EE5471: Interpolation

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1 Introduction

figure(2)

In this assignment we will study interpolation. The codes are in C but we will call them from Python and graph the results.

2 Polynomial Interpolation

We will use the Fortran code in Numerical Recipes for interpolation. The code can be compiled and and linked to a main program in Fortran, but that is not our interest. We want to link this code to Python. To do this we use f2py. This is a package that is part of numpy, a package installed as a part of python.

f2py is also available as a seperate commandline command when you install numpy, and that is the way we will use it here. Given the fortran code polint.f (or polint.f90), we run the following command:

```
f2py -c -m polint polint.f
```

This compiles polint.f (which is what the -c triggers), and then creates python module polint (triggered by -m). The output of this command is a .so file:

```
polint.f testpolint.py polint.cp
```

polint.f and polint.f90 are source files. testpolint.py is a python file to test polint.f. polint is a sub directory that holds the compile files, usually removed after compilation. The library is the .so file. The name says polint has been converted by cpython for x86_64 archetecture on the gnu linux operating system.

If we look at testpolint.py we see how to use the library:

```
# script to test the polint module
from scipy import *
from matplotlib.pyplot import *
import polint as p
from numpy import sin,linspace,array # sin, linspace and
# array used to be part of scipy but have been shifted to
# numpy
# interpolate on a table of sin(x) as a test xx=linspace(0,2*pi,10) # creat
yy=sin(xx)
x=linspace(-pi,3*pi,501) # points at which to interpolate
y=[p.polint(xx,yy,w)[0] for w in x]
dy=[p.polint(xx,yy,w)[1] for w in x]
# plot the outputs
figure(1) plot(xx,yy,'ro',x,y,'r',x,sin(x),'g')
title("Interpolating sin(x)")
legend(["Table values","Interpolated values","True function"])
```

```
semilogy(x,abs(array(dy)),'r',x,abs(array(sin(x)-y)),'g') title("Estimated
legend(["Estimated Error","True Error"])
show()
#end if
```

In all the following problems, plot both the interpolated values and the actual values in a plot. Also show both the actual error vs the estimated error in another plot. Use semilog plots when showing error.

1. In python sample $\sin(x+x^2)$ from 0 to 1 at 5 points. Use these points as your table and do fourth order interpolation on these 200 points

```
xx=linspace(-0.5, 1.5, 200)
```

Since all the points in the table are used for 4^{th} order interpolation, this allows you to see what the effect of choosing a window that is not centred about the desired xx value.

- 2. Sample the same function at 30 points from 0 to 1. Now you have to choose the nearest 5 points and do fourth order interpolation. How does the accuracy change? What is the change due to?
- 3. With the same table of values, vary the order of interpolation. How does the error vary. Plot the error vs *x* for different orders in a semi log plot. Explain the curves you get.
- 4. Vary the interpolation order *n* from 3 to 20 and determine the way the maximum error varies with order.
- 5. We require a 6 digit accurate method to compute the function

$$f(x) = \frac{\sin(\pi x)}{\sqrt{1 - x^2}}\tag{1}$$

between 0.1 and 0.9. The function is known *exactly* (to 15 digits) at certain locations, $x_k = x_0 + kdx$, k = 0, ..., n where n is the order of interpolation required.

- (a) Convert the function to a table, spaced 0.05 apart, sampling it from 0.1 to 0.9.
- (b) In Python, plot this function and determine its general behaviour. Is it analytic in that region? What is the radius of convergence? What is the nature of the function's behaviour near ± 1 ?
- (c) Use the polint routine to interpolate the function at a thousand points between 0.1 and 0.9 for different orders. What order gives 6 digit accuracy? Explain the convergence in terms of the table spacing and the ROC.

```
\langle *2 \rangle \equiv \langle code\text{-}old \text{ (never defined)} \rangle \\ \langle code1 \text{ (never defined)} \rangle
```