## **Geometric Transforms**

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Since translation, rotation, and scaling are all affine transformations, I implemented a routine that takes an affine transformation matrix and an input image, applies the transformation, and performs bilinear interpolation during target-to-source mapping.

```
def affine_transfrom(I, T, n_out, m_out):
Function to perform affine transformation T on I
n_out, m_out : Desired shape of the output image
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n, m = I.shape
inv_T = np.linalq.inv(T)
I_out = np.zeros((n_out,m_out))
for x_ in range(n_out):
    for y_ in range(m_out):
        x, y, w = inv_T.dot(np.array([x_,y_,1]))
        x, y = x/w, y/w
        # bilinear interpolation using
        # multilinear polynomial fitting
        x_1, y_1 = int(x), int(y)
        x_2, y_2 = int(x) + 1, int(y) + 1
        if 0 \le x_1 \le n and 0 \le x_2 \le n and
                 0 \le y_1 \le m and 0 \le y_2 \le m:
             f = np.array([I[x_1,y_1], I[x_1,y_2],
                          I[x_2, y_1], I[x_2, y_2])
            N = np.array([[1, x_1, y_1, x_1*y_1],
                         [1, x_1, y_2, x_1*y_2],
                         [1, x_2, y_1, x_2*y_1],
                         [1, x_2, y_2, x_2*y_2]]
             a = np.linalg.inv(N).dot(f)
            val = np.dot(a, np.array([1, x, y, x*y]))
        else:
            val = 0.0
        I_out[x_, y_] = val
return I_out
```

The results are shown on the following pages.

## 1 Translation



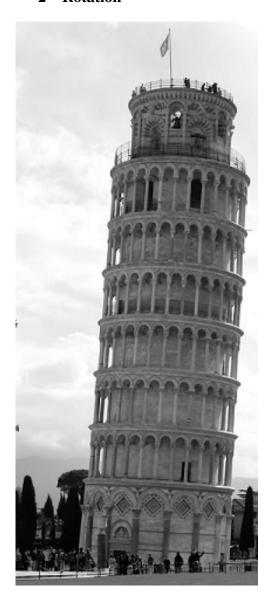
Figure 1: Source image



Figure 2: After translating by  $t_x=3.75$  and  $t_y=4.3$  pixels

The shape of the output image is the same as that of the input image.

## 2 Rotation



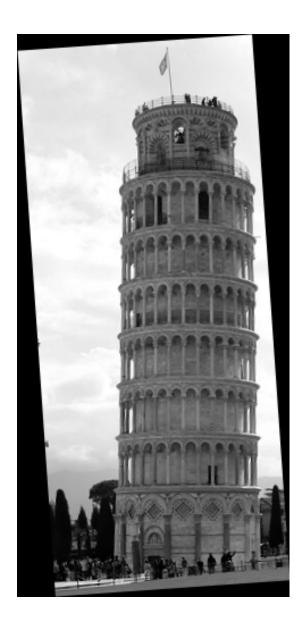


Figure 3: Source Image

Figure 4: After rotating by  $3.97^{\circ}$ 

Since the rotation happens around the axis passing the upper left corner of the image, I had to apply translation to bring the center of the source image to the center of the new target with an appropriate bounding box.

## 3 Scaling

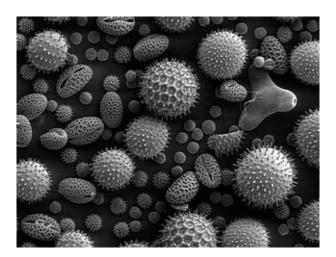


Figure 5: Source Image

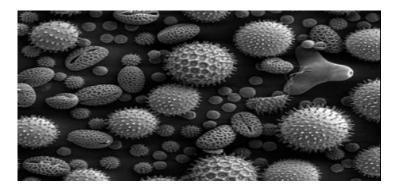


Figure 6: After scaling by factors of  $0.8\ \mathrm{and}\ 1.3$