

Class Notes

Statistical Computing & Machine Learning

Class 13

Review

The multivariate Gaussian

- Mean is specified by a vector $\bar{\mu}$; the mean for each predictor.
- Matrix Σ : Covariance matrix among predictors.

Example

Plotting the decision region for LDA and QDA

```
require(ISLR)
require(MASS, quietly = TRUE)

##
## Attaching package: 'MASS'

## The following object is masked from 'package:dplyr':
##
##      select

mod1 <- lda(default ~ balance + income, data = Default)
# plot(mod1)

pts <- with(Default,
  expand.grid(
    balance = seq(min(balance), max(balance), length = 100),
    income = seq(min(income), max(income), length = 100)
  ))
out <- predict(mod1, newdata = pts)$class
pts <- cbind(pts, prediction = out)
plot(balance ~ income, data = Default, col = default)

plot(balance ~ income, data = pts, col = prediction, pch = 20)
```

Now fit the model with prior = c(.5, .5)
Show as well for qda()

LDA

All classes are treated as having the same Σ .

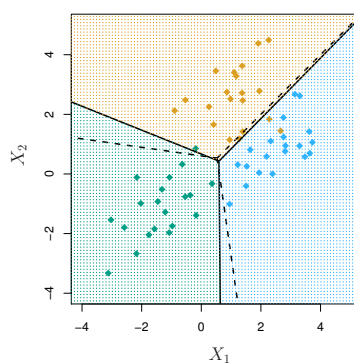
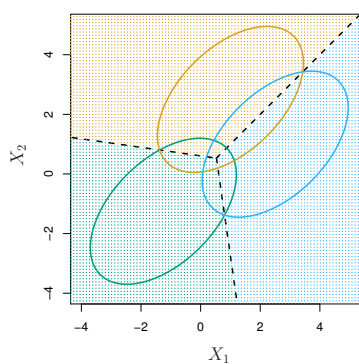
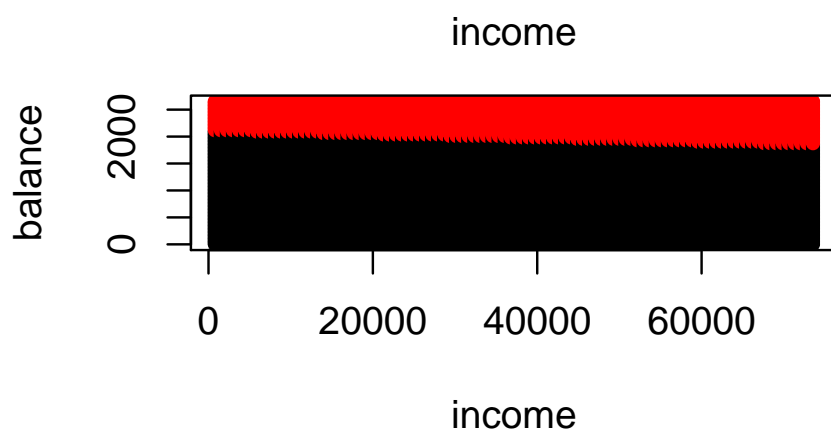
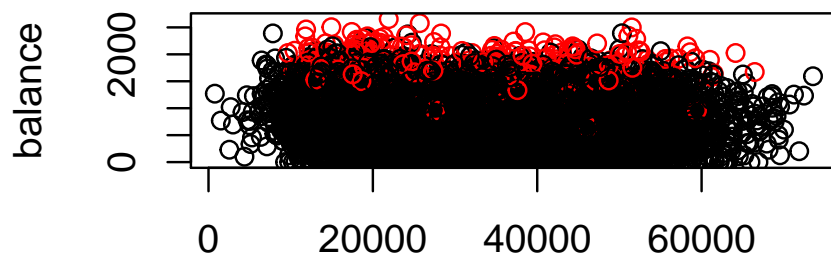


Figure 4.6 from ISL

QDA

Classes are treated with different Σ_i .

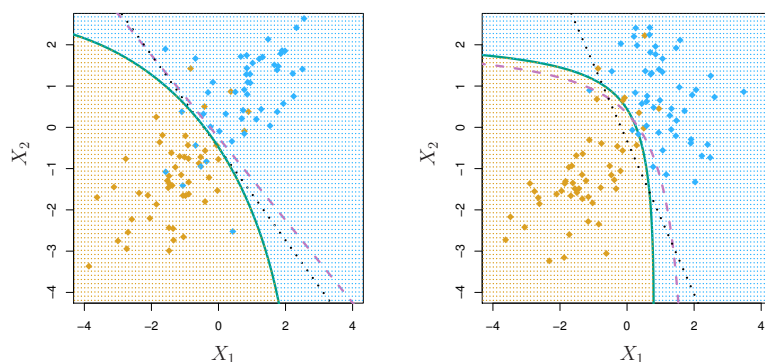


Figure 4.9 from ISL. Left: Bayes (purple dashed), LDA (black dotted), and QDA (green solid)

decision boundaries for a two-class problem with $\Sigma_1 = \Sigma_2$. Right: QDA

Error test rates on various classifiers

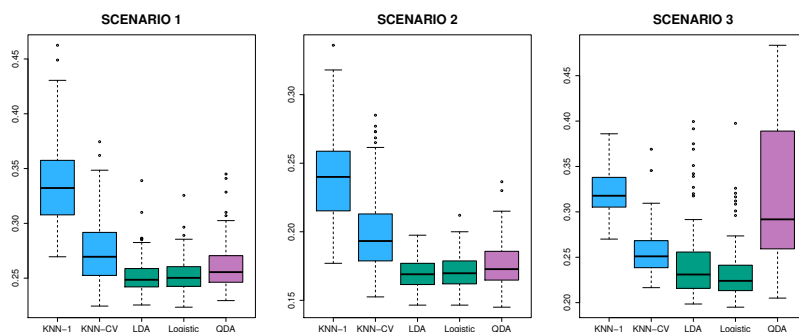


Figure 4.10 from ISL

Scenarios: In all, class means are different.

1. Each class is two uncorrelated Gaussian random vars.
2. Both classes had a correlation of -0.5
3. Uncorrelated, like (1), but the distribution is $t(df=?)$: long tailed to right.

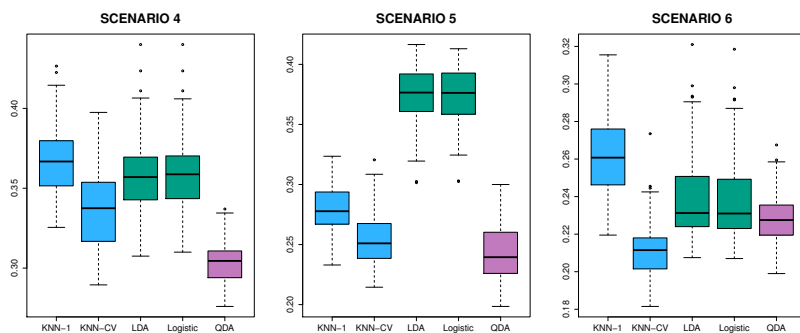


Figure 4.11 from ISL

4. Like (2), but one class has $\rho = 0.5$ and the other $\rho = -0.5$
5. A nonlinear predictor with $X_1^2, X_2^2, X_1 \times X_2$ giving a quadratic decision boundary
6. A decision boundary more complicated than a quadratic.