

Rajendra Singh

Fourth year

Computer Science and Engineering

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SUMMARY

◆ Domain	:	Artificial intelligence(AI) and Robotics
◆ Internships	:	UST Global, Researchshala and IIT Madras.
◆ Projects	:	SLAM, Swarm robotics, Manipulators
◆ Position	:	Former Head, Robotics club, IIT Palakkad
◆ Achievements	:	KVPY fellowship, AWES Scholarship
◆ About	:	I have passionate interest in vision-based robotics. I'm research oriented, team player and looking forward to work with enthusiastic team or startup in this domain.

EDUCATION

Program	Institution	%/CGPA	Year
• B. Tech	Indian Institute of Technology, Palakkad	7.19 (Till VI Semester)	2016 - April, 2020
• XII	Delhi Public School, Udaipur	89%	2015 - 16
• X	Delhi Rajasthan Public School, Rajsamand	96%	2013 - 14

TECHNICAL SKILLS

Area	Skills
► Robotics	• SLAM(2D gmapping/3D RtabMap) • Perception(Feature matching, Semantic segmentation, Object detection) • Motion and path planning • Sensor fusion(Kalman, Particle filter) • Swarm behaviour and algorithms • Robot kinematics and dynamics(DH/Newton/Eular/Lagrangian method) • Closed loop control system • Embedded system(ARM, RTOS, FPGA)
► Reinforcement Learning	Q-learning, Sarsa, Monto carlo, TD, Multi-armed bandit, DQN, Genetic algorithm
► Machine Learning	Linear Regression, Regularization(Ridge,LASSO), Classification(Naive Bayes, SVM, KNN, Decision Trees), Clustering(K-mean/DBSCAN/BIRCH/DIANA), PCA, Ensembling, Cross validation
► Deep Learning	CNN, RNN, LSTM, Unstructured data, Topic modeling, Word embedding
► Languages	C, C++ , Python
► Software/Tools	ROS 1/2, Moveit, Gazebo, V-REP, Matlab, Fusion 360, Keil, Atmel studio 6, OpenGL
► Hardware	Rplidar A2M8, Realsense D435, Nvidia Jetson(Tx2, nano), Raspi3B+, GstarIV GPS, Zybo-zyng FPGA, KL25Z arm cortex-M0+ , Atmega16/32/2560, NodeMCU, GSM, Pyboard, OpenMV, PlutoX
► Other	Shell scripting, Latex, Open source projects, Review and reasearch paper, Knowledge of patents

WORK EXPERIENCES

May-July, 2019

● Research intern, UST Global

- Trivandrum, India

Studied various **SLAM** algorithm and implemented it using ROS by fusing sensor data of lidar and 3d depth camera. Later, I worked on control and planning of robotics manipulator for vision based pick and place task.

May-July, 2018

● Data Science intern, Researchshala

- Chandigarh, India

Worked on **NLP projects** related to transfer learning, topic modelling, web and pdf scraping, extrating and analysing useful information from unstructured data.

May-June, 2017

● Vistaar Program, Centre for Inovation, IIT Madras

- Chennai, India

Studied state of art 3D printing technology and then built **Prusa i3 3D printer** and a robotic arm using this printer.

SEMINAR PRESENTATIONS

August, 2019

● Visual SLAM on mobile manipulator using robot operating system

- Industry-Academia Conclave, IIT Palakkad

Presented a **poster** showcasing implementation of 3D visual SLAM on a industrial manipulator robot.

October, 2017

● Low cost Prusa-i3 3D printer

- Open House, Centre for Innovation(CFI), IIT Madras

Showcased low cost, self made Prusa-i3 3D printer and its applications.

SELECTED PROJECTS

► Swarm	Simulating swarm behaviour of flocking and foraging in V-REP and Argos simulator	October-December, 2019
► Q-learning	Q-learning based controlled for ARdrone, simulated in gazebo using ROS	August - October, 2019
► Manipulator	Vision based control and trajectory planning of robotics manipulator in pointcloud data	June - July, 2019
► SLAM	Implemented SLAM on AGV by sensor fusion of data from 2D lidar and 3D camera	May - June, 2019
► Biomedical	Built EOG based typing system for individual with motor neuron diseases	January - April, 2019

To know more about these projects, please visit: <https://iamrajee.github.io/projects/>

COMPETITIONS

► SIH, Hardware	Path planning to fly two drones in synchronized manner, maintaining same altitude and attitude.	January - June, 2019
► E-yantra	Simulated thirsty crow story using wheel robot, overhead camera, aruco marker, blender models, Augment environment using OpenGL, Path planning and navigation on hexagon grid us IR sensors.	August,18-March, 2019
► Inter-IIT	Build model for Satellite image classification using just 14 images, IIT Bombay	July - December, 2018
► Inter-IIT	Built automated Toilet Cleaning Robot for cleaning toilet seat and floor, IIT Madras	July - December, 2017

RELEVANT COURSES AND WORKSHOPS

Area	Courses
► Maths	Linear algebra, Probability, Stochastic Process and Statistics, Differential Calculus
► CS	Data Structures and Algorithms, DBMS, OS, Computer networks, Compilers, Parallel programming
► AI	ML basic(workshop), Principle of machine learning(CS4801), ML by Andrew Ng(CS229), DL(CS5007), RL basic and Advanced
► Robotics	Robotics manipulation and control, Robotics basics and Advanced, IOT basics, Embedded system, Signal and system, Engineering mechanics, Biomedical and Instrumentation, ROS basics and Advanced, Navigation stack, ROS Manipulation, ROS OpenAI gym

POSITION OF RESPONSIBILITY

➤ Head of Robotics Club, IIT Palakkad

July 2018 - May 2019

- Taught basics and advance concept of robotics to group of 40 students(12 teams).
- Supervised 9 student projects.
- Mentored 2 student projects(Humanoid and Submarine robots).
- Encouraged and motivated student to participate in regional and national competition.

SCHOLASTIC ACHIEVEMENTS

- 2017 ♦ Winner, Kaizen Robotics Competition, Lema labs.
- 2016 ♦ Awarded Kishore Vaigyanik Protsahan Yojana(KVPY) Fellowship by DST, Govt. of India.
- 2016 ♦ Qualified IIT-Jee Advanced 2016 with a percentile of 99.3 amongst a total of 1.2 million students.
- 2015 ♦ Best Student of Year Award 2014-15, Rajsamand District Private Education Committee.
- 2014 ♦ Awarded Merit Scholarship Class X, Army Welfare Education Society(AWES).

REFERENCES

• Mr. Ashok Nair

Director Service Delivery,
UST Global, Thiruvananthapuram
E-Mail: ashok.nair@ust-global.com

• Mr. Shubham Jain

Founder and CEO,
Researchshala, Chandigarh
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• Dr. Piyush P. Kurur

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