Q1.

Explain each step of the genetic algorithm using the **Traveling Salesman Problem (TSP)** as the application scenario. Clearly describe population initialization, fitness evaluation, selection, crossover, and mutation using appropriate terminology. Illustrate your explanation with an example involving at least five cities and provide step-by-step calculations wherever applicable."

Answer: Genetic Algorithm (GA) is a heuristic search technique inspired by Charles Darwin's theory of natural evolution. It is widely used to solve optimization and search problems.

When applied to the **Traveling Salesman Problem (TSP)**, the GA attempts to find the shortest possible route that visits each city exactly once and returns to the starting city.

Steps to solve TSP using Genetic Algorithm:

i. Define Encoding Mechanism (Chromosome Representation)

- In TSP, an **individual (chromosome)** is a possible tour (i.e., an ordered list of cities).
- For example, for **5 cities A, B, C, D, E**, one possible chromosome is:
- Chromosome = [A, C, E, D, B]

ii. Define Fitness Function

- The goal is to minimize the total tour length.
- Fitness function:

• Fitness =
$$\frac{1}{\text{Total distance of the Tour}}$$

• This ensures shorter routes have higher fitness values.

iii. Initialize a Population (Assume population size = 4)

Let the distances (in km) between cities be defined by the following symmetric matrix:

	Α	В	С	D	Е
Α	0	10	15	20	25
В	10	0	35	25	30
С	15	35	0	30	20
D	20	25	30	0	15
Е	25	30	20	15	0

Initial population:

Parent	Chromosome Route	Parent	Chromosome Route
P1	$A \rightarrow B \rightarrow C \rightarrow D \rightarrow E \rightarrow A$	P3	$A \to D \to C \to B \to E \to A$
P2	$A \rightarrow C \rightarrow E \rightarrow B \rightarrow D \rightarrow A$	P4	$A \rightarrow E \rightarrow D \rightarrow C \rightarrow B \rightarrow A$

iv. Calculate the Fitness of all individuals

Compute the tour length and fitness:

- P1: A-B-C-D-E-A = 10+35+30+15+25 = 115, Fitness = 1/115 ≈ 0.0087
- **P2**: A-C-E-B-D-A = 15+20+30+25+20 = 110, Fitness = $1/110 \approx 0.0091$
- **P3**: A-D-C-B-E-A = 20+30+35+30+25 = 140, Fitness = $1/140 \approx 0.0071$
- **P4**: A-E-D-C-B-A = 25+15+30+35+10 = **115**, Fitness = 1/115 ≈ **0.0087**

v. Selection of Parents

- Use roulette wheel selection based on fitness.
- Assign probabilities:
 - o P1: 0.0087 / total ≈ 0.22
 - o P2: 0.0091 / total ≈ 0.23
 - o P3: 0.0071 / total ≈ 0.18
 - o P4: 0.0087 / total ≈ 0.22

Select P2 and P4 for crossover (based on higher fitness).

vi. Crossover

- Use Order Crossover (OX) for permutation-based chromosomes.
- Example:
 - o Parent 1: A-C-E-B-D
 - o Parent 2: A-E-D-C-B
 - o Crossover between position 3 to 4:
 - Segment from P1: E-B
 - Fill remaining from P2 preserving order: A-D-C
 - Resultant child

vii. Mutation

- Apply **swap mutation** to introduce diversity.
- E.g., swap position 2 and 4:

o **Before C1**: [A, D, E, B, C]

o After: **C3** [A, B, E, D, C]

viii. Stopping Criteria

- Continue repeating steps iv to vii until:
 - o A solution with minimum tour distance is found,
 - o or max generations reached,
 - o or improvement plateaus.

Conclusion: Using GA on TSP helps approximate near-optimal routes efficiently. The solution evolves generation-by-generation through selection, crossover, and mutation — mimicking natural evolution to solve combinatorial optimization problems.

Common Stopping Criteria for GA in TSP:

1. Maximum Number of Generations

- Stop after a fixed number of generations (e.g., 500, 1000).
- Simple and ensures time-bounded execution.
- X Might stop too early or run unnecessarily long.

2. No Improvement in Best Fitness

- An interpretation in the last section in the last sec
- II Stop if no improvement occurs for N generations.
- Example: "If best distance hasn't changed for 100 generations, stop."
- Efficient and adaptive.
- X Might stop prematurely due to local optima.

3. Target Fitness Reached

- **③** Stop when a route below a desired length is found.
- Example: If optimal/near-optimal TSP length is known, set a threshold.
- Works well if you know the benchmark.
- X Not always feasible; real-world TSP solutions may not have a known best.

4. Time Limit

- Stop after a fixed amount of computation time.
- Useful in real-time or time-constrained systems.
- X Doesn't guarantee best possible solution.

5. Diversity Threshold

- Stop when most individuals in the population are too similar.

- Indicates convergence (or stagnation).
- X Can be computationally expensive to track.

6. Combination of Criteria (Recommended)

• Use multiple conditions for better control:

Stop if:

- Max generations reached, OR
- No improvement in best fitness for 100 generations, OR
- Time limit exceeded

Best Practice for TSP:

- TSP is a hard NP-Hard problem.
- It's better to balance exploration and exploitation, so using:

✓ "No improvement in N generations" + "Max generations"

is usually the most effective combo.