delta[n-1] + 4\delta[n] + 4\delta[n+1] + 3\delta[n+2] + \delta[n+3]$$

$$H(e^{j\omega}) = e^{-j3\omega} + 3e^{-j2\omega} + 4e^{-j\omega} + 4 + 4e^{j\omega} + 3e^{j2\omega} + e^{j3\omega}$$

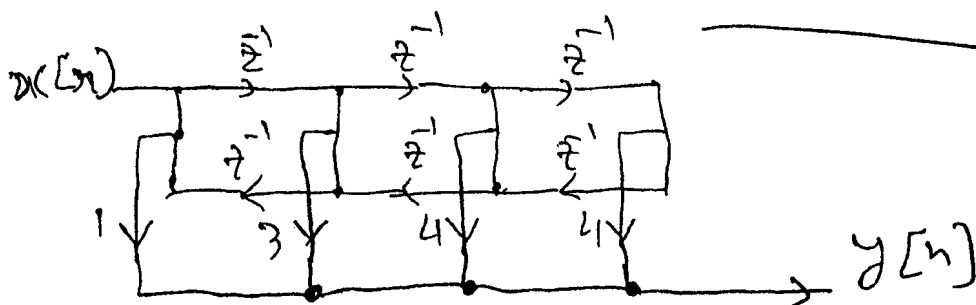
$$H(e^{j\omega}) = 4 + 4(e^{j\omega} + e^{-j\omega}) + 3(e^{j2\omega} + e^{-j2\omega}) + (e^{j3\omega} + e^{-j3\omega})$$

$$H(e^{j\omega}) = 4 + 8\cos\omega + 6\cos 2\omega + 2\cos 3\omega$$

Q4 We shift the impulse response by three samples to have no component with  $n < 0$ .  
<sub>non-zero</sub>

$$\bar{h}[n] = \delta[n] + 3\delta[n-1] + 4\delta[n-2] + 4\delta[n-3] + 3\delta[n-4] + \delta[n-5]$$

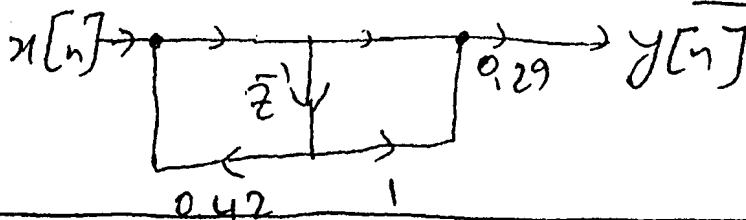
$\bar{h}[n]!$   
 can/91



Q5  $H(j\omega) = \frac{a}{j\omega + a}$   $|H(j\omega)| = \frac{|a|}{\sqrt{\omega^2 + a^2}}$   $|H(j0)| = 1$   
 $\omega_c = \frac{2}{T} \tan \frac{\omega_c}{2} \Rightarrow a = \frac{2}{T} \tan \frac{0.25\pi}{2} = \frac{0.828}{T}$

$H(s) = \frac{0.828/T}{s + 0.828/T}$   $s = \frac{2}{T} \left( \frac{1-z^{-1}}{1+z^{-1}} \right) \Rightarrow H(z) = \frac{0.29(1+z^{-1})}{1-0.42z^{-2}}$

$|H(e^{j0})| = 1$  &  $|H(e^{j0.25\pi})| = \frac{0.29 \|1 + e^{j0.25\pi}\|}{\|1 - 0.42e^{j0.5\pi} + 0.42e^{j1.0\pi}\|} = 0.7$   
 therefore  $0.25\pi$  is cutoff



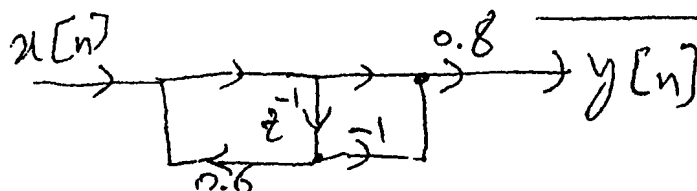
Q6  $\omega_p = 0.25\pi$   $\omega_s = 0.15\pi$   $\alpha = -\frac{G(\frac{0.25\pi + 0.15\pi}{2})}{G(\frac{0.25\pi - 0.15\pi}{2})} = -0.82$

$z^{-1} \rightarrow -\frac{z^{-1} + \alpha}{1 + \alpha z^{-1}} = -\frac{z^{-1} - 0.82}{1 - 0.82z^{-1}}$   $H(z) = \frac{0.29(1 - \frac{z^{-1} - 0.82}{1 - 0.82z^{-1}})}{1 + 0.42 \frac{z^{-1} - 0.82}{1 - 0.82z^{-1}}}$

$H(z) = \frac{0.8(1 - z^{-1})}{1 - 0.6z^{-1}}$

$|H(e^{j0})| = \frac{0.8(1 - e^{j0})}{1 - 0.6e^{j0}} = 1$   $|H(e^{j0.15\pi})| = 0.7$

Therefore  $0.15\pi$  is cutoff



Q7

$$y[n] + \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = \frac{1}{4}x[n] + n[n-1]$$

$$y(z) + \frac{3}{4}z^{-1}y(z) + \frac{1}{8}z^{-2}y(z) = \frac{1}{4}x(z) + z^{-1}x(z)$$

$$H(z) = \frac{y(z)}{x(z)} = \frac{\frac{1}{4} + z^{-1}}{1 + \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}} = \frac{\frac{1}{4}z(z+4)}{(z+\frac{1}{2})(z+\frac{1}{4})}$$

Zeros: 0 &amp; -4

Poles:  $-\frac{1}{2}$  &  $-\frac{1}{4}$ 

For a minimum phase system, the system and its inverse should be stable and causal. Therefore, all poles and zeros should be inside unit circle.

This system is not min phase since zero at -4 is outside unit circle.

Q8,  $H(z) = \frac{\frac{1}{4} + z^{-1}}{(1+\frac{1}{2}z^{-1})(1+\frac{1}{4}z^{-1})} = \underbrace{G(z)}_{\text{all pass}} \cdot \underbrace{H_{\min}(z)}_{\text{min}}$

We choose  $G(z) = \frac{z^{-1} + \frac{1}{4}}{1 + \frac{1}{4}z^{-1}}$  to remove the zero at -4 from  $H(z)$ . We know that  $|G(e^{j\omega})| = 1$ .

$$\frac{\frac{1}{4} + z^{-1}}{(1+\frac{1}{2}z^{-1})(1+\frac{1}{4}z^{-1})} = \frac{z^{-1} + \frac{1}{4}}{1 + \frac{1}{4}z^{-1}} \cdot H_{\min}(z)$$

$$H_{\min}(z) = \frac{1}{1 + \frac{1}{2}z^{-1}}$$

 $-\frac{1}{2} \angle \pi$ 

$$h_{\min}[n] = (-\frac{1}{2})^n u[n]$$

**Question 9:**

$$x_d[n] = x_c(nT) \xleftrightarrow{FT} X_d(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c\left(\frac{\omega}{T} - j\frac{2k\pi}{T}\right)$$

$$x[n] = \begin{cases} x_d\left[\frac{n}{7}\right] & n = \pm 7k \\ 0 & \text{otherwise} \end{cases} \xleftrightarrow{FT} X(e^{j\omega}) = X_d(e^{j7\omega})$$

$$y[n] = x[n] * h[n] \xleftrightarrow{FT} Y(e^{j\omega}) = H(e^{j\omega})X(e^{j\omega})$$

$$y_d[n] = y[4n] \xleftrightarrow{FT} Y_d(e^{j\omega}) = \frac{1}{4} \sum_{k=0}^3 Y\left(e^{j\left(\frac{\omega-2k\pi}{4}\right)}\right)$$

$$y_c(t) = \left\{ \sum_{n=-\infty}^{\infty} y_d[n] \delta\left(t - \frac{4nT}{7}\right) \right\} * h_{DC}(t) \xleftrightarrow{FT} Y_c(j\Omega) = \begin{cases} \frac{4T}{7} Y_d\left(e^{j\frac{4\Omega T}{7}}\right) & |\Omega| < \frac{\pi}{10T} \\ 0 & \text{otherwise} \end{cases}$$

**Question 10:**

$$y_c(t) = \frac{7}{4T} x_c(t) \xleftrightarrow{FT} Y_c(j\Omega) = \frac{7}{4T} X_c(j\Omega)$$

