

Exercise 1

(a)

$$[A|b] = \left(\begin{array}{ccc|c} 2 & 7 & 1 & 1 \\ 1 & 4 & 3 & 1 \\ 0 & 2 & 5 & 2 \end{array} \right) \xrightarrow{R_1 \leftrightarrow R_2} \left(\begin{array}{ccc|c} 1 & 4 & 3 & 1 \\ 2 & 7 & 1 & 1 \\ 0 & 2 & 5 & 2 \end{array} \right) \xrightarrow{-2R_1 + R_2 \rightarrow R_2} \left(\begin{array}{ccc|c} 1 & 4 & 3 & 1 \\ 0 & -1 & -5 & -1 \\ 0 & 2 & 5 & 2 \end{array} \right)$$

$$\xrightarrow{2R_2 + R_3 \rightarrow R_3} \left(\begin{array}{ccc|c} 1 & 4 & 3 & 1 \\ 0 & -1 & -5 & -1 \\ 0 & 0 & -5 & 0 \end{array} \right) \quad \begin{aligned} -5x_3 &= 0 \Rightarrow x_3 = 0 \\ -x_2 - 5x_3 &= -1 \Rightarrow x_2 = 1 \\ x_1 + 4x_2 + 3x_3 &= 1 \Rightarrow x_1 = -3 \end{aligned} \quad \therefore S = \left\{ \begin{pmatrix} -3 \\ 1 \\ 0 \end{pmatrix} \right\}$$

(b)

$$[A|b] = \left(\begin{array}{ccc|c} 1 & 2 & 2 & 10 \\ 3 & 4 & 3 & 5 \end{array} \right) \xrightarrow{-3R_1 + R_2 \rightarrow R_2} \left(\begin{array}{ccc|c} 1 & 2 & 2 & 10 \\ 0 & -2 & -3 & -25 \end{array} \right)$$

$$-2x_2 - 3x_3 = -25 \Rightarrow x_2 = \frac{25}{2} - \frac{3}{2}x_3$$

$$x_1 + 2x_2 + 2x_3 = 10 \Rightarrow x_1 = 10 - 2x_2 - 2x_3 = 10 - (25 - 3x_3) - 2x_3 = -15 + x_3$$

$$\therefore S = \left\{ \left(\begin{pmatrix} -15 \\ 25 \\ 0 \end{pmatrix} + \left(\begin{pmatrix} \frac{3}{2} \\ 1 \\ 1 \end{pmatrix} x_3 \mid x_3 \in \mathbb{R} \right) \right\}$$

Exercise 2

$$\text{Let } A = \begin{pmatrix} 1 & 1 & 2 \\ 2 & 3 & 1 \\ 3 & 4 & 2 \end{pmatrix}, \text{ then } [A|I_3] = \left(\begin{array}{ccc|ccc} 1 & 1 & 2 & 1 & 0 & 0 \\ 2 & 3 & 1 & 0 & 1 & 0 \\ 3 & 4 & 2 & 0 & 0 & 1 \end{array} \right).$$

$$[A|I_3] \xrightarrow{\begin{array}{l} -2R_1 + R_2 \rightarrow R_2 \\ -3R_1 + R_3 \rightarrow R_3 \end{array}} \left(\begin{array}{ccc|ccc} 1 & 1 & 2 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 1 & -4 & -3 & 0 & 1 \end{array} \right) \xrightarrow{\begin{array}{l} -R_2 + R_3 \rightarrow R_3 \\ \dots \end{array}} \left(\begin{array}{ccc|ccc} 1 & 1 & 2 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & -1 & -1 & -1 & 1 \end{array} \right)$$

$$\xrightarrow{-R_3 \rightarrow R_3} \left(\begin{array}{ccc|ccc} 1 & 1 & 2 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & -1 \end{array} \right) \xrightarrow{\begin{array}{l} 3R_3 + R_2 \rightarrow R_2 \\ -2R_3 + R_1 \rightarrow R_1 \end{array}} \left(\begin{array}{ccc|ccc} 1 & 1 & 0 & -1 & -2 & 2 \\ 0 & 1 & 0 & 1 & 4 & -3 \\ 0 & 0 & 1 & 1 & 1 & -1 \end{array} \right) \xrightarrow{\begin{array}{l} -R_2 + R_1 \rightarrow R_1 \\ \dots \end{array}} \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & -2 & -6 & 5 \\ 0 & 1 & 0 & 1 & 4 & -3 \\ 0 & 0 & 1 & 1 & 1 & -1 \end{array} \right)$$

$$= [I_3 | A^{-1}] \quad \therefore A^{-1} = \begin{pmatrix} -2 & -6 & 5 \\ 1 & 4 & -3 \\ 1 & 1 & -1 \end{pmatrix}$$

Exercise 3.

(a) No. Let $\lambda = -1$, $\vec{a} = (a_1, a_2, a_3) \in A$, where $a_i > 0$

Then $\lambda\vec{a} = -\vec{a} = (-a_1, -a_2, -a_3) \notin A$. because $-a_i \leq 0$

(b) Yes. 1) $B \in \mathbb{R}^3$ 2) $B \neq \emptyset$, and $\vec{0}_3 = (0, 0, 0) \in B$

3) Suppose $\vec{b}^1 = (b_1^1, b_2^1, b_3^1) \in B$, where $\sum_{i=1}^3 b_i^1 = 0$

$\vec{b}^2 = (b_1^2, b_2^2, b_3^2) \in B$, where $\sum_{i=1}^3 b_i^2 = 0$

then $\vec{b}^1 + \vec{b}^2 = (b_1^1 + b_1^2, b_2^1 + b_2^2, b_3^1 + b_3^2) \in B$

because $(b_1^1 + b_1^2) + (b_2^1 + b_2^2) + (b_3^1 + b_3^2) = (b_1^1 + b_2^1 + b_3^1) + (b_1^2 + b_2^2 + b_3^2) = 0 + 0 = 0$

4) Suppose $\lambda \in \mathbb{R}$, $\vec{b} = (b_1, b_2, b_3) \in B$, where $\sum_{i=1}^3 b_i = 0$

then $\lambda\vec{b} = (\lambda b_1, \lambda b_2, \lambda b_3) \in B$

because $\lambda b_1 + \lambda b_2 + \lambda b_3 = \lambda(b_1 + b_2 + b_3) = \lambda \cdot 0 = 0$

(c) No. Let $\vec{c}^1 = (1, 1, 0) \in C$, $\vec{c}^2 = (0, 1, 1) \in C$

then $\vec{c}^1 + \vec{c}^2 = (1, 2, 1) \notin C$

because it has no zero entry

(d) If the solution set is \emptyset , then the solution set is not a vector space.

If the solution set is not \emptyset ,

When $\vec{b} = \vec{0}_3$: If the solution set only contains $\vec{0}_3$, i.e. $S = \{\vec{0}_3\}$, then S is a vector space.

Prove: ① $S \in \mathbb{R}^3$ ② $S \neq \emptyset$, and $\vec{0}_3 \in S$

③ Suppose $\vec{x} = \vec{0}_3 \in S$, $\vec{y} = \vec{0}_3 \in S$, then $\vec{x} + \vec{y} = \vec{0}_3 + \vec{0}_3 = \vec{0}_3 \in S$

④ Suppose $\vec{x} = \vec{0}_3 \in S$, $\lambda \in \mathbb{R}$, then $\lambda\vec{x} = \lambda \cdot \vec{0}_3 = \vec{0}_3 \in S$

• If the solution set has infinitely many elements, ($A\vec{x} = \vec{0}$ in REF has free variables) then the solution set S is a vector space.

Prove: ① $S \in \mathbb{R}^3$ ② $S \neq \emptyset$, and $\vec{0}_3 \in S$ ($A \cdot \vec{0}_3 = \vec{0}_3$)

③ Suppose $\vec{x} \in S$, $\vec{y} \in S$, we have $A\vec{x} = \vec{0}_3$, $A\vec{y} = \vec{0}_3$

then $\vec{x} + \vec{y} \in S$, since $A(\vec{x} + \vec{y}) = A\vec{x} + A\vec{y} = \vec{0}_3 + \vec{0}_3 = \vec{0}_3 \in S$

④ Suppose $\vec{x} \in S$, $\lambda \in \mathbb{R}$, we have $\lambda A(\vec{x}) = \vec{0}_3$

then $\lambda \cdot \vec{x} \in S$, since $A(\lambda \cdot \vec{x}) = \lambda A(\vec{x}) = \lambda \cdot \vec{0}_3 = \vec{0}_3 \in S$

when $\vec{b} \neq \vec{0}_3$ • If the solution set has only one element, $S = \{\vec{0}_3\}$, then S is not a vector space
Because $\vec{0}_3 \notin S$.

• If the solution set has infinitely many elements ($A\vec{x} = \vec{b}$ in REF has free variables)
then the solution set S is not a vector space, since $\vec{0}_3 \notin S$.

Exercise 4.

(a) Let $\vec{o}_v \in V, \vec{o}_w \in W$. Then $T(\vec{o}_v) = T(\vec{o}_v + \vec{o}_v) = T(\vec{o}_v) + T(\vec{o}_v)$
 Subtract $T(\vec{o}_v)$ from both sides, we have $T(\vec{o}_v) = \vec{o}_w$.

(b) According to the definition of linear transformation, $T(\vec{a} + \vec{b}) = T(\vec{a}) + T(\vec{b})$, $T(c\vec{a}) = cT(\vec{a})$
 we have $T(c_1\vec{v}_1 + \dots + c_n\vec{v}_n) = T(c_1\vec{v}_1) + \dots + T(c_n\vec{v}_n) = c_1T(\vec{v}_1) + \dots + c_nT(\vec{v}_n)$

(c) Suppose $c_i \in \mathbb{R}$ ($i=1, \dots, n$), $\vec{o}_v \in V, \vec{o}_w \in W$.

According to the definition, $T(c_1\vec{v}_1 + \dots + c_n\vec{v}_n) = c_1T(\vec{v}_1) + \dots + c_nT(\vec{v}_n) = c_1\vec{w}_1 + \dots + c_n\vec{w}_n$
 $\vec{v}_1, \dots, \vec{v}_n$ are not independent. i.e. if $c_1\vec{v}_1 + \dots + c_n\vec{v}_n = \vec{o}_v$, c_1, \dots, c_n can not be all zeros.
 Then, we have $T(c_1\vec{v}_1 + \dots + c_n\vec{v}_n) = T(\vec{o}_v) = \vec{o}_w = c_1\vec{w}_1 + \dots + c_n\vec{w}_n$.
 Thus, $\sum_{i=1}^n c_i \vec{w}_i = \vec{o}_w$ has at least one non zero solution, then $\vec{w}_1, \dots, \vec{w}_n$ are dependent either.

(d) We already knew that $T: V \rightarrow W, S: W \rightarrow X$, then $L: V \rightarrow X$ can be represented as

$$L: V \rightarrow W \rightarrow X. \text{ i.e. } L(\vec{v}) = S(T(\vec{v})) = (S \circ T)(\vec{v}), (\vec{v} \in V)$$

$$\begin{aligned} \text{For proving } L \text{ is a linear transformation, we start from } c_1\vec{v}_1 + \dots + c_n\vec{v}_n & \quad (c_i \in \mathbb{R}, \vec{v}_i \in V, i=1, \dots, n) \\ \text{then } L(c_1\vec{v}_1 + \dots + c_n\vec{v}_n) &= S(T(c_1\vec{v}_1 + \dots + c_n\vec{v}_n)) \\ &= S(c_1T(\vec{v}_1) + \dots + c_nT(\vec{v}_n)) \\ &= c_1S(T(\vec{v}_1)) + \dots + c_nS(T(\vec{v}_n)) \\ &= c_1L(\vec{v}_1) + \dots + c_nL(\vec{v}_n) \end{aligned}$$

Thus, according to the definition, $L: V \rightarrow X$ is a linear transformation.

Exercise 5.

(a) Because the inner product $\langle \cdot, \cdot \rangle$ is linear in its first argument,

$$\text{then we have } \langle \lambda \vec{a} + \varphi \vec{b}, \vec{c} \rangle = \lambda \langle \vec{a}, \vec{c} \rangle + \varphi \langle \vec{b}, \vec{c} \rangle. (\vec{a}, \vec{b}, \vec{c} \in \mathbb{R}^n, \lambda, \varphi \in \mathbb{R})$$

Because $\langle \cdot, \cdot \rangle$ is symmetric, we have

$$\langle \lambda \vec{a} + \varphi \vec{b}, \vec{c} \rangle = \langle \vec{c}, \lambda \vec{a} + \varphi \vec{b} \rangle, \lambda \langle \vec{a}, \vec{c} \rangle = \lambda \langle \vec{c}, \vec{a} \rangle, \varphi \langle \vec{b}, \vec{c} \rangle = \varphi \langle \vec{c}, \vec{b} \rangle,$$

$$\text{then } \langle \vec{c}, \lambda \vec{a} + \varphi \vec{b} \rangle = \lambda \langle \vec{c}, \vec{a} \rangle + \varphi \langle \vec{c}, \vec{b} \rangle$$

Then $\langle \cdot, \cdot \rangle$ is linear in its second argument.

Thus, $\langle \cdot, \cdot \rangle$ is bilinear.

$$(b) \text{ Symmetric : } \langle \vec{x}, \vec{y} \rangle = x_1 y_1 + x_2 y_2 - (x_1 + x_2 + y_1 + y_2) \\ = y_1 x_1 + y_2 x_2 - (y_1 + y_2 + x_1 + x_2) = \langle \vec{y}, \vec{x} \rangle, \text{ where } \vec{x}, \vec{y} \in \mathbb{R}^2$$

Thus, $\langle \cdot, \cdot \rangle$ is symmetric.

positive define: For $\vec{x} \in \mathbb{R}^2 \setminus \{\vec{0}\}$, $\langle \vec{x}, \vec{x} \rangle = x_1^2 + x_2^2 - 2(x_1 + x_2)$

$$\text{Suppose } x_1 = x_2 = 1, \text{ then } \langle \vec{x}, \vec{x} \rangle = 1 + 1 - 2 \times 2 = -2 < 0$$

Thus, $\langle \cdot, \cdot \rangle$ is not positive define.

$$\text{For } \vec{0}_2 \in \mathbb{R}^2, \langle \vec{0}_2, \vec{0}_2 \rangle = \vec{0}_2$$

Bilinear: Suppose $\lambda, \psi \in \mathbb{R}$, $\vec{x}, \vec{y}, \vec{z} \in \mathbb{R}^2$

$$\begin{aligned} \text{We have } \langle \lambda \vec{x} + \psi \vec{y}, \vec{z} \rangle &= (\lambda x_1 + \psi y_1) z_1 + (\lambda x_2 + \psi y_2) z_2 \\ &\quad - (\lambda x_1 + \psi y_1 + \lambda x_2 + \psi y_2 + z_1 + z_2) \\ &= \lambda (x_1 z_1 + x_2 z_2) + \psi (y_1 z_1 + y_2 z_2) \\ &\quad - \lambda (x_1 + x_2) - \psi (y_1 + y_2) - (z_1 + z_2) \\ &= \lambda (x_1 z_1 + x_2 z_2 - (x_1 + x_2)) + \psi (y_1 z_1 + y_2 z_2 - (y_1 + y_2)) \\ &\quad - (z_1 + z_2) \end{aligned}$$

$$\lambda \langle \vec{x}, \vec{z} \rangle = \lambda (x_1 z_1 + x_2 z_2 - (x_1 + x_2)) - \lambda (z_1 + z_2)$$

$$\psi \langle \vec{y}, \vec{z} \rangle = \psi (y_1 z_1 + y_2 z_2 - (y_1 + y_2)) - \psi (z_1 + z_2)$$

$$\text{Because } \langle \lambda \vec{x} + \psi \vec{y}, \vec{z} \rangle - (\lambda \langle \vec{x}, \vec{z} \rangle + \psi \langle \vec{y}, \vec{z} \rangle) \neq 0$$

$$\text{then } \langle \lambda \vec{x} + \psi \vec{y}, \vec{z} \rangle \neq \lambda \langle \vec{x}, \vec{z} \rangle + \psi \langle \vec{y}, \vec{z} \rangle$$

then $\langle \cdot, \cdot \rangle$ is not linear in its first argument

Thus, $\langle \cdot, \cdot \rangle$ is not bilinear.

Exercise 6.

(a) Prove: Given that $\vec{x}, \vec{y} \in V \setminus \{\vec{0}\}$ ($\vec{x} \neq \vec{y}$), if $\vec{x} \perp \vec{y}$, then we have $\langle \vec{x}, \vec{y} \rangle = 0$

Suppose \vec{x} and \vec{y} are not independent, i.e. $\vec{y} = \lambda \vec{x}$, $\lambda \in \mathbb{R}$.

$$\text{Then, } \langle \vec{x}, \vec{y} \rangle = \langle \vec{x}, \lambda \vec{x} \rangle = \lambda \langle \vec{x}, \vec{x} \rangle$$

According to the definition of $\langle \cdot, \cdot \rangle$, $\langle \vec{x}, \vec{x} \rangle = 0$.

$$\text{Then, } \langle \vec{x}, \vec{y} \rangle = \lambda \langle \vec{x}, \vec{x} \rangle = \lambda \cdot 0 = 0 \quad (\vec{x} \neq \vec{y}),$$

which conflicts with the definition $\langle \vec{x}, \vec{y} \rangle > 0$ for $\forall \vec{x}, \vec{y} \in V \setminus \{\vec{0}\}$.

Thus, \vec{x} and \vec{y} are independent.

(b) Disprove: Suppose $\vec{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \in \mathbb{R}^3$, $\vec{y} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \in \mathbb{R}^3$, \vec{x} and \vec{y} are independent.

If we use dot product as $\langle \cdot, \cdot \rangle$, then $\langle \vec{x}, \vec{y} \rangle = 1 \neq 0$

Thus, given \vec{x} and \vec{y} are independent, they are not orthogonal.

(c) $\vec{0}$ is dependent with other vectors in the same vector space.

Prove: Suppose $\vec{x} \in V$, then $\lambda\vec{0} + \varphi\vec{x} = \vec{0}$ has non zero solutions. (e.g. $\lambda=1, \varphi=0$)

$\vec{0}$ is orthogonal with other vectors in the same vector space.

Prove: Suppose $\vec{x} \in V$, then $\langle \vec{0}, \vec{x} \rangle = \langle \vec{0} + \vec{0}, \vec{x} \rangle = \langle \vec{0}, \vec{x} \rangle + \langle \vec{0}, \vec{x} \rangle$, then $\langle \vec{0}, \vec{x} \rangle = 0$

For (a) If \vec{x} and \vec{y} are orthogonal, given $\vec{x} = \vec{0}$ and $\vec{y} \neq \vec{0}$ (or $\vec{x} \neq \vec{0}$ and $\vec{y} = \vec{0}$)

then \vec{x} and \vec{y} are not independent

If $\vec{x} = \vec{y} = \vec{0}$, then \vec{x} and \vec{y} are orthogonal and not independent.

For (b) If $\vec{x} = \vec{0}$ and $\vec{y} \neq \vec{0}$ (or $\vec{x} \neq \vec{0}$ and $\vec{y} = \vec{0}$), \vec{x} and \vec{y} are not independent.

the precondition is not satisfied

If $\vec{x} = \vec{y} = \vec{0}$, \vec{x} and \vec{y} are not independent, the precondition is not satisfied.