

Language Modeling on the Penn Treebank Dataset

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Abstract

This project investigates the effectiveness of transformer-based models for autoregressive language modeling, with a focus on minimizing perplexity as a measure of predictive performance. Leveraging a custom implementation of attention mechanisms, the model was trained and evaluated on a widely used benchmark dataset. The results highlight the ability of transformers to efficiently capture sequence dependencies and demonstrate their potential for generalizing to unseen data.

1 Introduction

Language modeling involves predicting the likelihood of a sequence of words, which is fundamental to many natural language processing tasks. In this project, I focused on autoregressive language modeling, an unsupervised learning task where the objective is to predict the next token given the previous ones in a sequence. For example, given the sequence `<s> NLP 243 is the best </s>`, the model learns to predict tokens such as NLP based on `<s>` or is based on `<s>, NLP, 243`.

The formal objective of this project is to develop a transformer-based language model that minimizes perplexity, a metric that evaluates the model's ability to predict sequences. Specifically, the goal is to optimize the predictive performance of the model on the Penn Treebank dataset, a widely used benchmark for natural language processing tasks. Perplexity is defined as:

$$PPL = \exp \left(\frac{1}{N} \sum_{i=1}^N \log p(w_i | w_{<i}) \right)$$

where N is the total number of tokens, w_i represents the current token, and $w_{<i}$ represents all preceding tokens in a sequence. Lower perplexity indicates better predictive performance.

The dataset used for this project is the Penn Treebank (PTB) text-only dataset. It consists of

approximately one million tokens split into three subsets: training, validation, and test. Each subset comprises sentences, with each sentence treated as an individual data point. Table 1 summarizes the dataset statistics.

Split	Number of Sentences	Number of Tokens
Training	42,068	929,589
Validation	3,370	73,761
Test	3,761	82,431

Table 1: Penn Treebank dataset statistics.

The input to the model is a sequence of tokens, and the output is the probability distribution over the vocabulary for the next token in the sequence. The dataset includes both common words and unknown tokens represented as `<unk>`. For example, a sample sentence from the dataset is:

```
<s> Mr. <unk> is chairman of <unk>  
N.V. the Dutch publishing group  
</s>
```

By training the model on the training split, I aim to predict the next token in sequences while minimizing perplexity, thus improving the model's ability to generalize to unseen data in the validation and test sets.

2 Dataset Analysis

The Penn Treebank (PTB) dataset is a widely recognized benchmark for language modeling tasks, offering a compact and standardized corpus that facilitates fair comparisons between models. Despite its utility, the dataset presents several challenges:

2.1 Challenges in PTB

- **Small Size:** The dataset contains just under one million tokens, which can limit the generalizability of larger models. This necessitates

careful hyperparameter tuning to avoid overfitting.

- **Out-of-Vocabulary (OOV) Tokens:** Rare words are replaced by a generic <unk> token, which may obscure nuanced distinctions between similar sentences.
- **Sparsity of High-Frequency Tokens:** A significant portion of the tokens occurs only a few times, making it challenging for the model to learn meaningful patterns without overfitting to the training data.

2.2 Token Distribution and Examples

The token distribution in the PTB dataset follows a power-law, where a small number of words (e.g., function words such as the, is, and of) dominate the vocabulary, while many tokens occur infrequently. For example:

```
<s> The company reported a profit  
of $3.5 million </s>
```

This sentence demonstrates a typical structure, including proper nouns and numerical values, which the model must learn to handle effectively. Additionally, sentences like:

```
<s> Mr. <unk> announced a merger  
with <unk> Corp. </s>
```

highlight the prevalence of the <unk> token for handling rare or unseen words.

2.3 Justification for Using PTB

The PTB dataset is chosen for its historical significance and standardization in language modeling benchmarks. Despite its small size, PTB allows for quick experimentation and comparison with prior work. Furthermore, its fixed vocabulary and well-defined splits provide a controlled environment for evaluating model performance on sequence prediction tasks. These features make PTB a suitable choice for exploring the effectiveness of transformer-based architectures in language modeling.

3 Model

3.1 Transformer Architecture

My model is based on the transformer encoder architecture, introduced in the paper "Attention is All You Need" by (1). This architecture was selected

for its ability to capture long-range dependencies efficiently, making it well-suited for autoregressive language modeling tasks. Additionally, I followed the implementation guidelines and insights from the tutorial by (2), which provided practical advice for training transformer-based models.

3.2 Embedding Methods

The model uses learned embeddings to convert input tokens into dense vectors of fixed size, determined by the embedding dimension (d_{model}). These embeddings are scaled by the square root of the model dimension to maintain numerical stability, as recommended by (1). Positional encodings are added to the embeddings to encode token order in the sequence, using sinusoidal functions that vary with position. This approach allows the model to distinguish between tokens based on their positions.

Learned embeddings were chosen over pre-trained embeddings (e.g., GloVe or word2vec) because pre-trained embeddings were disallowed for this project. Moreover, learned embeddings allow the model to optimize representations specifically for the Penn Treebank dataset.

3.3 Transformer Encoder Components

The transformer encoder consists of the following components:

3.3.1 Input Embeddings and Positional Encoding

Input tokens are converted into dense vectors using an embedding layer. Positional encodings are added to these embeddings to provide information about token positions in the sequence. The embeddings are scaled by $\sqrt{d_{model}}$ to prevent exploding gradients during training.

3.3.2 Self-Attention Mechanism

The self-attention mechanism allows the model to focus on relevant parts of the input sequence when predicting the next token. Multi-head self-attention is used, where multiple attention "heads" process the input in parallel, capturing diverse relationships within the sequence. This mechanism was implemented using the scaled dot-product attention as described in (1).

3.3.3 Feedforward Network

Each encoder block includes a feedforward network, which applies two linear transformations

with a ReLU activation in between. This component introduces non-linearity, expanding the model's capacity to learn complex patterns.

3.3.4 Layer Normalization and Residual Connections

Layer normalization and residual connections stabilize training by normalizing intermediate representations and adding them back to the input. These techniques help prevent overfitting and improve convergence.

3.3.5 Projection Layer

The output of the encoder is passed through a projection layer, which maps the dense representations back to the vocabulary size. This layer outputs logits for each token in the sequence.

3.4 Training and Hyperparameters

The model was trained using the Adam optimizer with a learning rate of 10^{-4} and a batch size of 32. These hyperparameters, adopted from the "Attention is All You Need" paper (1), were selected for their demonstrated ability to stabilize training in transformer models. The loss function used was cross-entropy, with padding tokens (<pad>) ignored during computation. Training was conducted for 10 epochs, allowing sufficient convergence as monitored by validation perplexity.

The hyperparameters used during training are summarized in Table 2. These values were validated through experimentation on the Penn Treebank dataset, with the objective of minimizing validation perplexity.

The training, validation, and testing process involved the following steps:

- **Training Phase:** The model was trained on the Penn Treebank training set. During this phase, the objective was to minimize the cross-entropy loss between predicted token probabilities and the true tokens in the sequences.
- **Validation Phase:** After each epoch, the model was evaluated on the validation set to monitor its generalization performance. Perplexity, a measure of how well the model predicts sequences, was used as the primary evaluation metric.
- **Testing Phase:** Once training was complete, the model configuration with the lowest validation perplexity was selected for evaluation

on the test set. The final test perplexity reflects the model's ability to generalize to completely unseen data.

Perplexity (PPL) was calculated as:

$$PPL = \exp \left(\frac{1}{N} \sum_{i=1}^N \log p(w_i | w_{<i}) \right)$$

where N is the total number of tokens in the sequence, w_i is the current token, and $w_{<i}$ represents all preceding tokens. A lower perplexity score indicates better performance, with a value of 1 representing perfect predictions.

3.5 Implementation Details

The transformer was implemented in PyTorch, following the architecture and principles described in (1). Additional insights were gained from the tutorial by (2), which helped refine the training strategy and hyperparameter tuning. Key features of the implementation include:

- Learned embeddings for input tokens and sinusoidal positional encodings.
- Multi-head self-attention for sequence modeling.
- Layer normalization and residual connections for stabilization.
- A projection layer to map encoder outputs to vocabulary size.
- Masking mechanisms to handle padding tokens and maintain causality.

Random seed 24 was used globally in all components to ensure reproducibility. The entire pipeline, including data loading, training, and evaluation, was configured to produce consistent results.

3.6 Model Rationale

The transformer encoder was chosen because it eliminates the recurrence bottleneck in traditional RNNs and LSTMs. Its ability to capture long-range dependencies through self-attention makes it well-suited for language modeling tasks, where the context of distant tokens can significantly influence predictions.

4 Experiments

4.1 Dataset and Preprocessing

I used the Penn Treebank dataset, split into training, validation, and test sets, as shown in Table 1. Sentences were tokenized, and I built a vocabulary with a minimum frequency threshold of 3 to handle rare words and reduce data sparsity. Tokens that appeared fewer times than the threshold were replaced with the <unk> token.

4.2 Hyperparameter Configurations

Key hyperparameters used in the experiments are listed in Table 2. I trained the model for 10 epochs using the Adam optimizer with a learning rate of 10^{-4} and a batch size of 32. These hyperparameters, adopted from the "Attention is All You Need" paper (1), were selected as the baseline configuration.

In addition to the baseline, I experimented with two alternative configurations, summarized in Tables 3 and 4. These configurations were chosen based on common practices in transformer-based language modeling to evaluate the impact of different parameter choices on model performance.

Hyperparameter	Value
Sequence Length (seq_len)	50
Embedding Dimension (d_model)	512
Learning Rate (lr)	10^{-4}
Batch Size	32
Minimum Frequency (min_freq)	3

Table 2: Baseline hyperparameters used in training.

Hyperparameter	Value
Sequence Length (seq_len)	40
Embedding Dimension (d_model)	256
Learning Rate (lr)	10^{-3}
Batch Size	16
Minimum Frequency (min_freq)	5

Table 3: Alternative Configuration 1: Reduced model size and faster learning rate.

5 Results

I evaluated the performance of each configuration on the validation and test sets using perplexity. Table 5 summarizes the perplexity scores achieved by the baseline and alternative configurations.

Hyperparameter	Value
Sequence Length (seq_len)	60
Embedding Dimension (d_model)	768
Learning Rate (lr)	5×10^{-5}
Batch Size	64
Minimum Frequency (min_freq)	2

Table 4: Alternative Configuration 2: Larger model size with slower learning rate.

Configuration	Validation Perplexity	Test Perplexity
Baseline	42.58	83.35
Alternative Configuration 1	17.61	39.11
Alternative Configuration 2	80.35	134.72

Table 5: Perplexity scores for baseline and alternative configurations.

5.1 Comparison of Configurations

The baseline configuration achieved a validation perplexity of 42.58 and a test perplexity of 83.35. Alternative Configuration 1 significantly outperformed the baseline, achieving a validation perplexity of 17.61 and a test perplexity of 39.11. The reduced model size and faster learning rate likely contributed to better generalization and faster convergence.

Alternative Configuration 2, however, showed poorer performance, with a validation perplexity of 80.35 and a test perplexity of 134.72. The increased model capacity may have led to overfitting on the small dataset, and the slower learning rate might not have allowed the model to converge effectively within the given training epochs.

5.2 Discussion

The experiments revealed the importance of balancing model size, learning rate, and regularization:

- **Alternative Configuration 1:** The smaller embedding size and increased learning rate proved beneficial. Faster learning with a moderate capacity helped the model generalize better.
- **Alternative Configuration 2:** Larger embedding size and slower learning rate led to sub-optimal performance. While larger models often excel on extensive datasets, the Penn

Treebank’s limited size likely caused overfitting.

- **Baseline Configuration:** Although effective, the baseline was not as competitive as Alternative Configuration 1, suggesting room for improvement by adjusting parameters such as learning rate and embedding size.

These findings align with prior research indicating that smaller models with tuned hyperparameters can outperform larger, more complex models on constrained datasets (1).

5.3 Conclusion

Alternative Configuration 1 emerged as the best-performing setup, achieving the lowest perplexity on both validation and test sets. These results underline the importance of tailoring hyperparameters to the dataset and task. Future work could explore additional regularization techniques or longer training schedules for larger configurations to mitigate overfitting and improve convergence.

6 Alignment with Findings in Research

The results of this study align closely with insights presented in recent research on hyperparameter tuning for transformer models, particularly on small datasets like the Penn Treebank. By varying key hyperparameters such as embedding dimensions, learning rate, and batch size, the experiments revealed patterns that corroborate prior findings in the literature.

6.1 Improved Generalization with Smaller Models and Faster Learning Rates

The success of **Alternative Configuration 1**, which used a smaller embedding size ($d_{\text{model}} = 256$) and a faster learning rate ($1r = 10^{-3}$), reflects observations in (3) and (4). Zhang et al. (3) demonstrate that for smaller datasets, reducing model capacity while increasing learning rates can enhance generalization by avoiding overfitting and converging to sharper minima. Similarly, Wang et al. (4) emphasize that learning rate tuning is pivotal for improving stability and efficiency, particularly when using adaptive optimizers like Adam. These findings align with the observed lower perplexity in **Alternative Configuration 1**, suggesting that a smaller model with faster learning effectively balances capacity and regularization.

6.1.1 Challenges of Larger Models on Small Datasets

The poor performance of **Alternative Configuration 2**, which featured a larger embedding size ($d_{\text{model}} = 768$) and a slower learning rate ($1r = 5 \times 10^{-5}$), highlights the risks of overfitting, as noted in (3). Zhang et al. argue that larger models require stronger regularization or substantially more data to generalize well. Wang et al. corroborate this by showing that smaller learning rates can exacerbate convergence issues, particularly in high-dimensional parameter spaces. These results explain why **Alternative Configuration 2** performed worse, despite its theoretically higher capacity for complex representations.

6.1.2 Baseline as a Balanced Starting Point

The baseline configuration adopted from (1) serves as a robust starting point, as its hyperparameter choices were designed for larger datasets. While effective, the baseline was outperformed by **Alternative Configuration 1**, suggesting that tuning hyperparameters for the specific constraints of smaller datasets, as supported by both (3) and (4), yields better performance.

6.1.3 Summary

The experiments underscore the importance of tailoring transformer configurations to the dataset and task:

- **Alternative Configuration 1** illustrates how smaller embedding dimensions and faster learning rates enable efficient generalization, aligning with findings from (3) and (4).
- **Alternative Configuration 2** highlights the limitations of larger models on small datasets, as described in (3).
- The baseline configuration, while balanced, benefits from task-specific tuning, further supporting the value of adaptive hyperparameter selection.

These results reinforce the conclusions in the cited works and provide practical guidance for optimizing transformer models on constrained datasets.

References

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