

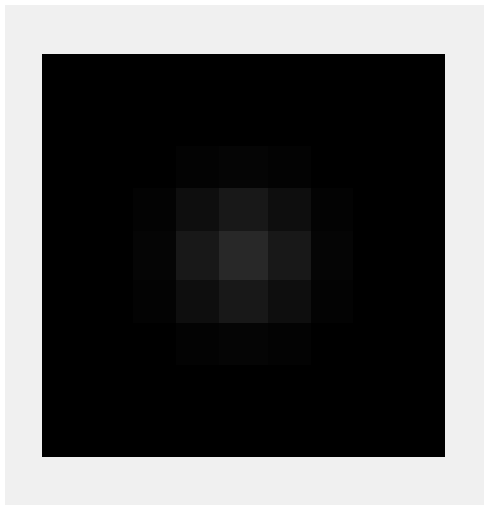
Q1)

a) $q = 2.48$ was chosen

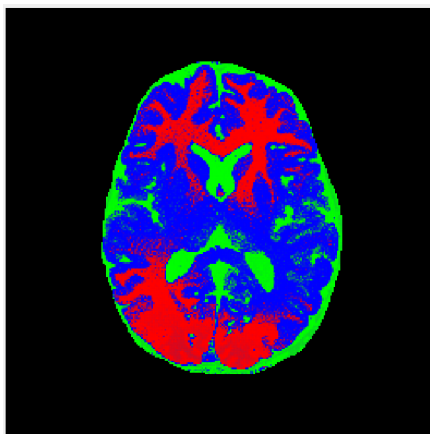
I iterated in steps of 0.02 from $q=1.6$ to $q=3.6$ and checked J values for all those cases. J converged to a global optimum at $q=2.48$ and elsewhere there were local optima only

b) The neighborhood mask was chosen arbitrarily on discussion with peers. I took a 9x9 filter with mean the central pixel and $\text{std} = 1$

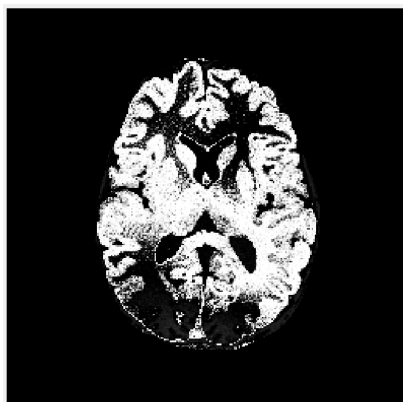
As an image:



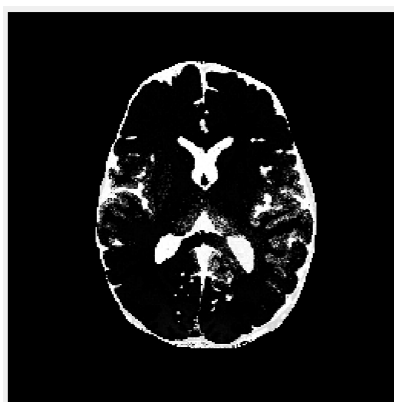
c) Initial estimate for U_{jk} was by doing the fuzzy c means update for U given C:
Shown as images:



RGB channels for different classes



Class 1



Class 2



Class 3

I chose this initialization as I felt it was a quick initialisation and would lead to faster convergence as the U values would be (in theory) closer to the ideal U values

d) Initial class mean estimate I did by k means on the image with 4 classes. Discarding one class which corresponded to the background. This C was used to initialize U.

e) The objective function :- (Varies for different initialisations)

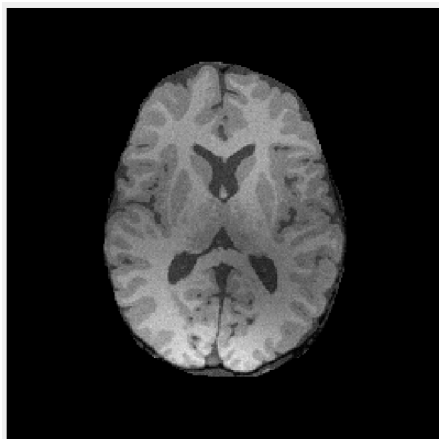
```
J_set =
```

```
1×4 single row vector
```

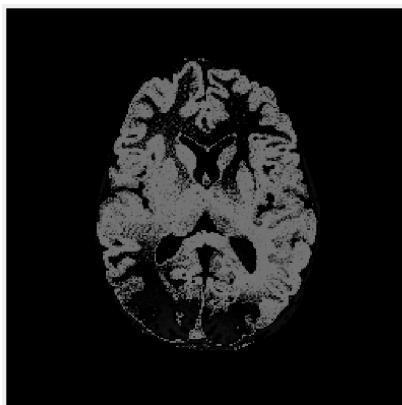
```
29.9957    22.5349    20.8842    20.7514
```

Minimum at J = 20.7514

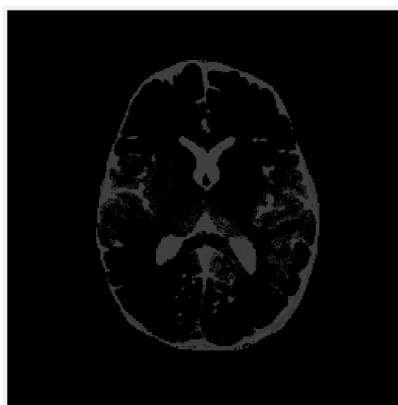
f) Corrupted image provided:-



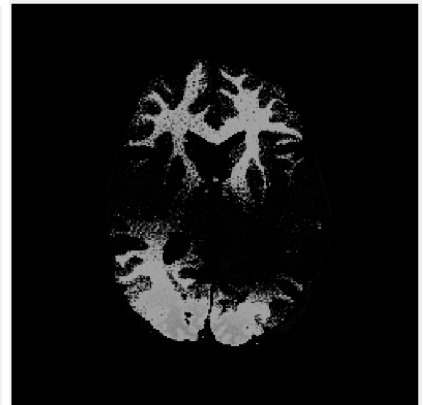
Optimal class estimates:- (Via Fuzzy Cmeans)



Class 1



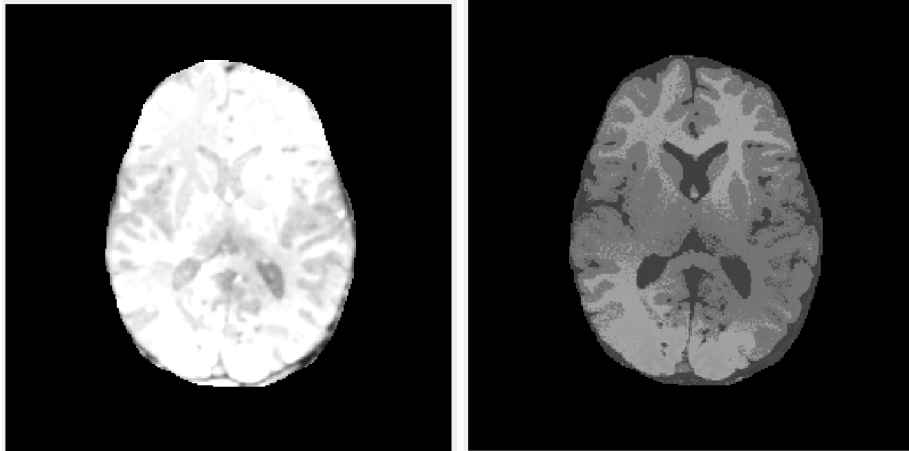
Class 2



Class 3

Bias field:-

Bias removed image:-



Residual image:-



(Increase brightness to view subtle features)

g) The optimal mean values are:

```
C =  
  
3×1 single column vector  
  
0.4690  
0.2737  
0.6133
```

Note that they keep varying each time I run the same code.

I feel this does not lead to a unique solution as whenever I run it there are small differences in final results

Q3) We know probability dist of θ : $P(\theta)$

$$\arg \max_{\theta} P(\theta|y)$$

$$\equiv \arg \max_{\theta} \frac{P(y|\theta) P(\theta)}{P(y)} \quad \text{--- (Using Bayes' Rule)}$$

$$\therefore \log \left(\frac{P(y|\theta) P(\theta)}{P(y)} \right) = [\log(P(y|\theta)) + \log(P(\theta)) - \log(P(y))]$$

$$\text{Let } G(q, \theta) = \log(P(\theta|y)) - \lambda L(q \| p(x|y, \theta))$$

E step:

Design $q(\cdot)$ to maximize $G(q, \theta_i)$

$$G(q, \theta) = \log(P(\theta|y)) - \lambda L(q \| p(x|y, \theta))$$
$$\therefore q(x) = P(x|y, \theta_i)$$

$G(\cdot)$ is lower bound of the log posterior function ~~and~~

$$\text{and: } G(q, \theta_i) = \log(P(y|\theta_i)) \text{ at } \theta = \theta_i$$

M step:

Choose θ to max $G(q, \theta)$

We know

$$\log(P(y|\theta)) - \lambda L(q \| p(x|y, \theta)) = E_{q(\cdot)} [\log(p(x|y, \theta))] + H(q)$$

$$\text{where } H(q) = E(-\log q)$$

$$\therefore G(q, \theta) = E_{q(\cdot)} [\log(p(x|y, \theta))] + H(q) + \log P(\theta) - \log P(y)$$

$$\text{Let } Q(\theta, \theta_i) = E_{q(\cdot)} [\log(p(x|y, \theta))]$$

$$\therefore \text{We maximise } Q(\theta, \theta_i) + \log(P(\theta))$$