

MATLAB INTRODUCTION

Hyperbolic Trigonometrical Function

```
cosh(0.55)
```

```
ans = 1.1551
```

```
tanh(3)
```

```
ans = 0.9951
```

```
cosh(54)
```

```
ans = 1.4154e+23
```

```
sin(123)
```

```
ans = -0.4599
```

Inverse Hyperbolic

similar to sine cosine

```
asinh(39)
```

```
ans = 4.3569
```

```
atanh(56)
```

```
ans = 0.0179 + 1.5708i
```

Exponential, , and Ln Function

```
%e this will give an error as undefines function
```

e is not recognisable as exponential

```
exp(10)
```

```
ans = 2.2026e+04
```

```
exp(2)
```

```
ans = 7.3891
```

```
2.7183^2
```

ans = 7.3892

Logarithmic

$\log(3)$

ans = 1.0986

this natural log base e, here $\ln(x)=\log(x)$

$\log(5)$

ans = 1.6094

$\log(10)$

ans = 2.3026

for **base 10**= $\log_{10}(x)$

$\log_{10}(1000)$

ans = 3

$\log_{10}(10)$

ans = 1

$\log_{10}(11.5)$

ans = 1.0607

$\log(\exp(1))$

ans = 1

Introduction to complex numbers

$1i$

ans = 0.0000 + 1.0000i

$1i$

ans = 0.0000 + 1.0000i

i and j are same

```
(2-1i)
```

```
ans = 2.0000 - 1.0000i
```

```
(2-1i)*1i
```

```
ans = 1.0000 + 2.0000i
```

```
(1-4i)-(5-4i)
```

```
ans = -4
```

```
(1-4i)*(1+4i)
```

```
ans = 17
```

```
1i*1i
```

```
ans = -1
```

```
sqrt(-1)
```

```
ans = 0.0000 + 1.0000i
```

```
A=3-1i;  
b=7+5i;  
A*b
```

```
ans = 26.0000 + 8.0000i
```

```
A=b
```

```
A = 7.0000 + 5.0000i
```

```
A^b
```

```
ans = -1.2891e+05 + 8.9340e+04i
```

abs()

```
C=2;  
d=-5;  
p=5i;  
abs(d)
```

```
ans = 5
```

```
abs(p)
```

```
ans = 5
```

```
abs(b)
```

```
ans = 8.6023
```

```
abs(A)
```

```
ans = 8.6023
```

angle()

angle between complex and real part in radian

```
angle(A)
```

```
ans = 0.6202
```

```
angle(C)
```

```
ans = 0
```

```
angle(d)*180/pi
```

```
ans = 180
```

real()

```
real(A)
```

```
ans = 7
```

imag()

```
imag(A)
```

```
ans = 5
```

```
imag(d)
```

```
ans = 0
```

conj() or ()'

```
conj(A)
```

```
ans = 7.0000 - 5.0000i
```

A'

ans = 7.0000 - 5.0000i

complex(x,y)

complex(5,6)

ans = 5.0000 + 6.0000i

symbolic toolbox and complex number

A

A = 7.0000 + 5.0000i

log(A)

ans = 2.1520 + 0.6202i

b

b = 7.0000 + 5.0000i

exp(A)

ans = 3.1107e+02 - 1.0516e+03i

sin(A)

ans = 48.7549 + 55.9420i

sym(angle(A))

ans =

$$\frac{5586710707897953}{9007199254740992}$$

A=3+3i

A = 3.0000 + 3.0000i

sym(angle(A))

ans =

$$\frac{\pi}{4}$$

```
A=1+1i
```

```
A = 1.0000 + 1.0000i
```

```
abs(A)
```

```
ans = 1.4142
```

```
sym(abs(A))
```

```
ans =  $\sqrt{2}$ 
```

```
(4-5i)*(5+6i)
```

```
ans = 50.0000 - 1.0000i
```

```
A=3-4i
```

```
A = 3.0000 - 4.0000i
```

```
sym a
```

```
ans =  $a$ 
```

```
A=sym(3-4i)
```

```
A =  $3 - 4i$ 
```

```
A*A
```

```
ans =  $-7 - 24i$ 
```

```
sqrt(A)
```

```
ans =  $\sqrt{3 - 4i}$ 
```

```
A^4-20*A^5+12*A^2
```

```
ans =  $4129 - 62272i$ 
```

Vectors in Matlab - Let'slay the foundation

A=12

A = 12

b=-3

b = -3

A=[1 2 3]

A = 1×3
1 2 3

b=[1 4 7]

b = 1×3
1 4 7

C=[3 5 1]

C = 1×3
3 5 1

A=[1 2 3 4 5 6 7]

A = 1×7
1 2 3 4 5 6 7

A=[1,2,3]

A = 1×3
1 2 3

A=[1, 2, 3]

A = 1×3
1 2 3

Transpose of vector/Matrix

A=[1;2;3]

A = 3×1
1
2
3

b=[1 2 3;2 3 4;3 2 1]

b = 3×3

1	2	3
2	3	4
3	2	1

b'

```
ans = 3x3
1 2 3
2 3 2
3 4 1
```

A'

```
ans = 1x3
1 2 3
```

C'

```
ans = 3x1
3
5
1
```

Extract elememeents

A=[1 2 3 4]

```
A = 1x4
1 2 3 4
```

A(2)

```
ans = 2
```

b=[3 -1 4 5 8 9 7]

```
b = 1x7
3 -1 4 5 8 9 7
```

b(2)

```
ans = -1
```

b(6)

```
ans = 9
```

b'

```
ans = 7x1
3
-1
4
5
8
```


9
7

```
A=[2 5 6 8]
```

```
A = 1×4  
    2     5     6     8
```

```
b=[3 1 5 9]
```

```
b = 1×4  
    3     1     5     9
```

```
A(2)/b(2)
```

```
ans = 5
```

algebra

```
A=[1 2 3 4 5];  
b=[5 6 7 8 2];  
C=[0 9 6 2 4];  
A+b
```

```
ans = 1×5  
    6     8    10    12     7
```

```
A-b
```

```
ans = 1×5  
   -4    -4    -4    -4     3
```

```
b-A
```

```
ans = 1×5  
    4     4     4     4    -3
```

```
A+b+C
```

```
ans = 1×5  
    6    17    16    14    11
```

```
%a*c this will give error
```

```
A*C' %this will execute correctly
```

```
ans = 64
```

```
8*A
```

```
ans = 1×5
```

8 16 24 32 40

```
-2*A
```

```
ans = 1x5
      -2   -4   -6   -8  -10
```

dot product

```
dot(A,b)
```

```
ans = 80
```

cross product

```
A=[1 2 3];
b=[5 6 7];
cross(A,b)
```

```
ans = 1x3
      -4     8    -4
```

Length of vector

```
A=[1 2 3 5 7]
```

```
A = 1x5
      1     2     3     5     7
```

```
length(A)
```

```
ans = 5
```

```
b=[ 1 2 3 5 6 84 5 6 6]
```

```
b = 1x9
      1     2     3     5     6    84     5     6     6
```

```
length(b)
```

```
ans = 9
```

```
length(A)/length(b)
```

```
ans = 0.5556
```

sum,length,min,max of elements

```
sum(A)
```

```
ans = 18
```

```
b
```

```
b = 1×9  
    1    2    3    5    6    84    5    6    6
```

```
sum(b)
```

```
ans = 118
```

```
length(b)
```

```
ans = 9
```

```
sum(b)/length(b)
```

```
ans = 13.1111
```

```
mean(b)
```

```
ans = 13.1111
```

```
min(b)
```

```
ans = 1
```

```
max(b)
```

```
ans = 84
```

Creating vectors

a:b vector a

```
A=2:6
```

```
A = 1×5  
    2    3    4    5    6
```

```
C=1:2:8
```

```
C = 1×4  
    1    3    5    7
```

```
A=1:8
```

```
A = 1×8  
    1    2    3    4    5    6    7    8
```

```
A(4)
```

```
ans = 4
```

```
A(2:5)
```

```
ans = 1×4
      2      3      4      5
```

linspace

```
help linspace
```

linspace Linearly spaced vector.

linspace(X1, X2) generates a row vector of 100 linearly equally spaced points between X1 and X2.

linspace(X1, X2, N) generates N points between X1 and X2. For N = 1, **linspace** returns X2.

Class support for inputs X1,X2:
float: double, single

See also logspace, colon.

Reference page for linspace
Other functions named linspace

```
linspace(1,10)
```

```
ans = 1×100
      1.0000      1.0909      1.1818      1.2727      1.3636      1.4545      1.5455      1.6364 ...
```

```
linspace(1,10,5)
```

```
ans = 1×5
      1.0000      3.2500      5.5000      7.7500     10.0000
```

```
mean(ans)
```

```
ans = 5.5000
```

```
length(ans)
```

```
ans = 1
```

```
A=[1 2 3 6 9 5 6]
```

```
A = 1×7
      1      2      3      6      9      5      6
```

```
b=[3 6 -1 7 1 8 6 7 8]
```

```
b = 1×9  
    3     6    -1     7     1     8     6     7     8
```

```
vector1=A(3:5)
```

```
vector1 = 1×3  
    3     6     9
```

```
vector2=b(2:7)
```

```
vector2 = 1×6  
    6    -1     7     1     8     6
```

```
vector3=[vector1,vector2]
```

```
vector3 = 1×9  
    3     6     9     6    -1     7     1     8     6
```

```
vector3=[vector1,vector2]'
```

```
vector3 = 9×1  
    3  
    6  
    9  
    6  
   -1  
    7  
    1  
    8  
    6
```

```
vector4=linspace(1,9,5)
```

```
vector4 = 1×5  
    1     3     5     7     9
```

```
vector3=[vector1,vector2,vector4]'
```

```
vector3 = 14×1  
    3  
    6  
    9  
    6  
   -1  
    7  
    1  
    8  
    6  
    1  
    ⋮  
    ⋮
```

```
sum(vector4)
```

```
ans = 25
```

```
sum(vector3)
```

```
ans = 70
```

element wise multiplication(.*) and division ./)

```
A=[1 2 3 4 5 6 8 9 5 2 7]
```

```
A = 1×11  
    1     2     3     4     5     6     8     9     5     2     7
```

```
b=[7 8 9 5 4 2 3 6 5 2 8]
```

```
b = 1×11  
    7     8     9     5     4     2     3     6     5     2     8
```

```
dot(A,b)
```

```
ans = 265
```

```
%a*b it will show error as dimension error  
A.*b    %element wise multiplication
```

```
ans = 1×11  
    7    16    27    20    20    12    24    54    25     4    56
```

```
A./b    %elementwise division
```

```
ans = 1×11  
    0.1429    0.2500    0.3333    0.8000    1.2500    3.0000    2.6667    1.5000 ...
```

```
A=[1 2 4 -7 -2 2-9];  
b=[1 4 5 6 5 6 8];  
abs(A)
```

```
ans = 1×6  
    1     2     4     7     2     7
```

```
sin(A)
```

```
ans = 1×6  
    0.8415    0.9093   -0.7568   -0.6570   -0.9093   -0.6570
```

```
log(A)
```

```
ans = 1×6 complex  
    0.0000 + 0.0000i    0.6931 + 0.0000i    1.3863 + 0.0000i    1.9459 + 3.1416i ...
```

```
sqrt(b)
```

```
ans = 1×7
```

```
1.0000    2.0000    2.2361    2.4495    2.2361    2.4495    2.8284
```

```
tan(A)
```

```
ans = 1x6
    1.5574   -2.1850    1.1578   -0.8714    2.1850   -0.8714
```

```
sinh(b)
```

```
ans = 1x7
103 x
    0.0012    0.0273    0.0742    0.2017    0.0742    0.2017    1.4905
```

```
acos(b)
```

```
ans = 1x7 complex
    0.0000 + 0.0000i    0.0000 + 2.0634i    0.0000 + 2.2924i    0.0000 + 2.4779i ...
```

```
%a^2 error
A.^2
```

```
ans =
    1     4    16    49     4    49
```

```
%a^b error
%a.^b
```

Creating vector by Random function

```
rand
```

```
ans = 0.8147
```

```
rand
```

```
ans = 0.9058
```

```
help rand
```

rand Uniformly distributed pseudorandom numbers.
R = **rand**(N) returns an N-by-N matrix containing pseudorandom values drawn from the standard uniform distribution on the open interval(0,1). **rand**(M,N) or **rand**([M,N]) returns an M-by-N matrix. **rand**(M,N,P,...) or **rand**([M,N,P,...]) returns an M-by-N-by-P-by-... array. **rand** returns a scalar. **rand**(SIZE(A)) returns an array the same size as A.

Note: The size inputs M, N, P, ... should be nonnegative integers. Negative integers are treated as 0.

R = **rand**(..., CLASSNAME) returns an array of uniform values of the specified class. CLASSNAME can be 'double' or 'single'.

R = **rand**(..., 'like', Y) returns an array of uniform values of the same class as Y.

The sequence of numbers produced by **rand** is determined by the settings of the uniform random number generator that underlies **rand**, **RANDI**, and **RANDN**. Control that shared random number generator using **RNG**.

Examples:

Example 1: Generate values from the uniform distribution on the interval (a, b).

```
r = a + (b-a).*rand(100,1);
```

Example 2: Use the **RANDI** function, instead of **rand**, to generate integer values from the uniform distribution on the set 1:100.

```
r = randi(100,1,5);
```

Example 3: Reset the random number generator used by **rand**, **RANDI**, and **RANDN** to its default startup settings, so that **rand** produces the same random numbers as if you restarted MATLAB.

```
rng('default')  
rand(1,5)
```

Example 4: Save the settings for the random number generator used by **rand**, **RANDI**, and **RANDN**, generate 5 values from **rand**, restore the settings, and repeat those values.

```
s = rng  
u1 = rand(1,5)  
rng(s);  
u2 = rand(1,5) % contains exactly the same values as u1
```

Example 5: Reinitialize the random number generator used by **rand**, **RANDI**, and **RANDN** with a seed based on the current time. **rand** will return different values each time you do this. NOTE: It is usually not necessary to do this more than once per MATLAB session.

```
rng('shuffle');  
rand(1,5)
```

See [Replace Discouraged Syntaxes of rand and randn to use RNG to replace rand](#) with the 'seed', 'state', or 'twister' inputs.

See also [randi](#), [randn](#), [rng](#), [RandStream](#), [RandStream/rand](#), [sprand](#), [sprandn](#), [randperm](#).

Reference page for [rand](#)
Other functions named [rand](#)

```
rand(1,4)
```

```
ans =  
    0.1270    0.9134    0.6324    0.0975
```

```
rand(1,4)
```

```
ans =  
    0.2785    0.5469    0.9575    0.9649
```

```
rand(2,4)
```

```
ans =  
    0.1576    0.9572    0.8003    0.4218  
    0.9706    0.4854    0.1419    0.9157
```

```
rand(2,4)
```



```
ans =  
    0.7922    0.6557    0.8491    0.6787  
    0.9595    0.0357    0.9340    0.7577
```

```
sin(rand(1,4))
```

```
ans =  
    0.6766    0.3822    0.6095    0.1704
```

```
randperm(5)
```

```
ans =  
     2     4     5     3     1
```

```
randperm(100,5)
```

```
ans =  
    83    69    32    93     4
```

```
help randperm
```

randperm Random permutation.

P = **randperm**(N) returns a vector containing a random permutation of the integers 1:N. For example, **randperm**(6) might be [2 4 5 6 1 3].

P = **randperm**(N,K) returns a row vector containing K unique integers selected randomly from 1:N. For example, **randperm**(6,3) might be [4 2 5].

randperm(N,K) returns a vector of K unique values. This is sometimes referred to as a K-permutation of 1:N or as sampling without replacement. To allow repeated values in the selection, sometimes referred to as sampling with replacement, use **RANDI**(N,1,K).

randperm calls **RAND** and therefore changes the state of the random number generator that underlies **RAND**, **RANDI**, and **RANDN**. Control that shared generator using **RNG**.

See also **nchoosek**, **perms**, **rand**, **randi**, **rng**.

Reference page for **randperm**
Other functions named **randperm**

```
help ones
```

ones Ones array.

ones(N) is an N-by-N matrix of ones.

ones(M,N) or **ones**([M,N]) is an M-by-N matrix of ones.

ones(M,N,P,...) or **ones**([M N P ...]) is an M-by-N-by-P-by-... array of ones.

ones(**SIZE**(A)) is the same size as A and all ones.

ones with no arguments is the scalar 1.

ones(..., CLASSNAME) is an array of ones of class specified by the string CLASSNAME.

`ones(..., 'like', Y)` is an array of ones with the same data type, sparsity, and complexity (real or complex) as the numeric variable `Y`.

Note: The size inputs `M`, `N`, and `P...` should be nonnegative integers. Negative integers are treated as 0.

Example:

```
x = ones(2,3,'int8');
```

See also `eye`, `zeros`.

Reference page for `ones`

Other functions named `ones`

```
ones(3,4)
```

```
ans =  
     1     1     1     1  
     1     1     1     1  
     1     1     1     1
```

```
ones(1,4)
```

```
ans =  
     1     1     1     1
```

```
help zeros
```

zeros Zeros array.

`zeros(N)` is an N-by-N matrix of zeros.

`zeros(M,N)` or `zeros([M,N])` is an M-by-N matrix of zeros.

`zeros(M,N,P,...)` or `zeros([M N P ...])` is an M-by-N-by-P-by-... array of zeros.

`zeros(SIZE(A))` is the same size as `A` and all zeros.

`zeros` with no arguments is the scalar 0.

`zeros(..., CLASSNAME)` is an array of zeros of class specified by the string `CLASSNAME`.

`zeros(..., 'like', Y)` is an array of zeros with the same data type, sparsity, and complexity (real or complex) as the numeric variable `Y`.

Note: The size inputs `M`, `N`, and `P...` should be nonnegative integers. Negative integers are treated as 0.

Example:

```
x = zeros(2,3,'int8');
```

See also `eye`, `ones`.

Reference page for `zeros`

Other functions named `zeros`

```
zeros(2,4)
```

```
ans =  
     0     0     0     0
```

```
0    0    0    0
```

```
zeros(1,4)
```

```
ans =  
0    0    0    0
```

```
A=randperm(5)
```

```
A =  
5    2    1    3    4
```

```
help sort
```

```
sort Sort in ascending or descending order.  
B = sort(A) sorts in ascending order.  
The sorted output B has the same type and size as A:  
- For vectors, sort(A) sorts the elements of A in ascending order.  
- For matrices, sort(A) sorts each column of A in ascending order.  
- For N-D arrays, sort(A) sorts along the first non-singleton dimension.  
  
B = sort(A,DIM) also specifies a dimension DIM to sort along.  
  
B = sort(A,DIRECTION) and B = sort(A,DIM,DIRECTION) also specify the  
sort direction. DIRECTION must be:  
    'ascend' - (default) Sorts in ascending order.  
    'descend' - Sorts in descending order.  
  
B = sort(A,...,'MissingPlacement',M) also specifies where to place the  
missing elements (NaN/NaT/<undefined>/<missing>) of A. M must be:  
    'auto' - (default) Places missing elements last for ascending sort  
              and first for descending sort.  
    'first' - Places missing elements first.  
    'last' - Places missing elements last.  
  
B = sort(A,...,'ComparisonMethod',C) specifies how to sort complex  
numbers. The comparison method C must be:  
    'auto' - (default) Sorts real numbers according to 'real', and  
              complex numbers according to 'abs'.  
    'real' - Sorts according to REAL(A). Elements with equal real parts  
              are then sorted by IMAG(A).  
    'abs' - Sorts according to ABS(A). Elements with equal magnitudes  
              are then sorted by ANGLE(A).  
  
[B,I] = sort(A,...) also returns a sort index I which specifies how the  
elements of A were rearranged to obtain the sorted output B:  
- If A is a vector, then B = A(I).  
- If A is an m-by-n matrix and DIM = 1, then  
    for j = 1:n, B(:,j) = A(I(:,j),j); end
```

The sort ordering is stable. Namely, when more than one element has the same value, the order of the equal elements is preserved in the sorted output B and the indices I relating to equal elements are ascending.

Examples:

```
% Sort a vector in ascending order  
sort([0 3 1 0 2 0 1 6])  
% Sort each column or row of a matrix  
A = [3 7 5; 0 4 2]  
B1 = sort(A,1) % sort each column  
B2 = sort(A,2) % sort each row  
% Sort complex numbers according to their real part
```

```
A = [1+1j ; 1-1j ; -2-2j ; 0 ; -2+2j]
B = sort(A,'ComparisonMethod','real')
```

See also issorted, sortrows, min, max, mink, maxk.

Reference page for sort

Other functions named sort

```
A=randperm(8)
```

```
A =
     6     2     1     3     8     7     4     5
```

```
b=sort(A)
```

```
b =
     1     2     3     4     5     6     7     8
```

Statistical Analysis on Vectors

```
data=[10 25 25 58 56 89 42 42 42 5 5 4 ]
```

```
data =
    10    25    25    58    56    89    42    42    42     5     5     4
```

```
mean(data)
```

```
ans = 33.5833
```

```
median(data)
```

```
ans = 33.5000
```

```
std(data)
```

```
ans = 26.2764
```

```
var(data)
```

```
ans = 690.4470
```

```
sqrt(var(data))
```

```
ans = 26.2764
```

Matrices

```
vector1=[2 6 8 0 1]
```

```
vector1 =
     2     6     8     0     1
```

```
vector1(4)
```

```
ans = 0
```

```
matrix1=[1 2;2 3]
```

```
matrix1 =  
     1     2  
     2     3
```

```
matrix2=[1 3 7;4 8 1;9 5 -2]
```

```
matrix2 =  
     1     3     7  
     4     8     1  
     9     5    -2
```

```
matrix3=[2 5 9;-2 -1 0]
```

```
matrix3 =  
     2     5     9  
    -2    -1     0
```

```
matrix4=[1 2 7 3;-8 9 5 2;9 6 3 2;7 5 3 4]
```

```
matrix4 =  
     1     2     7     3  
    -8     9     5     2  
     9     6     3     2  
     7     5     3     4
```

```
matrix4(3,4)
```

```
ans = 2
```

```
matrix4(6)
```

```
ans = 9
```

```
matrix4(2)
```

```
ans = -8
```

```
matrix4(1:9)
```

```
ans =  
     1    -8     9     7     2     9     6     5     7
```

```
matrix4(2:4,1:3)
```

```
ans =  
    -8     9     5  
     9     6     3  
     7     5     3
```

```
b=matrix4(1:2,3:4)
```

```
b =  
    7    3  
    5    2
```

```
b=matrix4(4,2:4)
```

```
b =  
    5    3    4
```

```
matrix4(2:end,1:3)
```

```
ans =  
   -8    9    5  
    9    6    3  
    7    5    3
```

Multiply Matrices and Elementwise Multiplication

```
A=[1 2;3 4]
```

```
A =  
    1    2  
    3    4
```

```
b=[5 8;6 1]
```

```
b =  
    5    8  
    6    1
```

```
A+b
```

```
ans =  
    6   10  
    9    5
```

```
A-b
```

```
ans =  
   -4   -6  
   -3    3
```

```
A*b %matrix multiplication
```

```
ans =  
   17   10  
   39   28
```

```
A.*b %element wise multiplication
```

```
ans =  
    5   16
```

```
%a+matrix4 (error Mtrix dimension must agree)
pi*A
```

```
ans =
    3.1416    6.2832
    9.4248   12.5664
```

```
3/8*8*sqrt(5)*sym(-5/8*A)
```

```
ans =
```

$$\begin{pmatrix} -\frac{15\sqrt{5}}{8} & -\frac{15\sqrt{5}}{4} \\ -\frac{45\sqrt{5}}{8} & -\frac{15\sqrt{5}}{2} \end{pmatrix}$$

```
double ans
```

```
ans =
    97    110    115
```

```
help double
```

double Convert to double precision.

double(X) returns the double precision value for X.

If X is already a double precision array, **double** has no effect.

double is called for the expressions in FOR, IF, and WHILE loops if the expression isn't already double precision. **double** should be overloaded for all objects where it makes sense to convert it into a double precision value.

See also `single`, `datatypes`, `isfloat`, `isnumeric`.

Reference page for double
Other functions named double

```
C=[1 2 3;4 5 6;7 8 9]
```

```
C =
     1     2     3
     4     5     6
     7     8     9
```

```
i*C
```

```
ans =
    0.0000 + 1.0000i    0.000
    0.0000 + 4.0000i    0.000
    0.0000 + 7.0000i    0.000
```

```
(3-8i)*C
```

```
ans =  
    3.0000 - 8.0000i    6.000  
   12.0000 -32.0000i   15.000  
   21.0000 -56.0000i   24.000
```

```
vector1=[1 2 3 5 4 86 6]
```

```
vector1 =  
    1     2     3     5     4    86     6
```

```
sum(vector1)
```

```
ans = 107
```

```
matrix=[1 2 3;4 5 6;7 8 9]
```

```
matrix =  
    1     2     3  
    4     5     6  
    7     8     9
```

```
sum(matrix) %return the sum of the column
```

```
ans =  
    12    15    18
```

```
sum(ans)
```

```
ans = 45
```

```
sum(sum(matrix))
```

```
ans = 45
```

Min Max element in matrix

```
vector1=[1 2 3 5 4 86 6]
```

```
vector1 =  
    1     2     3     5     4    86     6
```

```
min(vector1)
```

```
ans = 1
```

```
max(vector1)
```

```
ans = 86
```

```
A=[1 2 -4 6 8;-9 0 12 -85 9;102 6 9 -23 76]
```



```
A =
     1     2    -4     6     8
    -9     0    12   -85     9
   102     6     9   -23    76
```

```
min(A) %return min of each column
```

```
ans =
    -9     0    -4   -85     8
```

```
min(ans)
```

```
ans = -85
```

```
max(A) %return max of each column
```

```
ans =
   102     6    12     6    76
```

```
max(ans)
```

```
ans = 102
```

```
min(min(A))
```

```
ans = -85
```

```
max(max(A))
```

```
ans = 102
```

size and numel function

```
size(A)
```

```
ans =
     3     5
```

```
numel(A)
```

```
ans = 15
```

augment a matrix

```
A=[1 2 3;4 5 6;6 7 8]
```

```
A =
     1     2     3
     4     5     6
     6     7     8
```

```
B=[5 6;4 3]
```

```
B =  
     5     6  
     4     3
```

```
%c=[A;B] ERROR using vertcat.  
% dimensions of arrays being  
% concatenated are not consistent
```

```
B=[5 6 5;4 3 7]
```

```
B =  
     5     6     5  
     4     3     7
```

```
C=[A;B]
```

```
C =  
     1     2     3  
     4     5     6  
     6     7     8  
     5     6     5  
     4     3     7
```

important functions for working with Matrices

```
A=[1 2 3;4 5 6;6 7 8]
```

```
A =  
     1     2     3  
     4     5     6  
     6     7     8
```

```
sin(A)
```

```
ans =  
     0.8415     0.9093     0.1411  
    -0.7568    -0.9589    -0.2794  
    -0.2794     0.6570     0.9894
```

```
sinh(A)
```

```
ans =  
     0.0012     0.0036     0.0100  
     0.0273     0.0742     0.2017  
     0.2017     0.5483     1.4905
```

```
sqrt(A)
```

```
ans =  
     1.0000     1.4142     1.7321  
     2.0000     2.2361     2.4495
```

2.4495 2.6458 2.8284

```
%doc sqrtm
help sqrtm
```

sqrtm Matrix square root.

$X = \text{sqrtm}(A)$ is the principal square root of the square matrix A .
That is, $X*X = A$.

X is the unique square root for which every eigenvalue has nonnegative real part. If A has any real, negative eigenvalues then a complex result is produced. If A is singular then A may not have a square root. A warning is printed if exact singularity is detected.

$[X, \text{RESNORM}] = \text{sqrtm}(A)$ does not print any warning, and returns the residual, $\text{norm}(A-X^2,1)/\text{norm}(A,1)$.

$[X, \text{ALPHA}, \text{CONDX}] = \text{sqrtm}(A)$ returns a stability factor ALPHA and an estimate CONDX of the matrix square root condition number of X , in the 1-norm. The residual $\text{norm}(A-X^2,1)/\text{norm}(A,1)$ is bounded approximately by $N*\text{ALPHA}*\text{EPS}$ and the 1-norm relative error in X is bounded approximately by $N*\text{ALPHA}*\text{CONDX}*\text{EPS}$, where N is the size of the matrix.

See also `expm`, `logm`, `funm`.

Reference page for `sqrtm`
Other functions named `sqrtm`

$X = \text{sqrtm}(A)$

```
X =
 0.4518 + 0.7500i    0.564
 1.0328 - 0.0000i    1.291
 1.4201 - 0.5000i    1.775
```

$X*X$

```
ans =
 1.0000 - 0.0000i    2.000
 4.0000 - 0.0000i    5.000
 6.0000 - 0.0000i    7.000
```

$\text{exp}(A)$

```
ans =
 0.0027    0.0074    0.0201
 0.0546    0.1484    0.4034
 0.4034    1.0966    2.9810
```

$\text{expm}(A)$

```
ans =
 0.3814    0.4767    0.5721
 0.8717    1.0897    1.3076
 1.1986    1.4983    1.7980
```

`log(A)`

```
ans =  
      0      0.6931      1.0986  
  1.3863      1.6094      1.7918  
  1.7918      1.9459      2.0794
```

`logm(A)`

Warning: Principal matrix logarithm is not defined for A with nonpositive real eigenvalues. A non-principal matrix logarithm is returned.

```
ans =  
-4.6228 + 2.3562i  12.741  
10.5997 - 0.0000i -23.791  
-3.9458 - 1.5708i  13.588
```

`logm(expm(A))`

```
ans =  
  1.0000      2.0000      3.0000  
  4.0000      5.0000      6.0000  
  6.0000      7.0000      8.0000
```

`log(exp(A))`

```
ans =  
  1      2      3  
  4      5      6  
  6      7      8
```

`A^2`

```
ans =  
  27      33      39  
  60      75      90  
  82     103     124
```

`A.^2`

```
ans =  
  1      4      9  
  16     25     36  
  36     49     64
```

Special matrices

`A=zeros(5)`

```
A =  
  0      0      0      0      0  
  0      0      0      0      0  
  0      0      0      0      0
```

```
0 0 0 0 0
0 0 0 0 0
```

`ones(5)`

```
ans =
1 1 1 1 1
1 1 1 1 1
1 1 1 1 1
1 1 1 1 1
1 1 1 1 1
```

`zeros(3,4)`

```
ans =
0 0 0 0
0 0 0 0
0 0 0 0
```

`ones(3,5)`

```
ans =
1 1 1 1 1
1 1 1 1 1
1 1 1 1 1
```

`eye(4)`

```
ans =
1 0 0 0
0 1 0 0
0 0 1 0
0 0 0 1
```

`eye(3,5)`

```
ans =
1 0 0 0 0
0 1 0 0 0
0 0 1 0 0
```

`eye(4,3)`

```
ans =
1 0 0
0 1 0
0 0 1
0 0 0
```

`help magic`

```
magic Magic square.
magic(N) is an N-by-N matrix constructed from the integers
1 through N^2 with equal row, column, and diagonal sums.
Produces valid magic squares for all N > 0 except N = 2.
```

magic(3)

```
ans =
     8     1     6
     3     5     7
     4     9     2
```

magic(5)

```
ans =
    17    24     1     8    15
    23     5     7    14    16
     4     6    13    20    22
    10    12    19    21     3
    11    18    25     2     9
```

Transpose of the vector**A=[1 2 3 4;5 6 8 9]**

```
A =
     1     2     3     4
     5     6     8     9
```

A'

```
ans =
     1     5
     2     6
     3     8
     4     9
```

A=[1 2 3;4 5 6;6 7 8]

```
A =
     1     2     3
     4     5     6
     6     7     8
```

D=diag(A)

```
D =
     1
     5
     8
```

D'

```
ans =
     1     5     8
```

```
triu(A)
```

```
ans =  
     1     2     3  
     0     5     6  
     0     0     8
```

```
tril(A)
```

```
ans =  
     1     0     0  
     4     5     0  
     6     7     8
```

```
triu(A)+tril(A)
```

```
ans =  
     2     2     3  
     4    10     6  
     6     7    16
```

solve equations using Matrices-

rref(reduced row echelon form) function

```
help rref
```

rref Reduced row echelon form.

`R = rref(A)` produces the reduced row echelon form of `A`.

`[R,jb] = rref(A)` also returns a vector, `jb`, so that:

`r = length(jb)` is this algorithm's idea of the rank of `A`,

`x(jb)` are the bound variables in a linear system, $Ax = b$,

`A(:,jb)` is a basis for the range of `A`,

`R(1:r,jb)` is the `r`-by-`r` identity matrix.

`[R,jb] = rref(A,TOL)` uses the given tolerance in the rank tests.

Roundoff errors may cause this algorithm to compute a different value for the rank than `RANK`, `ORTH` and `NULL`.

Class support for input `A`:

float: double, single

See also `rank`, `orth`, `null`, `qr`, `svd`.

Reference page for `rref`

Other functions named `rref`

$$4x+3y=5$$

$$5x+8y=3$$

```
A=[4 3 5;5 8 3]
```

```
A =
```

4	3	5
5	8	3

rref(A)

```
ans =
    1.0000    0    1.8235
         0    1.0000   -0.7647
```

B=[1 3 -2 6;5 6 4 7;1 -23 8 2]

```
B =
     1     3    -2     6
     5     6     4     7
     1   -23     8     2
```

rref(B)

```
ans =
    1.0000    0    0    3.8029
         0    1.0000    0   -0.6350
         0     0    1.0000   -2.0511
```

trace,inverse...

A=[10 2 3;7 5 6;6 7 8]

```
A =
    10     2     3
     7     5     6
     6     7     8
```

trace(A)

```
ans = 23
```

rank(A)

```
ans = 3
```

det(A)

```
ans = -3.0000
```

inv(A)

```
ans =
    0.6667   -1.6667    1.0000
    6.6667  -20.6667   13.0000
   -6.3333   19.3333  -12.0000
```


symbolic calculation in matrix

syms x A B

A=[2-x 3*x^3;4*x^2-3*x, 9*x^3+2]

A =

$$\begin{pmatrix} 2-x & 3x^3 \\ 4x^2-3x & 9x^3+2 \end{pmatrix}$$

B=[2*x-x^3 8*x+1;x-x^3 5*x+8*x^3]

B =

$$\begin{pmatrix} 2x-x^3 & 8x+1 \\ x-x^3 & 5x^3+8x \end{pmatrix}$$

inv(A)

ans =

$$\begin{pmatrix} -\frac{9x^3+2}{\sigma_1} & \frac{3x^3}{\sigma_1} \\ -\frac{3x-4x^2}{\sigma_1} & \frac{x-2}{\sigma_1} \end{pmatrix}$$

where

$$\sigma_1 = 2(6x^5 - 9x^3 + x - 2)$$

A*B

ans =

$$\begin{pmatrix} 3x^3(x-x^3) - \sigma_4(x-2) & 3x^3\sigma_1 - (8x+1)(x-2) \\ (x-x^3)\sigma_3 - \sigma_4\sigma_2 & \sigma_1\sigma_3 - (8x+1)\sigma_2 \end{pmatrix}$$

where

$$\sigma_1 = 8x^3 + 5x$$

$$\sigma_2 = 3x - 4x^2$$

$$\sigma_3 = 9x^3 + 2$$

$$\sigma_4 = 2x - x^3$$

```
A.*B
```

```
ans =
```

$$\begin{pmatrix} -(2x - x^3)(x - 2) & 3x^3(8x + 1) \\ -(x - x^3)(3x - 4x^2) & (8x^3 + 5x)(9x^3 + 2) \end{pmatrix}$$

```
trace(B)
```

```
ans = 7x^3 + 7x
```

```
det(A)
```

```
ans = -12x^5 + 18x^3 - 2x + 4
```

Introduction to Calculus and Engineering Functions in Matlab

Create Functions in Matlab-

sin(),abs(),...etc are some predefined function now we are going to make a customised function.

```
pramod=inline('abs(x)','x')
```

```
pramod =
```

```
Inline function:  
pramod(x) = abs(x)
```

```
pramod(3)
```

```
ans = 3
```

```
pramod(-5)
```

```
ans = 5
```

```
clear pramod  
%pramod(5) ERROR
```

```
new=inline('exp(x)-abs(x)+sqrt(x)','x')
```

```
new =
```

```
Inline function:  
new(x) = exp(x)-abs(x)+sqrt(x)
```

```
new(0)
```

```
ans = 1
```

```
new(-2)
```

```
ans = -1.8647 + 1.4142i
```

```
clear new
```

```
parabolic=inline('sin(x)+cos(y)','x','y')
```

```
parabolic =
```

```
Inline function:
```

```
parabolic(x,y) = sin(x)+cos(y)
```

```
parabolic(2,6)
```

```
ans = 1.8695
```

```
parabolic(0,0)
```

```
ans = 1
```

```
parabolic(pi/2,pi/2)
```

```
ans = 1
```

Anonymous Function

Anonymous Functions :

There are times that we can define a Mathematical function only using one expression instead of a separate function Or separate script. That is when we can use the useful [Anonymous Function](#).

We used to have [inline function](#), but that is no longer supported in newer version of Matlab. Therefore, we are going To use the [Anonymous function](#) instead.

$F = @(<arg1>, <arg2>, \dots) <expression>$

Example 1

$$f(t) = t^5 e^{-2t} \cos(3t)$$

```
f=@(t) t.^5 .* exp(-2*t) .* cos(3*t)
```

Example 2

$$g = (x, y, a, b, c) = x^a e^{-bx} \cos(cy)$$

```
g= @(x,y,a,b,c) x.^a .* exp(-b.*x) .*cos(c.*y)
```

```
f=@(t)t.^5.*exp(-2*t).*cos(3*t)
```

```
f = function_handle with value:
```

```
@(t)t.^5.*exp(-2*t).*cos(3*t)
```

```
x=[0:0.1:1]'
```

```
x =  
    0  
    0.1000  
    0.2000  
    0.3000  
    0.4000  
    0.5000  
    0.6000  
    0.7000  
    0.8000  
    0.9000  
    ⋮  
    ⋮
```

```
f(x)
```

```
ans =  
    0  
    0.0000  
    0.0002  
    0.0008  
    0.0017  
    0.0008  
   -0.0053  
   -0.0209  
   -0.0488  
   -0.0882  
    ⋮  
    ⋮
```

```
f(-2)
```

```
ans = -1.6776e+03
```

```
f(0:2)
```

```
ans =  
    0   -0.1340    0.5628
```

```
f(2)
```

```
ans = 0.5628
```

```
A=[1 2 3;4 5 6;7 8 9]
```

```
A =  
    1    2    3  
    4    5    6  
    7    8    9
```

```
f(A)
```

```
ans =  
   -0.1340    0.5628   -0.5488  
    0.2899   -0.1078    0.0315  
   -0.0077    0.0016   -0.0003
```

```
f(rand(6))
```

```
ans =  
    0.0001    0.0003   -0.1151    0.0005    0.0004   -0.0013  
    0.0000   -0.0336   -0.0012   -0.0538   -0.0071   -0.0959  
    0.0009    0.0005    0.0000    0.0004    0.0014    0.0007  
   -0.1154    0.0006    0.0000   -0.1013    0.0013   -0.0353  
    0.0012   -0.0207    0.0005    0.0013   -0.0599   -0.0343  
   -0.0039   -0.0843   -0.0636    0.0002   -0.0039    0.0016
```

```
f=@(t)t.^5*exp(-2*t)*cos(3*t) %without dot
```

```
f = function_handle with value:  
    @(t)t.^5*exp(-2*t)*cos(3*t)
```

```
f(3)
```

```
ans = -0.5488
```

```
%f(-1:0.1:1) ERROR to perform elementwise multiplication use .*  
f=@(t)t.^5.*exp(-2*t).*cos(3*t)
```

```
f = function_handle with value:  
    @(t)t.^5.*exp(-2*t).*cos(3*t)
```

```
f([-1:.1:1])
```

```
ans =  
    7.3151    3.2296    1.1968    0.3441    0.0587   -0.0060   -0.0083   -0.0028 ...
```

```
g=@cos
```

```
g = function_handle with value:  
    @cos
```

```
g(0)
```

```
ans = 1
```

```
g(pi/3)
```

```
ans = 0.5000
```

```
g(pi/2)
```

```
ans = 6.1232e-17
```

```
g=@sin
```

```
g = function_handle with value:
```

```
@sin
```

```
g(0)
```

```
ans = 0
```

```
g(pi/2)
```

```
ans = 1
```

```
help heaviside
```

```
heaviside    Step function.  
heaviside(X) is 0 for X < 0 and 1 for X > 0.  
The value heaviside(0) is 0.5 by default. It  
can be changed to any value v by the call  
sympref('HeavisideAtOrigin', v).  
  
heaviside(X) is not a function in the strict sense.  
See also dirac.  
  
Reference page for heaviside  
Other functions named heaviside
```

```
t=@(x)((heaviside(x+1)-heaviside(x-1)).*(1-abs(x)))
```

```
t = function_handle with value:  
@(x)((heaviside(x+1)-heaviside(x-1)).*(1-abs(x)))
```

```
t(-1)
```

```
ans = 0
```

```
t(1)
```

```
ans = 0
```

```
t(0)
```

```
ans = 1
```

```
t(2)
```

```
ans = 0
```

```
t(0.5)
```

```
ans = 0.5000
```

```
t(0.3)
```

```
ans = 0.7000
```

```
t(0.75)
```

```
ans = 0.2500
```

```
help ezplot
```

```
ezplot (NOT RECOMMENDED) Easy to use function plotter
```

```
=====
ezplot is not recommended. Use Fplot or fimplicit instead.
=====
```

ezplot(FUN) plots the function FUN(X) over the default domain $-2\pi < X < 2\pi$, where FUN(X) is an explicitly defined function of X.

ezplot(FUN2) plots the implicitly defined function $\text{FUN2}(X,Y) = 0$ over the default domain $-2\pi < X < 2\pi$ and $-2\pi < Y < 2\pi$.

ezplot(FUN,[A,B]) plots FUN(X) over $A < X < B$.
ezplot(FUN2,[A,B]) plots $\text{FUN2}(X,Y) = 0$ over $A < X < B$ and $A < Y < B$.

ezplot(FUN2,[XMIN,XMAX,YMIN,YMAX]) plots $\text{FUN2}(X,Y) = 0$ over $X_{\min} < X < X_{\max}$ and $Y_{\min} < Y < Y_{\max}$.

ezplot(FUNX,FUNY) plots the parametrically defined planar curve $\text{FUNX}(T)$ and $\text{FUNY}(T)$ over the default domain $0 < T < 2\pi$.

ezplot(FUNX,FUNY,[TMIN,TMAX]) plots $\text{FUNX}(T)$ and $\text{FUNY}(T)$ over $T_{\min} < T < T_{\max}$.

ezplot(FUN,[A,B],FIG), **ezplot(FUN2,[XMIN,XMAX,YMIN,YMAX],FIG)**, or **ezplot(FUNX,FUNY,[TMIN,TMAX],FIG)** plots the function over the specified domain in the figure window FIG.

ezplot(AX,...) plots into AX instead of GCA or FIG.

H = ezplot(...) returns handles to the plotted objects in H.

Examples:

The easiest way to express a function is via a string:
`ezplot('x^2 - 2*x + 1')`

One programming technique is to vectorize the string expression using the array operators `.*` (TIMES), `./` (RDIVIDE), `.\` (LDIVIDE), `.^` (POWER). This makes the algorithm more efficient since it can perform multiple function evaluations at once.
`ezplot('x.*y + x.^2 - y.^2 - 1')`

You may also use a function handle to an existing function. Function handles are more powerful and efficient than string expressions.
`ezplot(@humps)`
`ezplot(@cos,@sin)`

ezplot plots the variables in string expressions alphabetically.
`subplot(1,2,1), ezplot('1./z - log(z) + log(-1+z) + t - 1')`
To avoid this ambiguity, specify the order with an anonymous function:
`subplot(1,2,2), ezplot(@(z,t)1./z - log(z) + log(-1+z) + t - 1)`

If your function has additional parameters, for example k in myfun:
%-----%
`function z = myfun(x,y,k)`

```

z = x.^k - y.^k - 1;
%-----%
then you may use an anonymous function to specify that parameter:
ezplot(@(x,y)myfun(x,y,2))

See also ezcontour, ezcontourf, ezmesh, ezmeshc, ezplot3, ezpolar,
ezsurf, ezsurfc, plot, vectorize, function_handle.

Reference page for ezplot
Other functions named ezplot

```

help fplot

fplot Plot 2-D function

fplot(FUN) plots the function FUN between the limits of the current axes, with a default of [-5 5].

fplot(FUN,LIMS) plots the function FUN between the x-axis limits specified by LIMS = [XMIN XMAX].

fplot(...,'LineSpec') plots with the given line specification.

fplot(X,Y,LIMS) plots the parameterized curve with coordinates X(T), Y(T) for T between the values specified by LIMS = [TMIN TMAX].

H = **fplot**(...) returns a handle to the function line object created by **fplot**.

fplot(AX,...) plots into the axes AX instead of the current axes.

Examples:

```

fplot(@sin)
fplot(@(x) x.^2.*sin(1./x),[-1,1])
fplot(@(x) sin(1./x), [0 0.1])

```

If your function cannot be evaluated for multiple x values at once, you will get a warning and somewhat reduced speed:

```

f = @(x,n) abs(exp(-1j*x*(0:n-1))*ones(n,1));
fplot(@(x) f(x,10),[0 2*pi])

```

See also fplot3, fsurf, fcontour, fimplicit, plot, function_handle.

Reference page for fplot

```

ezplot(@sin)
fplot(@sin)

ezplot(@tan)
fplot(@tan)

```

```

fplot(@sin,[-1,4])
fplot(@tan,[-2,+2])

```

Introduction to Differentiation

```

syms x
f=inline('sin(x)+2*cos(x)','x')

```


f =

```
Inline function:  
f(x) = sin(x)+2*cos(x)
```

```
f1=diff(f(x),x)
```

f1 = $\cos(x) - 2 \sin(x)$

```
%f1(4) ERROR f1 is not is not recognised as function but just an expression.  
% deine f1 in inline function too for f1(4)  
derivative=inline(diff(f(x),x),'x')
```

derivative =

```
Inline function:  
derivative(x) = cos(x)-sin(x).*2.0
```

```
derivative(4)
```

ans = 0.8600

Differentiation Symbolically

```
syms x  
func=x^3
```

func = x^3

```
%func(2) cause error  
diff(func,x)
```

ans = $3x^2$

```
syms x  
g=sin(x)/(x^2+3*cos(x))
```

g =

$$\frac{\sin(x)}{3 \cos(x) + x^2}$$

```
diff(g,x)
```

ans =

$$\frac{\cos(x)}{3 \cos(x) + x^2} - \frac{\sin(x) (2x - 3 \sin(x))}{(3 \cos(x) + x^2)^2}$$

Integration in Matlab

indefinite

```
f1=inline('exp(x)','x')
```

f1 =

Inline function:
f1(x) = exp(x)

```
f1(3)
```

ans = 20.0855

```
syms x  
integral=int(f1(x),x)
```

integral = e^x

```
f1=inline('x','x')
```

f1 =

Inline function:
f1(x) = x

```
integral=int(f1(x),x)
```

integral =

$$\frac{x^2}{2}$$

```
f2=inline('sin(x)+2*cos(x)','x')
```

f2 =

Inline function:
f2(x) = sin(x)+2*cos(x)

```
integral=int(f2(x),x)
```

integral =

$$-2 \cos\left(\frac{x}{2}\right) \left(\cos\left(\frac{x}{2}\right) - 2 \sin\left(\frac{x}{2}\right)\right)$$

```
integral=int(f2(x))
```

integral =

$$-2 \cos\left(\frac{x}{2}\right) \left(\cos\left(\frac{x}{2}\right) - 2 \sin\left(\frac{x}{2}\right)\right)$$

```
f3=inline('x*y+sin(x+y)-tan(y)+3*exp(x^3)','x','y')
```

f3 =

Inline function:
f3(x,y) = x*y+sin(x+y)-tan(y)+3*exp(x^3)

```
syms y
integral=int(f3(x,y),x)
```

integral =

$$\frac{x^2 y}{2} - x \operatorname{expint}\left(\frac{2}{3}, -x^3\right) - \cos(x+y) - x \tan(y)$$

```
inegral=int(f3(x,y),y)
```

inegral =

$$3 y e^{x^3} - \cos(x+y) - \frac{\log(\tan(y)^2 + 1)}{2} + \frac{x y^2}{2}$$

definite

```
f1
```

f1 =

Inline function:
f1(x) = x

```
integral=int(f1(x),-12,.8)
```

integral =

$$-\frac{1792}{25}$$

```
f2
```

f2 =

Inline function:
f2(x) = sin(x)+2*cos(x)

```
integral=int(f2(x),5,-5)
```

```
integral = -4 sin(5)
```

```
double(ans)
```

```
ans = 20.0855
```

```
f3
```

```
f3 =
```

```
Inline function:
```

```
f3(x,y) = x*y+sin(x+y)-tan(y)+3*exp(x^3)
```

```
integral=int(f3(x,y),x)
```

```
integral =
```

$$\frac{x^2 y}{2} - x \operatorname{expint}\left(\frac{2}{3}, -x^3\right) - \cos(x+y) - x \tan(y)$$

```
integral=int(f3(x,y),-1,4)
```

```
integral =
```

$$\frac{15 y}{2} + \cos(y-1) - \cos(y+4) - 5 \tan(y) - \operatorname{expint}\left(\frac{2}{3}, 1\right) - 4 \operatorname{expint}\left(\frac{2}{3}, -64\right) + 3 \left(\lim_{x \rightarrow 0^-} \sigma_1\right) - 3 \left(\lim_{x \rightarrow 0^+} \sigma_1\right)$$

where

$$\sigma_1 = -\frac{x \operatorname{expint}\left(\frac{2}{3}, -x^3\right)}{3}$$

Limit function

```
f1=inline('sin(x)/x','x')
```

```
f1 =
```

```
Inline function:
```

```
f1(x) = sin(x)/x
```

```
syms x
```

```
limit(f1(x),x,0)
```

```
ans = 1
```

```
syms x y
```

```
f2=inline('(sin(x+y)-sin(x)/y)','x','y')
```

f2 =

Inline function:
f2(x,y) = (sin(x+y)-sin(x)/y)

```
limit(f2(x,y),x,0)
```

ans = sin(y)

```
h=inline((4*x^3-x^2+2*x-1)/(3*x^3-7*x^2-1),'x')
```

h =

Inline function:
h(x) = -(x.*2.0-x.^2+x.^3.*4.0-1.0)./(x.^2.*7.0-x.^3.*3.0+1.0)

```
syms x  
pretty(h(x))
```

$$-\frac{4x^3 - x^2 + 2x - 1}{-3x^3 + 7x^2 + 1}$$

```
limit(h(x),x,0)
```

ans = 1

```
limit(h(x),x,inf)
```

ans =

$$\frac{4}{3}$$

```
syms x a  
v=[(1+a/x)^x exp(-x)]
```

v =

$$\left(\left(\frac{a}{x} + 1 \right)^x e^{-x} \right)$$

```
limit(v,x,inf)
```

ans = (e^a 0)

Partial Derivatives

```
syms x y
f1=inline('x^2+2*y^3','x','y')
```

f1 =

Inline function:
f1(x,y) = x^2+2*y^3

```
d1=diff(f1(x,y),x)
```

d1 = $2x$

```
d2=diff(f1(x,y),y)
```

d2 = $6y^2$

```
f2=inline('x*sin(y)-y^3*sqrt(x^4)','x','y')
```

f2 =

Inline function:
f2(x,y) = x*sin(y)-y^3*sqrt(x^4)

```
d1=diff(f2(x,y),x)
```

d1 =

$$\sin(y) - \frac{2x^3y^3}{\sqrt{x^4}}$$

```
d2=diff(f2(x,y),y)
```

d2 = $x \cos(y) - 3y^2 \sqrt{x^4}$

```
%d2(1,4) ERROR not defined as function for matlab
g2=inline(diff(f2(x,y),y),'x','y')
```

g2 =

Inline function:
g2(x,y) = y.^2.*sqrt(x.^4).*-3.0+x.*cos(y)

```
g2(1,2)
```

ans = -12.4161

```
g2(-1,37)
```

```
ans = -4.1078e+03
```

Graphs & Plots in Matlab

```
x=[1 2 3 4 5 6 7 8 9]
```

```
x =  
    1     2     3     4     5     6     7     8     9
```

```
y=[-1 3 -2 7 8 9 3 6 9]
```

```
y =  
   -1     3    -2     7     8     9     3     6     9
```

```
plot(x,y)  
xlabel('x values')  
ylabel('y values')  
title('my first graph')  
grid on
```

```
x
```

```
x =  
    1     2     3     4     5     6     7     8     9
```

```
y
```

```
y =  
   -1     3    -2     7     8     9     3     6     9
```

```
plot(x,y,'r')  
plot(x,y,'--m*')  
plot(x,y,'-.+')  
plot(x,y,'-.bo')  
plot(x,y,'^')  
plot(x,y,'s')
```

line specification in single ''

```
x=[1 2 3 4 5 6 7 8 9]
```

```
x =  
    1     2     3     4     5     6     7     8     9
```

```
y=[-1 3 -2 7 8 9 3 6 9]
```

```
y =
```

-1 3 -2 7 8 9 3 6 9

```
plot(x,y, 'om-.'
```

Plotting more than one function on single plot - hold on/off

```
x=0:pi/150:2*pi
```

```
x =
    0    0.0209    0.0419    0.0628    0.0838    0.1047    0.1257    0.1466 ...
```

```
y1=sin(4*x)
```

```
y1 =
    0    0.0837    0.1668    0.2487    0.3289    0.4067    0.4818    0.5534 ...
```

```
plot(x,y1)
hold on
y2=sin(x)
```

```
y2 =
    0    0.0209    0.0419    0.0628    0.0837    0.1045    0.1253    0.1461 ...
```

```
plot(x,y2, 'r')
```

```
plot(x,y1, 'r+--',x,y2, 'c:d')
```

```
hold off
y1=sin(x)*2
```

```
y1 =
    0    0.0419    0.0838    0.1256    0.1674    0.2091    0.2507    0.2922 ...
```

```
y2=sin(x)*3
```

```
y2 =
    0    0.0628    0.1256    0.1884    0.2510    0.3136    0.3760    0.4382 ...
```

```
y3=sin(x)*4
```

```
y3 =
    0    0.0838    0.1675    0.2512    0.3347    0.4181    0.5013    0.5843 ...
```

```
y4=sin(x)*5
```

```
y4 =
    0    0.1047    0.2094    0.3140    0.4184    0.5226    0.6267    0.7304 ...
```

```
plot(x,y1, 'o',x,y2, '--',x,y3, 'd',x,y4, 's')
```


Subplot

subplot will have three element- subplot(m,n,p)

help [subplot](#)

subplot Create axes in tiled positions.

H = **subplot**(m,n,p), or **subplot**(mnp), breaks the Figure window into an m-by-n matrix of small axes, selects the p-th axes for the current plot, and returns the axes handle. The axes are counted along the top row of the Figure window, then the second row, etc. For example,

```
subplot(2,1,1), PLOT(income)
subplot(2,1,2), PLOT(outgo)
```

plots income on the top half of the window and outgo on the bottom half. If the CurrentAxes is nested in a uipanel the panel is used as the parent for the subplot instead of the current figure.

subplot(m,n,p), if the axes already exists, makes it current.
subplot(m,n,p,'replace'), if the axes already exists, deletes it and creates a new axes.

subplot(m,n,p,'align') places the axes so that the plot boxes are aligned, but does not prevent the labels and ticks from overlapping.

subplot(m,n,P), where P is a vector, specifies an axes position that covers all the subplot positions listed in P.

subplot(H), where H is an axes handle, is another way of making an axes current for subsequent plotting commands.

subplot('position',[left bottom width height]) creates an axes at the specified position in normalized coordinates (in the range from 0.0 to 1.0).

subplot(..., PROP1, VALUE1, PROP2, VALUE2, ...) sets the specified property-value pairs on the subplot axes. To add the subplot to a specific figure pass the figure handle as the value for the 'Parent' property.

If a **subplot** specification causes a new axes to overlap an existing axes, the existing axes is deleted - unless the position of the new and existing axes are identical. For example, the statement **subplot**(1,2,1) deletes all existing axes overlapping the left side of the Figure window and creates a new axes on that side - unless there is an axes there with a position that exactly matches the position of the new axes (and 'replace' was not specified), in which case all other overlapping axes will be deleted and the matching axes will become the current axes.

subplot(111) is an exception to the rules above, and is not identical in behavior to **subplot**(1,1,1). For reasons of backwards compatibility, it is a special case of subplot which does not immediately create an axes, but instead sets up the figure so that the next graphics command executes CLF RESET in the figure (deleting all children of the figure), and creates a new axes in the default position. This syntax does not return a handle, so it is an error to specify a return argument. The delayed CLF RESET is accomplished by setting the figure's NextPlot to 'replace'.

Be aware when creating subplots from scripts that the Position

property of subplots is not finalized until either a `drawnow` command is issued, or MATLAB returns to await a user command. That is, the value obtained for subplot *i* by the command `h(i).Position` will not be correct until the script refreshes the plot or exits.

See also `gca`, `gcf`, `axes`, `figure`, `uipanel`

Reference page for `subplot`

```
subplot(2,2,1)
plot(x,sin(x))

subplot(2,1,1)
plot(x,sin(x))

subplot(2,1,2)
plot(x,cos(x))
plot(x,cos(x),'r--')
```

```
y1=sin(x)*2;
y2=sin(x)*3;
y3=sin(x)*4;
y4=sin(x)*5;
bar3(y1)
```

```
x=[1 2 5 3 9];
y=[x;1:5]
```

```
y =
     1     2     5     3     9
     1     2     3     4     5
```

```
subplot(2,2,1)
bar(x),title('a bar graph for vector x')
subplot(2,2,2)
bar(y),title('bar graph for y')
subplot(2,2,3)
bar3(y),title('this is a bar3 graph for y ')
subplot(2,2,4)
pie(x),title('this is apie graph for x')
clear
```

plot in easy way

```
close all hidden
x=0:0.5:2*pi
```

```
x =
```

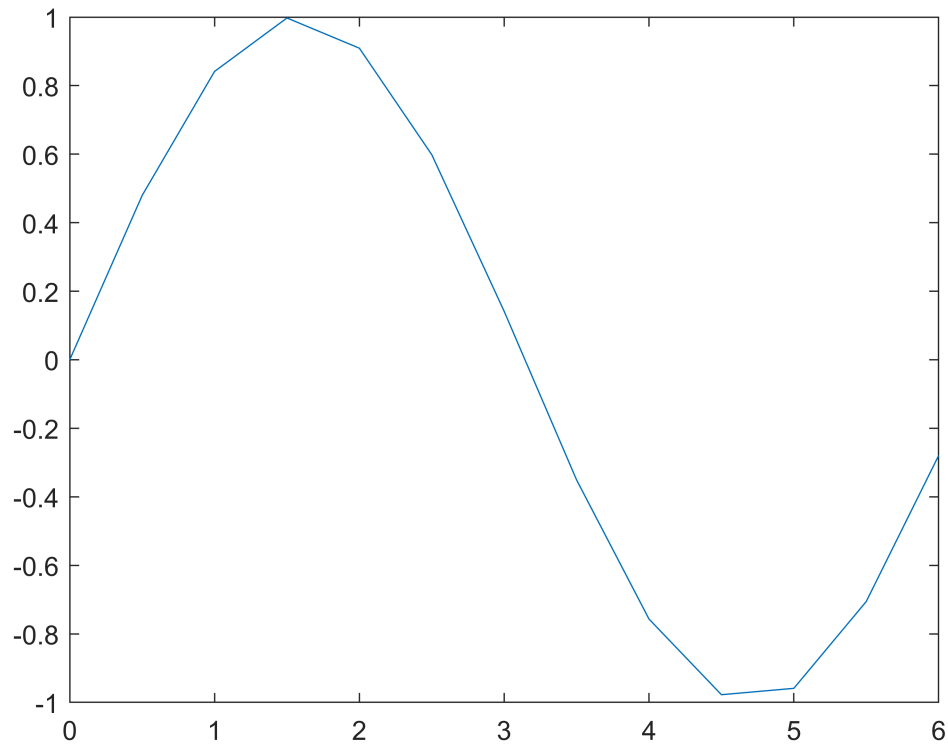
```
0    0.5000    1.0000    1.5000    2.0000    2.5000    3.0000    3.5000 ...
```

```
y=sin(x)
```

```
y =
```

```
0    0.4794    0.8415    0.9975    0.9093    0.5985    0.1411   -0.3508 ...
```

```
plot(x,y)
```



Loops, Conditions, and Intro to Programming in Matlab

```
x=4;  
y=-2;  
x<y
```

```
ans = logical  
0
```

```
x>y
```

```
ans = logical  
1
```

```
x=1:5
```

```
x =  
    1     2     3     4     5
```

```
y=x+3
```

```
y =  
    4     5     6     7     8
```

```
x<y
```

```
ans = 1x5 logical array  
    1    1    1    1    1
```

```
x>y
```

```
ans = 1x5 logical array  
    0    0    0    0    0
```

```
y=[2 1 -1 5 9]
```

```
y =  
    2     1    -1     5     9
```

```
x>y
```

```
ans = 1x5 logical array  
    0    1    1    0    0
```

```
y>x
```

```
ans = 1x5 logical array  
    1    0    0    1    1
```

```
x<=y
```

```
ans = 1x5 logical array  
    1    0    0    1    1
```

```
x>=y
```

```
ans = 1x5 logical array  
    0    1    1    0    0
```

```
x==y
```

```
ans = 1x5 logical array  
    0    0    0    0    0
```

```
x~=y %not equal
```

```
ans = 1x5 logical array  
    1    1    1    1    1
```

```
x=[-1 2 0 4 6]
```

```
x =  
   -1     2     0     4     6
```

```
y=[2 1 0 5 9]
```

```
y =  
     2     1     0     5     9
```

```
x~=y
```

```
ans = 1x5 logical array  
    1    1    0    1    1
```

```
x==y
```

```
ans = 1x5 logical array  
    0    0    1    0    0
```

Logical operator

and &

not -

or |

exclusively or xor

```
x=[1 2 3 4 5];  
y=[-2 0 2 4 6];  
x<y
```

```
ans = 1x5 logical array  
    0    0    0    0    1
```

```
z=[8 8 8 8 8];  
z>x & z>y
```

```
ans = 1x5 logical array  
    1    1    1    1    1
```

```
z>x | z>y
```

```
ans = 1x5 logical array
     1     1     1     1     1
```

```
x>y | x>z
```

```
ans = 1x5 logical array
     1     1     1     0     0
```

```
x>y & x>z
```

```
ans = 1x5 logical array
     0     0     0     0     0
```

```
speed=[63 67 65 55 69 40 95]
```

```
speed =
     63     67     65     55     69     40     95
```

```
result=find(speed>=65)
```

```
result =
         2         3         5         7
```

```
speed(result)
```

```
ans =
     67     65     69     95
```

Conditions in Matlab and and Introduction to Else

```
x=3;
if x<4
    disp('x is les than 4')
    disp(x)
end
```

```
x is les than 4
     3
```

```
x=5;
if x<4
    disp('x is les than 4')
    disp(x)
end
```

```
x=5
```

```
x = 5
```

```
if x>0
    y=log(x)
else
    disp("input of log can't be negative")
end
```

```
y = 1.6094
```

```
x=-6
```

```
x = -6
```

```
if x>0
    y=log(x)
else
    disp("input of log can't be negative")
end
```

```
input of log can't be negative
```

for loop

```
x=-4
```

```
x = -4
```

```
if x>0
    y=log(x)
else
    beep
    disp("input of log can't be negative")
end
```

```
input of log can't be negative
```

```
scores=[30 65 91 87 56 93 52 99 90];
count=0
```

```
count = 0
```

```
for k=1:length(scores)
    if scores(k)>90
        count=count+1
    end
end
```

```
count = 1  
count = 2  
count = 3
```

```
disp(count)
```

3

```
scores=[30 65 91 87 56 93 52 99 90];  
count=0;  
for k=1:length(scores)  
    if scores(k)>90  
        count=count+1;  
    end  
end  
disp(count)
```

3

elseif

```
age=15
```

```
age = 15
```

```
if age<16  
    disp('sorry you are too young too apply')  
elseif age<18  
    disp('yopu can apply for youth lecense')  
elseif age<70  
    disp('you may have standerd driving license')  
else  
    disp('driver over 70 will require aspecial license')  
end
```

```
sorry you are too young too apply
```

```
age=16
```

```
age = 16
```

```
if age<16  
    disp('sorry you are too young too apply')  
elseif age<18  
    disp('yopu can apply for youth lecense')  
elseif age<70  
    disp('you may have standerd driving license')  
else
```



```
disp('driver over 70 will require aspecial license')
end
```

yopu can apply for youth lecense

```
age=65;
if age<16
    disp('sorry you are too young too apply')
elseif age<18
    disp('yopu can apply for youth lecense')
elseif age<70
    disp('you may have standerd driving license')
else
    disp('driver over 70 will require aspecial license')
end
```

you may have standerd driving license

```
age=71;
if age<16
    disp('sorry you are too young too apply')
elseif age<18
    disp('yopu can apply for youth lecense')
elseif age<70
    disp('you may have standerd driving license')
else
    disp('driver over 70 will require aspecial license')
end
```

driver over 70 will require aspecial license

while loop

```
k=0;
while k<3
    k=k+1
end
```

k = 1
k = 2
k = 3

```
scores=[30 65 91 87 56 93 52 99 90];
count=0;
k=0;
while k<length(scores)
    k=k+1;
```

```

    if scores(k)>90
        count=count+1;

    end
end
disp(count)

```

3

for index[matrix]

commands to be execute

end

```

for i=[11 52 83]
    i
end

```

```

i = 11
i = 52
i = 83

```

```

i

```

```

i = 83

```

```

for k=1:4
    a=6^k
end

```

```

a = 6
a = 36
a = 216
a = 1296

```

Let's Code some Matlab Projects in Matlab

```

x=[12 13 87 31]

```

```

x =
    12    13    87    31

```

```

N=[5 1 7 54]

```

```

N =

```

5 1 7 54

```
xsize= size(x)
```

```
xsize =  
      1      4
```

```
Nsize= size(N)
```

```
Nsize =  
      1      4
```

```
if Nsize(2)~=xsize(2)  
    disp('Error-size should be equa')  
else  
    total=sum(N)  
    average=sum(x.*N)/total  
end
```

```
total = 67  
average = 35.1642
```

Project 1- Let's Create a function in Matlab with Example

```
%or we can save a function  
%here first argument in Numbers, and second is repetition.  
% function average=avg(x,N)  
%     xsize= size(x)  
%     Nsize= size(N)  
%     if Nsize(2)~=xsize(2)  
%         disp('Error-size should be equa')  
%     else  
%         total=sum(N)  
%         average=sum(x.*N)/total  
%     end  
% end
```

```
avg(x,N)
```

```
average = 35.1642  
ans = 35.1642
```

```
y=[1 25 6 68 97 85 24 56]
```

```
y =  
      1      25      6      68      97      85      24      56
```

```
M=[1 4 5 8 6 3 25 98]
```

```
M =  
    1     4     5     8     6     3    25    98
```

```
avg(y,M)
```

```
average = 50.6667  
ans = 50.6667
```

```
avg(y,N)
```

Error-size should be equal

```
avg(x,M)
```

Error-size should be equal

Project 2: How to evaluate a Polynomial for any number in Matlab

```
% function output=poly(x)  
% output=458.*x.^3+2.5*x.^2+137.*x+1;  
% end
```

```
poly(1)
```

```
ans = 621
```

```
poly(17)
```

```
ans = 2259709
```

```
poly([1 2 3 45])
```

```
ans =  
    621    4039    13003   41792041
```

Project 3 : Automate finding the area of a triangle for any base and height

```
a = input('enter the value for a: ')
```

```
a = 10
```

```
name=input('what is your name: ') %here string are not acceptable
```

```
name = 20
```

```
%for string input
```

```
name=input('what is your name: ','s')
```

```
name =  
'pky'
```

num2str

```
x=[1 2 3]
```

```
x =  
    1     2     3
```

```
y=[5 9 8]
```

```
y =  
    5     9     8
```

```
x+y
```

```
ans =  
    6    11    11
```

```
x=num2str(x)
```

```
x =  
'1  2  3'
```

```
%x+y here this error as x is now a string
```

```
%in this we are developing program to find area  
% of triangle via side input by user
```

```
b=input('enter the value of base: ');  
h=input('enter the value of height: ');  
triangle_area=0.5*h*b;  
disp(['the value for area is: ' num2str(triangle_area)])
```

```
the value for area is: 130
```

Import Excel in Matlab and change the data

- Put your excel file in matlab directory
- XLSREAD('name of the file')
- different argument when importing excel file into
MATLAB- **[num,text,row]=xlsread('name_of_the_xl_file')**
- 'ls' command give all xl file in the directory

```
ls
```

```
.          MATLAB_Introduction1.pdf  poly.m
..         anonymous.png            test_book.xlsx
MATLAB_Introduction1.mlx  avg.m
```

```
data=xlsread('test_book')
```

```
data =
    1.0000    52.0000   160.0000     2.0000     0.1783     0.0857     2.0000
    2.0000    49.0000   150.0000     3.0000     0.7597     0.2586     2.0000
    3.0000    39.0000   122.0000     1.0000     0.9149     0.3568     2.0000
    4.0000    58.0000   133.0000     5.0000     0.8159     0.2589     3.0000
    5.0000    52.0000   148.0000     3.0000     0.9169     0.7852     3.0000
    6.0000    41.0000   147.0000     2.0000     0.6169     0.1785     3.0000
    7.0000    32.0000   158.0000     1.0000     0.9179     0.6785     5.0000
    8.0000    65.0000   169.0000     2.0000     0.8199     0.5785     2.0000
    9.0000    45.0000    45.0000     3.0000     0.7149     0.6785     2.0000
   10.0000    52.0000   163.0000     4.0000     0.9186     0.7852     2.0000
    :
    :
```

```
[A,B,C]=xlsread('test_book')
```

```
A =
    1.0000    52.0000   160.0000     2.0000     0.1783     0.0857     2.0000
    2.0000    49.0000   150.0000     3.0000     0.7597     0.2586     2.0000
    3.0000    39.0000   122.0000     1.0000     0.9149     0.3568     2.0000
    4.0000    58.0000   133.0000     5.0000     0.8159     0.2589     3.0000
    5.0000    52.0000   148.0000     3.0000     0.9169     0.7852     3.0000
    6.0000    41.0000   147.0000     2.0000     0.6169     0.1785     3.0000
    7.0000    32.0000   158.0000     1.0000     0.9179     0.6785     5.0000
    8.0000    65.0000   169.0000     2.0000     0.8199     0.5785     2.0000
    9.0000    45.0000    45.0000     3.0000     0.7149     0.6785     2.0000
   10.0000    52.0000   163.0000     4.0000     0.9186     0.7852     2.0000
    :
    :
```

```
B = 1x7 cell array
    {'time'}    {'pressure'}    {'temp'}    {'level'}    {'density'}    {'viscosity'}    {'velocity'}
```

```
C = 19x7 cell array
    {'time'}    {'pressure'}    {'temp'}    {'level'}    {'density'}    {'viscosity'}    {'velocity'}
    {[ 1]}    {[ 52]}    {[ 160]}    {[ 2]}    {[ 0.1783]}    {[ 0.0857]}    {[ 2]}
    {[ 2]}    {[ 49]}    {[ 150]}    {[ 3]}    {[ 0.7597]}    {[ 0.2586]}    {[ 2]}
    {[ 3]}    {[ 39]}    {[ 122]}    {[ 1]}    {[ 0.9149]}    {[ 0.3568]}    {[ 2]}
    {[ 4]}    {[ 58]}    {[ 133]}    {[ 5]}    {[ 0.8159]}    {[ 0.2589]}    {[ 3]}
    {[ 5]}    {[ 52]}    {[ 148]}    {[ 3]}    {[ 0.9169]}    {[ 0.7852]}    {[ 3]}
    {[ 6]}    {[ 41]}    {[ 147]}    {[ 2]}    {[ 0.6169]}    {[ 0.1785]}    {[ 3]}
    {[ 7]}    {[ 32]}    {[ 158]}    {[ 1]}    {[ 0.9179]}    {[ 0.6785]}    {[ 5]}
    {[ 8]}    {[ 65]}    {[ 169]}    {[ 2]}    {[ 0.8199]}    {[ 0.5785]}    {[ 2]}
    {[ 9]}    {[ 45]}    {[ 45]}    {[ 3]}    {[ 0.7149]}    {[ 0.6785]}    {[ 2]}
    {[ 10]}    {[ 52]}    {[ 163]}    {[ 4]}    {[ 0.9186]}    {[ 0.7852]}    {[ 2]}
    {[ 11]}    {[ 55]}    {[ 123]}    {[ 5]}    {[ 0.8561]}    {[ 0.5785]}    {[ 2]}
    {[ 12]}    {[ 49]}    {[ 157]}    {[ 2]}    {[ 0.9566]}    {[ 0.8785]}    {[ 3]}
    {[ 13]}    {[ 48]}    {[ 145]}    {[ 3]}    {[ 0.9149]}    {[ 0.9785]}    {[ 9]}
    {[ 14]}    {[ 45]}    {[ 56]}    {[ 4]}    {[ 0.9179]}    {[ 0.4785]}    {[ 5]}
    {[ 15]}    {[ 42]}    {[ 6]}    {[ 2]}    {[ 0.8157]}    {[ 0.5785]}    {[ 2]}
    {[ 16]}    {[ 47]}    {[ 125]}    {[ 2]}    {[ 0.8210]}    {[ 0.6785]}    {[ 4]}
```

{[17]}	{[35]}	{[153]}	{[2]}	{[0.8156]}	{[0.7785]}	{[3]}
{[18]}	{[44]}	{[158]}	{[3]}	{[0.9358]}	{[0.6785]}	{[4]}

```
[~,B,~]=xlsread('test_book')
```

B = 1x7 cell array

'time'	'pressure'	'temp'	'level'	'density'	'viscosity'	'velocity'
--------	------------	--------	---------	-----------	-------------	------------

```
[A,~,~]=xlsread('test_book')
```

A =

1.0000	52.0000	160.0000	2.0000	0.1783	0.0857	2.0000
2.0000	49.0000	150.0000	3.0000	0.7597	0.2586	2.0000
3.0000	39.0000	122.0000	1.0000	0.9149	0.3568	2.0000
4.0000	58.0000	133.0000	5.0000	0.8159	0.2589	3.0000
5.0000	52.0000	148.0000	3.0000	0.9169	0.7852	3.0000
6.0000	41.0000	147.0000	2.0000	0.6169	0.1785	3.0000
7.0000	32.0000	158.0000	1.0000	0.9179	0.6785	5.0000
8.0000	65.0000	169.0000	2.0000	0.8199	0.5785	2.0000
9.0000	45.0000	45.0000	3.0000	0.7149	0.6785	2.0000
10.0000	52.0000	163.0000	4.0000	0.9186	0.7852	2.0000
⋮						
⋮						

```
[~,~,C]=xlsread('test_book')
```

C = 19x7 cell array

'time'	'pressure'	'temp'	'level'	'density'	'viscosity'	'velocity'
{[1]}	{[52]}	{[160]}	{[2]}	{[0.1783]}	{[0.0857]}	{[2]}
{[2]}	{[49]}	{[150]}	{[3]}	{[0.7597]}	{[0.2586]}	{[2]}
{[3]}	{[39]}	{[122]}	{[1]}	{[0.9149]}	{[0.3568]}	{[2]}
{[4]}	{[58]}	{[133]}	{[5]}	{[0.8159]}	{[0.2589]}	{[3]}
{[5]}	{[52]}	{[148]}	{[3]}	{[0.9169]}	{[0.7852]}	{[3]}
{[6]}	{[41]}	{[147]}	{[2]}	{[0.6169]}	{[0.1785]}	{[3]}
{[7]}	{[32]}	{[158]}	{[1]}	{[0.9179]}	{[0.6785]}	{[5]}
{[8]}	{[65]}	{[169]}	{[2]}	{[0.8199]}	{[0.5785]}	{[2]}
{[9]}	{[45]}	{[45]}	{[3]}	{[0.7149]}	{[0.6785]}	{[2]}
{[10]}	{[52]}	{[163]}	{[4]}	{[0.9186]}	{[0.7852]}	{[2]}
{[11]}	{[55]}	{[123]}	{[5]}	{[0.8561]}	{[0.5785]}	{[2]}
{[12]}	{[49]}	{[157]}	{[2]}	{[0.9566]}	{[0.8785]}	{[3]}
{[13]}	{[48]}	{[145]}	{[3]}	{[0.9149]}	{[0.9785]}	{[9]}
{[14]}	{[45]}	{[56]}	{[4]}	{[0.9179]}	{[0.4785]}	{[5]}
{[15]}	{[42]}	{[6]}	{[2]}	{[0.8157]}	{[0.5785]}	{[2]}
{[16]}	{[47]}	{[125]}	{[2]}	{[0.8210]}	{[0.6785]}	{[4]}
{[17]}	{[35]}	{[153]}	{[2]}	{[0.8156]}	{[0.7785]}	{[3]}
{[18]}	{[44]}	{[158]}	{[3]}	{[0.9358]}	{[0.6785]}	{[4]}

```
pressure=A(1:end,2)
```

pressure = 18x1

52
49
39

58
52
41
32
65
45
52
.
.
.

*** END ***