

## Task 1 – Hungry Bird

Welcome to Task 1 of Hungry Bird!!

This task is divided into two parts:

- Task 1.1 – Implementing Position Holding of Drone
- Task 1.2 – Implementing Path Planning to Avoid Obstacles

You will find the following folders in this folder along with this Read Me file.

- First Folder is [Task 1.1](#):
  - Please find the following files/folders in this folder:
    - ◆ [Problem Statement](#)
    - ◆ [Tutorials](#)
    - ◆ [Task\\_1\\_1\\_Instructions.pdf](#)
  - Follow the instructions in [Task\\_1\\_1\\_Instructions.pdf](#) to understand and successfully complete Task 1.1
- Second Folder is [Task 1.2](#):
  - Please find the following files/folder in this folder:
    - ◆ [Problem Statement](#)
    - ◆ [Tutorials](#)
    - ◆ [Task\\_1\\_2\\_Instructions.pdf](#)
  - Follow the instructions in [Task\\_1\\_2\\_Instructions.pdf](#) to understand and successfully complete Task 1.2