Rajendra Singh

Fourth year

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Computer Science and Engineering

D.O.B : 27th November 1997

Indian Institute of Technology, Palakkad Web : https://iamrajee.github.io/



SUMMARY

| ♦ Doi | main | : | Robotics and Computer Vision |
|--------|----------------|---|--|
| ♦ Inte | ernships | : | UST Global, Researshala and IIT Madras. |
| ◆ Pro | ojects | : | 3D SLAM on AGV, Cobots, Reinforcement Learning based UAV controller |
| ◆ Pos | sition | : | Former Head, Robotics club, IIT Palakkad |
| ◆ Acl | hievements | : | KVPY fellowship, AWES Scholarship |
| ◆ Coi | ntributions to | : | moveit_task_constructor, moveit_tutorials |
| ♦ Abo | out | : | I have a passionate interest in vision-based robotics. I'm research oriented, team player and looking forward to collaborate with enthusiastic team or startup researching in this domain. |

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EDUCATION

| Program | Institution | %/CGPA | Year |
|---------------------|---|-----------------------------|--------------------|
| • B. Tech (Present) | Indian Institute of Technology(IIT), Palakkad | 7.33/10 (Till VII Semester) | 2016 - April, 2020 |
| • XII | Delhi Public School(DPS), Udaipur | 89% | 2015 - 16 |
| • X | Delhi Rajasthan Public School, Rajsamand | 96% | 2013 - 14 |

TECHNICAL SKILLS

| Area | Skills |
|--------------------------|---|
| ► Robotics | SLAM(2D gmapping/3D RtabMap) Perception(Feature matching, Semantic segmentation, Object detection) Motion and Path planning Swarm behaviour and algorithms Feedback control system Perception(Feature matching, Semantic segmentation, Object detection) Sensor fusion(Kalman, Particle filter) Robot kinematics and dynamics(DH/Newton/Eular/Lagrangian method) Embedded System(ARM, RTOS, FPGA) |
| ► Reinforcement Learning | Q-learning, Sarsa, Monte Carlo, TD, Multi-armed bandit, DQN, Genetic algorithm |
| ► Machine Learning | Linear and Logistic Regression, Neural Networks(convolutional, recurrent), |
| ► Languages | C, C++, Python |
| ► Software/Tools | ROS 1/2, Moveit, Gazebo, V-REP, Matlab, Fusion 360, Keil, Atmel studio 6, OpenCV, OpenGL |
| ► Hardware | Rplidar A2M8, Realsense D435, Nvidia Jetson(Tx2, nano), Raspi3B+, GstarIV GPS, Zybo-zyng FPGA, KL25Z arm cortex-M0+, Atmega16/32/2560, NodeMCU, GSM, Pyboard, OpenMV, PlutoX |
| ► Other | Open Source Development, Shell scripting, Latex, Review and research paper, Knowledge of patents |

WORK EXPERIENCES

Jan'2020 - Present

Robotics Research Intern, Gadgeon Smart Systems

- Kochi, Indi

May-July, 2019

Working toward to develop cobot of two kinova jaco arm to perform complex manipulation task using softwares like ROS, Gazebo, Moveit and Moveit task constructor.

Computer Vision and Robotics Intern, UST Global

- Trivandrum, India

Studied various **SLAM** algorithm and implemented it using ROS by fusing sensor data of lidar and 3d depth camera. Later, I worked on control and planning of robotic manipulator for vision-based pick and place task.

May-July, 2018

Deep Learning Intern, Researchshala

- Chandigarh, India

Worked on deep learning **projects** related to transfer learning, topic modelling, web and pdf scraping, extracting and analysing useful information from unstructured data.

May-June, 2017

Vistaar Program, Centre for Inovation, IIT Madras

- Chennai, India

Studied state of art 3D printing technology and then built **Prusa i3 3D printer** and a robotic arm using this printer.

SEMINAR PRESENTATIONS

August, 2019

- Visual SLAM on mobile manipulator using a robot operating system
 - Industry-Academia Conclave, IIT Palakkad
 Presented a poster showcasing the implementation of 3D visual SLAM on an industrial manipulator robot.

October, 2017

- Low-cost Prusa-i3 3D printer
 - Open House, Centre for Innovation(CFI), IIT Madras
 Showcased low cost, self-made Prusa-i3 3D printer and its applications.

SELECTED PROJECTS

| ► Swarm | Simulating swarm behaviour of flocking and foraging in V-REP and Argos simulator | October-December, 2019 |
|---------------|--|------------------------|
| ▶ Q-learning | Q-learning based controlled for ARdrone, simulated in gazebo using ROS | August - October, 2019 |
| ► Manipulator | Vision-based control and trajectory planning of robotic manipulator in point-cloud data | June - July, 2019 |
| ► SLAM | Implemented SLAM on AGV by sensor fusion of data from 2D lidar and 3D camera | May - June, 2019 |
| ► Biomedical | Built EOG based typing system for the individual with motor neuron diseases | January - April, 2019 |

To know more about these projects, please visit: https://iamrajee.github.io/projects/

COMPETITIONS

| ► SIH, Hardware | Path planning to fly two drones in a synchronized manner, maintaining same altitude and attitude. | January - June, 2019 |
|-----------------|---|------------------------|
| ► E-yantra | Simulated thirsty crow story using wheeled robot, Overhead camera, Aruco marker, Blender models, Augment environment using OpenGL, Path planning and Navigation on hexagon grid using IR sensor | August, 18-March, 2019 |
| ► Inter-IIT | Build a model for Satellite image classification using just 14 images, IIT Bombay | July - December, 2018 |
| ► Inter-IIT | Built automated Toilet Cleaning Robot for cleaning toilet seat and floor, IIT Madras | July - December, 2017 |

RELEVANT COURSES AND WORKSHOPS

| Area | Courses |
|------------|---|
| ► Maths | Linear algebra, Probability, Stochastic Process and Statistics, Differential Calculus |
| ► CS | Data Structures and Algorithms, DBMS, OS, Computer networks, Compilers, Parallel programming |
| ► AI | ML basic(workshop), Principle of machine learning(CS4801), ML by Andrew Ng(CS229), DL(CS5007), RL basic and Advanced |
| ► Robotics | Robotics manipulation and control, Robotics basics and Advanced, IOT basics, Embedded system, Signal and system, Engineering mechanics, Biomedical and Instrumentation, ROS basics and Advanced, Navigation stack, ROS Manipulation, ROS OpenAI gym |

POSITION OF RESPONSIBILITY

Head of Robotics Club, IIT Palakkad

July 2018 - May 2019

- Taught basics and advanced concept of robotics to a group of 40 students(12 teams).
- Supervised 9 student projects.
- Mentored 2 student projects(Humanoid and Submarine robots).
- Encouraged and motivated student to participate in a regional and national competition.

SCHOLASTIC ACHIEVEMENTS

2017 • Winner, Kaizen Robotics Competition, Lema labs.

Awarded **KVPY** Fellowship by Department of Science and Technology(**DST**), Govt. of India.

Qualified IIT-Jee Advanced 2016 with a percentile of 99.3 amongst a total of 1.2 million students.

2015 ♦ Best Student of Year Award 2014–15, District Private Education Committee, Rajsamand

2014 Awarded Merit Scholarship Class X, Army Welfare Education Society(AWES).

REFERENCES

• Mr. Ashok Nair

Director Service Delivery UST Global, Thiruvananthapuram, India E-Mail: ashok.nair@ust-global.com

• Mr. Shubham Jain

Founder and CEO Researshala, Chandigarh, India E-Mail: **shubham@researchshala.com**

• Dr. Santhakumar Mohan

Professor of Robotics and Control, Department of Mechanical Engineering, IIT Palakkad E-Mail: santhakumar@iitpkd.ac.in