

Rajendra Singh

Fourth year
Computer Science and Engineering
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SUMMARY

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|-----------------------|--|
| ◆ Domain | : Artificial intelligence(AI) and Robotics |
| ◆ Internships | : UST Global, Researshala and IIT Madras. |
| ◆ Projects | : SLAM, Swarm robotics, Manipulators |
| ◆ Position | : Former Head, Robotics club, IIT Palakkad |
| ◆ Achievements | : KVPY fellowship, AWES Scholarship |
| ◆ About | : Passionate about vision-based robotics, research oriented and looking forward to work with enthusiastic team in this domain. |

EDUCATION

| Program | Institution | %/CGPA | Year |
|---------|--|-------------------------|--------------------|
| B. Tech | Indian Institute of Technology, Palakkad | 7.19 (Till VI Semester) | 2016 - April, 2020 |
| XII | Delhi Public School, Udaipur | 89% | 2015 - 16 |
| X | Delhi Rajasthan Public School, Rajsamand | 96% | 2013 - 14 |

TECHNICAL SKILLS

| Title | Skills |
|-------------------------------|--|
| Robotics | • SLAM(RtabMap, Gmapping, Hector) • Perception(Feature matching in 2d/3d, Semantic segmentation) • Sensor fusion(Kalman, Particle filter) • Motion and path planning • Swarm algorithms(PSO, Flocking) • Robot kinematics and dynamics(DH, Newton, Euler, Lagrangian method) • Embedded system(ARM, RTOS, FPGA) |
| Reinforcement Learning | Q-learning, Sarsa, Monte Carlo, TD, Multi-armed bandit, DQN, Genetic algorithm |
| Deep Learning | CNN, RNN(LSTM, Seq2seq, etc.), Unstructured data, Topic modeling, Word embedding |
| Languages | C++ , Python |
| Software/Tools | ROS1/2, Moveit, Gazebo, V-REP, Matlab, Fusion 360, Keil, Atmel studio 6, OpenGL |
| Hardware | Rplidar A2M8, RealSense D435, Nvidia Jetson(Tx2, nano), Raspberry3B+, GstarIV GPS, Zybo-zyng FPGA, KL25Z arm cortex-M0+ , Atmega16/32/2560, NodeMCU, GSM, Pyboard, OpenMV, PlutoX |

WORK EXPERIENCES

- May-July, 2019 ● **Summer intern, UST Global, Trivandrum**
Studied various [SLAM](#) algorithm and implemented it using ROS by fusing sensor data of lidar and 3d depth camera. Later, I worked on control and planning of robotics manipulator for vision based pick and place task.
- May-July, 2018 ● **Data Science intern, Researchshala, Chandigarh**
Worked on [NLP projects](#) related to transfer learning, topic modelling, web and pdf scraping, extracting and analysing useful information from unstructured data.
- May-June, 2017 ● **Vistaar Program, IIT Madras**
Studied state of art 3D printing technology and then built [Prusa i3 3D printer](#) and a robotic arm using this printer.

SEMINAR PRESENTATIONS

- Visual SLAM on [mobile manipulator](#) using ROS, Industry-Academia Conclave'19, IIT Palakkad August, 2019
- Low cost 3D printer [Prusa-i3](#), Open House'17, Centre for Innovation(CFI), IIT Madras October, 2017

SELECTED PROJECTS

- Implemented [SLAM](#) on automated guided vehicle([AGV](#)) by sensor fusion of data from 2D lidar and 3D camera.
- Vision based [control](#) and trajectory [planning](#) of robotics manipulator in pointcloud data.
- Path planning of [Swarm of drone](#) for flying in synchronized manner, under Smart India Hackerthon 2019.
- Built [EOG](#) based typing system for individual with motor neuron diseases.
- Built automated [Toilet Cleaning Robot](#) for cleaning toilet seat and floor, Inter-IIT 2017-18, IIT Madras.
- Build model for [Satellite image classification](#) using just 14 images, for Inter-IIT 2018-19, IIT Bombay.

To know more about these projects, please visit: <https://iamrajee.github.io/projects/>

RELEVANT COURSES

| Area | Courses |
|----------|--|
| Maths | Linear algebra, Probability, Stochastic Process and Statistics, Differential and Integral Calculus |
| CS | Data Structures and Algorithms, DBMS, OS, Computer networks, Compilers, Parallel programming |
| AI | Principle of machine learning, Deep learning, Reinforcement learning |
| Robotics | Robotics manipulation and control, Embedded system, Signal and system, Engineering mechanics, Biomedical and Instrumentation |

POSITION OF RESPONSIBILITY

- **Head of Robotics Club, IIT Palakkad** July 2018 - May 2019
- Teach basics and advance concept of robotics.
 - Mentor student projects.
 - Encourage student to participate in regional and national competition.
 - Prepare and lead team in competitions.

SCHOLASTIC ACHIEVEMENTS

- ◆ Winner, Kaizen Robotics Competition, Lema labs. 2017
- ◆ Awarded KVPY Fellowship by DST, Govt. of India. 2016
- ◆ Qualified IIT-Jee Advanced 2016 with a percentile of 99.3 amongst a total of 1.2 million students. 2016
- ◆ Best Student of Year Award 2014–15, Rajsamand District Private Education Committee. 2015
- ◆ Awarded Merit Scholarship Class X, Army Welfare Education Society(AWES). 2014

REFERENCES

• **Mr. Ashok Nair**

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• **Mr. Shubham Jain**

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