# Rajendra Singh

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#### **SUMMARY**

♦ Domain	:	Artificial intelligence(AI) and Robotics
<b>♦</b> Internships	:	UST Global, Researshala and IIT Madras.
<b>♦</b> Projects	:	SLAM, Swarm robotics, Manipulators
◆ Position	:	Former Head, Robotics club, IIT Palakkad
<b>♦</b> Achivements	:	KVPY fellowship, AWES Scholarship
◆ About	:	Passionate about vision-based robotics, research oriented and looking forward to work with enuthusiatic team in this domain.

## **EDUCATION**

Program	Institution	%/CGPA	Year
• B. Tech	Indian Institute of Technology, Palakkad	7.19 (Till VI Semester)	2016 - April, 2020
• XII	Delhi Public School, Udaipur	89%	2015 - 16
• X	Delhi Rajasthan Public School, Rajsamand	96%	2013 - 14

### **TECHNICAL SKILLS**

Title	Skills		
► Robotics	<ul> <li>SLAM(2D / 3D)</li> <li>Motion and path planning</li> <li>Swarm algorithms</li> <li>Control system</li> <li>Perception(Feature matching, Segmentation, Detection)</li> <li>Sensor fusion(Kalman, Particle filter)</li> <li>Robot kinematics and dynamics(DH/Newton/Eular/Lagrangian method)</li> <li>Embedded system(ARM, RTOS, FPGA)</li> </ul>		
► Reinforcment Learning	Q-learning, Sarsa, Monto carlo, TD, Multi-armed bandit, DQN, Genetic algorithm		
► Machine Learning	Linear Regression, Regularization(Ridge,LASSO), Classification(Naive Bayes, SVM, KNN, Decision Trees), Clustering(K-mean/DBSCAN/BIRCH/DIANA), Ensembling, Cross validation		
<b>▶</b> Deep Learning	CNN, RNN, LSTM, Unstructured data, Topic modeling, Word embedding		
► Languages	C++, Python		
► Software/Tools	ROS1/2, Moveit, Gazebo, V-REP, Matlab, Fusion 360, Keil, Atmel studio 6, OpenGL		
► Hardware	Rplidar A2M8, Realsense D435, Nvidia Jetson(Tx2, nano), Raspi3B+, GstarIV GPS, Zybo-zyng FPGA, KL25Z arm cortex-M0+, Atmega16/32/2560, NodeMCU, GSM, Pyboard, OpenMV, PlutoX		

#### **WORK EXPERIENCES**

May-July, 2019

Research intern, UST Global, Trivandrum

Studied various <u>SLAM</u> algorithm and implemented it using ROS by fusing sensor data of lidar and 3d depth camera. Later, I worked on control and planning of robotics maniputor for vision based pick and place task.

May-July, 2018

Data Science intern, Researchshala, Chandigarh

Worked on NLP projects related to transfer learning, topic modelling, web and pdf scraping, extrating and analysing useful information from unstructured data.

May-June, 2017

• Vistaar Program, IIT Madras

Studied state of art 3D printing technology and then built Prusa i3 3D printer and a robotic arm using this printer.

#### **SEMINAR PRESENTATIONS**

- Visual SLAM on mobile manipulator using ROS, Industry-Academia Conclave'19, IIT Palakkad
- Low cost 3D printer Prusa-i3, Open House'17, Centre for Inovation(CFI), IIT Madras

August, 2019 October, 2017

#### **SELECTED PROJECTS**

- Implemented <u>SLAM</u> on automated guided vehicle(<u>AGV</u>) by sensor fusion of data from 2D lidar and 3D camera.
- Vision based control and trajectory planning of robotics manipulator in pointcloud data.
- Path planning of Swarm of drone for flying in synchronized manner, under Smart India Hackerthon 2019.
- Built **EOG** based typing system for individual with motor neuron diseases.
- Built automated Toilet Cleaning Robot for cleaning toilet seat and floor, Inter-IIT 2017-18, IIT Madras.
- Build model for Satellite image classification using just 14 images, for Inter-IIT 2018-19, IIT Bombay.

To know more about these projects, please visit: <a href="https://iamrajee.github.io/projects/">https://iamrajee.github.io/projects/</a>

#### **RELEVANT COURSES**

Area	Courses
► Maths	Linear algebra, Probability, Stochastic Process and Statistics, Differential and Integral Calculus
► CS	Data Structures and Algorithms, DBMS, OS, Computer networks, Compilers, Parallel programming
► AI	Principle of machine learning, Deep learning, Reinforcement learning
► Robotics	Robotics manipulation and control, Embedded system, Signal and system, Engineering mechanics, Biomedical and Instrumentation

#### POSITION OF RESPONSIBILITY

#### Head of Robotics Club, IIT Palakkad

July 2018 - May 2019

- Teach basics and advance concept of robotics.
- Mentor student projects.
- Encourage student to participate in regional and national competition.
- Prepare and lead team in competitions.

#### SCHOLASTIC ACHIEVEMENTS

•	Winner, Kaizen Robotics Competition, Lema labs.	2017
•	Awarded Kishore Vaigyanik Protsahan Yojana(KVPY) Fellowship by DST, Govt. of India.	2016
•	Qualified IIT-Jee Advanced 2016 with a percentile of 99.3 amongst a total of 1.2 million students.	2016
•	Best Student of Year Award 2014–15, Rajsamand District Private Education Committee.	2015
•	Awarded Merit Scholarship Class X, Army Welfare Education Society(AWES).	2014

#### REFERENCES

• Mr. Ashok Nair

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Founder and CEO, Researshala, Chandigarh

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· Dr. Piyush P. Kurur

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