Hagard ID	Situational Analysis							Hazard Mertification						Hazardous Evert Classification						Determination of ASIL and Safety Goals	
	Operational Mode	Operational Scenario	Environmental Details	Situation Details	Other Details (optional)	(function)	Situation Description	Function	Deviation	Deviation Details	Hazardous Event (resulting effect)	Event Details	Hazardous Event Description	Exposure (of situation)	Rationale (for exposure)	Severby (of potential harm)	Rationale (for severity)	Controllability (of hazardous event)	Rationale (for controllability)	ASIL Determination	Safety Goal
HA-001	OM03 - Normal Driving	OS04 - Highway	Ehtlii - Rain (ulippery road)	SD02 - High speed			(sippery road) with high speed and correctly used system.	Lane Departure Warning (LDW) function shall apply an oscillating steering sorque to provide the driver with haptic	DV04 - Actor effect is too much	an oscillating turgue with very high torque (above limit.)	other vehicle.	High haptic feedback can affect driver's ability so steer as interned. The driver loose control and could colide with another vehicle or side of the road.	function applies an oscillating torque with very high torque	£3 - Medium probability	Driving on a highway with tain could happen between 1% and 10% of the time-operating the sehicle.	fattal injuries	Collitions at high speed could cause tentilinjuries.		I is difficult to stay calm and next properly when the steeling well is moving too much.		The occiliating steeling turque from the Lane Departure Warning function shall be limbed.
HA-002	OM03 - Normal Driving	OSSR - Country Road	END! - Normal conditions	SD02 - High speed			Normal driving on a country road during scenal conditions with high speed and inconectly used system.		DV03 - Function is always activated			Driver use the function as if the car was a self-driving car and isose driving attention.	The driver do not use the function properly.	£2 - Low probability		fattal injuries	Collitions arthigh speed could cause total injuries.		When the driver loose focus on driving, it is difficult to se-focus in the case of immilient collision.		The Lane Keeping Assistance function shall be time limbed, and additional specing torque shall end after a given time interval so the diver cannot minuse the system for autonomous driving.
HA-003	OM03 - Normal Driving	OSM - Highway	END1 - Normal conditions	SD02 - High speed			conditions with high speed and correctly used system.	function shall apply an	activated	working and the Lane Departure Warning function continue to be activated.	other vehicle.	steering wheel making the driver to loose control with potential collision with other vehicle.	The Lane Departure Warning start acting randomly when the camera sensor is not working.	E3 - Medium probability	Driving on a highway with rain could happen between 1% and 10% of the time-operating the webicle.		Colitions anhigh speed could cause tarsi injuries.	uncontrollable	When the diver loose como of the vechicle is very difficult to realize the situation and act accordently.	c	The Lane Departure Warning function shall be deactivated when the camera sensor stop working.
HACOM	OM03 - Normal Driving	OSSR - Country Road	END! - Normal conditions	SD02 - High speed					Function		other vehicle.	continue to be activated starting	The Lane Keeping Assistance start acting randomly when the camera sensor is not working.		Driving on a highway with rain could happen between 1% and 10% of the time-operating the sehicle.		Collitions arthigh speed could cause total injuries.	uncontrollable	When the driver loose commit of the vectricie is very difficult to resize the abustion and act accordently.	c	The Lane Keeping Assistance function shall be descripted when the camera sensor stop working.