

Krishna Varadarajan

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EDUCATION

- ✂ **The Pennsylvania State University**, M.S. in Mechanical Engineering (3.96/4.00) 2016-2019
Specialization: Robotics, State estimation, Controls University Park, PA
Awards: Graduate Teaching, and Research Assistantships
- ✂ **Vellore Institute of Technology**, B.Tech. in Mechanical Engineering (9.20/10.00 – top 2% of ~600) 2010-2014
Specialization: Dynamics Vellore, India
Awards: MIT-Harvard Medical Hackathon Winner, Special Achievers' Award, Merit Award
- ✂ **Indian Institute of Technology, Madras**, Visiting Summer Scholar Summer 2013
Area: Dynamics Chennai, India

EXPERIENCE

- ✂ **Rivian Automotive LLC** 2019-Present
Perception Engineer, Self-Driving Palo Alto, CA
- **Lane Change Feature:** Developing multi-object tracker for camera-based lane change feature
 - **Lane Confidence Estimation:** Developing algorithm to estimate confidence of lane coefficients obtained from HD Map, and front and wing cameras
 - **Camera Out-of-Focus Detection:** Developing fail-safe algorithm to detect when the vehicle-mounted camera goes out-of-focus
 - **Overpass Detection:** Developed algorithm to mitigate detect overpasses using HD Map and RADAR data. The algorithm helped reduce false positives, improving the sensor fusion stack
 - **Regression Test Framework:** Developed a templated and modular end-to-end platform-agnostic regression test framework to test the L2 self-driving algorithms. The framework uses different sources of ground truth and sensor measurements to calculate and log key performance indicators for the algorithms.
 - **CI/CD pipeline:** Designed and deployed the Jenkins pipeline for ADAS production GIT repository, which builds the regression test to ensure KPI thresholds are met before code merges
 - **Database design:** Modeled, designed and deployed a DybamoDB database on AWS to log and track algorithm performance on different on collected sensor datasets, integrating it with Airflow, Jenkins, and visualization dashboard
- ✂ **NIO USA Inc.** 2018-2019
Perception Engineer, Autonomous Driving San Jose, CA
- **Multi-Object Tracking and Data Association :** Developed multi-object tracking and data-association algorithms for L4 autonomous driving perception stack using RADAR, LiDAR, and vision sensors
 - **Regression Testing :** Developed the KPI (Key Performance Indicators) pipeline for testing, and tuning the sensor fusion algorithms; KPIs used for regression testing
 - **Multiple Hypothesis Tracking :** Developed track-to-track association logic (track labeling) across hypotheses for MHT-based object fusion
 - **DNN-Based Combined Detection & Tracking :** Led the sensor fusion team's efforts on using low-level features from DNN object detection model to perform data association and object tracking
 - **Additional Contributions:** : Robust, time and space-optimized Intersection Over Union (IOU) algorithm; Parser for KITTI and Scale AI annotation datasets; Simulation environment development for tracker validation
- ✂ **Volvo Group Trucks Technology** Fall 2017
Advanced Technology and Research Co-Op, Connected Vehicles Hagerstown, MD
- **Algorithm Design :** Developed algorithms to calculate trip parameters, driving behavior, hotel mode, and stop-start analysis parameters for Volvo customer trucks for energy management operations with teams in Greensboro, and Lyon (France)
 - **App development :** Developed an application in C# for engine dynamometer test cell to run vehicle duty-cycles through a Simulink model
 - **Road Topology Estimation :** Developed an algorithm to estimate the road topology distribution of a route using log-vehicle, and simulation data validation

⚡ **Intelligent Vehicles and Systems Group, Penn State**
Graduate Student Researcher, Connected Vehicles

2016-2018
University Park, PA

- **Hardware Instrumentation** : Instrumented an experimental truck with ADAS sensors for HIL, SIL, and on-road testing
- **On-Road Data Collection** : Collected test data on the experimental truck on multiple routes in the states of PA and MD
- **Traffic Modeling and Simulation** : Set-up traffic modeling and simulation capabilities in the research lab, and performed microscopic traffic simulations on AIMSUN to analyze control algorithms
- **Traffic Visualization** : Developed a visualization tool to visualize traffic captured using a front-facing RADAR on a mobile truck
- **Free Space Estimation** : Developed algorithm to measure the available free space in ego-vehicle's lane by fusing lane map markers with front-facing RADAR, and a camera

⚡ **Department of Mechanical Engineering, Penn State**
Graduate Teaching Assistant

2016-2018
University Park, PA

- **Classes Assisted/Taught** : Vehicle Road Dynamics (senior-year class), ME Design Methodology (junior-year class), Introduction to Thermal Sciences (inter-department class)
- **Highlight** : Mentored 8 project teams to deliver industry-sponsored design projects as part of the junior-year design class

⚡ **Indian Institute of Science**
Junior Research Fellow

2014-2016
Bengaluru, India

- **Smart-Manufacturing Lab** : Designed, and established India's first smart manufacturing laboratory, funded by Boeing R&T
- **Patient Transfer Device** : Designed, and fabricated an assistive device to transfer patients from one bed to another, also testing the device in hospitals. The work was filed for an Indian patent in June 2015.

SKILLS

⌘: C/C++, Python, YAML, MATLAB, R, HTML/CSS
📦: ROS, RTI-DDS, LINUX, MacOS

➤: CMake, waf, GDB, Protobuf, Git
🔧: GoogleTest, JIRA, JAMA

CERTIFICATIONS

⚡ **Deep Learning Specialization** by deeplearning.ai

2019-Present

Courses: Neural Networks and Deep Learning, Improving DNNs, Structuring Machine Learning Projects, Convolutional Neural Networks, Sequence Models

PUBLICATIONS

⚡ Krishna Varadarajan, et al. (2019) (*Presented in invited session*) "Analyzing the Effects of Geometric Lane Constraints on RADAR-based Sensing of Available Vehicle Headway using Mapped Lane Geometry and Camera Registration of Lane Position" *In: ASME Dynamic Systems and Control Conference (DSCC)* [[Link](#)]

⚡ V.S.Krishna Prasad, et al. (2013) "Simulation and Modeling of Performance Characteristic of Wire Cut EDM on Inconel825 using Multiple Regression and ANN" *In: International Conference on Mathematical Computer Engineering - ICMCE*. pp. 157-165

PATENTS

⚡ "Subject Transfer Apparatus" - Application No.: 2972/CHE/2015 (*Status: Pending*)
/brief: Assistive device to transfer patients with limited mobility from one platform to another

LEADERSHIP (*most recent five*)

2020-21	President and Founding Member , Rvian West-Coast ToastMasters	San Jose, CA
2017-18	President , Indian Graduate Students' Association, Penn State	University Park, PA
2017-18	Seminar Chair , Mechanical Graduate Student Council, Penn State	University Park, PA
2015-16	Organizing Team Member , ICORD'15 and 3rd ICDC international conferences	Bengaluru, India
2013-14	General Secretary , Society of Automotive Engineers-VIT Chapter	Vellore, India