



**Autonomous Vehicle Simulation (AVS) Laboratory,  
University of Colorado**

**Basilisk Technical Memorandum**

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**DISCRETIZATE UTILITY**

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<b>Status:</b> Tested
<b>Scope/Contents</b>
The Basilisk Discretize Utility discretizes a given state vector.

Rev	Change Description	By	Date
1.0	First draft	S Carnahan	20180116

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## 1 Model Description

The discretize utility discretizes a given state vector according to a set of given least significant bits (LSBs). It can round toward zero, away from zero, or to the nearest multiple of the LSB.

## 2 Model Functions

The Gauss Markov functions are:

- **Set LSB:** Sets the least significant bit as a vector of length  $n$ .
- **Set Round Direction:** Sets the round direction when discretizing as to zero, away from zero, or nearest LSB multiple.
- **Set Carry Error:** Takes a boolean to state whether or not to carry over discretization error.
- **Discretize:** Discretizes a state vector of size  $n$  by corresponding LSBs
- **Get Discretization Error:** retrieves the discretization error for use by user.

## 3 Model Assumptions and Limitations

- **LSB Only:** Right now, discretization can only be set by giving a least significant bit. In the future, capability should be added to allow for discretization by max/min and number of bits.

## 4 Test Description and Success Criteria

This test is located at `src/simulation/utilitiesSelfCheck`.

### 4.1 Test Descriptions

1. To Zero Checks discretization toward zero.
2. From Zero: Checks discretization away from zero.
3. Near Checks discretization to the closest LSB multiple.
4. Carry Checks error carrying.

## 5 Test Results

All test results below

**Table 2:** Test results

Test	Pass/Fail
All Tests	PASSED

## 6 User Guide

For the best examples of the using the discretize utility, please see the IMU unit test and .cpp files.