Semester 2, 2022 Tutorial 1

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COMP3670/6670: Introduction to Machine Learning

Question 1

Systems of Linear Equations

Let

$$\mathbf{A} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 1 \\ 0 & 0 & 0 & -1 & 0 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \\ b_5 \end{bmatrix}$$

for some constants $b_1, \ldots, b_5 \in \mathbb{R}$.

1. Show that **A** is non-invertible.

Solution. We row reduce **A** as follows,

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 1 \\ 0 & 0 & 0 & -1 & 0 \end{bmatrix}$$

$$\downarrow (R_3 = R_3 + R_1)$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 1 \\ 0 & 0 & 0 & -1 & 0 \end{bmatrix}$$

$$(R_5 = R_5 + R_3)$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Since we can row reduce the matrix to one with a zero row, this means that the matrix does not have a pivot in each column, and thus is non-invertible.

2. Find the set of solutions $\{x : Ax = b\}$.

Solution. We form the augmented matrix, and row reduce as above.

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & b_1 \\ -1 & 0 & 1 & 0 & 0 & b_2 \\ 0 & -1 & 0 & 1 & 0 & b_3 \\ 0 & 0 & -1 & 0 & 1 & b_4 \\ 0 & 0 & 0 & -1 & 0 & b_5 \end{bmatrix}$$

$$\begin{vmatrix}
(R_3 = R_3 + R_1) \\
0 & 1 & 0 & 0 & 0 & b_1 \\
-1 & 0 & 1 & 0 & 0 & b_2 \\
0 & 0 & 0 & 1 & 0 & b_3 + b_1 \\
0 & 0 & -1 & 0 & 1 & b_4 \\
0 & 0 & 0 & -1 & 0 & b_5
\end{vmatrix}$$

$$\begin{vmatrix}
(R_5 = R_5 + R_3) \\
(R_5 = R_5 + R_3)
\end{vmatrix}$$

$$\begin{bmatrix}
0 & 1 & 0 & 0 & 0 & b_1 \\
-1 & 0 & 1 & 0 & 0 & b_2 \\
0 & 0 & 0 & 1 & 0 & b_3 + b_1 \\
0 & 0 & -1 & 0 & 1 & b_4 \\
0 & 0 & 0 & 0 & 0 & b_5 + b_3 + b_1
\end{vmatrix}$$

Now, if $b_5 + b_3 + b_1 \neq 0$, then we have a contradiction, and no solutions exist. If $b_5 + b_3 + b_1 = 0$, then we can read off the equations and rearrange to obtain

$$x_1$$
 free $x_2 = b_1$ $x_3 = b_2 + x_1$ $x_4 = b_3 + b_1$ $x_5 = b_4 + b_2 + x_1$

so the solution space can be written as

$$\left\{ \begin{bmatrix} 0 \\ b_1 \\ b_2 \\ b_3 + b_1 \\ b_4 + b_2 \end{bmatrix} + \alpha \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} : \alpha \in \mathbb{R} \right\}$$

$$\varnothing \qquad \text{if } b_5 + b_3 + b_1 = 0$$

3. Hence, or otherwise, find a non-zero value for \mathbf{x} such that $\mathbf{A}\mathbf{x} = \mathbf{0}$.

Solution. Simply let all the b_i be zero, and use the same solution set as before

$$\left\{ \alpha \begin{bmatrix} 1\\0\\1\\0\\1 \end{bmatrix} : \alpha \in \mathbb{R} \right\}$$

We can then obtain the required value of \mathbf{x} by choosing α to be any non-zero constant, say, 1. Hence, choosing

$$\mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

satisfies Ax = 0.

Question 2

Matrix Inverses

Let

$$\mathbf{A} = \begin{bmatrix} 1 & -a & 0 & 0 \\ 0 & 1 & -b & 0 \\ 0 & 0 & 1 & -c \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

for some constants $a, b, c \in \mathbb{R}$.

1. For what values of a, b, c is the inverse of **A** defined?

Solution. We directly compute the inverse via row reduction, and we don't require any assumptions on a, b, c for the inverse to exist.

Row reduce $[\mathbf{A} \ I]$ to get $[I \ \mathbf{A}^{-1}]$ as follows (here R_i stands for ith row):

$$\begin{bmatrix} 1 & -a & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & -b & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -c & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{pmatrix}
(R_1 = R_1 + aR_2) \\
(R_2 = R_2 + bR_2) \\
(R_3 = R_3 + cR_4)
\end{pmatrix}$$

$$\begin{bmatrix} 1 & 0 & -ab & 0 & & 1 & a & 0 & 0 \\ 0 & 1 & 0 & -bc & & 0 & 1 & b & 0 \\ 0 & 0 & 1 & 0 & & 0 & 0 & 1 & c \\ 0 & 0 & 0 & 1 & & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\downarrow (R_1 = R_1 + abR_3)
\downarrow (R_2 = R_2 + bcR_4)$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & & 1 & a & ab & abc \\ 0 & 1 & 0 & 0 & & 0 & 1 & b & bc \\ 0 & 0 & 1 & 0 & & 0 & 0 & 1 & c \\ 0 & 0 & 0 & 1 & & 0 & 0 & 0 & 1 \end{bmatrix}$$

2. Find \mathbf{A}^{-1} assuming the properties on a, b, c to ensure the inverse exists.

Solution. We found A^{-1} above.

$$\mathbf{A}^{-1} = \begin{bmatrix} 1 & a & ab & abc \\ 0 & 1 & b & bc \\ 0 & 1 & 1 & c \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Question 3

Which matricies commute?

Let

$$\mathbf{A} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}.$$

Find all matrices $\mathbf{B} \in \mathbb{R}^{2 \times 2}$ such that $\mathbf{AB} = \mathbf{BA}$.

Solution. We write **B** as an arbitrary 2×2 matrix, form the equation AB = BA, and then find what constraints are required on **B**. So, we can write **B** as

$$\mathbf{B} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

and then expand out AB = BA.

$$\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \cdot \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$
$$\begin{bmatrix} a - c & b - d \\ c - a & d - b \end{bmatrix} = \begin{bmatrix} a - b & b - a \\ c - d & d - c \end{bmatrix}$$

This gives us the 4 constraints

$$a - c = a - b$$

$$b - d = b - a$$

$$c - a = c - d$$

$$d - b = d - c$$

which, when rearranged (and removing redundant equations) gives

$$a = d$$
 $b = c$

when means that AB = BA if and only if

$$\mathbf{B} = \begin{bmatrix} a & b \\ b & a \end{bmatrix}$$

for some $a, b \in \mathbb{R}$.

Question 4

Proving Properties of Matrix Operations

For each of the following statements, if it is true, prove it. If it is false, give a counter-example.

1. Let $\mathbf{A} \in \mathbb{R}^{n \times n}$, $\mathbf{B} \in \mathbb{R}^{n \times n}$. Assume that both \mathbf{A} and \mathbf{B} are invertible. Does $(\mathbf{A}\mathbf{B})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$ hold?

Solution. True, we merely need to verify that $\mathbf{B}^{-1}\mathbf{A}^{-1}$ is an inverse of \mathbf{AB} , by left multiplying to see if we obtain the identity, and the same with right multiplication.

$${f B}^{-1}{f A}^{-1}{f A}{f B}={f B}^{-1}{f I}{f B}={f B}^{-1}{f B}={f I}$$

 ${f A}{f B}{f B}^{-1}{f A}^{-1}={f A}{f I}{f A}^{-1}={f A}{f A}^{-1}={f I}$

2. Let $\mathbf{A} \in \mathbb{R}^{n \times n}$, $\mathbf{B} \in \mathbb{R}^{n \times n}$. Assume that both \mathbf{A} and \mathbf{B} are invertible. Does $(\mathbf{A} + \mathbf{B})^{-1} = \mathbf{A}^{-1} + \mathbf{B}^{-1}$ hold?

Solution. False, we choose $\mathbf{A} = \mathbf{I}$ and $\mathbf{B} = -\mathbf{I}$. Then, $\mathbf{A}^{-1} + \mathbf{B}^{-1} = \mathbf{I} + -\mathbf{I} = \mathbf{0}$, but $(\mathbf{A} + \mathbf{B})^{-1} = (\mathbf{I} + -\mathbf{I})^{-1} = \mathbf{0}^{-1}$, which is undefined.

3. Let $\mathbf{A} \in \mathbb{R}^{m \times n}$. Both $\mathbf{A}\mathbf{A}^T$ and $\mathbf{A}^T\mathbf{A}$ are well-defined and symmetric matrices.

Solution. True, as shown

$$(\mathbf{A}\mathbf{A}^T)^T = (\mathbf{A}^T)^T \mathbf{A}^T = \mathbf{A}\mathbf{A}^T$$
$$(\mathbf{A}^T \mathbf{A})^T = \mathbf{A}^T (\mathbf{A}^T)^T = \mathbf{A}^T \mathbf{A}$$

Also note that $\mathbf{A} \in \mathbb{R}^{m \times n}$, so the products $\mathbf{A}\mathbf{A}^T$ and $\mathbf{A}^T\mathbf{A}$ are well-defined.

¹as in, the matrix product is defined

²A symmetric matrix is one equal to it's own transpose.

4. Let $\mathbf{A} \in \mathbb{R}^{m \times n}$. If \mathbf{A} is non-invertible, then there must exist two different vectors $\mathbf{u} \in \mathbb{R}^n$ and $\mathbf{v} \in \mathbb{R}^n$ such that $\mathbf{A}\mathbf{u} = \mathbf{A}\mathbf{v}$.

Solution. False, consider the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

which is clearly non-invertible, as it isn't even square. Then, taking two arbitrary vectors

$$\mathbf{u} = \begin{bmatrix} u_x \\ u_y \end{bmatrix}, \mathbf{v} = \begin{bmatrix} v_x \\ v_y \end{bmatrix}$$

we evaluate the equation Au = Av which gives

$$\begin{bmatrix} u_x \\ u_y \\ 0 \end{bmatrix} = \begin{bmatrix} v_x \\ v_y \\ 0 \end{bmatrix}$$

which is true iff $\mathbf{u} = \mathbf{v}$.

5. Let $\mathbf{A} \in \mathbb{R}^{m \times n}$. If there exists two different vectors $\mathbf{u} \in \mathbb{R}^n$ and $\mathbf{v} \in \mathbb{R}^n$ such that $\mathbf{A}\mathbf{u} = \mathbf{A}\mathbf{v}$, then \mathbf{A} is non-invertible.

Solution. True, assume for a contradiction that **A** is invertible. Then,

$$\mathbf{A}\mathbf{u} = \mathbf{A}\mathbf{v}$$
$$\mathbf{A}^{-1}\mathbf{A}\mathbf{u} = \mathbf{A}^{-1}\mathbf{A}\mathbf{v}$$
$$\mathbf{I}\mathbf{u} = \mathbf{I}\mathbf{v}$$
$$\mathbf{u} = \mathbf{v}$$

a contradiction, as we have that \mathbf{u} and \mathbf{v} are different.

6. If there exists two different vectors $\mathbf{u} \in \mathbb{R}^n$ and $\mathbf{v} \in \mathbb{R}^n$ such that $\mathbf{A}\mathbf{u} = \mathbf{A}\mathbf{v}$, then there exists a non-zero vector \mathbf{x} such that $\mathbf{A}\mathbf{x} = \mathbf{0}$.

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Solution. True, as shown,

$$\mathbf{A}\mathbf{u} = \mathbf{A}\mathbf{v}$$
$$\mathbf{A}\mathbf{u} - \mathbf{A}\mathbf{u} = \mathbf{A}\mathbf{v} - \mathbf{A}\mathbf{u}$$
$$\mathbf{0} = \mathbf{A}(\mathbf{v} - \mathbf{u})$$

Since $\mathbf{v} \neq \mathbf{u}$ we have that $\mathbf{v} - \mathbf{u} \neq \mathbf{0}$, as required.